# Planar surface gantries

FESTO

# Characteristics

## At a glance

The planar surface gantry facilitates movement in 2D space.
Depending on the requirements, the gantry is either composed of several axis modules (YXCF) or using the planar surface gantries EXCM or EXCH (YXMF). All of these are tried-and-tested components from Festo.

- Can be used universally for light to very heavy workpieces or high payloads
- Especially suitable for very long strokes
- High mechanical rigidity and sturdy design
- Freely positionable/any intermediate positions

Range of applications:
- For any movements in 2D space
- Very high requirements for precision and/or very heavy workpieces combined with long strokes (YXCR)
- Cost-effective handling unit in a compact format for small parts handling and simple tasks (YXCR-B)


[1] Servo motor for the Y-module
[2] Servo motor for the X-module
[3] Multi-pin plug distributor which collectively transfers all electrical signals such as for end-position sensing
[4] Energy chain for the X-module
[5] Energy chain for the Y-module
[6] Y-axis
[7] X-axis
[8] Profile mounting/adjusting kit

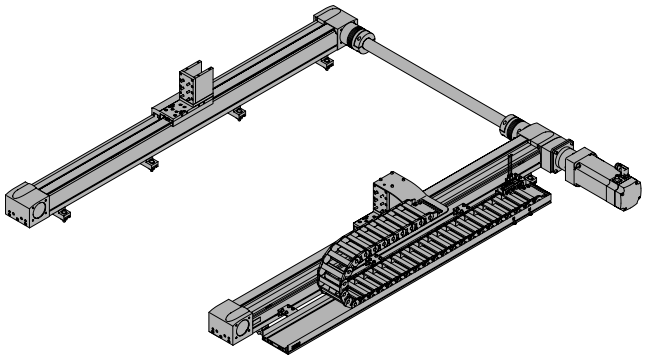
## Description of the modules

X-module

Design:

Depending on the configuration, the X-module comprises either two drive axes joined together by a connecting shaft (YXCF) or one drive axis + separate guide axis (YXCF-B).
They are powered by a servo or stepper motor.
Adapters are mounted on the slides of the X-axes to connect the Y-module.
The position of the motor and energy chain can be selected using the configurator.
The following components are located on the motor side:
- Energy chain (optional)
- Multi-pin plug distributor for proximity switch (if a sensor package has been selected)

Sample image:



# Characteristics

**Description of the modules**

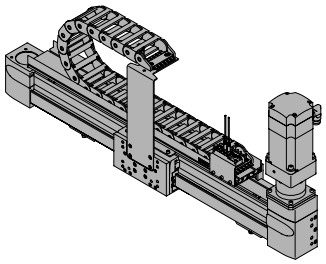
Y-module

Design:

The Y-module EHMY comprises a linear axis which is powered by a servo or stepper motor.
The position of the motor and energy chain is dependent on the position of the motor on the X-module.
The following components are located on the motor side:

- Energy chain (optional)
- Multi-pin plug distributor for proximity switch (if a sensor package has been selected)

Sample image:

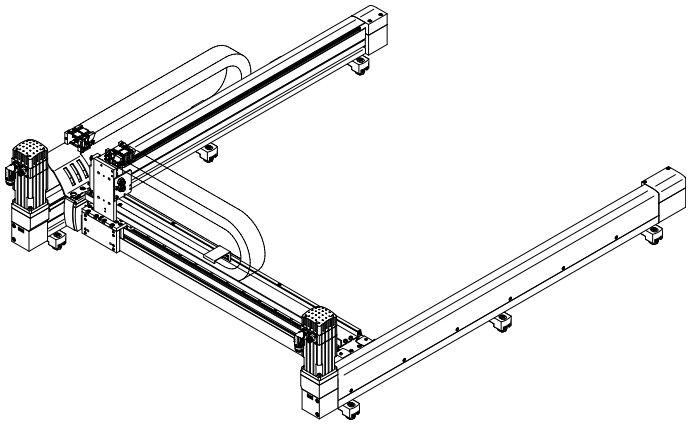


XY-module (EXCM, EXCH)

Design:

A slide is moved in a two-dimensional space (X-axis/Y-axis) via a toothed belt. The system is powered by two fixed motors. The motors are coupled to the toothed belt. The belt is guided by pulleys so that the slide can move to any position in a working space when the motors are actuated.
When using attachment components, additional processes can be carried out by independent Z-axes.

Sample image:



Dispatch options

Fully assembled:

The planar surface gantry is fully assembled. All cables are installed and connected. The system is already set up on delivery, but must be adapted to the particular mounting surface during installation.
Note flatness ➔ table below.

Partially assembled:

The planar surface gantry is delivered partially assembled. This means that both axis modules (X-/Y-axis) are assembled, each with optional motors. The partially assembled system must be completed by the customer. Help can be found in the assembly instructions provided.
Optional accessories (➔ page 10) are enclosed.
Note flatness ➔ table below.

**System overview**[1)]

| Size | YXCF-1 | YXCF-2 | YXCF-3 | YXCF-4 | YXMF-1 | YXMF-2 | YXMF-3 |
|---|---|---|---|---|---|---|---|
| Max. working stroke | X: 1900 mm<br>Y: 1800 mm | X: 3000 mm<br>Y: 1820 mm | X: 3000 mm<br>Y: 1755 mm | X: 3000 mm<br>Y: 1640 mm | X: 700 mm<br>Y: 510 mm | X: 2000 mm<br>Y: 1000 mm | X: 2500 mm<br>Y: 1500 mm |
| Max. payload | Dependent on the selected dynamic response | | | | | | |
| Required flatness of the mounting surface | ≤ 0.1 mm/m | | | | | | |
| Mounting position | Horizontal | | | | | | |

| Size | YXCF-1-B | YXCF-2-B |
|---|---|---|
| Max. working stroke | X: 800 mm<br>Y: 600 mm | X: 1000 mm<br>Y: 800 mm |
| Max. payload | Dependent on the selected dynamic response | |
| Required flatness of the mounting surface | ≤ 0.1 mm/m | |
| Mounting position | Horizontal | |

1) Drive package depends on the configuration selected.

