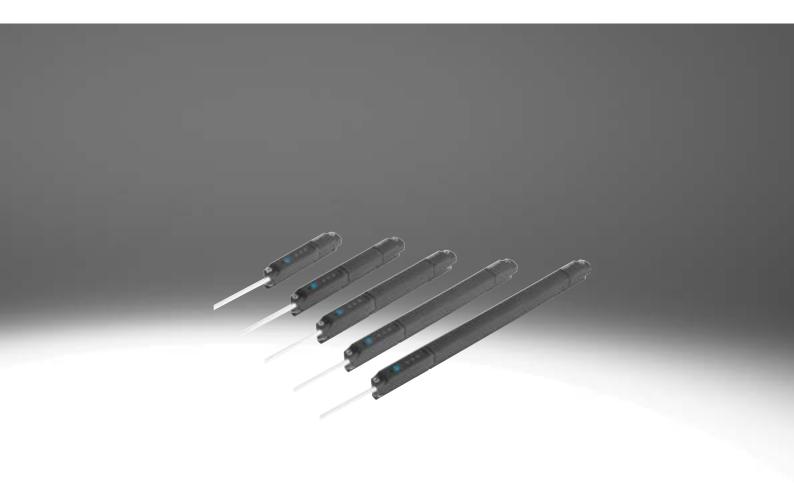
# Position transmitters SDAT-MHS, for T-slot

# **FESTO**



### Key features

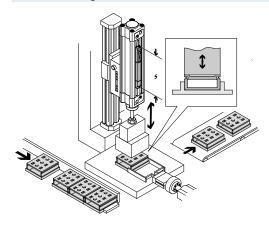
#### General

Position transmitters are used to provide feedback on piston movement in pneumatic drives. They are situated between simple proximity switches

and more expensive displacement encoders, both in terms of price and complexity. They are the ideal solution for applications in which reliable ana-

logue feedback on the piston stroke is required with high repetition accuracy, such as in press-fitting, screwing, riveting, ultrasonic welding, good/bad selection and other applications.

#### **Ultrasonic** welding



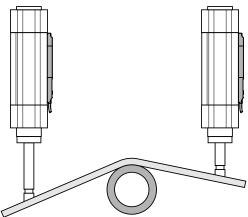
The SDAT-MHS is a position transmitter which continuously records the movement of the piston within the sensing range and makes it available as an output signal proportional to the displacement.

The sensing ranges are 50, 80, 100, 125 and 160 mm, making them perfectly harmonised to the stroke of the

best-selling Festo cylinders.

The SDAT has a 4 ... 20 mA analogue output, so it can be connected to analogue inputs without accessories. An IO-Link/switching output is available as a second interface. There is thus a choice between: switching output 24 V or IO-Link operation. The switching output is directly programmed into

# Bending

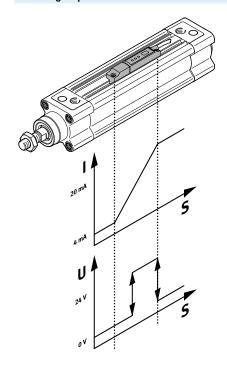


the device using a teach button; the IO-Link function is programmed via a graphic user interface in the controller. The programming options in the two operating modes are: proximity switch function, window comparator, hysteresis comparator.

The IO-Link/switching output is therefore the universal interface for simple

programming of routine application functions without needing to evaluate the analogue output.

#### **Switching output**



**O**IO-Link

Everything in a single device

- Analogue 4 ... 20 mA
- IO-Link
- Switching output

Programming options:

- Proximity switch function
- · Window comparator
- Hysteresis comparator
- NO/NC

