Rotary drive units ERMS







Key features

At a glance

Plug and work with the Simplified Motion Series



The simplicity of pneumatics is now combined for the first time with the advantages of electric automation thanks to the Simplified Motion Series. These integrated drives are the perfect solution for all users who are looking for an electric alternative for very simple movement and positioning tasks between two mechanical end positions, but don't want the commissioning process for traditional electric drive systems that can often be quite complex.

Integrated

The integrated electronics in the drive are at the core of the Simplified Motion Series.

Simple

For commissioning, simply set all relevant parameters directly on the drive:

- · Speed and force
- Reference end position and cushioning
- Manual operation

IO-Link

There is no need for any software since operation is simply based on the "plug and work" principle. Digital I/O (DIO) and IO-Link are always automatically included – a product with two types of control as standard.

Standardised

Electrical connection via M12 plug design

- Power (4-pin): power supply for the motor
- Logic (8-pin): control signal, sensor signal and power for the integrated electronics

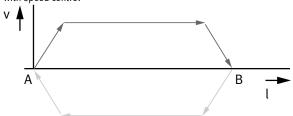
Connected

Use of extended functions possible via IO-Link.

- Motion parameters can be set remotely
- Copy and backup function for transferring parameters
- Read function for extended process parameters

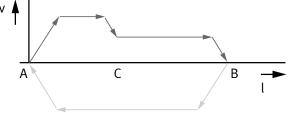
The functions of the Simplified Motion Series

Basic profile for movement between two end positions: with speed control



- These drives are designed for simple movements between two end positions.
- Proximity sensors are required in order to implement any intermediate positions.

Extended motion profile for simplified press-fitting and clamping functions: with speed and force control



The products in the Simplified Motion Series

Spindle axis unit ELGS-BS-KF



Toothed belt axis unit ELGE



Toothed belt axis unit ELGS-TB-KF



Rotary drive unit ERMS



Mini slide unit EGSS-BS-KF



Electric cylinder unit



Electric cylinder unit



Key features

At a glance



- Without external servo drive: all the necessary electronic components are combined in the integrated drive
- Two control options integrated as standard: digital I/O and IO-Link
- Complete solution for simple movements between mechanical end positions
- Simplified commissioning: all parameters can be manually set directly on the drive
- · No special expertise required for commissioning
- End-position feedback similar to that of a conventional proximity sensor is integrated as standard
- Sealed hollow shaft for the integrated through-feed of cables and tubing
- Standardised mounting interface for direct connection to the electric mini slides EGSL, EGSC and EGSS

Modular and flexible with motor, motor mounting kit and servo drive

This product is also available within the Optimised Motion Series as rotary drive ERMO:



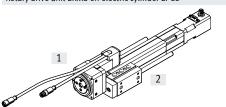
Rotary drive and motor in one unit. Compact and powerful rotating and swivelling with no limits. Sturdy and precise owing to backlash-free ball bearing.

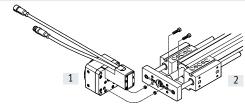
- Rotary drive in 4 sizes for torque of up to 5 Nm
- Hollow shaft for energy through-feed for attachments
- Optional pneumatic or electric energy chain
- Optional proximity sensor for homing or position sensing
- · Optional holding brake
- Modular: individual combinations with servo drive

Key features

Possible combinations with Festo drives

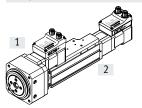
Rotary drive unit ERMS on electric cylinder EPCO

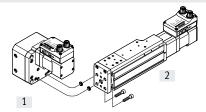




Size		Accessories	
[1] ERMS [2] EPCO		Centring sleeve Screw	
25	40	ZBH-7 (x2)	M5x20 (x2)

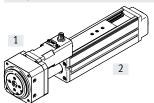
Rotary drive unit ERMS on mini slide unit EGSS

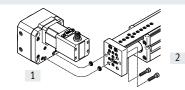




Size		Accessories	
[1] ERMS [2] EGSS		Centring sleeve Screw	
25	45, 60	ZBH-7 (x2)	M5x12 (x2)
32	60	ZBH-7 (x2)	M5x15 (x2)

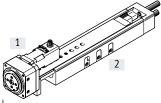
Rotary drive unit ERMS on mini slide EGSL



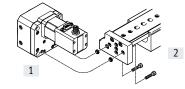


Size		Accessories	
[1] ERMS [2] EGSL		Centring sleeve Screw	
25	55	ZBH-7 (x2)	M5x14 (x2)
32	55	ZBH-7 (x2)	M5x14 (x2)

Rotary drive unit ERMS on mini slide DGSL



The proximity sensor SIEN cannot be used as a reference sensor on the ERMO when ERMO-12 is combined with DGSL-12.