# Characteristics

**Configurator: Handling Guide Online (HGO)**

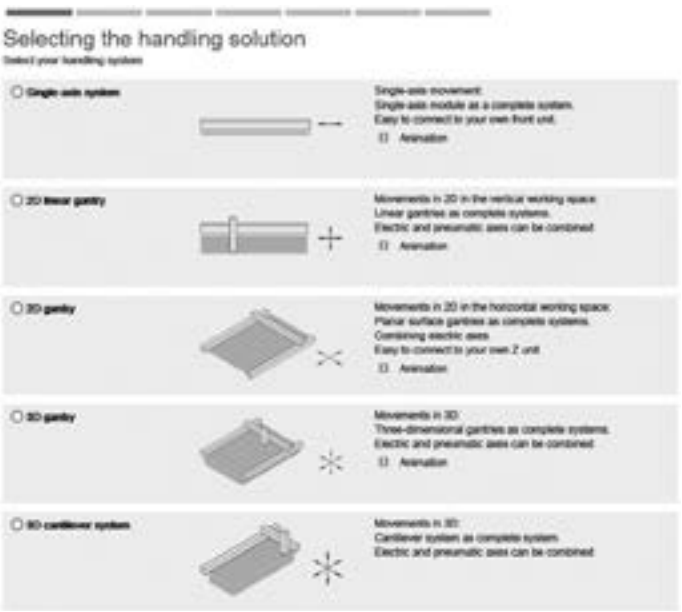
Selecting a handling system

Planning complex handling systems takes a lot of time. You can use the configurator "Handling Guide Online" (HGO) to design a customised handling system for your application in just a few steps.
You can choose from the following systems:

- Single-axis system
- 2D linear gantry
- 2D planar surface gantry
- 3-dimensional gantry
- 3D cantilever system

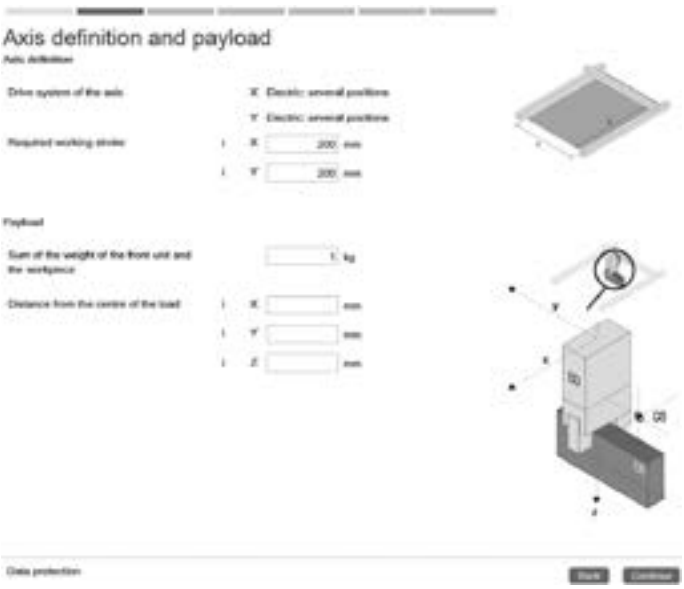
**Advantages:**

- Automatic selection of all relevant components
- Automatic design and calculation of the workload
- Quote created automatically
- CAD model available immediately
- Configuration-specific parameters for servo drives available immediately
- Complete Eplan project can be ordered according to the individual configuration
- Fully automated processing
- You can order fully or partially assembled systems through the Online Shop
- Lots of possible options




Entering the application data

- Payload
- Drive system of the axis
- Distance from the centre of the load
- Working stroke
- Reference cycle



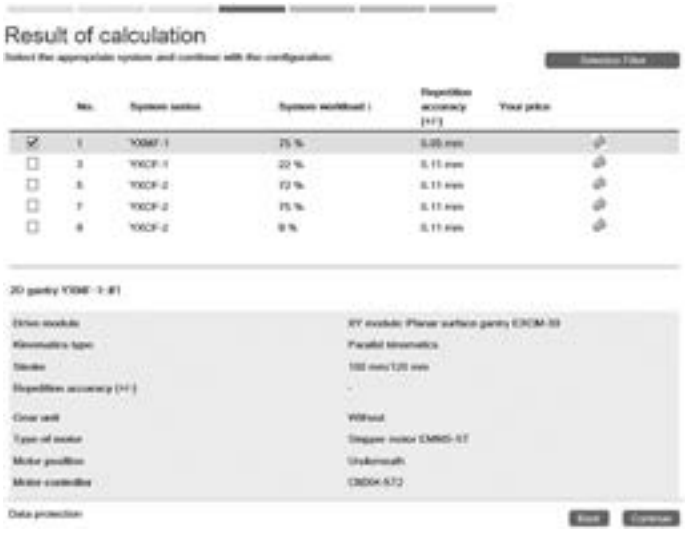
# Characteristics

**Configurator: Handling Guide Online (HGO)**

Result of calculation

You will be offered a selection of systems calculated based on the application data you entered.

