

Electric cylinders EPCO, with spindle drive

FESTO



Characteristics

At a glance		
General information	Features	Application areas
The electric cylinder EPCO is a mechanical linear drive with piston rod and permanently attached motor. The driving component consists of an electrically actuated spindle that converts the rotary motion of the motor into linear motion of the piston rod.	• With ball screw • Available with female thread • Available with holding brake • Degree of protection IP40 • Compact dimensions • Extensive mounting accessories for various installation situations	• Suitable for simple applications in factory automation that in the past were mostly carried out using pneumatic solutions

Optimised Motion Series (OMS)

A package that makes positioning easier than ever before.
The Optimised Motion Series is as easy to handle as a pneumatic cylinder, but with the functionality of an electric drive.



Simple selection	Ordering and logistics	Quick to configure
• Easy sizing and selection using cycle time charts • No special knowledge of electric drive technology required	• All the necessary individual parts under a single part number • Motors mounted on electric cylinders	• Parameterisation and commissioning via web server/browser • Parameterise up to 7 freely definable positions directly on the PC

For simple positioning tasks

Electric cylinder EPCO



Motor controller CMMO-ST



Characteristics

Motor mounting variants

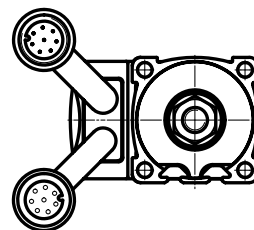
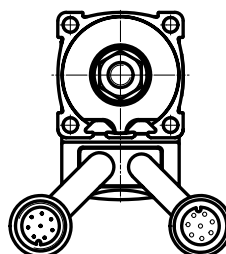
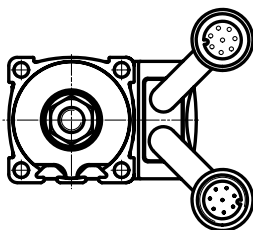
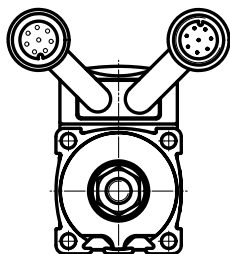
EPCO-16

Standard

Right (characteristic R)

Underneath (characteristic D)

Left (characteristic L)



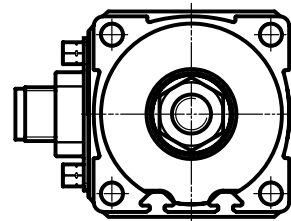
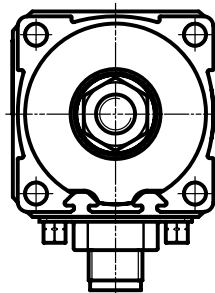
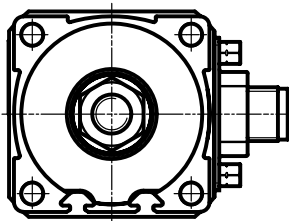
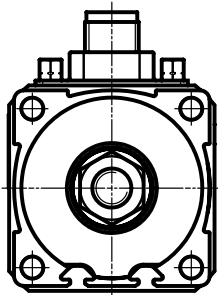
EPCO-25/-40

Standard

Right (characteristic R)

Underneath (characteristic D)

Left (characteristic L)



Electric cylinder EPCO with guide unit EAGF-P1



The guide unit provides protection from torsion in the case of high torque loads. It offers a high level of guide precision for workpiece handling and other applications.

The guide unit can optionally be ordered via the modular product system.

Integrated mounting interfaces permit direct mounting with numerous multi-axis combinations, such as with:

- Toothed belt axis ELGR
- Rotary drive ERMO
- Mini slide DGSL

Technical data

→ Page 15

Ordering data

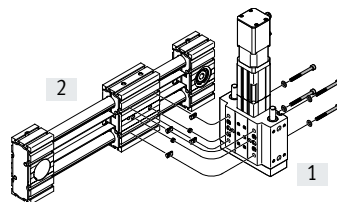
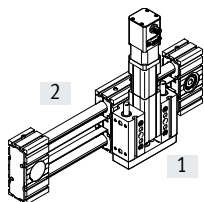
EPCO with guide unit EAGF assembled → page 26

Guide unit EAGF as an accessory → page 35

Characteristics

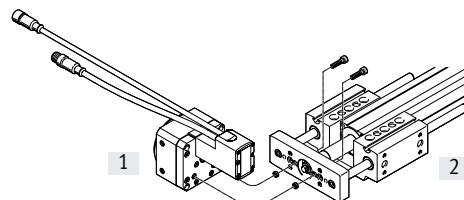
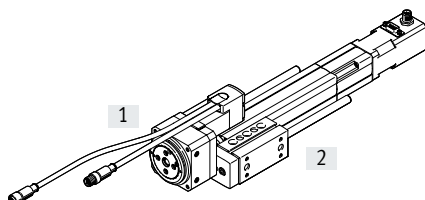
Combination options within the Optimised Motion Series (OMS)

Electric cylinder EPCO on toothed belt axis ELGR



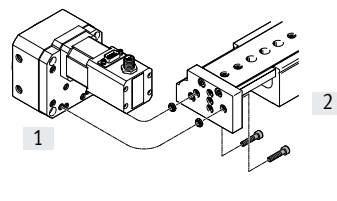
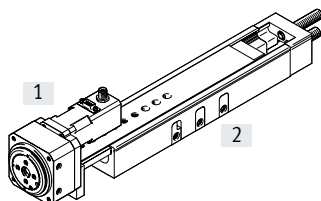
Size	Accessories				
[1] EPCO	[2] ELGR	Slot nut	Centring sleeve	Screw	Washer
16	35	NST-3-M3 (x4)	ZBH-7 (x2)	M3x10 (x4)	–
25	45	NST-5-M5 (x4)	ZBH-7 (x2)	M5x50 (x4)	DIN125-A5.3 (x4)
40	55	NST-5-M5 (x4)	ZBH-7 (x2)	M5x65 (x4)	DIN125-A5.3 (x4)

Rotary drive ERM0 on electric cylinder EPCO



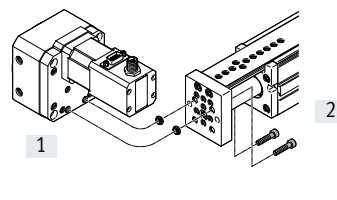
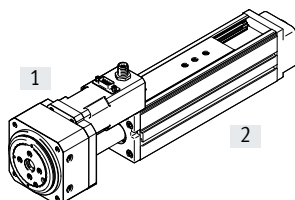
Size	Accessories		
[1] ERM0	[2] EPCO	Centring sleeve	Screw
12	16	ZBH-7 (x2)	M4x16 (x2)
16	25	ZBH-7 (x2)	M5x18 (x2)
25	40	ZBH-7 (x2)	M5x20 (x2)

Rotary drive ERM0 on mini slide DGSL



Size	Accessories		
[1] ERM0	[2] DGSL	Centring sleeve	Screw
12	12	ZBH-7 (x2)	M4x18 (x2)
25	20	ZBH-9-7 (x2)	M5x22 (x2)
25	25	ZBH-9-7 (x2)	M5x22 (x2)

Rotary drive ERM0 on mini slide EGSL

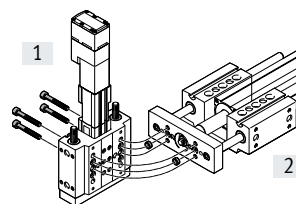
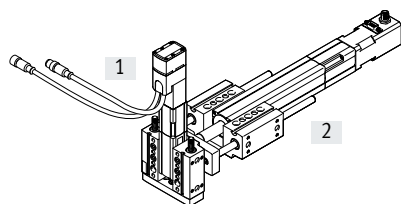


Size	Accessories		
[1] ERM0	[2] EGSL	Centring sleeve	Screw
12	35	ZBH-7 (x2)	M4x12 (x2)
16	45	ZBH-7 (x2)	M5x12 (x2)
25	55	ZBH-7 (x2)	M5x14 (x2)
32	55	ZBH-7 (x2)	M5x14 (x2)

Characteristics

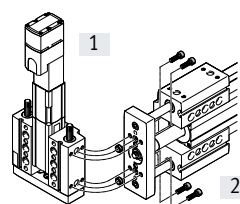
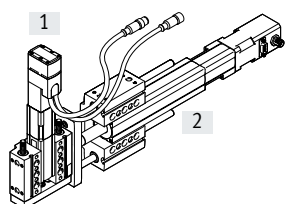
Combination options within the Optimised Motion Series (OMS)

Electric cylinder EPCO on electric cylinder EPCO, horizontal



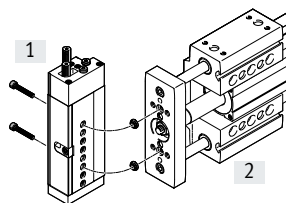
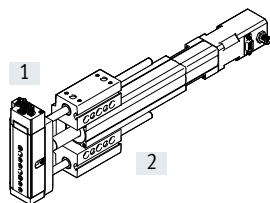
Size		Accessories	
[1] EPCO	[2] EPCO	Centring sleeve	Screw
16	25	ZBH-9 (x2)	M6x40 (x4)
25	40	ZBH-9 (x2)	M6x55 (x4)

Electric cylinder EPCO on electric cylinder EPCO, vertical



Size		Accessories	
[1] EPCO	[2] EPCO	Centring sleeve	Screw
16	25	ZBH-9 (x2)	M5x18 (x4)
25	40	ZBH-9 (x2)	M5x22 (x4)

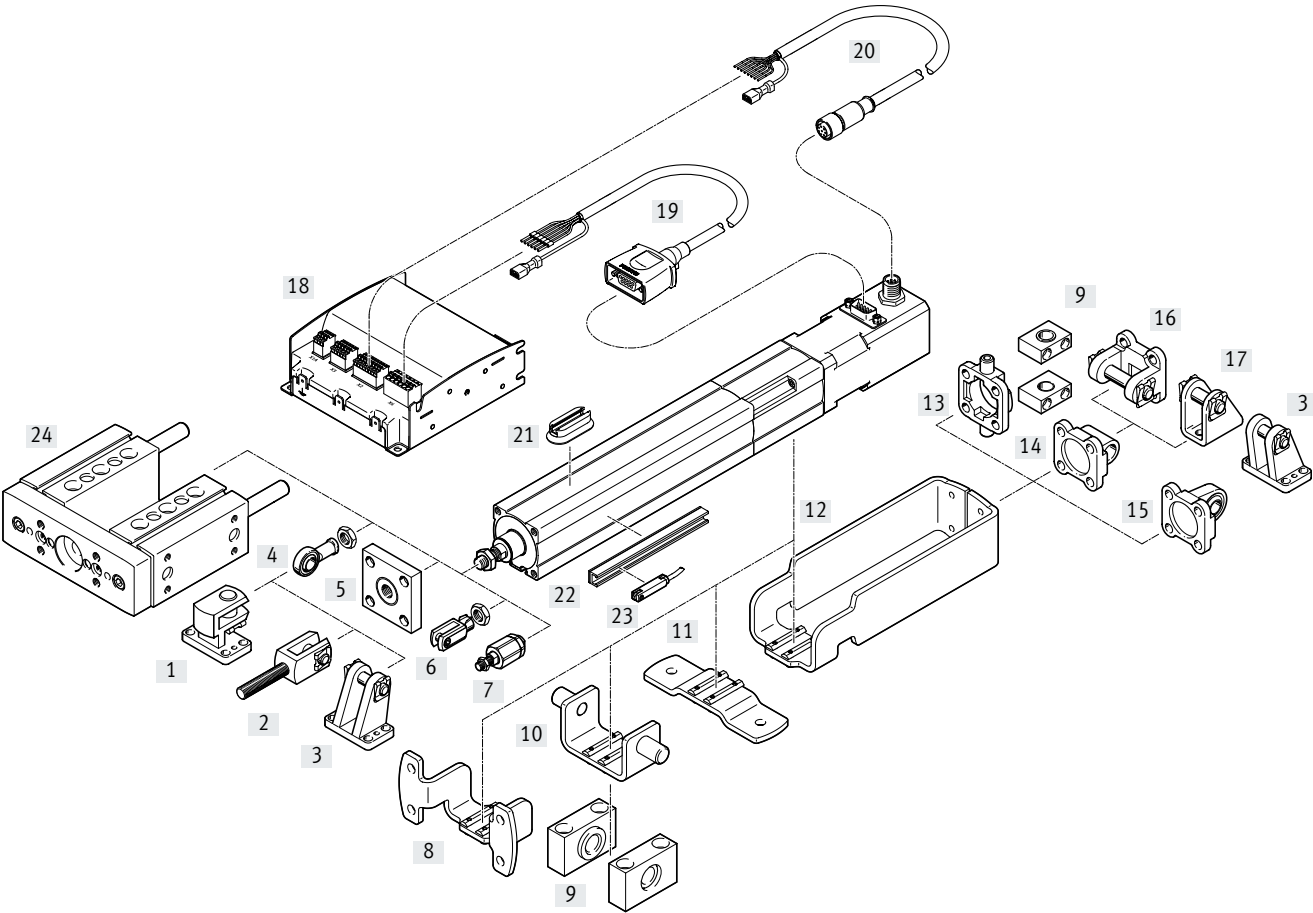
Mini slide DGSL on electric cylinder EPCO