Size		Accessories	
[1] ERMS [2] DGSL		Centring sleeve Screw	
25	20	ZBH-9-7 (x2)	M5x22 (x2)
25	25	ZBH-9-7 (x2)	M5x22 (x2)

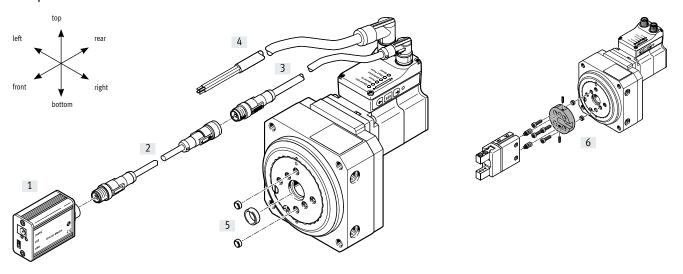
NEW

Type codes

001	Series
ERMS	Rotary drive
002	Size
25	25
32	32
003	Nominal swivel angle
90	90°
180	180°
004	Motor type
ST	Stepper motor ST
005	Controller
М	Integrated
006	Control panel
H1	Integrated
007	Bus protocol/activation
PLK	PNP and IO-Link®
NLK	NPN and IO-Link®

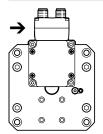
800	End-position sensing
AA	With integrated end-position sensing
009	Cable outlet direction
	Standard
L	Left
R	Right
010	Electrical accessories
	None
L1	Adapter for operation as IO-Link® device
011	Operating instructions
	With operating instructions
DN	No operating instructions

Peripherals overview

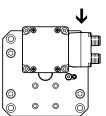




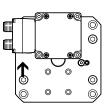
Standard



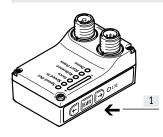
[L] Left



[R] Right



Control elements



[1] Pushbutton actuators for parameterisation and control

Rotary drive units ERMS

NEW

Peripherals overview

Acce	ssories		
	Type/order code	Description	→ Page/Internet
[1]	IO-Link master USB CDSU-1	For straightforward use of the mini slide unit via IO-Link	21
[2]	Adapter NEFC-M12G8	Connection between the motor and the IO-Link master Only for use with IO-Link Port Class A Master (recommended)	21
[3]	Connecting cable NEBC-M12	For connection to a controller	20
[4]	Supply cable NEBL-T12	For connecting load and logic supply	20
[5]	Centring sleeve ZBH	For centring attachments For centring the rotary drive	20
[6]	Adapter kit DHAA	For drive/gripper connections	adapter kit

- **Ø** - Size

25, 32

Rotation angle 90°, 180°



General technical data	General technical data				
Size		25	32		
Design		Electromechanical rotary drive with i	ntegrated drive		
Rotation angle		90, 180			
Gear ratio		9:1	7:1		
Mounting position		Optional			
Additional functions		Integrated end-position sensing	Integrated end-position sensing		
		User interface	User interface		
Display		LED			
Homing		Positive fixed stop block	Positive fixed stop block		
		Negative fixed stop block	Negative fixed stop block		
Type of mounting		Via female thread	Via female thread		
Max. cable length					
Inputs/outputs	[m]	15			
IO-Link operation	[m]	20			
Product weight	[g]	1472	2304		

Mechanical data			
Size		25	32
Permissible mass moment of inertia	[kgcm ²]	65	164
Peak torque	[Nm]	2.7	5.6
Max. speed	[rpm]	150	100
Max. speed at 90°	[rpm]	105	100
Speed press	[rpm]	3	2
Angular acceleration	[rad/s ²]	≤140	
Repetition accuracy	[°]	±0.05	±0.1
Torsional backlash ¹⁾	[°]	0.2	0.2