The following are available immediately:
- CAD model
- Datasheet of the selected system
- Price information




System overview

You will be given an overview of the complete system.
You will also have the following options:

- Show price
- Send request
- Add to basket

# Characteristics

## Standard components within the handling system

The handling system comprises a number of tried-and-tested standard components from Festo. Different components are used depending on the configuration. The single axes installed will be displayed in the configurator HGO on the "Result of calculation" page.

## Drives/axes

X-axis

**Toothed belt axis EGC-TB-KF**

- Electric
- Rigid, closed profile
- Recirculating ball bearing guide for high loads and torques
- High dynamic response and minimum vibration

**Spindle axis ELGC-BS**

- Electric
- Optimal installation space to working space ratio
- Protected against external influences by internal guide
- Various spindle pitches

**Guide axis ELFC**

- Driveless linear guide unit with guide and freely movable slide unit
- The guide axis is designed to support forces and torques in multi-axis applications

Y-axis

**Toothed belt axis EGC-TB-KF**

- Electric
- Rigid, closed profile
- Recirculating ball bearing guide for high loads and torques
- High dynamic response and minimum vibration

**Spindle axis ELGC-BS**

- Electric
- Optimal installation space to working space ratio
- Protected against external influences by internal guide
- Various spindle pitches

**Toothed belt axis EGC-HD-TB**

- Electric
- Flat drive unit with rigid, closed profile
- Duo guide rail
- For maximum loads and torques, high feed forces and speeds and long service life

# Characteristics

**Possible axis combinations**[1)]

| Size | X-module | Y-module |
|---|---|---|
| YXCF-1 | • Toothed belt axis<br>EGC-50-TB-KF | • Toothed belt axis<br>EGC-50-TB-KF |
| YXCF-1-B | • Spindle axis<br>ELGC-60-BS | • Spindle axis<br>ELGC-45-BS<br>• Spindle axis<br>ELGC-60-BS |
| YXCF-2 | • Toothed belt axis<br>EGC-80-TB-KF | • Toothed belt axis<br>EGC-80-TB-KF<br>• Toothed belt axis with heavy-duty guide<br>EGC-HD-125-TB |
| YXCF-2-B | • Spindle axis<br>ELGC-80-BS | • Spindle axis<br>ELGC-60-BS<br>• Spindle axis<br>ELGC-80-BS |
| YXCF-3 | • Toothed belt axis<br>EGC-120-TB-KF | • Toothed belt axis<br>EGC-120-TB-KF<br>• Toothed belt axis with heavy-duty guide<br>EGC-HD-160-TB |
| YXCF-4 | • Toothed belt axis<br>EGC-185-TB-KF | • Toothed belt axis<br>EGC-185-TB-KF<br>• Toothed belt axis with heavy-duty guide<br>EGC-HD-220-TB |
| YXMF-1 | • Planar surface gantry<br>EXCM-30 | • Planar surface gantry<br>EXCM-30 |
| YXMF-2 | • Planar surface gantry<br>EXCM-40, EXCH-40 | • Planar surface gantry<br>EXCM-40, EXCH-40 |
| YXMF-3 | • Planar surface gantry<br>EXCH-60 | • Planar surface gantry<br>EXCH-60 |

1) Drive package depends on the configuration selected.

# Characteristics

## Standard components within the handling system

The handling system comprises a number of tried-and-tested standard components from Festo. Different components are used depending on the configuration. You can alter the scope and design of the drive package in the configurator HGO on the "System configuration" page.

## Motors and controllers

### Servo motors EMMT-AS

- Dynamic, brushless, permanently excited servo motor
- Digital absolute displacement encoder in single-turn or multi-turn version
- With optional brake

### Servo motors EMME-AS

- Dynamic, brushless, permanently excited servo motor
- Digital absolute displacement encoder in single-turn or multi-turn version
- With optional brake

### Servo motors EMMS-AS

- Dynamic, brushless, permanently excited servo motor
- Digital absolute displacement encoder in single-turn or multi-turn version
- With optional brake

### Servo motors EMMB-AS

- Dynamic, brushless, permanently excited servo motor
- Digital absolute displacement encoder in single-turn or multi-turn version
- With optional brake

### Stepper motors EMMS-ST

- 2-phase hybrid technology
- Step angle 1.8°
- With optional brake

### Gear unit EMGA

- Low-backlash planetary gear
- Gear ratio
  i = 3 and 5
- Life-time lubrication

### Motor controller CMMP-AS, for servo motor

- Complete integration of all components for controller and power unit, including USB interface
- Integrated brake chopper
- Integrated EMC filters
- Automatic activation for a brake

Options:

- Safety function: safe torque off (STO)/category 4, Performance Level e
- Additional digital inputs and outputs

- Bus protocols
  - CANopen
  - DeviceNet
  - EtherCAT
  - EtherNet/IP
  - PROFIBUS DP
  - PROFINET

# Characteristics

**Standard components within the handling system**

The handling system comprises a number of tried-and-tested standard components from Festo. Different components are used depending on the configuration. You can alter the scope and design of the drive package in the configurator HGO on the "System configuration" page.