Size		Accessories	
[1] DGSL	[2] EPCO	Centring sleeve	Screw
8 (40 mm) ¹⁾	16	ZBV-9-7 (x2)	M4x16 (x2)
10 (30 mm) ¹⁾	25	ZBV-9-7 (x2)	M4x20 (x2)
12 (40 mm) ¹⁾	40	ZBV-9-7 (x2)	M5x20 (x2)

1) Minimum stroke

Peripherals overview



Mounting components and accessories		Description	For size			→ Page/Internet
			16	25	40	
[1]	Right angle clevis foot LQG	For rod eye SGS	–	–	■	34
[2]	Rod clevis SGA	For rod eye SGS, for swivelling cylinder mounting	–	–	■	35
[3]	Clevis foot LBG	For rod eye SGS, for spherical bearing	–	–	■	34
[4]	Rod eye SGS/CRSGS	For spherical bearing	■	■	■	35
[5]	Coupling piece KSG	For compensating radial deviations	–	–	■	35
[6]	Rod clevis SG/CRSG	Permits a swivelling movement of the cylinder in one plane	■	■	■	35

Peripherals overview

Mounting components and accessories		For size			→ Page/Internet
		16	25	40	
[7]	Self-aligning rod coupler FK	■	■	■	35
[8]	Flange mounting EAHH	■	■	■	29
[9]	Trunnion support LNZG	■	■	■	32
[10]	Swivel mounting EAHS	■	■	■	30
[11]	Foot mounting EAHF	■	■	■	28
[12]	Adapter kit EAHA	■	■	■	31
[13]	Trunnion flange ZNCF	–	–	■	32
[14]	Swivel flange SNCL	■	■	■	33
[15]	Swivel flange SNCS	–	–	■	33
[16]	Swivel flange SNCB/SNCB-...-R3	–	–	■	34
[17]	Clevis foot LBN	■	■	■	34
[18]	Motor controller CMMO	■	■	■	38
[19]	Motor cable NEBM	■	■	■	38
[20]	Encoder cable NEBM	■	■	■	38
[21]	Mounting kit CRSMB	■	■	■	37
[22]	Sensor rail SAMH	■	■	■	37
[23]	Proximity switches SME/SMT-8	■	■	■	36
[24]	Guide unit EAGF-P1	■	■	■	35

**Note**

In the case of high loads, mounting should not just be using the mounting threads on the front.

The mass of the motor, reinforced by the leverage effect, can lead to the mounting threads being torn out.

Type codes

001	Series
EPCO	Electric cylinder, with spindle drive

002	Size
16	16
25	25
40	40

003	Stroke
50	50
75	75
100	100
125	125
150	150
175	175
200	200
250	250
300	300
350	350
400	400

004	Spindle pitch
3P	3 mm
5P	5 mm
8P	8 mm
10P	10 mm
12.7P	12.7 mm

005	Piston rod thread type
	Male thread
F	Female thread

006	Piston rod extension
	None
...E	1 ... 200 mm

007	Position sensing
	None
A	For proximity sensor

008	Motor type
ST	Stepper motor ST

009	Measuring unit
	None
E	Encoder

010	Brake
	None
B	With brake

011	Cable outlet direction
	Standard
D	Underneath
L	Left
R	Right

012	Guide unit
	None
KF	Recirculating ball bearing with two guide rods

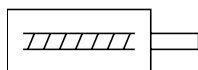
013	Connecting cable to motor controller
	None
1.5E	1.5 m, suitable for energy chains, straight plug
2.5E	2.5 m, suitable for energy chains, straight plug
5E	5 m, suitable for energy chains, straight plug
7E	7 m, suitable for energy chains, straight plug
10E	10 m, suitable for energy chains, straight plug
1.5EA	1.5 m, suitable for energy chains, angled plug
2.5EA	2.5 m, suitable for energy chains, angled plug
5EA	5 m, suitable for energy chains, angled plug
7EA	7 m, suitable for energy chains, angled plug
10EA	10 m, suitable for energy chains, angled plug

014	Controller type
	None
C5	CMMO, 5 A

015	Bus protocol/activation
	None
DIO	Digital I/O interface
LK	IO-Link®

016	Switching input/output
	None
P	PNP
N	NPN

Data sheet



Size
16 ... 40



Stroke length
50 ... 400 mm



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General technical data

Size	16	25	40
Design	Electric cylinder with ball screw and motor		
Piston rod thread			
Male thread	M6	M8	M10x1.25
Female thread	M4	M6	M8
Working stroke [mm]	50 ... 200	50 ... 300	50 ... 400
Stroke reserve [mm]	0		
Max. angle of rotation at the piston rod [°]	≤ ±2	≤ ±1.5	≤ ±1
Impact energy in the end positions [J]	0.1 x 10 ⁻³	0.2 x 10 ⁻³	0.4 x 10 ⁻³
Position sensing	Via proximity switch		
Type of mounting	With female thread		
	With accessories		
Mounting position	Any		

Mechanical data

Size		16		25		40	
Spindle design		3P	8P	3P	10P	5P	12.7P
Spindle pitch ¹⁾ [mm/rev]		3	8	3	10	5	12.7
Spindle diameter [mm]		8	8	10	10	12	12.7
Guide value for payload							
Horizontal ²⁾ [kg]		24	8	60	20	120	40
Vertical [kg]		12	4	30	10	60	20
Max. feed force F _x [N]		125	50	350	105	650	250
Max. speed [mm/s]		125	300	150	500	180	460
Max. acceleration [m/s ²]		10					
Reversing backlash ³⁾ [mm]		≤ 0.1					
Repetition accuracy [mm]		±0.02					

1) Nominal value varies due to component tolerances

2) Note max. transverse load

3) In new condition

Data sheet

Electrical data				
Size		16	25	40
Motor				
Nominal voltage	[V DC]	24		
Nominal current	[A]	1.4	3	4.2
Holding torque	[Nm]	0.09	0.5	1.13
Brake				
Nominal voltage	[V DC]	24 ±10%		
Nominal power	[W]	8		
Holding torque	[Nm]	0.2	0.4	0.4
Mass moment of inertia	[kgmm ²]	1.8	8.2	29
Encoder				
Rotor position sensor		Incremental		
Rotor position sensor measuring principle		Optical		
Pulses/revolution	[1/rev]	500		
Interface		RS422, TTL, AB channel, zero index		
Operating voltage of encoder	[V DC]	5		
Operating and environmental conditions				
Ambient temperature ¹⁾	[°C]	0 ... +50		
Storage temperature	[°C]	−20 ... +60		
Relative humidity	[%]	0 ... 85 (non-condensing)		
Degree of protection to IEC 60529		IP40		
Corrosion resistance CRC ²⁾		1		
Duty cycle	[%]	100		
CE marking (see declaration of conformity)		To EU EMC Directive ³⁾		
Certification		c UL us - Recognized (OL)		
		RCM compliance mark		

1) Note operating range of proximity switches.

2) Corrosion resistance class CRC 1 to Festo standard FN 940070

Low corrosion stress. Dry internal application or transport and storage protection. Also applies to parts behind coverings, in the non-visible interior area, and parts which are covered in the application (e.g. drive trunnions).

3) For information about the area of use, see the EC declaration of conformity at: www.festo.com/sp → Certificates.

If the devices are subject to usage restrictions in residential, commercial or light-industrial environments, further measures for the reduction of the emitted interference may be necessary.

Data sheet

Weight [kg]						
Size	16		25		40	
Basic weight with 0 mm stroke						
EPCO-....	0.62		1.04		2.49	
EPCO-....-E	0.62		1.13		2.59	
EPCO-....-B	0.68		1.22		2.71	
EPCO-....-EB	0.68		1.28		2.77	
EPCO-....-KF	1.22 ... 1.28		2.12 ... 2.36		4.40 ... 4.68	
Additional weight per 100 mm stroke						
EPCO-....	0.17		0.34		0.55	
EPCO-....-KF	0.25		0.46		0.73	
Moving mass with 0 mm stroke						
EPCO-....	0.07		0.15		0.42	
EPCO-....-KF	0.23		0.45		0.98	
Moving mass per 100 mm stroke						
EPCO-....	0.020		0.026		0.049	
EPCO-....-KF	0.100		0.146		0.229	

Mass moments of inertia							
Size	16			25		40	
Spindle design	3P	8P	3P	10P	5P	12.7P	
J ₀ with 0 mm stroke							
EPCO-....	[kg mm ²]	2.28	2.29	9.33	9.40	33.25	33.75
EPCO-....-B	[kg mm ²]	2.97	2.98	10.63	10.70	34.55	35.05
j _S per meter stroke	[kg mm ² /m]	2.53	2.65	4.87	5.78	11.66	16.70
j _L per kg payload	[kg mm ² /kg]	0.23	1.62	0.23	2.54	0.64	4.09

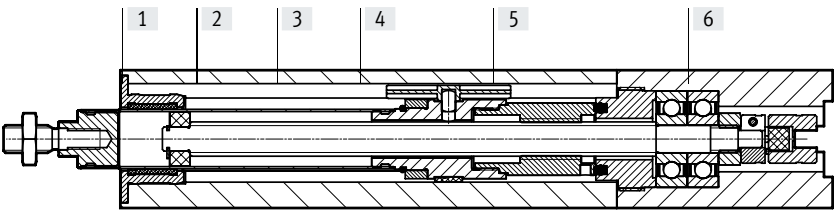
The mass moment of inertia J_A of the electric cylinder is calculated as follows:

$$J_A = J_0 + j_S \times \text{working stroke [m]} + j_L \times m_{\text{moving payload [kg]}}$$

Data sheet

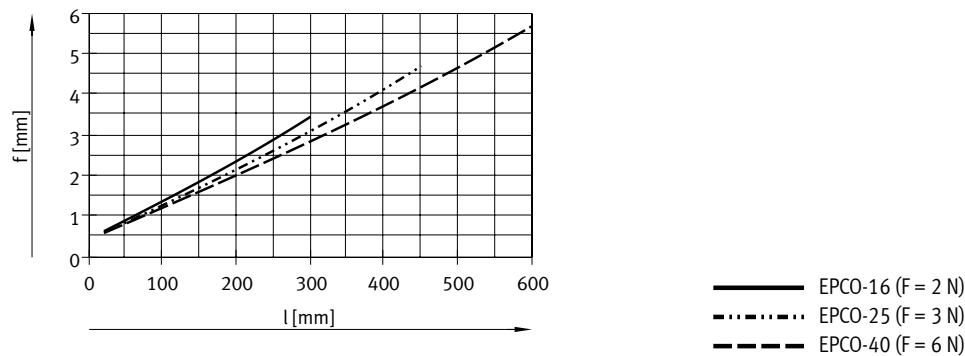
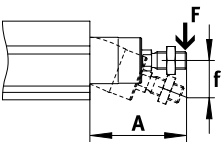
Materials