¹⁾ Without load in new condition



Electrical data				I
Size		25	32	
Motor	-			
Nominal voltage DC	[V]	24 (±15%)		
Nominal current	[A]	3	5.3	
Max. current consumption (load)	[A]	3	5.3	
Max. current consumption (logic)	[mA]	300		
Encoder				
Rotor position encoder		Absolute encoder, single turn		
Rotor position encoder measuring principle		Magnetic		
Rotor position encoder resolution	[bit]	16		

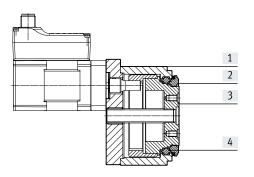
Interfaces					
Size		25	32		
Parameterisation interface					
IO-Link		Yes			
User interface		Yes			
Digital inputs					
Quantity		2			
Switching logic		PNP			
		NPN	NPN		
Characteristics		Not galvanically isolated			
		Configurable			
Specification		Based on IEC 61131-2, type 1			
Operating range	[V]	24			
Digital outputs					
Quantity		2			
Switching logic		PNP			
			NPN		
Rotor position encoder		Absolute encoder, single turn			
Characteristics		Not galvanically isolated			
		Configurable			
Max. current	[mA]	100			

Technical data – IO-Link				
Size		25	32	
SIO mode support		Yes		
Communication mode		COM3 (230.4 kBd)		
Connection technology		Plug		
Port class		A		
Number of ports		1		
Process data width OUT	[byte]	2		
Process data content OUT	[bit]	1 (Move in)		
	[bit]	1 (Move out)		
	[bit]	1 (Quit Error)		
Process data width IN	[byte]	2		
Process data content IN	[bit]	1 (State Device)		
	[bit]	1 (State Move)		
	[bit]	1 (State in)		
	[bit]	1 (State out)		
Service data content IN	[bit]	32 (Force)		
	[bit]	32 (Position)		
	[bit]	32 (Speed)		
Minimum cycle time	[ms]	1		
Data memory required	[kilobyte]	0.5		
Protocol version		Device V 1.1		

Operating and environmental cond	ditions						
Size		25	32				
Insulation class		В					
Ambient temperature	[°C]	0 +50					
Storage temperature	[°C]	-20 +60					
Note on ambient temperature		Above an ambient temperature of 30°C, the power must be reduced by 2% per K					
Temperature monitoring		Switch-off for excessive temperature					
		Integrated precise CMOS temperate	Integrated precise CMOS temperature sensor with analogue output				
Relative humidity	[%]	0 85					
Protection class		III					
Degree of protection		IP40					
Duty cycle	[%]	100					
CE marking		To EU EMC Directive					
		To EU RoHS Directive					
KC mark		KC EMC					
Certification		RCM compliance mark					
Vibration resistance		Transport application test with sev	rerity level 1 to FN 942017-4 and EN 61800-2 and EN 61800-5-1				
Shock resistance		Shock test with severity level 1 to FN 942017-5 and EN 61800-2					
Maintenance interval		Lifetime lubrication	Lifetime lubrication				

Materials

Sectional view



Rotary	Rotary drive						
[1]	Housing	Anodised wrought aluminium alloy					
[2]							
[3]							
[4]	Ball bearing	Rolled steel					
	Sealing ring	NBR					
	Note on materials	RoHS-compliant					
	Contains paint-wetting impairment substance						

Pin allocation

Power supply

Plug

M12x1, 4-pin, T-coded to EN 61076-2-111



Pin	Function				
1 Power voltage supply (24 V DC)					
2 Reference potential, power voltage supply (GND)					
3	Reserved, do not connect				
4	Functional earth (FE)				

Logic interface

Plug

M12x1, 8-pin, A-coded to EN 61076-2-101



When used wit	h digital I/O			
Pin Function				
1 Logic voltage supply (24 V DC)				
2	2 Digital output 1 (State "In")			
3	Digital output 2 (State "Out")			
4	Reference potential, logic voltage supply (GND)			
5	Digital input 1 (Move "In")			
6	Digital input 2 (Move "Out")			
7 Reserved, do not connect				
8	Reference potential, logic voltage supply (GND)			