**Servo drive CMMT-AS, for servo motor**

- Universal servo drive
- For synchronous servo motors
- Integrated EMC filters
- Integrated brake chopper
- Integrated braking resistor
- Position controller
- Speed controller
- Force controller
- Range of control functions

Options:
- Safety function: safe torque off (STO)/category 4, Performance Level e
- Safe stop 1 (SS1)
- Safe brake control (SBC) up to SIL3/ category 3, Performance Level e

- Bus protocols
  - EtherCAT
  - PROFINET RT/IRT
  - EtherNet/IP
  - Modbus TCP

**Servo drive CMMT-ST, for stepper motor**

- Servo drive for operating stepper motors and brushless direct current motors
- Options for point-to-point and interpolating motion and for precise positioning
- Primary voltage from 24 ... 48 V DC
- Position controller
- Speed controller
- Force controller
- Range of control functions

Options:
- Safety function: safe torque off (STO)/category 3, Performance Level e
- Safe stop 1 time controlled (SS1-t)

- Bus protocols
  - EtherCAT
  - PROFINET RT/IRT
  - EtherNet/IP
  - Modbus TCP

**Controller CMXH-ST2, for stepper motor**

- The controller controls two stepper motors in servo mode which drive an H-shaped recirculating toothed belt. The toothed belt moves a slide whose position is calculated by the controller using the encoder signals from the motors

Options:
- Safety function: safe torque off (STO)/category 3, Performance Level e

- Bus protocols
  - I/O interface
  - CAN interface
  - Ethernet TCP/IP

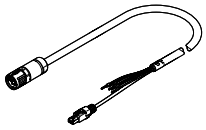
# Ordering data – Accessories

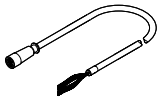
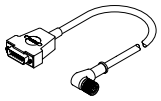
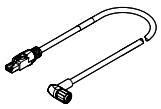
## Module/motor combinations

We recommend that the planar surface gantry is operated with the proposed motors from Festo. These precisely match the mechanical system. When using third-party motors, it is essential that the technical limits are observed.

| Module | Motor | | | | |
|---|---|---|---|---|---|
| | Servo motor | | | | Stepper motor |
| **X-module** | | | | | |
| EHMX-EGC-50-TB-KF | – | – | EMME-AS-40-M-LV-... | – | EMMS-ST-42-S-... |
| EHMX-EGC-80-TB-KF | EMMT-AS-60-L-LS-... | – | EMME-AS-60-M-LS-... | – | EMMS-ST-57-S-... |
| | EMMT-AS-100-M-HS-... | | | | |
| EHMX-EGC-120-TB-KF | EMMT-AS-80-L-LS-... | – | EMME-AS-80-S-LS-... | – | – |
| | EMMT-AS-80-L-HS-... | | | | |
| EHMX-EGC-185-TB-KF | EMMT-AS-100-L-HS-... | – | – | – | – |
| EHMX-ELGC-60-BS | – | – | – | EMMB-AS-80-07 | EMMS-ST-57-M |
| EHMX-ELGC-80-BS | – | – | – | EMMB-AS-80-07 | EMMS-ST-87-M |
| | | | | | |
| **Y-module** | | | | | |
| EHMY-...-EGC-50-TB-KF | – | – | EMME-AS-40-S-LV-... | – | EMMS-ST-57-M-... |
| EHMY-...-EGC-80-TB-KF | EMMT-AS-60-S-LS-... | – | EMME-AS-60-M-LS-... | – | EMMS-ST-57-S-... |
| EHMY-...-EGC-120-TB-KF | EMMT-AS-80-L-LS-... | – | EMME-AS-80-S-LS-... | – | EMMS-ST-87-S-... |
| | EMMT-AS-80-L-HS-... | | | | |
| EHMY-...-EGC-125-TB-HD | EMMT-AS-60-L-LS-... | – | EMME-AS-60-M-LS-... | – | EMMS-ST-57-S-... |
| EHMY-...-EGC-160-TB-HD | EMMT-AS-80-M-LS-... | – | EMME-AS-80-S-LS-... | – | EMMS-ST-87-S-... |
| | EMMT-AS-80-L-HS-... | | | | |
| EHMY-...-EGC-185-TB-KF | EMMT-AS-100-L-HS-... | – | EMME-AS-100-M-HS-... | – | – |
| EHMY-...-EGC-220-TB-HD | EMMT-AS-100-L-HS-... | – | EMME-AS-100-M-HS-... | – | – |
| EHMY-RP-ELGC-45-BS | – | – | – | EMMB-AS-40-01 | EMMS-ST-42-S |
| EHMY-RP-ELGC-60-BS | – | – | – | EMMB-AS-60-04 | EMMS-ST-57M |
| EHMY-RP-ELGC-80-BS | – | – | – | EMMB-AS-60-04 | EMMS-ST-87-M |
| | | | | | |
| **XY-module (EXCM, EXCH)** | | | | | |
| EXCM-30 | – | – | – | – | EMMS-ST-42-S-... |
| EXCM-40 | – | – | – | – | EMMS-ST-57-M-... |
| EXCH-40 | – | EMMS-AS-70-M-LS-... | – | – | – |
| EXCH-40 | – | EMMS-AS-100-S-HS-... | – | – | – |
| EXCH-60 | – | EMMS-AS-100-M-HS-... | – | – | – |
| EXCH-60 | – | EMMS-AS-140-S-HV-... | – | – | – |