Sectional view



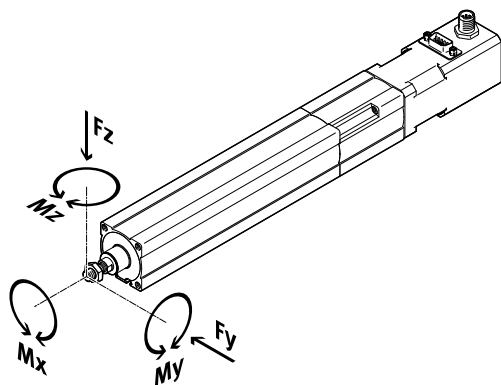
Electric cylinder		
[1]	Bearing cap	Smooth-anodised wrought aluminium alloy
[2]	Cylinder barrel	Smooth-anodised wrought aluminium alloy
[3]	Piston rod	High-alloy stainless steel
[4]	Spindle	Rolled steel
[5]	Spindle nut	Steel
[6]	Drive cover	Wrought aluminium alloy
Note on materials		RoHS-compliant
		Contains paint-wetting impairment substances

Piston rod deflection f as a function of projection A and transverse load F



Data sheet

Maximum permissible loads on the piston rod



If there are several forces and torques simultaneously acting on the piston rod, the following equations must be satisfied:

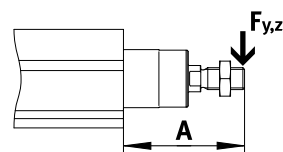
F_1/M_1 = dynamic value

F_2/M_2 = maximum value

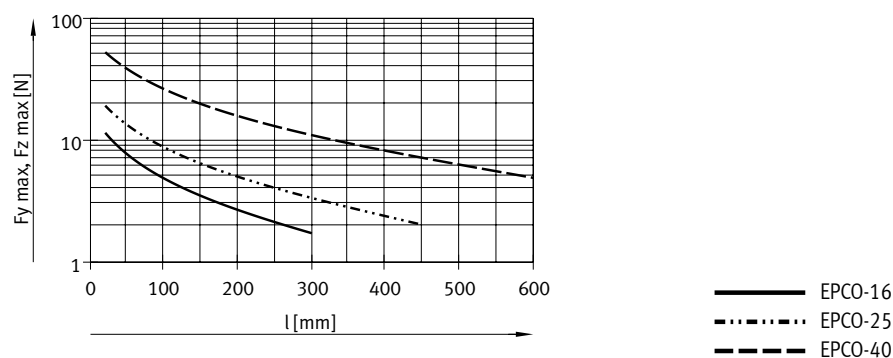
$$f_v = \frac{|F_{y1}|}{F_{y2}} + \frac{|F_{z1}|}{F_{z2}} + \frac{|M_{y1}|}{M_{y2}} + \frac{|M_{z1}|}{M_{z2}} \leq 1$$

$$|F_x| \leq F_{x_{max}}$$

$$|F_x| \leq F_{x_{max}}$$



Maximum permissible transverse loads $F_{y_{max}}$ and $F_{z_{max}}$ on the piston rod as a function of projection A



Size	16		25		40	
Spindle design	3P	8P	3P	10P	5P	12.7P
$F_{x_{max}}$ (static) [N]	125	50	350	105	650	250
$M_{x_{max}}$ [Nm]	0		0		0	
$M_{y_{max}}, M_{z_{max}}$ [Nm]	0.6		1.0		3.3	

**Note**

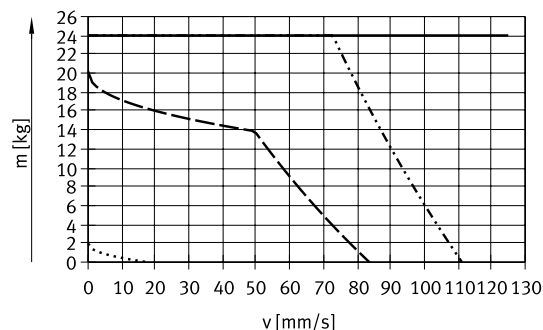
Engineering software
Electric Motion Sizing
→ www.festo.com

Data sheet

Payload m as a function of speed v and acceleration a

Horizontal mounting position

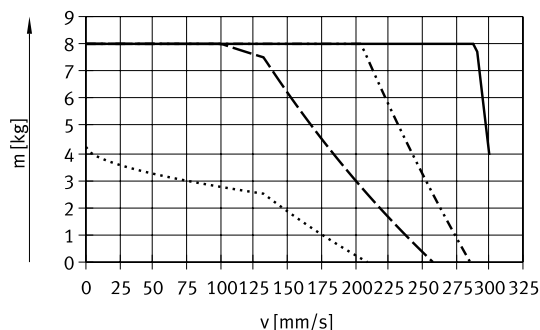
EPCO-16-3P



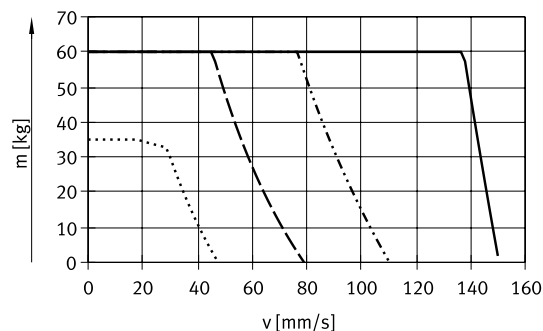
For EPCO-.../EPCO-...-KF

- $a = 0.5 \text{ m/s}^2$
- $a = 2.5 \text{ m/s}^2$
- - - $a = 5 \text{ m/s}^2$
- · - · - $a = 10 \text{ m/s}^2$

EPCO-16-8P



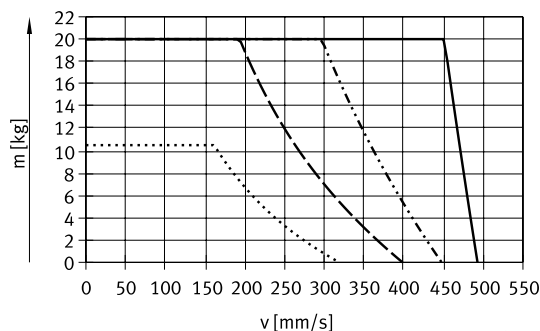
EPCO-25-3P



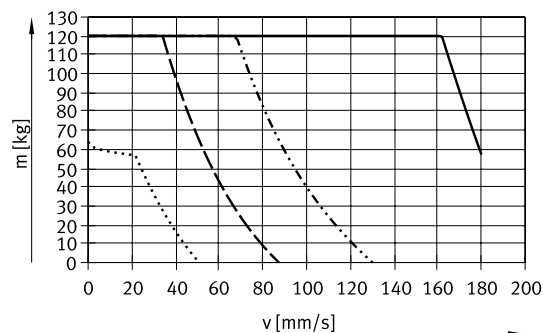
For EPCO-.../EPCO-...-KF

- $a = 0.5 \text{ m/s}^2$
- $a = 2.5 \text{ m/s}^2$
- - - $a = 5 \text{ m/s}^2$
- · - · - $a = 10 \text{ m/s}^2$

EPCO-25-10P



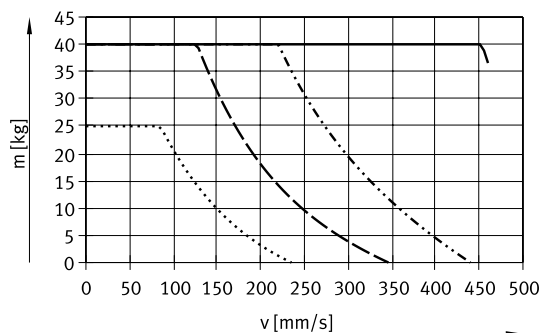
EPCO-40-5P



For EPCO-.../EPCO-...-KF

- $a = 0.5 \text{ m/s}^2$
- $a = 2.5 \text{ m/s}^2$
- - - $a = 5 \text{ m/s}^2$
- · - · - $a = 10 \text{ m/s}^2$

EPCO-40-12.7P



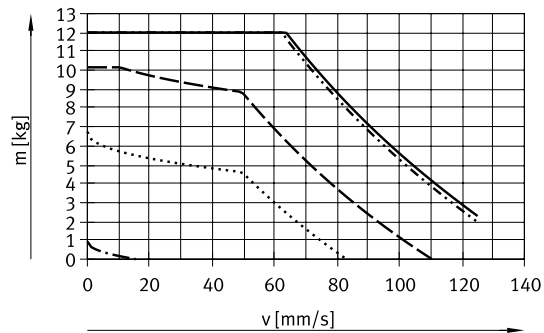
Data sheet

Payload m as a function of speed v and acceleration a

Vertical mounting position

The moving net mass of the guide unit (EPCO-...-KF) results in lower acceleration values with identical payload/speed.

EPCO-16-3P



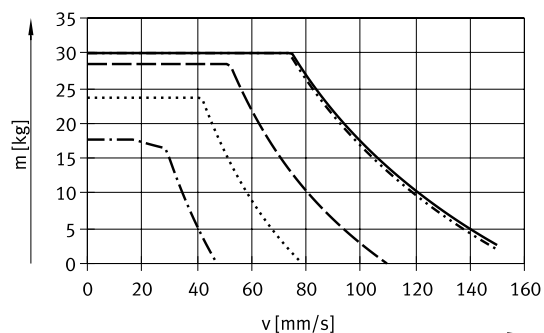
For EPCO-...

- $a = 0 \text{ m/s}^2$
- - - $a = 0.2 \text{ m/s}^2$
- - - $a = 2.5 \text{ m/s}^2$
- $a = 5 \text{ m/s}^2$
- · - · $a = 10 \text{ m/s}^2$

For EPCO-...-KF

- $a = 0 \text{ m/s}^2$
- $a = 2.3 \text{ m/s}^2$
- $a = 4.7 \text{ m/s}^2$
- $a = 9.6 \text{ m/s}^2$

EPCO-25-3P



For EPCO-...

- $a = 0 \text{ m/s}^2$
- - - $a = 0.2 \text{ m/s}^2$
- - - $a = 2.5 \text{ m/s}^2$
- $a = 5 \text{ m/s}^2$
- · - · $a = 10 \text{ m/s}^2$

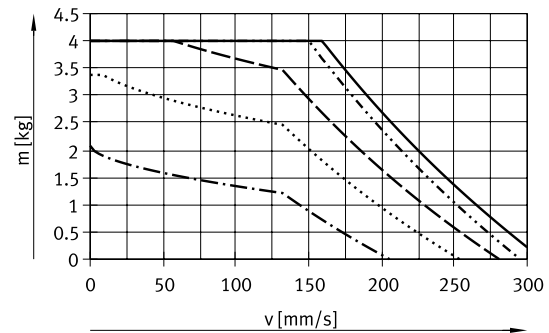
For EPCO-...-KF

- $a = 0 \text{ m/s}^2$
- $a = 2.4 \text{ m/s}^2$
- $a = 4.9 \text{ m/s}^2$
- $a = 9.8 \text{ m/s}^2$

Further technical data for the guide unit EAGF-P1

→ www.festo.com/eagf-p1

EPCO-16-8P



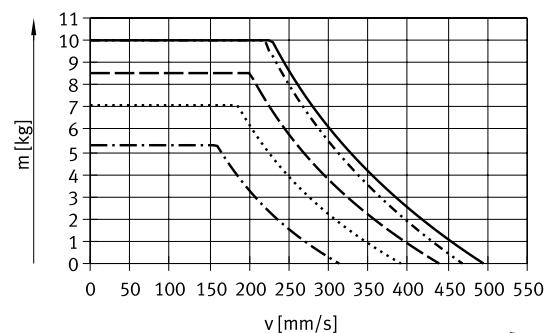
For EPCO-...

- $a = 0 \text{ m/s}^2$
- - - $a = 1.2 \text{ m/s}^2$
- - - $a = 2.5 \text{ m/s}^2$
- $a = 5 \text{ m/s}^2$
- · - · $a = 10 \text{ m/s}^2$

For EPCO-...-KF

- $a = 0 \text{ m/s}^2$
- $a = 1.2 \text{ m/s}^2$
- $a = 3.4 \text{ m/s}^2$
- $a = 7.8 \text{ m/s}^2$

EPCO-25-10P



For EPCO-...