When used with IO-Link				
Pin	Function			
1	L+ IO-Link power supply (24 V DC)			
2	Reserved, do not connect			
3	C/Q communication with the IO-Link master			
4	L – Reference potential, IO-Link power supply (0 V)			
5	Reserved, do not connect			
6	Reserved, do not connect			
7	Reserved, do not connect			
8	L – Reference potential, IO-Link power supply (0 V)			

Sizing example

Application data:

• Mass moment of inertia: 100 kgcm²

• Mounting position: horizontal

• Rotation angle: 180°

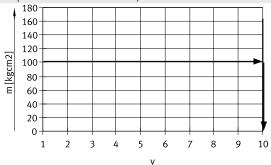
• Max. permitted positioning time: 1 s (one direction)

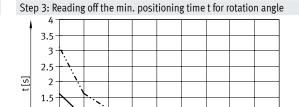
Step 1: Selection of the possible size from the table → page 8

Mechanical data		
Size	25	32
Permissible mass moment of inertia [kgcm ²]	65	164

→ Smallest possible size: ERMS-32-180

Step 2: Selection of max. velocity level v for mass moment of inertia





5 6

8

10



0.5

0

→ Max. speed level for payload: level 10

 \rightarrow Min. positioning time for 180° at level 10: 0.5 s

3

Result

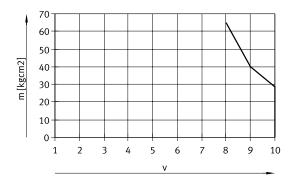
The application can be implemented using ERMS-32-180. A minimum positioning time (one direction) of 0.5 s is achieved. Longer positioning times can be selected at any time using a lower speed level.

NEW Rotary drive units ERMS

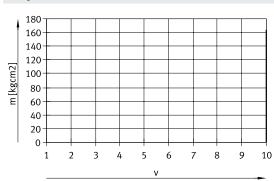
Data sheet

Mass moment of inertia m as a function of velocity level v

Size 25

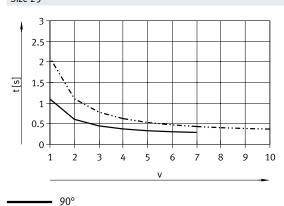


Size 32

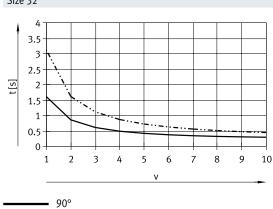


Positioning time t as a function of velocity level v and rotation angle

Size 25

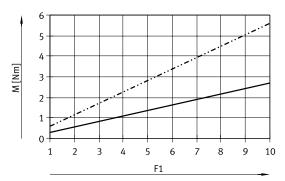


Size 32



---- 180°

Torque M as a function of force level F1



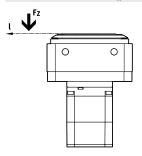
ERMS-25 ERMS-32

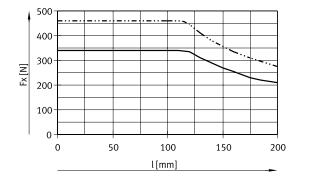
---- 180°

Max. permissible axial and radial force Fx/Fz

Size		25	32	
Static				
Axial force F _x	[N]	700	800	
Radial force F _z [N]		1200	2000	
Dynamic				
Axial force F _x	[N]	350	450	
Radial force F _z	[N]	450	550	

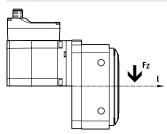
Max. dynamic axial force $\boldsymbol{F}_{\boldsymbol{x}}$ as a function of lever arm \boldsymbol{l}