Repetition accuracy: 0.1 mm



#### Note

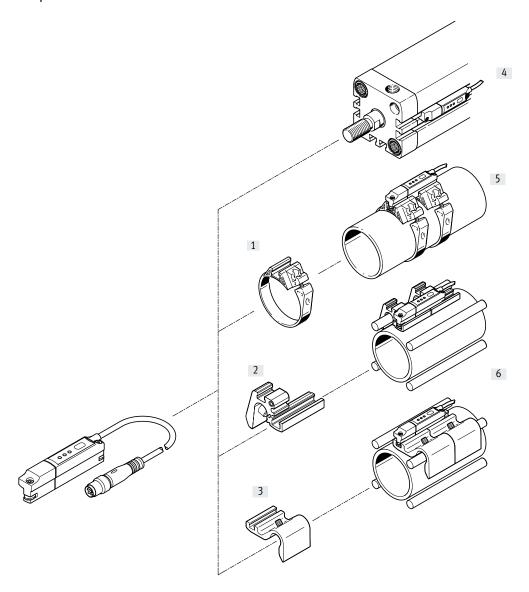
Sensors that detect magnetic fields, such as the position transmitter SDAT, must not be secured onto the drive using mountings made from ferritic materials, as this can lead to malfunction.

# Key features

For drive	Piston ∅		
Standards-based cylinders			
ADN	Ø 12, 16, 20, 25, 32, 40, 50, 63, 80		
	Ø 100, 125		
DSNU	Ø 8, 10, 12, 16, 20, 25, 32, 40, 50		
	Ø 63		
DNC	Ø 32, 40, 50, 63, 80, 100, 125		
DNCB	Ø 32, 40, 50, 63, 80, 100		
DNG	Ø 32, 40, 50, 63, 80, 100, 125		
DSBC	Ø 32, 40, 50, 63, 80, 100, 125		
DSBG	Ø 32, 40, 50, 63, 80, 100, 125, 160		
	Ø 200, 250, 320		
Piston rod cylinders			
ADVC	Ø 40, 50, 63, 80, 100		
ADVU	Ø 12, 16, 20, 25, 32, 40, 50		
	Ø 63, 80, 100, 125		
DMM	Ø 10, 16, 20, 25, 32		
DZF	Ø 12, 18, 25, 32, 40, 50, 63		
DZH	Ø 16, 20, 25		
Function-oriented drives			
DFST	ø 50, 63, 80		
STAF	ø 50, 80		

For drive Piston Ø			
Rodless cylinders			
DGC-K	Ø 18, 25, 32, 40, 50, 63, 80		
DGC-KF	Ø 18, 25, 32, 40, 50, 63		
DGC-G	ø 18, 25, 32, 40, 50, 63		
DGC-GF	Ø 18, 25, 32, 40, 50, 63		
Drives with linear guide			
DFM	Ø 12, 16, 20, 25, 32, 40, 50, 63, 80		
	Ø 100		
DFM-B	Ø 12, 16, 20, 25, 32, 40, 50, 63		
DGST	Ø 16, 20, 25		
DPZ	Ø 10, 16, 20, 25, 32		
SLE	ø 32, 40, 50		
Swivel/linear drive units			
DSL	Ø 16, 20, 25, 32, 40		
	2 10, 20, 25, 52, 10		
Semi-rotary drives with gear rack	and pinion		
DRQD	Ø 16, 20, 25, 32, 40, 50		
DRRD	Ø 16, 20, 25, 32, 40, 50, 63		
Mechanical grippers			
DHPS	Ø 35		
DHRS	Ø 32, 40		
DHWS	ø 32, 40		
HGP	Ø 35		
HGR	ø 32, 40		
HGW	Ø 32, 40		
HGPL	Ø 63		
HGPL B	Ø 14, 25, 40, 63		
HGPT G	Ø 63, 80		
HGRT	Ø 40, 50		

# Peripherals overview



Access	ories	→ Page/Internet
[1]	Mounting kit SMBR	9
[2]	Mounting SMBZ-8	9
[3]	Sensor bracket DASP-M4	9
[4]	Standards-based cylinder DNC	dnc
	Compact cylinder ADN	adn
	Short-stroke cylinder ADVC/AEVC	advc
	Compact cylinder ADVU/AEVU	advu
	Flat cylinder DZF	dzf
	Linear drive DGC	dgc
	Guided drive DFM	dfm

Access	ories	→ Page/Internet
[5]	Standards-based/round cylinder DSNU	dsnu
	Linear drive unit SLE	sle
[6]	Standards-based cylinder DSBG	dsbg