- $a = 0 \text{ m/s}^2$
- - - $a = 1.2 \text{ m/s}^2$
- - - $a = 2.5 \text{ m/s}^2$
- $a = 5 \text{ m/s}^2$
- · - · $a = 10 \text{ m/s}^2$

For EPCO-...-KF

- $a = 0 \text{ m/s}^2$
- $a = 1.6 \text{ m/s}^2$
- $a = 3.9 \text{ m/s}^2$
- $a = 8.3 \text{ m/s}^2$

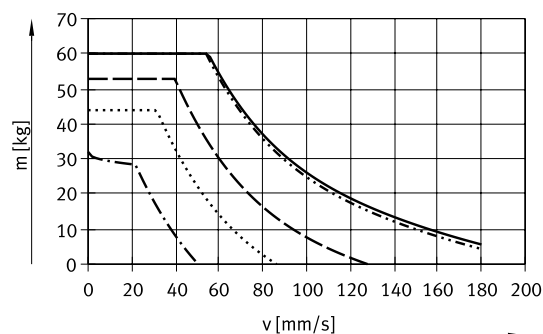
Data sheet

Payload m as a function of speed v and acceleration a

Vertical mounting position

The moving net mass of the guide unit (EPCO-...-KF) results in lower acceleration values with identical payload/speed.

EPCO-40-5P



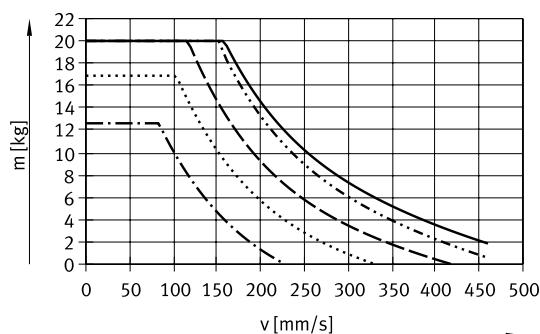
For EPCO-...

- $a = 0 \text{ m/s}^2$
- $a = 0.2 \text{ m/s}^2$
- - - $a = 2.5 \text{ m/s}^2$
- · - · - $a = 5 \text{ m/s}^2$
- - - - - $a = 10 \text{ m/s}^2$

For EPCO-...-KF

- $a = 0 \text{ m/s}^2$
- $a = 2.4 \text{ m/s}^2$
- $a = 4.8 \text{ m/s}^2$
- $a = 9.7 \text{ m/s}^2$

EPCO-40-12.7P



For EPCO-...

- $a = 0 \text{ m/s}^2$
- $a = 1.2 \text{ m/s}^2$
- - - $a = 2.5 \text{ m/s}^2$
- · - · - $a = 5 \text{ m/s}^2$
- - - - - $a = 10 \text{ m/s}^2$

For EPCO-...-KF

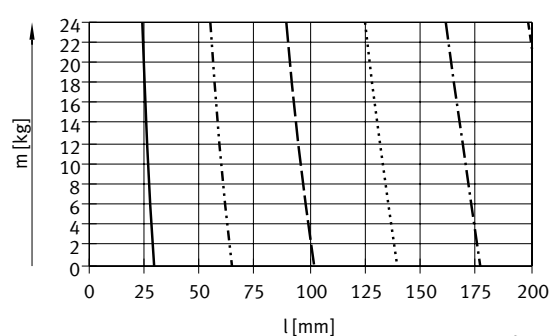
- $a = 0 \text{ m/s}^2$
- $a = 1.8 \text{ m/s}^2$
- $a = 4.0 \text{ m/s}^2$
- $a = 8.5 \text{ m/s}^2$

Payload m as a function of travel distance l and positioning time t

Horizontal mounting position

The moving net mass of the guide unit (EPCO-...-KF) results in longer positioning times with identical payload/travel distance.

EPCO-16-3P



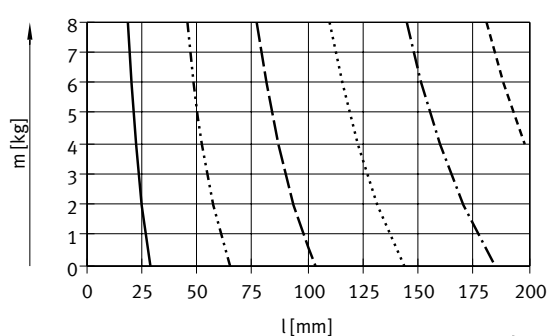
For EPCO-...

- $t = 0.30 \text{ s}$
- $t = 0.60 \text{ s}$
- - - $t = 0.90 \text{ s}$
- · - · - $t = 1.20 \text{ s}$
- - - - - $t = 1.50 \text{ s}$
- - - - - $t = 1.80 \text{ s}$

For EPCO-...-KF

- $t = 0.30 \text{ s}$
- $t = 0.60 \text{ s}$
- $t = 0.90 \text{ s}$
- $t = 1.20 \text{ s}$
- $t = 1.55 \text{ s}$
- $t = 1.85 \text{ s}$

EPCO-16-8P



For EPCO-...

- $t = 0.15 \text{ s}$
- $t = 0.30 \text{ s}$
- - - $t = 0.45 \text{ s}$
- · - · - $t = 0.60 \text{ s}$
- - - - - $t = 0.75 \text{ s}$
- - - - - $t = 0.90 \text{ s}$

For EPCO-...-KF

- $t = 0.15 \text{ s}$
- $t = 0.30 \text{ s}$
- $t = 0.45 \text{ s}$
- $t = 0.65 \text{ s}$
- $t = 0.80 \text{ s}$
- $t = 0.95 \text{ s}$

Further technical data for the guide unit EAGF-P1

→ www.festo.com/eagf-p1

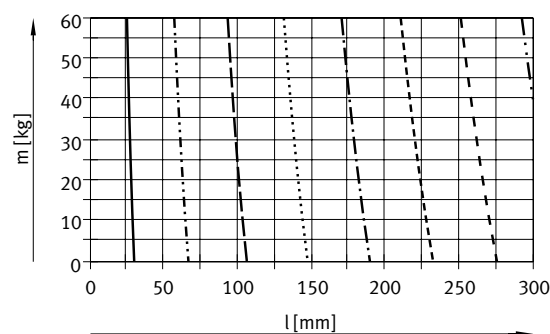
Data sheet

Payload m as a function of travel distance l and positioning time t

Horizontal mounting position

The moving net mass of the guide unit (EPCO-...-KF) results in longer positioning times with identical payload/travel distance.

EPCO-25-3P



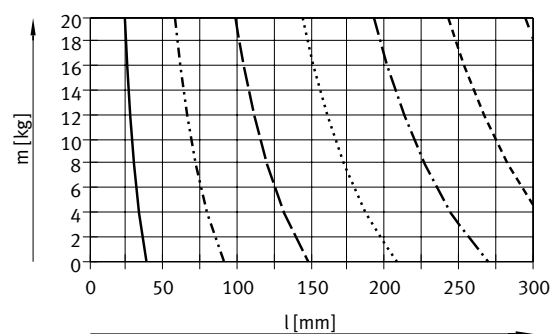
For EPCO-...

————— $t = 0.30$ s
 $t = 0.60$ s
 - - - - - $t = 0.90$ s
 $t = 1.20$ s
 - . - . - $t = 1.50$ s
 - - - - - $t = 1.80$ s
 - - - - - $t = 2.10$ s
 - . . - - $t = 2.40$ s

For EPCO-...-KF

$t = 0.30$ s
 $t = 0.60$ s
 $t = 0.90$ s
 $t = 1.20$ s
 $t = 1.50$ s
 $t = 1.80$ s
 $t = 2.10$ s
 $t = 2.40$ s

EPCO-25-10P



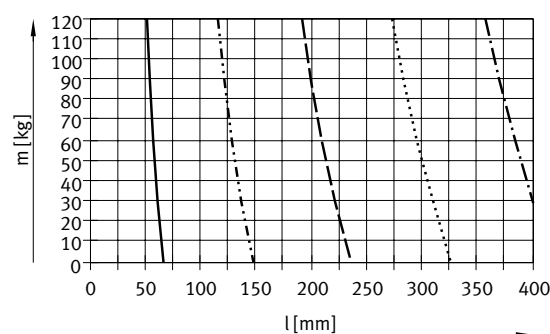
For EPCO-...

————— $t = 0.15$ s
 $t = 0.30$ s
 - - - - - $t = 0.45$ s
 $t = 0.60$ s
 - . - . - $t = 0.75$ s
 - - - - - $t = 0.90$ s
 - - - - - $t = 1.05$ s

For EPCO-...-KF

$t = 0.15$ s
 $t = 0.30$ s
 $t = 0.45$ s
 $t = 0.60$ s
 $t = 0.80$ s
 $t = 0.95$ s
 $t = 1.10$ s

EPCO-40-5P



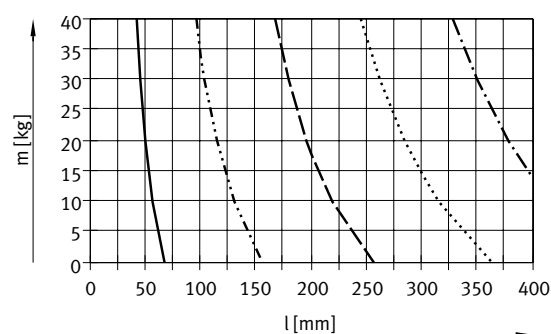
For EPCO-...

————— $t = 0.50$ s
 $t = 1.00$ s
 - - - - - $t = 1.50$ s
 $t = 2.00$ s
 - . - . - $t = 2.50$ s

For EPCO-...-KF

$t = 0.50$ s
 $t = 1.00$ s
 $t = 1.55$ s
 $t = 2.05$ s
 $t = 2.55$ s

EPCO-40-12.7P



For EPCO-...

————— $t = 0.25$ s
 $t = 0.50$ s
 - - - - - $t = 0.75$ s
 $t = 1.00$ s
 - . - . - $t = 1.25$ s

For EPCO-...-KF

$t = 0.25$ s
 $t = 0.50$ s
 $t = 0.80$ s
 $t = 1.05$ s
 $t = 1.30$ s

Further technical data for the guide unit EAGF-P1

→ www.festo.com/eagf-p1

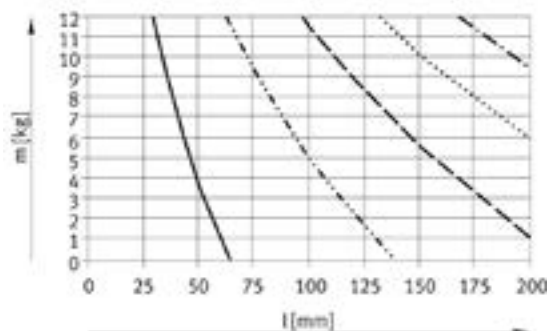
Data sheet

Payload m as a function of travel distance l and positioning time t

Vertical mounting position

The moving net mass of the guide unit (EPCO-...-KF) results in longer positioning times with identical payload/travel distance.

EPCO-16-3P



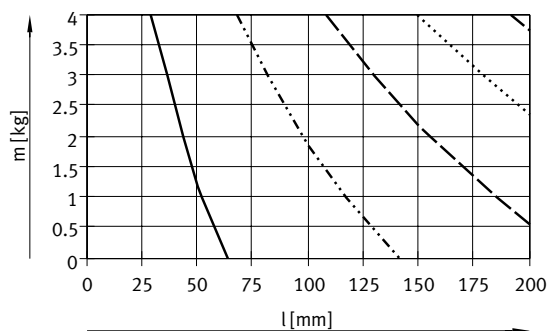
For EPCO-...

- $t = 0.60$ s
- $t = 1.20$ s
- - - $t = 1.80$ s
- · - · - $t = 2.40$ s
- - - - $t = 3.00$ s

For EPCO-...-KF

- $t = 0.60$ s
- $t = 1.25$ s
- $t = 1.85$ s
- $t = 2.50$ s
- $t = 3.10$ s

EPCO-16-8P



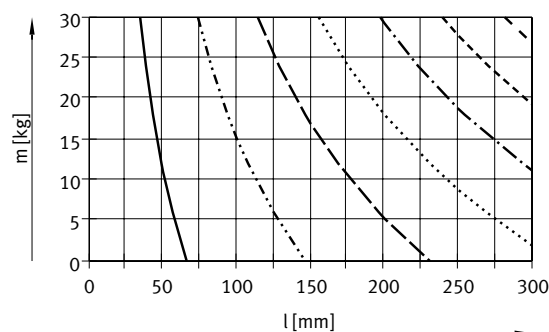
For EPCO-...