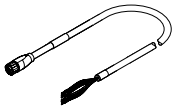
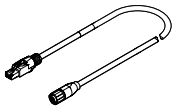
# Ordering data – Accessories

| Ordering data | | | | |
|---|---|---|---|---|
| | Description | Cable length [m] | Part no. | Type |
| **For servo motor EMMT-AS** | | | | |
| **Motor cable** | | | | |
|  | • For EMMT-AS-60/80 with CMMT-AS | 2.5 | **5251374** | **NEBM-M23G15-EH-2.5-Q7N-R3LEG14** |
| | | 5 | **5251375** | **NEBM-M23G15-EH-5-Q7N-R3LEG14** |
| | | 7.5 | **5251376** | **NEBM-M23G15-EH-7.5-Q7N-R3LEG14** |
| | | 10 | **5251377** | **NEBM-M23G15-EH-10-Q7N-R3LEG14** |
| | | 15 | **5251378** | **NEBM-M23G15-EH-15-Q7N-R3LEG14** |
| | | 20 | **5251379** | **NEBM-M23G15-EH-20-Q7N-R3LEG14** |
| | • For EMMT-AS-100 with CMMT-AS | 2.5 | **5251381** | **NEBM-M23G15-EH-2.5-Q9N-R3LEG14** |
| | | 5 | **5251382** | **NEBM-M23G15-EH-5-Q9N-R3LEG14** |
| | | 7.5 | **5251383** | **NEBM-M23G15-EH-7.5-Q9N-R3LEG14** |
| | | 10 | **5251384** | **NEBM-M23G15-EH-10-Q9N-R3LEG14** |
| | | 15 | **5251385** | **NEBM-M23G15-EH-15-Q9N-R3LEG14** |
| | | 20 | **5251386** | **NEBM-M23G15-EH-20-Q9N-R3LEG14** |

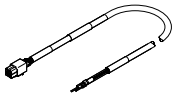
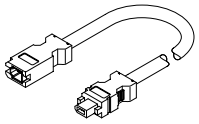
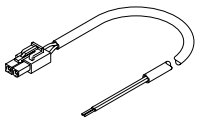
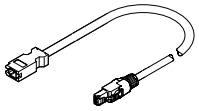
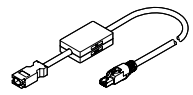
| Designation | Description | Cable length [m] | Part no. | Type |
|---|---|---|---|---|
| **For servo motor EMMS-AS** | | | | |
| **Motor cable**[1] | | | | |
|  | • For servo motor EMMS-AS-70/100/140 with CMMP-AS | 5 | **550310** | **NEBM-M23G8-E-5-Q9N-LE8** |
| | | 10 | **550311** | **NEBM-M23G8-E-10-Q9N-LE8** |
| | | 15 | **550312** | **NEBM-M23G8-E-15-Q9N-LE8** |
| | • For servo motor EMMS-AS-70/100/140 with CMMT-AS | 5 | **5391141** | **NEBM-M23G8-E-5-Q9N-LE8-1** |
| | | 10 | **5391144** | **NEBM-M23G8-E-10-Q9N-LE8-1** |
| | | 15 | **5391139** | **NEBM-M23G8-E-15-Q9N-LE8-1** |
| **Encoder cable**[1] | | | | |
|  | • For servo motor EMMS-AS-70/100/140 with CMMP-AS | 5 | **550318** | **NEBM-M12W8-E-5-N-S1G15** |
| | | 10 | **550319** | **NEBM-M12W8-E-10-N-S1G15** |
| | | 15 | **550320** | **NEBM-M12W8-E-15-N-S1G15** |
|  | • For servo motor EMMS-AS-70/100/140 with CMMT-AS | 5 | **5213423** | **NEBM-M12W8-E-5-N-R3G8** |
| | | 10 | **5213425** | **NEBM-M12W8-E-10-N-R3G8** |
| | | 15 | **5213426** | **NEBM-M12W8-E-15-N-R3G8** |

1) Cables especially suitable for the motor controller and motor.
Degree of protection to IP65 (in assembled state)

# Ordering data – Accessories

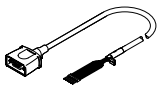
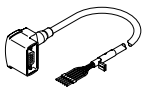
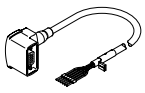
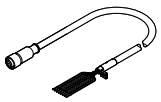
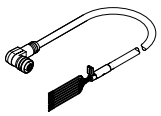
| Ordering data | Description | Cable length [m] | Part no. | Type |
|---|---|---|---|---|
| **For servo motor EMME-AS** | | | | |
| **Motor cable** | | | | |
|  | • For EMME-AS-40/60 with CMMT-AS | 2.5 | **5391541** | **NEBM-M16G8-E-2.5-Q7-LE8-1** |
| | | 5 | **5391543** | **NEBM-M16G8-E-5-Q7-LE8-1** |
| | | 7.5 | **5391548** | **NEBM-M16G8-E-7.5-Q7-LE8-1** |
| | | 10 | **8085952** | **NEBM-M16G8-E-10-Q7-LE8-1** |
| | | 15 | **8085953** | **NEBM-M16G8-E-15-Q7-LE8-1** |
| | | 20 | **611113** | **NEBM-M16G8-E-20-Q7-LE8-1** |
| | • For EMME-AS-80/100 with CMMT-AS | 2.5 | **5391540** | **NEBM-M16G8-E-2.5-Q9-LE8-1** |
| | | 5 | **5391545** | **NEBM-M16G8-E-5-Q9-LE8-1** |
| | | 7.5 | **5391547** | **NEBM-M16G8-E-7.5-Q9-LE8-1** |
| | | 10 | **5391549** | **NEBM-M16G8-E-10-Q9-LE8-1** |
| | | 15 | **5391550** | **NEBM-M16G8-E-15-Q9-LE8-1** |
| | | 20 | **611114** | **NEBM-M16G8-E-20-Q9-LE8-1** |
| **Encoder cable** | | | | |
|  | • For EMME-AS-40/60/80/100 with CMMT-AS | 2.5 | **5212312** | **NEBM-M12G8-E-2.5-N-R3G8** |
| | | 5 | **5212313** | **NEBM-M12G8-E-5-N-R3G8** |
| | | 7.5 | **5212314** | **NEBM-M12G8-E-7.5-N-R3G8** |
| | | 10 | **5212315** | **NEBM-M12G8-E-10-N-R3G8** |
| | | 15 | **5212316** | **NEBM-M12G8-E-15-N-R3G8** |
| | | 20 | **611112** | **NEBM-M12G8-E-20-N-R3G8** |