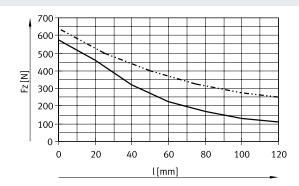




ERMS-25 ERMS-32

Max. dynamic radial force F_z as a function of lever arm I



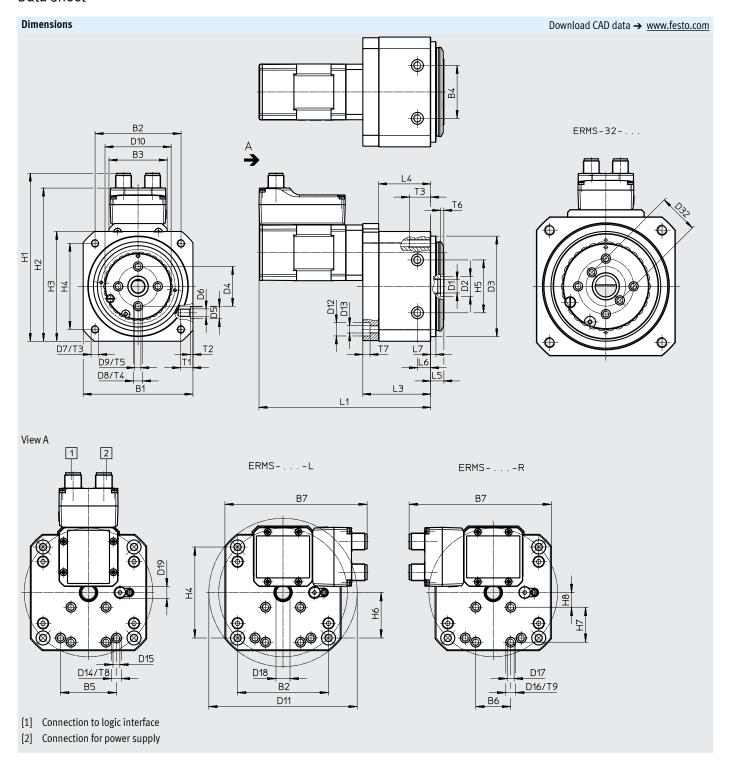


ERMS-25 ERMS-32

NEW Rotary drive units ERMS

Data sheet

Axial eccentricity and concentricity Axial eccentricity Concentricity Measured on the surface of the rotat-Measured at the centring hole of the ing plate at the plate edge, when new. $\,$ rotating plate, when new. 0 PY 0 - AZ 0 32 25 Axial eccentricity Y [mm] <0.02 <0.04 Concentricity Z [mm] <0.02 <0.04



Rotary drive units ERMS

NEW

Data sheet

Size	B1	B2	В3	B4	B5	B6	B7	D1	D2	D3	D4
	±0.3			±0.03	±0.02	±0.02		Ø	Ø H8	ø f8	ø ±0.02
25	83	65	44	40	40	25	101.6	5 10	15	76	30
32	105	85	58	60	_	25	120	16	20	96	42
Size	D5	D6	D7	D8	D9	D10	D11	D12	D13	D14	D15
	Ø H7			Ø H7		Ø	ø ±0.5	Ø	Ø	Ø H7	
25	9	M6	M6	7	M5	50	106	10	5.5	7	M5
32	12	M8	M8	7	M5	65	135	11	6.6	_	-
Size	D16 Ø	D17	D18	D19	D3	32	H1	H2	Н3	H4	H5
	H7		max.		±0.	.02			±0.3		±0.03
25	7	M5	10	M8x1	-	-	127.1	115.9	83	65	40
32	7	M5	9	M8x1	3	0	149	137.8	105	85	60
Size	H6	H7	H8	L1	L	3	L4	L5	L6	L7	T1
		±0.02		±1.5	±0	.6		±0.2	±0.1	±0.1	
25	32.5	25	10.5	129.8	51	.3	39.3	10	10	4	9.5
32	-	25	15	127	46	.5	34.5	12	10	6	15
Size	T2	TS	3	T4	T5		T6	T7		T8	Т9
	+0.1			+0.1			+0.1				
25	2	16	5	1.5	8.5		2.5	5.5		1.5	1.5
32	2.5	20)	1.5	10		2.8	6.8		-	1.5

Ordering data

Ordering data	Size	Rotation angle	Part no.	Туре
.8 _a .	25	90°	8087819	ERMS-25-90-ST-M-H1-PLK-AA
		180	8087820	ERMS-25-180-ST-M-H1-PLK-AA
	32	90°	8087821	ERMS-32-90-ST-M-H1-PLK-AA
		180°	8087822	ERMS-32-180-ST-M-H1-PLK-AA

Rotary drive units ERMS

NEW

Ordering data – Modular product system

Ordering table					
Size	25	32	Conditions	Code	Enter code
Module no.	8087808	8087809			
Series	ERMS			ERMS	ERMS
Size	25	32			
Nominal swivel angle [°]	90, 180	90, 180			
Motor type	Stepper motor ST	Stepper motor ST			-ST
Controller	Integrated		-M	-M	
Control panel	Integrated			-H1	-H1
Bus protocol/actuation	NPN and IO-Link	NPN and IO-Link			
	PNP and IO-Link		-PLK		
End-position detection	With integrated end-position sens	ing		-AA	-AA
Cable outlet direction	Standard				
	Left			-L	
	Right			-R	
Electrical accessories	Without				
	Adapter for operation as IO device			+L1	
Operating instructions	With operating instructions				
	Without operating instructions			DN	