# Type codes

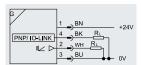
001	Series				
SDAT	Position transmitter, magnetic				
002	Sensor version				
M	Can be inserted in the slot				
003	Sensor principle				
HS	Hall sensor				
004	Measuring range				
M50	50 mm				
M80	80 mm				
M100	100 mm				
M125	125 mm				
M160	160 mm				

005	Nominal operating voltage	
1	24 V DC	
006	Display	
L	LED	
007	Switching input/output	
SA	PNP or NPN, 1 analogue output 4 20 mA, IO-Link®	
008	Cable characteristic	
E	Suitable for energy chains/robot applications	
009	Cable length [m]	
0.3	0.3	
010	Electrical connection	
M8	Plug M8	

### Position transmitters SDAT-MHS, for T-slot

### Data sheet

Function Normal operation





General technical data							
Туре		M50	M80	M100	M125	M160	
Design		For T-slot					
Type of mounting		Inserted in the sl	lot from above, screw-cla	mped			
Mounting position		Any					
Certification		RCM				,	
		c UL us listed (Ol	_)				
Degree of protection		IP65, IP68	IP65, IP68				
CE marking (see declaration	on of conformity)	To EU EMC Direct	To EU EMC Directive				
KC mark		KC EMC	KCEMC				
Note on materials		Halogen-free, Ro	HS-compliant				
Weight	[g]	19	23	26	30	35	
In much a immal/management	lamant						
Input signal/measuring e	tement	Luco	Luca	1,4400	Luce	Lucco	
Туре		M50	M80	M100	M125	M160	
Measuring principle		Magnetic Hall					
Measured variable		Position					
Sensing range	[mm]	0 50	0 80	0 100	0 125	0 160	
iisiiig iaiige	Į liiliij	0 50	0 80	0 100	J U 125	0 100	

lype		M50	M80	M100	M125	M160
Measuring principle		Magnetic Hall				
Measured variable		Position				
Sensing range	[mm]	0 50	0 80	0 100	0 125	0 160
Ambient temperature	[°C]	-25 70				
Ambient temperature with flexible cable	[°C]	-20 70				
installation						
·	[ 0]	20 70				

Signal processing		
Typical sampling interval	[ms]	1
Max. speed of travel	[m/s]	3

	[/-]	-					
Output, general							
Path resolution	[mm]	0.05					
Analogue output		M50	l M80	M100	M125	M160	

	M50	MOU	M100	M125	M160
[mA]	4 20				
[mA/mm]	0.32	0.2	0.16	0.128	0.1
[mm]	±0.25				
[mm]	0.1				
[Ω]	500		-	-	
	[mA/mm] [mm] [mm]	[mA] 4 20 [mA/mm] 0.32 [mm] ±0.25 [mm] 0.1	[mA] 4 20   [mA/mm] 0.32   [mm] ±0.25   [mm] 0.1	[mA] 4 20   [mA/mm] 0.32 0.2 0.16   [mm] ±0.25   [mm] 0.1	[mA] 4 20   [mA/mm] 0.32 0.2 0.16 0.128   [mm] ±0.25   [mm] 0.1

## Data sheet

Output, additional data	
Short circuit current rating	Yes
Overload protection	Provided

Electronics		
Operating voltage range	[V DC]	1530
Reverse polarity protection		For all electrical connections
Switching output		PNP
Switching element function		N/C or N/O, switchable
Residual ripple	[%]	10
Switch-on time	[ms]	.2
Switch-off time	[ms]	.2
Max. switching frequency	[kHz]	1
Max. output current	[mA]	100
Max. switching capacity DC	[W]	2.7
Voltage drop	[V]	2.5

Electromechanics	
Electrical connection	4-pin
	M8x1, A-coded to EN 61076-2-104
	Screw-type lock
Outlet direction of connection	In-line
Cable characteristic	Suitable for energy chains/robot applications
Cable test conditions	Bending strength: to Festo standard
	Cable chain: 5 million cycles, bending radius 28 mm
	Torsional resistance: > 300,000 cycles, ±270°/0.1 m

Display/operation		
Setting options	IO-Link	
	Pushbutton	
Ready status indication	Green LED	
Switching status indication	Yellow LED	
Status indication	Red LED	