# Ordering data – Accessories

| Ordering data | | | | |
|---|---|---|---|---|
| | | Cable length [m] | Part no. | Type |
| **For servo motor EMMB-AS** | | | | |
| **Motor cable** | | | | |
|  | • For EMMB-AS-40/60/80 with CMMT-AS | 2.5 | **5219197** | **NEBM-H6G4-E-2.5-Q13N-LE4** |
| | | 5 | **5219198** | **NEBM-H6G4-E-5-Q13N-LE4** |
| | | 7.5 | **5219199** | **NEBM-H6G4-E-7.5-Q13N-LE4** |
| | | 10 | **5219200** | **NEBM-H6G4-E-10-Q13N-LE4** |
| | | 15 | **8097203** | **NEBM-H6G4-E-15-Q13N-LE4** |
| **Encoder cable** | | | | |
|  | • For EMMB-AS-40/60/80 with CMMT-AS | 2.5 | **5219213** | **NEBM-REG6-E-2.5-Q14N-REG6** |
| | | 5 | **5219214** | **NEBM-REG6-E-5-Q14N-REG6** |
| | | 7.5 | **5219215** | **NEBM-REG6-E-7.5-Q14N-REG6** |
| | | 10 | **5219216** | **NEBM-REG6-E-10-Q14N-REG6** |
| | | 15 | **8097200** | **NEBM-REG6-E-15-Q14N-REG6** |
| **Connecting cable for brake** | | | | |
|  | • For EMMB-AS-40/60/80 with CMMT-AS | 2.5 | **5219205** | **NEBM-H7G2-E-2.5-Q14N-LE2** |
| | | 5 | **5219206** | **NEBM-H7G2-E-5-Q14N-LE2** |
| | | 7.5 | **5219207** | **NEBM-H7G2-E-7.5-Q14N-LE2** |
| | | 10 | **5219208** | **NEBM-H7G2-E-10-Q14N-LE2** |
| | | 15 | **8097206** | **NEBM-H7G2-E-15-Q14N-LE2** |
| **Adapter for encoder cable (absolutely essential)** | | | | |
|  | • For EMMB-AS-40/60/80 with CMMT-AS | **For single-turn version with CMMT-AS** | | |
| | | 0.5 | **8097197** | **NEFM-REG6-K-0.5-R3G8** |
|  | • For EMMB-AS-40/60/80 with CMMT-AS | **For multi-turn version with CMMT-AS**[1] | | |
| | | 0.5 | **8097195** | **NEFM-REG6-K-0.5-B-R3G8** |
| | | **For multi-turn version with CMMB-AS**[1] | | |
| | | 0.5 | **8097196** | **NEFM-REG6-K-0.5-B-REG6** |

1) The required battery is not included in the scope of delivery

# Ordering data – Accessories

| Designation | Description | Cable length [m] | Part no. | Type |
|---|---|---|---|---|
| **For stepper motor EMMS-ST** | | | | |
| **Motor cable**[1] | | | | |
|  | • For stepper motor EMMS-ST-42/57 with CMMT-ST<br>• Straight plug | 2.5 | **1450369** | **NEBM-S1G9-E-2.5-Q5-LE6** |
| | | 5 | **1450370** | **NEBM-S1G9-E-5-Q5-LE6** |
| | | 7 | **1450371** | **NEBM-S1G9-E-7-Q5-LE6** |
| | | 10 | **1450372** | **NEBM-S1G9-E-10-Q5-LE6** |
| | | 15 | **5085055** | **NEBM-S1G9-E-15-Q5-LE6** |
| | | 20 | **5085056** | **NEBM-S1G9-E-20-Q5-LE6** |
|  | • For stepper motor EMMS-ST-42/57 with CMMT-ST<br>• Angled plug | 2.5 | **1450737** | **NEBM-S1W9-E-2.5-Q5-LE6** |
| | | 5 | **1450738** | **NEBM-S1W9-E-5-Q5-LE6** |
| | | 7 | **1450739** | **NEBM-S1W9-E-7-Q5-LE6** |
| | | 10 | **1450740** | **NEBM-S1W9-E-10-Q5-LE6** |
| | | 15 | **610856** | **NEBM-S1W9-E-15-Q5-LE6** |
|  | • For stepper motor EMMS-ST-87 with CMMT-ST<br>• Angled plug | 2.5 | **1450944** | **NEBM-S1W15-E-2.5-Q7-LE6** |
| | | 5.0 | **1450945** | **NEBM-S1W15-E-5-Q7-LE6** |
| | | 7.0 | **1450946** | **NEBM-S1W15-E-7-Q7-LE6** |
| | | 10 | **1450947** | **NEBM-S1W15-E-10-Q7-LE6** |
| | | 15 | **610857** | **NEBM-S1W15-E-15-Q7-LE6** |
| **Encoder cable**[1] | | | | |
|  | • For stepper motor EMMS-ST-42/57/87 with CMMT-ST<br>• Straight plug | 2.5 | **1451587** | **NEBM-M12G8-E-2.5-LE8** |
| | | 5 | **1451588** | **NEBM-M12G8-E-5-LE8** |
| | | 7 | **1451589** | **NEBM-M12G8-E-7-LE8** |
| | | 10 | **1451590** | **NEBM-M12G8-E-10-LE8** |
| | | 15 | **611110** | **NEBM-M12G8-E-15-LE8** |
| | | 20 | **611111** | **NEBM-M12G8-E-20-LE8** |
|  | • For stepper motor EMMS-ST-42/57/87 with CMMT-ST<br>• Angled plug | 2.5 | **1451675** | **NEBM-M12W8-E-2.5-LE8** |
| | | 5 | **1451676** | **NEBM-M12W8-E-5-LE8** |
| | | 7 | **1451677** | **NEBM-M12W8-E-7-LE8** |
| | | 10 | **1451678** | **NEBM-M12W8-E-10-LE8** |
| | | 15 | **610858** | **NEBM-M12W8-E-15-LE8** |