Accessories

Ordering data -	Centring sleeves			Data sheets → Inter	net: zbh
	For size	Description	Part no.	Туре	PU ¹⁾
	25	For centring the drive in the case of side mounting	8137184	ZBH-9-B	10
	32		8137185	ZBH-12-B] [
	25, 32	For centring attachments on the rotating plate	186717	ZBH-7	
	25	For centring attachments in the middle of the rotating plate	191409	ZBH-15	
	32		150901	SLZZ-25/16	1

1) Packaging unit

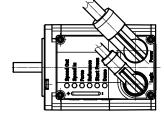
	Ordering data – Supply cables								
		Electrical connection, left	Electrical connection, right	Cable length	Part no.	Туре			
				[m]					
Ī		Angled socket, M12x1, 4-pin	Cable, open end, 4-wire	2	8080778	NEBL-T12W4-E-2-N-LE4			
				5	8080779	NEBL-T12W4-E-5-N-LE4			
				10	8080780	NEBL-T12W4-E-10-N-LE4			
	•			15	8080781	NEBL-T12W4-E-15-N-LE4			
ſ		Straight socket, M12x1, 4-pin	Cable, open end, 4-wire	2	8080790	NEBL-T12G4-E-2-N-LE4			
	(1)			5	8080791	NEBL-T12G4-E-5-N-LE4			
				10	8080792	NEBL-T12G4-E-10-N-LE4			
	<u>-</u>			15	8080793	NEBL-T12G4-E-15-N-LE4			

Ordering data – Connecting cables Data sheets → Internet: nebc									
	Electrical connection, left	Electrical connection, right	Cable length	Part no.	Туре				
			[m]						
	Angled socket, M12x1, 8-pin	Cable, open end, 8-wire	2	8094476	NEBC-M12W8-E-2-N-B-LE8				
			5	8094478	NEBC-M12W8-E-5-N-B-LE8				
			10	8094481	NEBC-M12W8-E-10-N-B-LE8				
			15	8094479	NEBC-M12W8-E-15-N-B-LE8				
E		Straight plug, M12x1, 8-pin	2	8080786	NEBC-M12W8-E-2-N-M12G8				
			5	8080787	NEBC-M12W8-E-5-N-M12G8				
			10	8080788	NEBC-M12W8-E-10-N-M12G8				
			15	8080789	NEBC-M12W8-E-15-N-M12G8				
	Straight socket, M12x1, 8-pin	Cable, open end, 8-wire	2	8094480	NEBC-M12G8-E-2-N-B-LE8				
OFFICE OF			5	8094477	NEBC-M12G8-E-5-N-B-LE8				
			10	8094482	NEBC-M12G8-E-10-N-B-LE8				
			15	8094475	NEBC-M12G8-E-15-N-B-LE8				
OLD TO THE REAL PROPERTY OF THE PERTY OF THE		Straight plug, M12x1, 8-pin	2	8080782	NEBC-M12G8-E-2-N-M12G8				
			5	8080783	NEBC-M12G8-E-5-N-M12G8				
			10	8080784	NEBC-M12G8-E-10-N-M12G8				
			15	8080785	NEBC-M12G8-E-15-N-M12G8				



- Note

The cables are positioned at a 45° angle to the axis.





Accessories

	Ordering data -	ering data – 10-Link master USB							
		Description			Part no.	Туре			
	For using the unit with IO-Link An external power supply plug is additionally required (not included in the scope of delivery)				8091509	CDSU-1			
Ordering data – Adapter Data sheets → Internet: nefc									
		Electrical connection, left	Electrical connection, right	Cable length [m]	Part no.	Туре			
	OLD OLD DE	Straight socket, M12x1, 8-pin	Straight plug, M12x1, 5-pin Only for use with IO-Link Port Class A Master (recommended)	0.3	8080777	NEFC-M12G8-0.3-M12G5-LK			