- $t = 0.30$ s
- $t = 0.60$ s
- - - $t = 0.90$ s
- · - · - $t = 1.20$ s
- - - - $t = 1.50$ s

For EPCO-...-KF

- $t = 0.35$ s
- $t = 0.65$ s
- $t = 1.00$ s
- $t = 1.30$ s
- $t = 1.65$ s

EPCO-25-3P



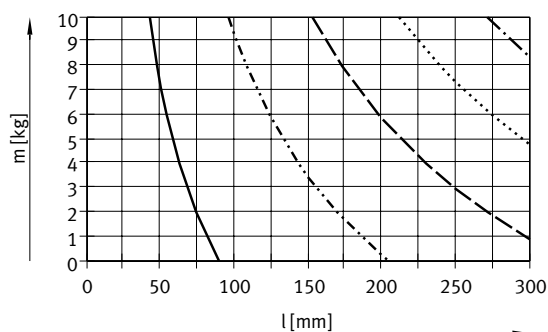
For EPCO-...

- $t = 0.60$ s
- $t = 1.20$ s
- - - $t = 1.80$ s
- · - · - $t = 2.40$ s
- - - - $t = 3.00$ s
- - - - $t = 3.60$ s
- - - - $t = 4.20$ s

For EPCO-...-KF

- $t = 0.60$ s
- $t = 1.20$ s
- $t = 1.85$ s
- $t = 2.45$ s
- $t = 3.05$ s
- $t = 3.70$ s
- $t = 4.30$ s

EPCO-25-10P



For EPCO-...

- $t = 0.30$ s
- $t = 0.60$ s
- - - $t = 0.90$ s
- · - · - $t = 1.20$ s
- - - - $t = 1.50$ s

For EPCO-...-KF

- $t = 0.30$ s
- $t = 0.65$ s
- $t = 0.95$ s
- $t = 1.25$ s
- $t = 1.60$ s

Further technical data for the guide unit EAGF-P1

→ www.festo.com/eagf-p1

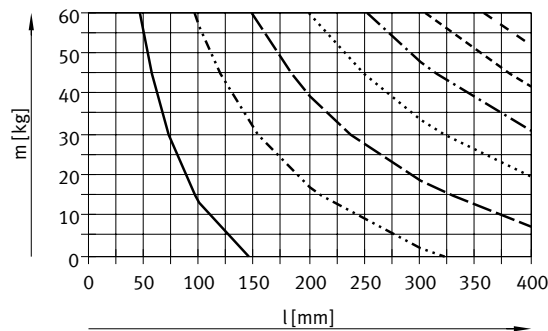
Data sheet

Payload m as a function of travel distance l and positioning time t

Vertical mounting position

The moving net mass of the guide unit (EPCO-...-KF) results in longer positioning times with identical payload/travel distance.

EPCO-40-5P



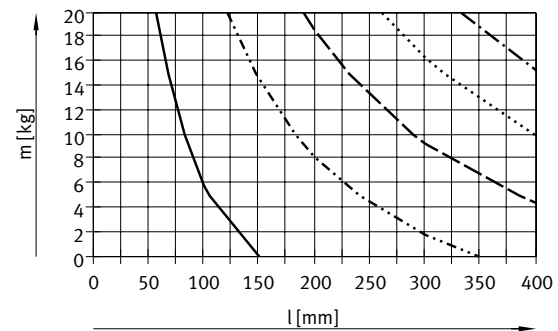
For EPCO-...

— $t = 1.00$ s
 $t = 2.00$ s
 - - - $t = 3.00$ s
 - · - · - $t = 4.00$ s
 - - - - $t = 5.00$ s
 - - - - $t = 6.00$ s
 - - - - $t = 7.00$ s

For EPCO-...-KF

$t = 1.05$ s
 $t = 2.05$ s
 $t = 3.10$ s
 $t = 4.10$ s
 $t = 5.15$ s
 $t = 6.20$ s
 $t = 7.20$ s

EPCO-40-12.7P



For EPCO-...

— $t = 0.55$ s
 $t = 1.00$ s
 - - - $t = 1.50$ s
 - · - · - $t = 2.00$ s
 - - - - $t = 2.50$ s

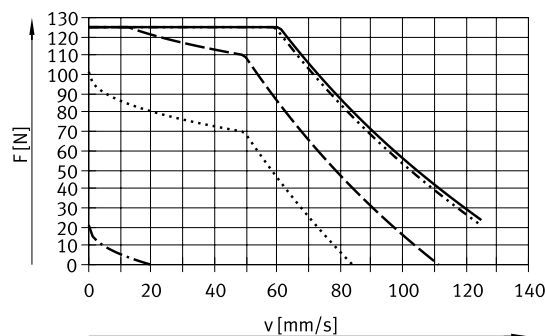
For EPCO-...-KF

$t = 0.55$ s
 $t = 1.10$ s
 $t = 1.60$ s
 $t = 2.15$ s
 $t = 2.70$ s

Feed force F as a function of speed v and acceleration a

The moving net mass of the guide unit (EPCO-...-KF) results in lower acceleration values with identical feed force/speed.

EPCO-16-3P



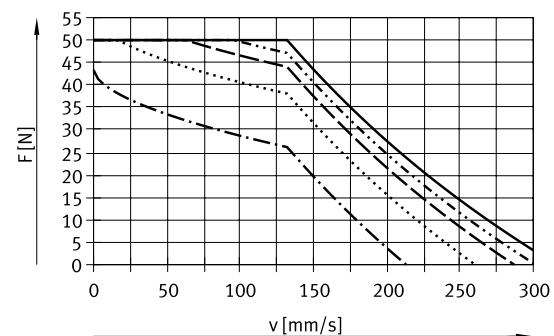
For EPCO-...

— $a = 0$ m/s²
 $a = 0.2$ m/s²
 - - - $a = 2.5$ m/s²
 - · - · - $a = 5$ m/s²
 - - - - $a = 10$ m/s²

For EPCO-...-KF

$a = 0$ m/s²
 $a = 2.3$ m/s²
 $a = 4.7$ m/s²
 $a = 9.6$ m/s²

EPCO-16-8P



For EPCO-...

— $a = 0$ m/s²
 $a = 1.2$ m/s²
 - - - $a = 2.5$ m/s²
 - · - · - $a = 5$ m/s²
 - - - - $a = 10$ m/s²

For EPCO-...-KF

$a = 0$ m/s²
 $a = 1.2$ m/s²
 $a = 3.4$ m/s²
 $a = 7.8$ m/s²

Further technical data for the guide unit EAGF-P1

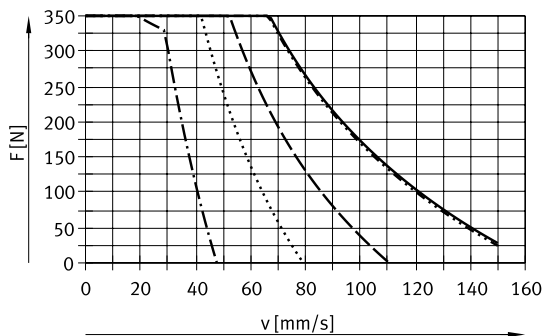
→ www.festo.com/eagf-p1

Data sheet

Feed force F as a function of speed v and acceleration a

The moving net mass of the guide unit (EPCO-...-KF) results in lower acceleration values with identical feed force/speed.

EPCO-25-3P



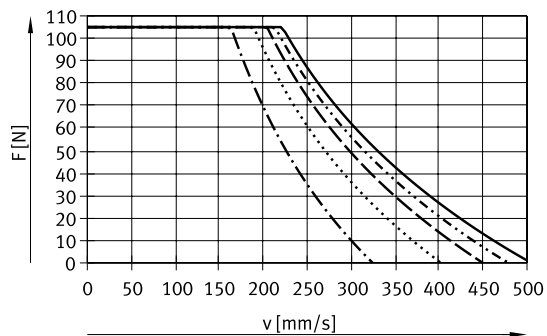
For EPCO-...

- $a = 0 \text{ m/s}^2$
- $a = 0.2 \text{ m/s}^2$
- - - $a = 2.5 \text{ m/s}^2$
- · - · - $a = 5 \text{ m/s}^2$
- - - - $a = 10 \text{ m/s}^2$

For EPCO-...-KF

- $a = 0 \text{ m/s}^2$
- $a = 2.4 \text{ m/s}^2$
- $a = 4.9 \text{ m/s}^2$
- $a = 9.8 \text{ m/s}^2$

EPCO-25-10P



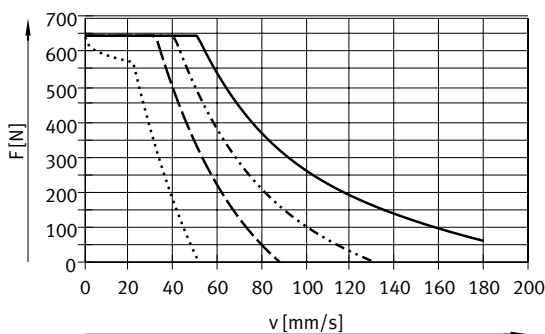
For EPCO-...

- $a = 0 \text{ m/s}^2$
- $a = 1.2 \text{ m/s}^2$
- - - $a = 2.5 \text{ m/s}^2$
- · - · - $a = 5 \text{ m/s}^2$
- - - - $a = 10 \text{ m/s}^2$

For EPCO-...-KF

- $a = 0 \text{ m/s}^2$
- $a = 1.6 \text{ m/s}^2$
- $a = 3.9 \text{ m/s}^2$
- $a = 8.3 \text{ m/s}^2$

EPCO-40-5P



For EPCO-...

- $a = 0 \text{ m/s}^2$
- $a = 0.2 \text{ m/s}^2$
- - - $a = 2.5 \text{ m/s}^2$
- · - · - $a = 5 \text{ m/s}^2$
- - - - $a = 10 \text{ m/s}^2$

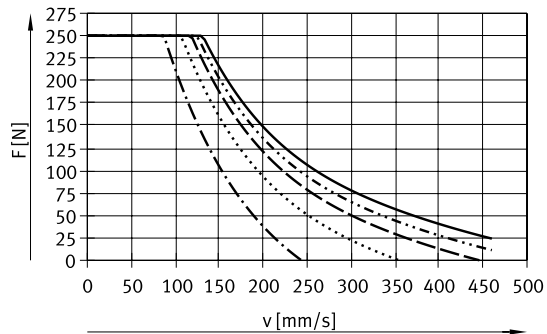
For EPCO-...-KF

- $a = 0 \text{ m/s}^2$
- $a = 2.4 \text{ m/s}^2$
- $a = 4.8 \text{ m/s}^2$
- $a = 9.7 \text{ m/s}^2$

Further technical data for the guide unit EAGF-P1

→ www.festo.com/eagf-p1

EPCO-40-12.7P



For EPCO-...