Materials	
Housing	High-alloy stainless steel
	Nickel-plated brass
	PA-reinforced
	Polyester
Union nut	Nickel-plated brass
Cable sheath, grey	TPE-U(PUR)
Film	Polyester
Pin contacts	Gold-plated copper alloy

### Terminal allocation

Plug M8x1, 4-pin



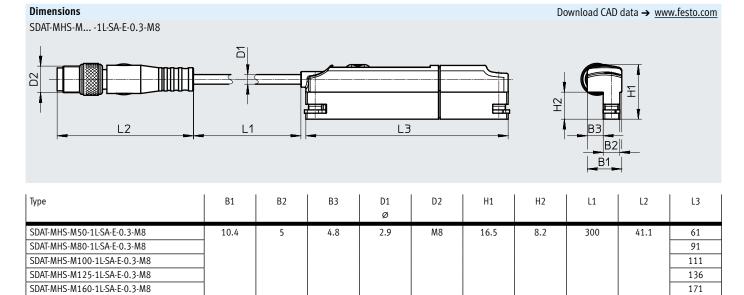
- 1 Operating voltage +24 V DC
- 2 Analogue output 4 ... 20 mA
- 3 0\
- 4 IO-Link/switching output

#### Wire colours

- 1 BN = brown
- 2 WH = white
- 3 BU = blue
- 4 BK = black

### Data sheet

IO-Link	
Protocol	IO-Link
	I-Port
Protocol version	Device V 1.1
Profile	Smart sensor profile
Function classes	Binary data channel (BDC)
	Diagnostics
	Identification
	Process data variable (PDV)
	Teach channel
Communication mode	COM3 (230.4 kBd)
SIO mode support	Yes
Port class	A
Process data width IN	2 bytes
Process data content IN	12 bit PDV (measured position value)
	4 bit BDC (position monitoring)
Minimum cycle time [ms]	1



Ordering data					
	Electrical connection	Cable length [m]	Part no.	Туре	
	4-pin, cable with plug, rotatable thread M8	0.3	1531265	SDAT-MHS-M50-1L-SA-E-0.3-M8	
			1531266	SDAT-MHS-M80-1L-SA-E-0.3-M8	
			1531267	SDAT-MHS-M100-1L-SA-E-0.3-M8	
			1531268	SDAT-MHS-M125-1L-SA-E-0.3-M8	
			1531269	SDAT-MHS-M160-1L-SA-E-0.3-M8	

## Accessories

Ordering data – Mounting components					
	For piston Ø			Part no.	Туре
Mounting kit SMBI	R				
	8				SMBR-8-8
	10			175092	SMBR-8-10
	12				SMBR-8-12
	16				SMBR-8-16
	20		175095	SMBR-8-20	
	25			175096	SMBR-8-25
	32			175097	SMBR-8-32
	40			175098	SMBR-8-40
	50			175099	SMBR-8-50
	63			175100	SMBR-8-63
Mounting SMBZ					
A ~	32 100			537806	SMBZ-8-32/100
	125 320				SMBZ-8-125/320
Sensor bracket DA	CD M4				
Selisor bracket ba	For DSBG-125			1451483	DASP-M4-125-A
	For DSBG-125			1553813	DASP-M4-160-A
	For DSBG-250			1456781	DASP-M4-250-A
	For DSBG-320				DASP-M4-320-A
	101 0300 320			3015256	DASI III4 520 A
Ordering data – Co	nnecting cables NEBU-M8				Data sheets → Internet: nebu
_	Electrical connection, left	Electrical connection, right	Cable length	Part no.	Туре
			[m]		
	Straight socket, M8x1, 4-pin	Cable, open end, 4-wire	2.5	541342	NEBU-M8G4-K-2.5-LE4
			5	541343	NEBU-M8G4-K-5-LE4
		-	'		
	Straight socket, M8x1, 4-pin	Straight socket, M8x1, 4-pin	2.5	554035	NEBU-M8G4-K-2.5-M8G4
10 miles		<u> </u>			
	Angled socket, M8x1, 4-pin	Cable, open end, 4-wire	2.5	541344	NEBU-M8W4-K-2.5-LE4
			5	541345	NEBU-M8W4-K-5-LE4
3		1			