1) Cables especially suitable for the motor controller and motor.
Degree of protection to IP65 (in assembled state)

**Possible cable and tube lengths**

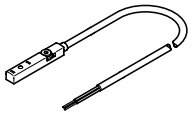
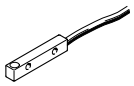
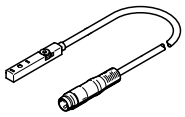
- Cables and tubing are selected so that the length specified when ordering will be the minimum connection length from the energy chain output.
- Cables and tubing are only available in fixed lengths as stated in the table below. This can mean that the cable plugs of the different cables do not end at the same point.

| Length | 1 m | 2 m | 5 m | 7 m | 10 m |
|---|---|---|---|---|---|
| Motor cable | – | ■ | ■ | ■ | ■ |
| Encoder cable | – | ■ | ■ | ■ | ■ |
| Multi-pin plug connecting cable | – | ■ | ■ | ■ | ■ |
| Tubing (for DHMZ only) | ■ | ■ | ■ | – | – |

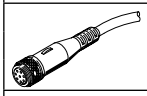
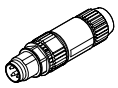
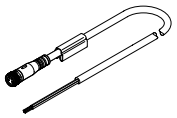
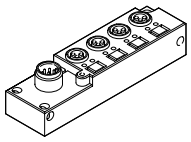
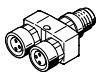
# Ordering data – Accessories

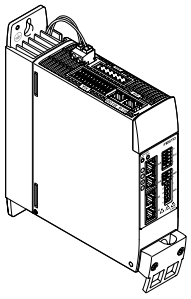
**Standard components within the handling system**

The handling system comprises a number of tried-and-tested standard components from Festo. Different components are used depending on the configuration. You can alter the scope and design of the accessories in the configurator HGO on the "System configuration" page.

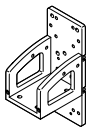
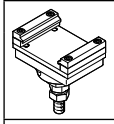
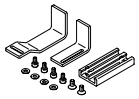
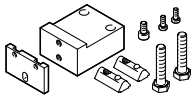
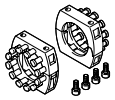
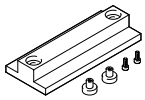
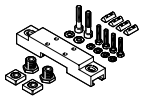
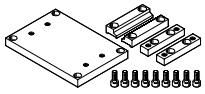
| Designation | Description | | Cable length [m] | Part no. | Type |
|---|---|---|---|---|---|
| **Proximity switch (inductive) for sensing the position of the slide on the X-/Y-/Z-axis** | | | | | |
|  | **Cable with open end** | | | | |
| | • For toothed belt axis EGC-TB, EGC-HD-TB<br>• For spindle axis EGC-BS<br>• For spindle axis ELGC-BS<br>• For DC voltage<br>Included if the "Festo sensor package" is selected:<br>• For EGC, ELGC: 2 pieces | PNP, N/C contact | 7.5 | **551391** | **SIES-8M-PO-24V-K-7.5-OE** |
| | | PNP, N/O contact | 7.5 | **551386** | **SIES-8M-PS-24V-K-7.5-OE** |
| | | NPN, N/C contact | 7.5 | **551401** | **SIES-8M-NO-24V-K-7.5-OE** |
| | | NPN, N/O contact | 7.5 | **551396** | **SIES-8M-NS-24V-K-7.5-OE** |
| **Proximity switches for sensing the position of the slide on the X-axis** | | | | | |
|  | • For EXCM-40, EXCH-40, EXCH-60 | PNP, N/O contact | – | **150491** | **SIES-V3B-PS-S-L** |
|  | • For EXCM-40, EXCH-40, EXCH-60 | PNP, N/C contact | – | **174552** | **SIES-Q8B-PO-K-L** |
| | Included if the "Festo sensor package" is selected:<br>• 1 piece | | | | |
| **Proximity switch (inductive) for sensing the position of the slide on the Y-axis** | | | | | |
|  | **Cable with plug** | | | | |
| | • For EXCM-40, EXCH-40, EXCH-60<br>• For DC voltage<br>Included if the "Festo sensor package" is selected:<br>• 1 piece | PNP, N/C contact | 0.3 | **551392** | **SIES-8M-PO-24V-K-0.3-M8D** |
| | | PNP, N/O contact | 0.3 | **551387** | **SIES-8M-PS-24V-K-0.3-M8D** |