- $a = 0 \text{ m/s}^2$
- $a = 1.2 \text{ m/s}^2$
- - - $a = 2.5 \text{ m/s}^2$
- · - · - $a = 5 \text{ m/s}^2$
- - - - $a = 10 \text{ m/s}^2$

For EPCO-...-KF

- $a = 0 \text{ m/s}^2$
- $a = 1.8 \text{ m/s}^2$
- $a = 4.0 \text{ m/s}^2$
- $a = 8.5 \text{ m/s}^2$

Data sheet

Calculating the mean feed force F_{xm} with the electric cylinder EPCO

The peak feed force value must not exceed the maximum feed force within a movement cycle. The peak value is generally achieved in vertical operation during the acceleration phase of the upwards stroke. If the maximum feed force is exceeded, this can increase wear and thus shorten the service life of the ball screw. The maximum speed must likewise not be exceeded:

$$F_x \leq F_{x\max.}$$

and

$$v_x \leq v_{x\max.}$$

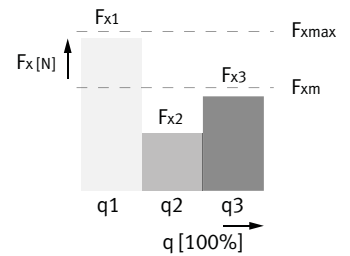
Mean feed force (to DIN 69051-4)

During operation, the continuous feed force may be briefly exceeded up to the maximum feed force. The continuous feed force must, however, be adhered to when averaged over a movement cycle:

$$F_{xm} \leq F_{x\text{continuous}}$$

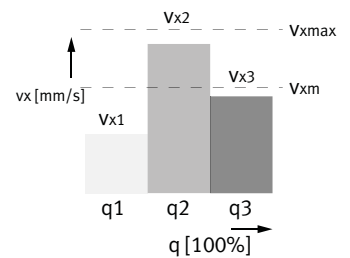
$$F_{xm} = \sqrt[3]{\sum F_x^3 \cdot \frac{v_x}{v_{xm}} \cdot \frac{q}{100}} =$$

$$F_{xm} = \sqrt[3]{F_{x1}^3 \cdot \frac{v_{x1}}{v_{xm}} \cdot \frac{q_1}{100} + F_{x2}^3 \cdot \frac{v_{x2}}{v_{xm}} \cdot \frac{q_2}{100} + F_{x3}^3 \cdot \frac{v_{x3}}{v_{xm}} \cdot \frac{q_3}{100} + \dots}$$



Mean feed speed (to DIN 69051-4)

$$v_{xm} = \sum v_x \cdot \frac{q}{100} = v_{x1} \cdot \frac{q_1}{100} + v_{x2} \cdot \frac{q_2}{100} + v_{x3} \cdot \frac{q_3}{100} + \dots$$

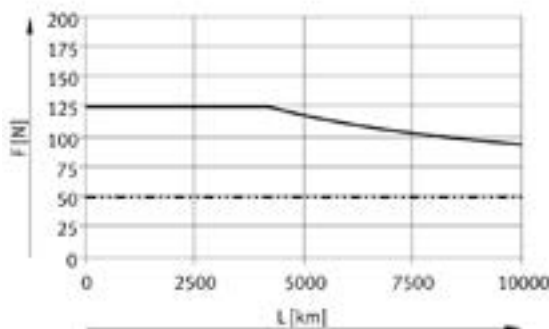


F_x	Feed force	v_x	Feed speed
F_{xm}	Mean feed force	v_{xm}	Mean feed speed
$F_{x\max.}$	Max. feed force	v_x	Max. feed speed
$F_{x\text{continuous}}$	Continuous feed force		

Data sheet

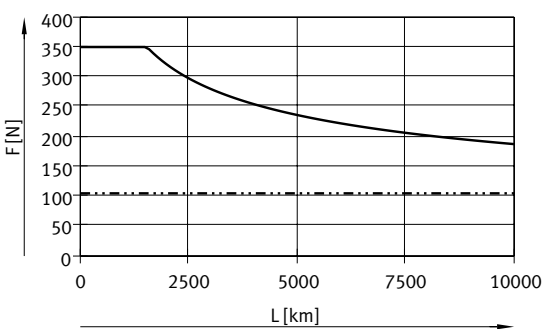
Mean feed force F as a function of running performance L (to DIN 69051-4)

EPCO-16



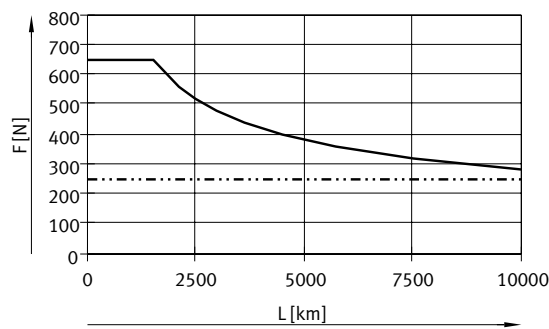
— EPCO-16-3P
- - - EPCO-16-8P

EPCO-25



— EPCO-25-3P
- - - EPCO-25-10P

EPCO-40



— EPCO-40-5P
- - - EPCO-40-12.7P

Note
The specifications for running performance are based on experimentally determined and theoretically calculated data. The running performance that can be achieved in practice can deviate considerably from the specified curves under different parameters.

Pin allocation

Motor

EPCO-16

PIN	Function
1	String A
2	String A/
3	String B
4	String B/
5	n.c.
6	n.c.
7	Brake +24 V DC ¹⁾
8	Brake GND ¹⁾
–	–

EPCO-25/-40

PIN	Function
1	String A
2	String A/
3	String B
4	String B/
5	n.c.
6	n.c.
7	Brake +24 V DC ¹⁾
8	Brake GND ¹⁾
9	n.c.

Encoder

EPCO-16/-25/-40

PIN	Function
1	Signal trace A
2	Signal trace A/
3	Signal trace B
4	Signal trace B/
5	Encoder GND
6	Signal trace N
7	Signal trace N/
8	VCC auxiliary supply +5 V
GND	Shielding on plug housing

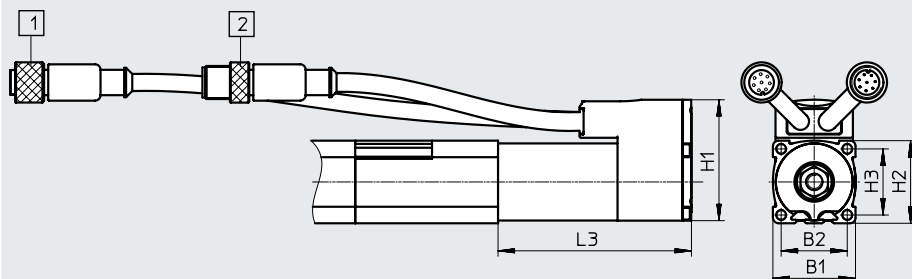
1) Only on motors with brake.

Data sheet

Dimensions

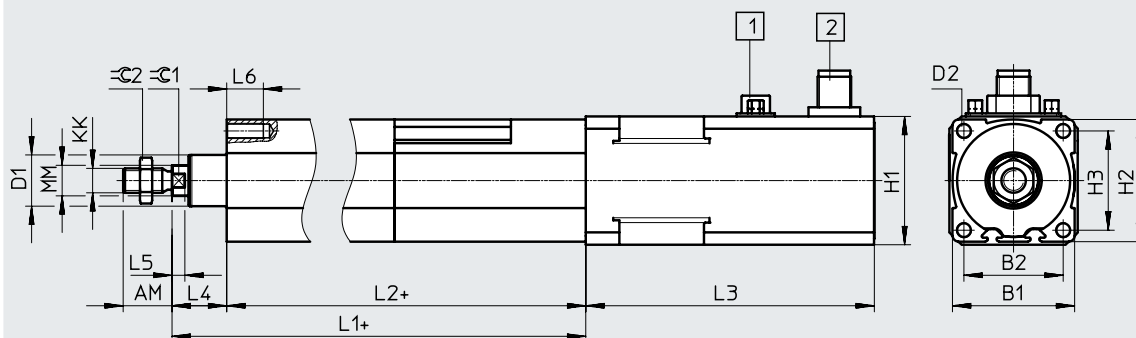
Download CAD data → www.festo.com

Size 16



- [1] Motor connection: round plug M12, 8-pin, bushing (cable length: 350 mm)
 [2] Encoder connection: round plug M12, 8-pin, pins (cable length: 250 mm)
 [3] Min. bending radius of the cables: 60 mm

Size 25, 40



- [1] Motor connection: SUB-D plug, 9-pin, pins
 [2] Encoder connection: round plug M12, 8-pin, pins
 + plus stroke length

Size	AM	B1	B2	D1 ø ±0.05	D2 ø	H1	H2	H3	KK	L1	L2 ±1
16	12	30	24	13.27	M4	44	30	24	M6	143	127
25	16	40	32.5	17.27	M5	42 ^{+0.3}	40	32.5	M8	174.6	156.6
40	19	55	42	26.52	M6	56.4	55	42	M10x1.25	214.2	192.7

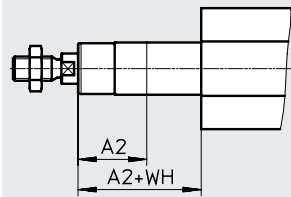
Size	L3				L4	L5	L6	MM	⌀1	⌀2
	EPCO-...	-E	-B	-EB						
16	70±1	70±1	96±1.5	96±1.5	16	3.7	10	8	7	10
25	66±1	94.4±1.2	114.4±1.3	127.4±1.3	18	4.2	12	10	9	13
40	73.5±0.8	102.5±1.1	123.5±1.1	138±1.1	21.5	4.7	14	12	10	17

Data sheet

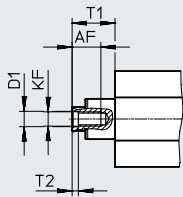
Dimensions Download CAD data → www.festo.com

Variants

E – Extended piston rod



F – Female piston rod thread



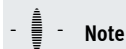
Size	A2 max.	AF	KF	T1	T2	D1	WH
16	100	10	M4	16	1.5	4.3	16
25	150	12	M6	18	2.6	6.4	18
40	200	14	M8	21.5	3.3	8.4	21.5

Data sheet

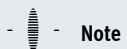
Ordering data – EPCO-16					
Stroke [mm]	Part no.	Type	Stroke [mm]	Part no.	Type
Spindle pitch 3 mm/rev, with encoder			Spindle pitch 8 mm/rev, with encoder		
50	1476415	EPCO-16-50-3P-ST-E	50	1476522	EPCO-16-50-8P-ST-E
100	1476417	EPCO-16-100-3P-ST-E	100	1476524	EPCO-16-100-8P-ST-E
150	1476419	EPCO-16-150-3P-ST-E	150	1476526	EPCO-16-150-8P-ST-E
200	1476421	EPCO-16-200-3P-ST-E	200	1476528	EPCO-16-200-8P-ST-E

Ordering data – EPCO-25					
Stroke [mm]	Part no.	Type	Stroke [mm]	Part no.	Type
Spindle pitch 3 mm/rev, with encoder			Spindle pitch 10 mm/rev, with encoder		
50	1470698	EPCO-25-50-3P-ST-E	50	1470769	EPCO-25-50-10P-ST-E
100	1470700	EPCO-25-100-3P-ST-E	100	1470771	EPCO-25-100-10P-ST-E
150	1470702	EPCO-25-150-3P-ST-E	150	1470773	EPCO-25-150-10P-ST-E
200	1470704	EPCO-25-200-3P-ST-E	200	1470775	EPCO-25-200-10P-ST-E
300	1470706	EPCO-25-300-3P-ST-E	300	1470777	EPCO-25-300-10P-ST-E

Ordering data – EPCO-40					
Stroke [mm]	Part no.	Type	Stroke [mm]	Part no.	Type
Spindle pitch 5 mm/rev, with encoder			Spindle pitch 12.7 mm/rev, with encoder		
50	1472501	EPCO-40-50-5P-ST-E	50	1472617	EPCO-40-50-12.7P-ST-E
100	1472503	EPCO-40-100-5P-ST-E	100	1472619	EPCO-40-100-12.7P-ST-E
150	1472505	EPCO-40-150-5P-ST-E	150	1472621	EPCO-40-150-12.7P-ST-E
200	1472507	EPCO-40-200-5P-ST-E	200	1472623	EPCO-40-200-12.7P-ST-E
300	1472509	EPCO-40-300-5P-ST-E	300	1472625	EPCO-40-300-12.7P-ST-E

**Note**

Variants ordered via modular product system → page 26

**Note**

Position sensing is only possible in combination with characteristic "A"
→ page 26 (modular product system)

Ordering data – Modular product system

Ordering table						
Size	16	25	40	Conditions	Code	Enter code
Module no.	1476585	1470874	1472887			
Function	Electric cylinder				EPCO	EPCO
Size	16	25	40		~...	
Stroke [mm]	50				~...	
	75				~...	
	100				~...	
	125				~...	
	150				~...	
	175				~...	
	200				~...	
	–	250			~...	
	–	300			~...	
	–		350		~...	
	–		400		~...	
Spindle pitch	3	3			~...P	
	–	–	5			
	8	–	–			
	–	10	–			
	–	–	12.7			
Piston rod thread type	Male thread					
	Female thread				-F	
Piston rod extension [mm]	Without					
	1 ... 100	1 ... 150	1 ... 200		~...E	
Position sensing	Without					
	Via proximity switch			[1]	-A	
Motor type	Stepper motor				-ST	ST

[1] **A** Must be selected if encoder E is not selected.

Ordering data – Modular product system

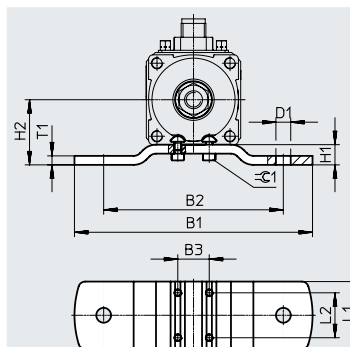
Ordering table						
Size	16	25	40	Conditions	Code	Enter code
Measuring unit	Without					
	Encoder				-E	
Brake	Without					
	Brake				B	
Cable outlet direction	Top (standard)					
	Underneath				-D	
	Left				-L	
	Right				-R	
Guide unit	Without					
	Recirculating ball bearing guide with 2 guide rods			[2]	-KF	
Connecting cable to motor controller, suitable for energy chains	Without					
	1.5 m, straight plug				+1.5E	
	1.5 m, angled plug			[3]	+1.5EA	
	2.5 m, straight plug			[3]	+2.5E	
	2.5 m, angled plug			[3]	+2.5EA	
	5 m, straight plug			[3]	+5E	
	5 m, angled plug			[3]	+5EA	
	7 m, straight plug			[3]	+7E	
	7 m, angled plug			[3]	+7EA	
	10 m, straight plug			[3]	+10E	
	10 m, angled plug			[3]	+10EA	
Controller type	Without					
	CMMO, 5 A				+C5	
Bus protocol/control	Without					
	Digital I/O interface			[4]	DIO	
	IO-Link			[4]	LK	
Switching input/output	Without					
	NPN			[4] [5]	N	
	PNP			[4]	P	

[2] **KF** Not with piston rod extension ...E[3] **1.5E, 1.5EA, 2.5E, 2.5EA, 5E, 5EA, 7E, 7EA, 10E, 10EA, C5** Only with encoder E[4] **DIO, LK, N, P** Must be selected if controller type +C5 is selected[5] **N** Not with IO-Link LK

Accessories

Foot mounting EAHF

Material:
Galvanised steel
RoHS-compliant



The position is freely selectable along the entire cylinder length L2.

Dimensions and ordering data

For size	B1	B2	B3	D1 Ø	H1	H2	L1
16	86	60	10	5.5	7	22	30
25	106	80	14	6.6	9	29	30
40	130	100	18	9	10.5	38	40

For size	L2	T1	⌀C1	CRC ¹⁾	Weight [g]	Part no.	Type
16	20	3	2.5	1	60	1434903	EAHF-P1-16
25	20	4	2.5	1	100	1434904	EAHF-P1-25
40	20	4	4	1	160	1434905	EAHF-P1-40

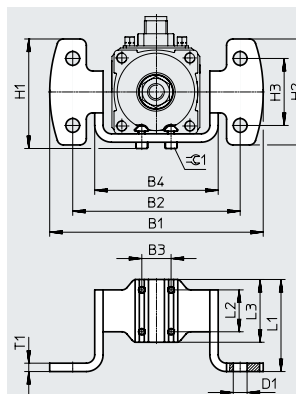
1) Corrosion resistance class CRC 1 to Festo standard FN 940070

Low corrosion stress. Dry internal application or transport and storage protection. Also applies to parts behind coverings, in the non-visible interior area, and parts which are covered in the application (e.g. drive trunnions).

Accessories

Flange mounting EAHH

Material:
Galvanised steel
RoHS-compliant



The position is freely selectable along the entire cylinder length L2.

Dimensions and ordering data

For size	B1	B2	B3	B4	D1 Ø	H1	H2	H3	L1
16	77.2	60	10	45	5.5	38.3	34.6	20	43
25	102	80	14	59	6.6	52.3	50.6	32	44
40	119	100	18	76	9	64.5	56	36	54

For size	L2	L3	T1	≈G1	CRC ¹⁾	Weight [g]	Part no.	Type
16	20	30	3	2.5	1	80	1434906	EAHH-P1-16
25	20	30	4	2.5	1	150	1434907	EAHH-P1-25
40	20	40	4	4	1	240	1434908	EAHH-P1-40

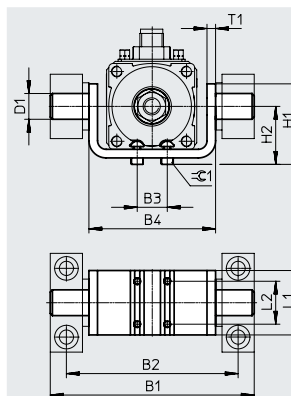
1) Corrosion resistance class CRC 1 to Festo standard FN 940070

Low corrosion stress. Dry internal application or transport and storage protection. Also applies to parts behind coverings, in the non-visible interior area, and parts which are covered in the application (e.g. drive trunnions).

Accessories

Swivel mounting EAHS

Material:
Galvanised steel
RoHS-compliant



The position is freely selectable along the entire cylinder length L2.

Dimensions and ordering data

For size	B1	B2	B3	B4	D1 Ø e9	H1	H2	
16	71	60	10	45	8	33	21	
25	95	80	14	59	12	37.5	27	
40	118	100	18	76	16	55	36.5	

For size	L1	L2	T1	≈G1	CRC ¹⁾	Weight [g]	Part no.	Type
16	30	20	3	2.5	1	80	1434909	EAHS-P1-16
25	30	20	4	2.5	1	140	1434910	EAHS-P1-25
40	40	20	4	4	1	260	1434911	EAHS-P1-40

1) Corrosion resistance class CRC 1 to Festo standard FN 940070

Low corrosion stress. Dry internal application or transport and storage protection. Also applies to parts behind coverings, in the non-visible interior area, and parts which are covered in the application (e.g. drive trunnions).

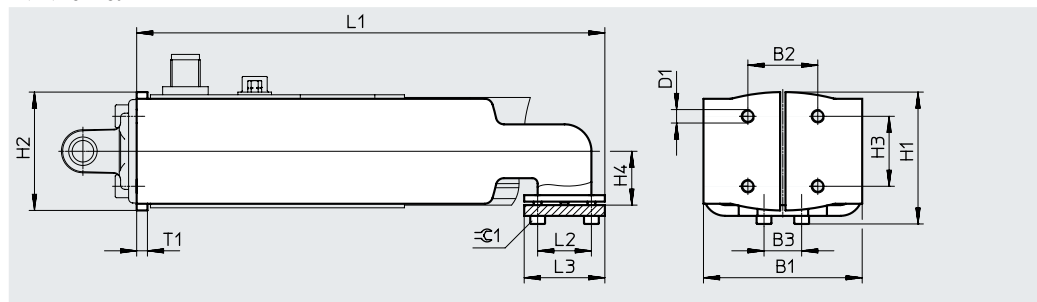
Accessories

Adapter kit EAHA

Material:

RoHS-compliant

Galvanised steel



Dimensions and ordering data

For size	B1	B2	B3	D1	H1	H2	H3	H4
16	45	18	10	M4	35.9	29.8	18	15
25	59	26	14	M5	49	44	26	20
40	76	38	18	M6	66.9	60.8	38	27.5

For size	L1	L2	L3	T1	≅1	CRC ¹⁾	Weight [g]	Part no.	Type
16	139	20	30	3	2.5	1	210	1434900	EAHA-P1-16
25	174	20	30	4	2.5	1	480	1434901	EAHA-P1-25
40	193.4	20	40	4	4	1	770	1434902	EAHA-P1-40

1) Corrosion resistance class CRC 1 to Festo standard FN 940070

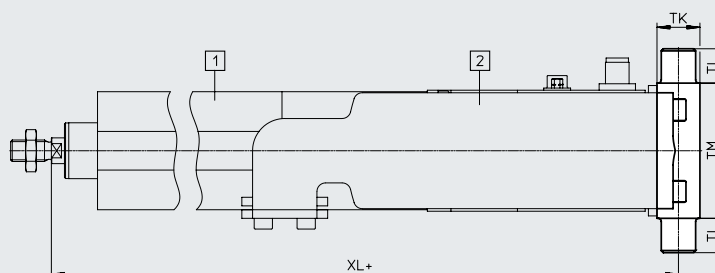
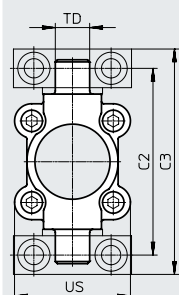
Low corrosion stress. Dry internal application or transport and storage protection. Also applies to parts behind coverings, in the non-visible interior area, and parts which are covered in the application (e.g. drive trunnions).

Accessories

Trunnion flange ZNCF

Material:
ZNCF: stainless steel casting

Free of copper and PTFE
RoHS-compliant



[1] Electric cylinder EPCO
[2] Adapter kit EAHA
+ = plus stroke length

The trunnion flange ZNCF cannot be mounted when turned by 90°.

Dimensions and ordering data

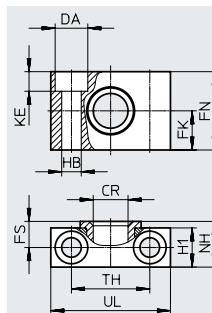
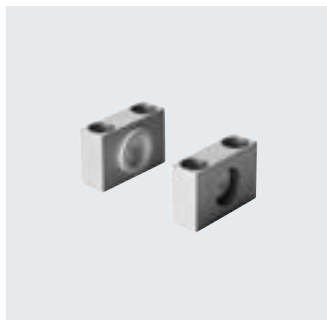
For size	C2	C3	TD ø e9	TK	TL	TM	US	XL				CRC ¹⁾	Weight	Part no.	Type
								EPCO-...	-E	-B	-EB		[g]		
40	87	105	16	20	16	63	54	306.7	335.7	356.7	371.2	2	285	174412	ZNCF-40

1) Corrosion resistance class CRC 2 to Festo standard FN 940070

Moderate corrosion stress. Indoor applications in which condensation can occur. External visible parts with primarily decorative surface requirements in direct contact with a normal industrial environment.

Trunnion support LNZG

Material:
Trunnion support: anodised aluminium
Plain bearing: plastic
Free of copper and PTFE
RoHS-compliant



Dimensions and ordering data

For size	CR ø D11	DA ø H13	FK ø ±0.1	FN	FS	H1	HB ø H13	KE	NH	TH ±0.2	UL	CRC ¹⁾	Weight	Part no.	Type
													[g]		
16	8	8	10	20	7.5	11	4.5	4.6	13	20	30	2	26	1434912	LNZG-16
25	12	11	15	30	10.5	15	6.6	6.8	18	32	46	2	83	32959	LNZG-32
40	16	15	18	36	12	18	9	9	21	36	55	2	129	32960	LNZG-40/50

1) Corrosion resistance class CRC 2 to Festo standard FN 940070

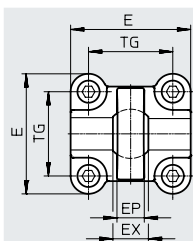
Moderate corrosion stress. Indoor applications in which condensation can occur. External visible parts with primarily decorative surface requirements in direct contact with a normal industrial environment.

Accessories

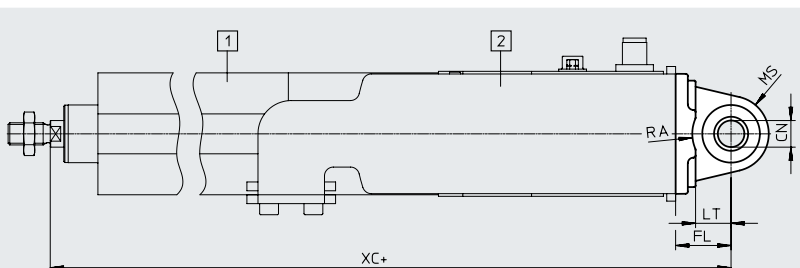
Swivel flange SNCS

Material:
Die-cast aluminium

Free of copper and PTFE
RoHS-compliant



- [1] Electric cylinder EPCO
[2] Adapter kit EAHA
+ = plus stroke length



Dimensions and ordering data

For size	CN Ø	E	EP +0.2	EX	FL ±0.2	LT	MS	RA +1	TG
40	12 ^{+0.015}	54 ^{+0.5}	12	16	25	16	17 ^{+0.5}	17.5	38

For size	XC				CRC ¹⁾	Weight [g]	Part no.	Type
	EPCO-...	-E	-B	-EB				
40	321.7	350.7	371.7	386.2	1	122	174398	SNCS-40

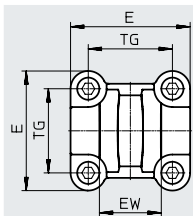
1) Corrosion resistance class CRC 1 to Festo standard FN 940070

Low corrosion stress. Dry internal application or transport and storage protection. Also applies to parts behind coverings, in the non-visible interior area, and parts which are covered in the application (e.g. drive trunnions).