# Ordering data – Accessories

| Designation | Description | Cable length [m] | Part no. | Type |
|---|---|---|---|---|
| **Plug socket with cable** | | | | |
|  | • Connection between multi-pin plug distributor NEDU and control cabinet | 5 | **525618** | **SIM-M12-8GD-5-PU** |
| | | 10 | **570008** | **SIM-M12-8GD-10-PU** |
| **Plug** | | | | |
|  | • For connection to the multi-pin plug distributor NEDU / distributor NEDY | – | **562024** | **NECU-S-M8G3-HX** |
| **Connecting cable** | | | | |
|  | • Connection between distributor NEDY and control cabinet | 2.5 | **541342** | **NEBU-M8G4-K-2.5-LE4** |
| | | 5 | **541343** | **NEBU-M8G4-K-5-LE4** |
| | | 7.5 | **610854** | **NEBU-M8G4-K-7.5-LE4** |
| | | 10 | **589560** | **NEBU-M8G4-K-10-LE4** |
| | | 15 | **610855** | **NEBU-M8G4-K-15-LE4** |
| **Multi-pin plug distributor** | | | | |
|  | • With the help of the multi-pin plug distributor, electrical signals such as for end-position sensing can be transferred collectively<br>Options:<br>– 4 individual connections<br>– 6 individual connections | – | **574586** | **NEDU-L4R1-M8G3L-M12G8** |
| | | | **574587** | **NEDU-L6R1-M8G3L-M12G8** |
|  | • With the help of the distributor, electrical signals such as for end-position sensing can be transferred collectively<br>– 2 individual connections | – | **8005312** | **NEDY-L2R1-V1-M8G3-N-M8G4** |

| Designation | Description |
|---|---|
| **Motor controller/servo drive** | |
|  | The accessories for the relevant motor controllers/servo drives can be found at:<br>• www.festo.com/catalogue/cmmp<br>• www.festo.com/catalogue/cmmt<br>• www.festo.com/catalogue/cmxh |

# Ordering data – Accessories

| Designation | Description | | Part no. | Type |
|---|---|---|---|---|
| **Mounting kit** | | | | |
|  | • Mounting kit for the energy chain and a Z-axis, such as EGSL, DGSL | • EXCM-30 | **4070088** | **EAHT-E9-FB-3D-30** |
| **Adjusting kit** | | | | |
|  | • Height-adjustable mounting kit | • EXCM-30 | **4070088** | **EADC-E11-30** |
| **Sensor mounting** | | | | |
|  | • For homing in combination with third-party motors | • EXCM-30 | **4070088** | **EAPR-E11-30** |
| **Sensor mounting** | | | | |
|  | • For mounting the proximity switches SIES-Q8B, SIES-V3B on the X-axis | • EXCM-40, EXCH-40 | **2536353** | **EAPR-E12-40** |
| | | EXCH-60 | **2478805** | **EAPR-E12-60** |
| **Energy chain** | | | | |
|  | • As a cable guide for the Z-axis | • EXCM-30 | **8059999** | **EADH-U-3D-30** |
| | | | **8060324** | **EADH-U-3D-40** |
| **Connector set** | | | | |
|  | • Retaining brackets for mounting the energy chain | • EXCM-30 | **8060325** | **EAHT-AE-3D-30** |
| | | | **8060326** | **EAHT-AE-3D-40** |
| **Adjusting tool** | | | | |
|  | • For aligning and checking the flatness of the planar surface gantry | EXCM-40, EXCH-40, EXCH-60 | **3197697** | **EADT-W-E12** |
| **Adjusting kit** | | | | |
|  | • Used to mount the handling system on the supporting surface<br>• Can be used to easily compensate for any unevenness in the supporting surface | EHMX-...-EGC-50-TB-KF | **8047565** | **EADC-E15-50-E7** |
| | | EHMX-...-EGC-80-TB-KF | **8047566** | **EADC-E15-80-E7** |
| | | EHMX-...-EGC-120-TB-KF | **8047567** | **EADC-E15-120-E7** |
| | | EHMX-...-EGC-185-TB-KF | **8047568** | **EADC-E15-185-E7** |
| | | EHMX-...-ELGC-60-BS | **8142650** | **EADC-E15-60-E22** |
| | | EHMX-...-ELGC-80-BS | **8142651** | **EADC-E15-80-E22** |
| **Profile mounting** | | | | |
|  | • Used to mount the handling system on the supporting surface<br>• It is not height-adjustable | EHMX-...-ELGC-60-BS | **8142652** | **EAHM-E15-60-E22** |
| | | EHMX-...-ELGC-80-BS | **8142653** | **EAHM-E15-80-E22** |

# Programming aid

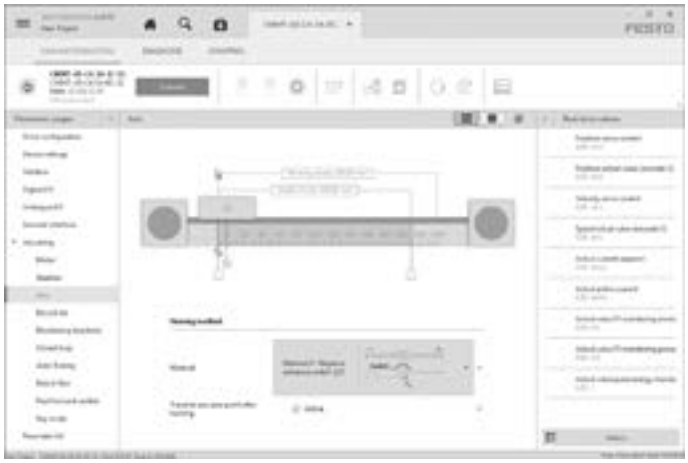
**FCT software – Festo Configuration Tool**

Software platform for electric drives from Festo (➔ www.festo.com/sp/fct)

- All drives in a system can be managed and saved in a common project
- Project and data management for all supported types of equipment
- Simple to use thanks to graphically supported parameter entry
- Universal mode of operation for all drives
- Work offline at your desk or online at the machine

**Festo Automation Suite**

Parameterisation and programming software for electronic devices from Festo



- Parameterisation, programming and commissioning in a clear and user-friendly interface
- Optimum support for complex processes thanks to guided wizards (e.g. for commissioning, drive configuration, etc.)
- Fast access to the required documents and additional information
- Easy integration of electric drives in the controller programming