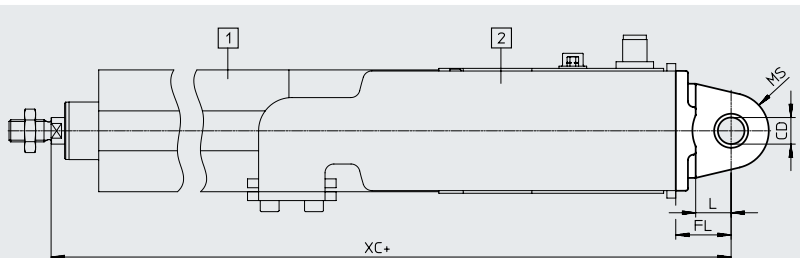
Swivel flange SNCL

Material:
Wrought aluminium alloy

Free of copper and PTFE
RoHS-compliant



- [1] Electric cylinder EPCO
[2] Adapter kit EAHA
+ = plus stroke length



Dimensions and ordering data

For size	CD Ø H9	EW h12	FL ±0.2	L	MR -0.5	XC				CRC ¹⁾	Weight [g]	Part no.	Type
						EPCO-...	-E	-B	-EB				
16	6	12	16	10	6	237	237	263	263	2	21	537791	SNCL-16
25	8	16	20	14	8	269.6	298	318	331	2	41	537793	SNCL-25
40	12	28	25	16	12	321.7	350.7	371.7	386.2	1	95	174405	SNCL-40

1) Corrosion resistance class CRC 1 to Festo standard FN 940070

Low corrosion stress. Dry internal application or transport and storage protection. Also applies to parts behind coverings, in the non-visible interior area, and parts which are covered in the application (e.g. drive trunnions).

Corrosion resistance class CRC 2 to Festo standard FN 940070

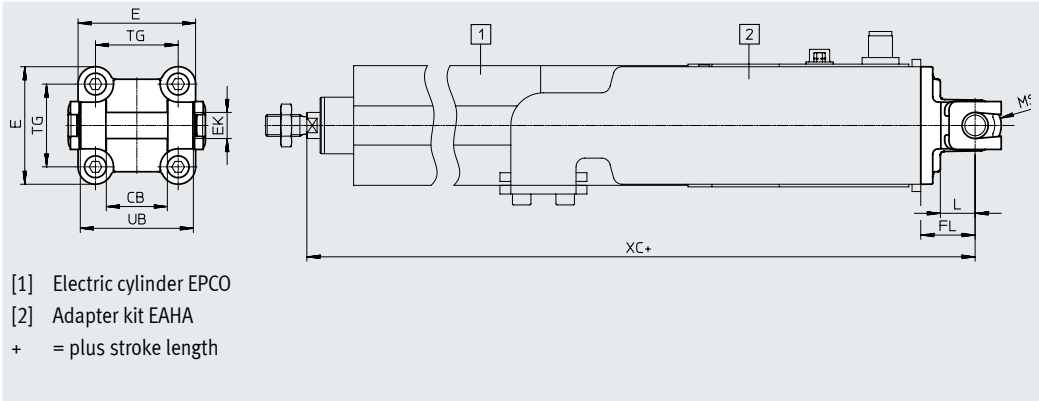
Moderate corrosion stress. Indoor applications in which condensation can occur. External visible parts with primarily decorative surface requirements in direct contact with a normal industrial environment.

Accessories

Swivel flange SNCB

Material:
Die-cast aluminium

Free of copper and PTFE
RoHS-compliant



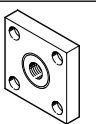
Dimensions and ordering data														
For size	CB	EK Ø	FL ±0.2	L	MR	UB h14	XC				CRC ¹⁾	Weight [g]	Part no.	Type
							EPCO-...	-E	-B	-EB				
40	28	12	25	16	12	52	321.7	350.7	371.7	386.2	1	155	174391	SNCB-40

1) Corrosion resistance class CRC 1 to Festo standard FN 940070
Low corrosion stress. Dry internal application or transport and storage protection. Also applies to parts behind coverings, in the non-visible interior area, and parts which are covered in the application (e.g. drive trunnions).

Ordering data – Mounting components				Data sheets → Internet: clevis foot			
Designation	For size	Part no.	Type	Designation	For size	Part no.	Type
Clevis foot LBG				Right angle clevis foot LQG			
	40	31762	LBG-40		40	31769	LQG-40
Clevis foot LBN							
	16	6058	LBN-12/16				
	25	6059	LBN-20/25				
	40	195861	LBN-40				

Accessories

Ordering data – Piston rod attachments

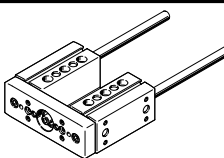
Designation	For size	Part no.	Type
Rod eye SGS			
	16	9254	SGS-M6
	25	9255	SGS-M8
	40	9261	SGS-M10x1.25
Self-aligning rod coupler FK			
	16	2061	FK-M6
	25	2062	FK-M8
	40	6140	FK-M10x1.25
Coupling piece KSG			
	40	32963	KSG-M10x1.25

Data sheets → Internet: piston rod attachment

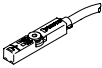
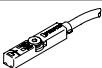
Designation	For size	Part no.	Type
Rod clevis SG			
	16	3110	SG-M6
	25	3111	SG-M8
	40	6144	SG-M10x1.25
Rod clevis SGA			
	40	32954	SGA-M10x1.25

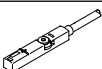
Ordering data – Guide unit

Data sheets → Internet: eagf

	For size	Stroke [mm]	Part no.	Type
	16	50	3192932	EAGF-P1-KF-16-50
		100	3192934	EAGF-P1-KF-16-100
		150	3192936	EAGF-P1-KF-16-150
		200	3192938	EAGF-P1-KF-16-200
		75, 125, 175	3192939	EAGF-P1-KF-16-
	25	50	3192943	EAGF-P1-KF-25-50
		100	3192945	EAGF-P1-KF-25-100
		150	3192947	EAGF-P1-KF-25-150
		200	3192949	EAGF-P1-KF-25-200
		300	3192951	EAGF-P1-KF-25-300
		75, 125, 175, 250	3192952	EAGF-P1-KF-25-
	40	50	3192955	EAGF-P1-KF-40-50
		100	3192957	EAGF-P1-KF-40-100
		150	3192959	EAGF-P1-KF-40-150
		200	3192961	EAGF-P1-KF-40-200
		300	3192963	EAGF-P1-KF-40-300
		75, 125, 175, 250 350, 400	3192966	EAGF-P1-KF-40-

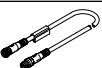
Accessories

Ordering data – Proximity switches for T-slot, magneto-resistive						Data sheets → Internet: smt
	Type of mounting	Switching output	Electrical connection	Cable length [m]	Part no.	Type
N/O contact						
	Insertable in the slot from above, flush with the cylinder profile, short design	PNP	Cable, 3-wire	2.5	574335	SMT-8M-A-PS-24V-E-2.5-OE
			Plug M8x1, 3-pin	0.3	574334	SMT-8M-A-PS-24V-E-0.3-M8D
			Plug M12x1, 3-pin	0.3	574337	SMT-8M-A-PS-24V-E-0.3-M12
		NPN	Cable, 3-wire	2.5	574338	SMT-8M-A-NS-24V-E-2.5-OE
			Plug M8x1, 3-pin	0.3	574339	SMT-8M-A-NS-24V-E-0.3-M8D
N/C contact						
	Insertable in the slot from above, flush with the cylinder profile, short design	PNP	Cable, 3-wire	7.5	574340	SMT-8M-A-PO-24V-E-7,5-OE

Ordering data – Proximity switches for T-slot, magnetic reed						Data sheets → Internet: sme
	Type of mounting	Switching output	Electrical connection	Cable length [m]	Part no.	Type
N/O contact						
	Insertable in the slot from above, flush with the cylinder profile	Contacting	Cable, 3-wire	2.5	543862	SME-8M-DS-24V-K-2.5-OE
				5.0	543863	SME-8M-DS-24V-K-5.0-OE
			Cable, 2-wire	2.5	543872	SME-8M-ZS-24V-K-2.5-OE
			Plug M8x1, 3-pin	0.3	543861	SME-8M-DS-24V-K-0.3-M8D
N/C contact						
	Insertable in the slot lengthwise, flush with the cylinder profile	Contacting	Cable, 3-wire	7.5	160251	SME-8-O-K-LED-24

**Note**

Position sensing is only possible in combination with characteristic "A"
→ page 26 (modular product system)

Ordering data – Connecting cable					Data sheets → Internet: nebu
	Description	Connection	Cable length [m]	Part no.	Type
Straight socket					
	Union nut M8, both ends	3-pin	0.5	541346	NEBU-M8G3-K-0.5-M8G3
			1.0	541347	NEBU-M8G3-K-1-M8G3
			2.5	541348	NEBU-M8G3-K-2.5-M8G3
			5.0	541349	NEBU-M8G3-K-5-M8G3

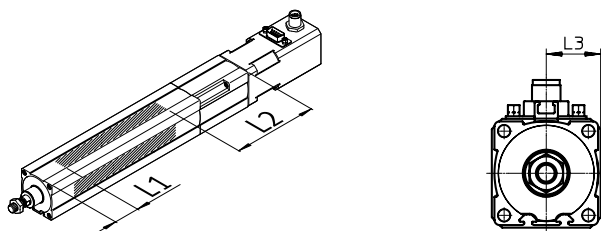
Accessories

Sensor mounting

The sensor mountings can only be attached within the highlighted area due to the asymmetry of the internal magnet.

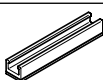
The proximity switches may not switch reliably if they are mounted outside of this area.

The overall length of the sensor rail SAMH corresponds to the length of the sensing range plus approx. 10 mm adjustment range on either side for the proximity switches.

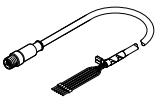
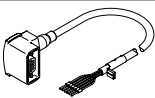
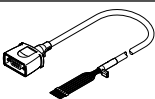
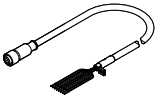
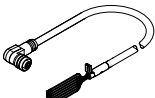


Size	L1	L2	L3
16	29	95	15
25	33	121	20
40	40	150	27.5

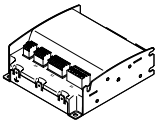
Ordering data – Sensor mounting for T-slot

	For size	Description	Length [mm]	Part no.	Type
Sensor rail					
	16, 25, 40	Size 25 can only be used with proximity switch SMT-8 (magneto-resistive).	50	1600093	SAMH-N8-SR-50
			100	1600118	SAMH-N8-SR-100
Mounting kit					
	16, 25, 40	–	35	525565	CRSMB-8-32/100

Accessories

Ordering data – Cables ¹⁾					
	For size	Description	Cable length [m]	Part no.	Type
Motor cable					
	16	Straight plug - Min. bending radius: 62 mm - Suitable for energy chains - Ambient temp.: –40 ... +80°C	1.5	1449600	NEBM-SM12G8-E-1.5-Q5-LE6
			2.5	1449601	NEBM-SM12G8-E-2.5-Q5-LE6
			5.0	1449602	NEBM-SM12G8-E-5-Q5-LE6
			7.0	1449603	NEBM-SM12G8-E-7-Q5-LE6
			10.0	1449604	NEBM-SM12G8-E-10-Q5-LE6
	25/-40	Angled plug - Min. bending radius: 62 mm - Suitable for energy chains - Ambient temp.: –40 ... +80°C	1.5	1450736	NEBM-S1W9-E-1.5-Q5-LE6
			2.5	1450737	NEBM-S1W9-E-2.5-Q5-LE6
			5.0	1450738	NEBM-S1W9-E-5-Q5-LE6
			7.0	1450739	NEBM-S1W9-E-7-Q5-LE6
			10.0	1450740	NEBM-S1W9-E-10-Q5-LE6
		Straight plug - Min. bending radius: 62 mm - Suitable for energy chains - Ambient temp.: –40 ... +80°C	1.5	1450368	NEBM-S1G9-E-1.5-Q5-LE6
			2.5	1450369	NEBM-S1G9-E-2.5-Q5-LE6
			5.0	1450370	NEBM-S1G9-E-5-Q5-LE6
			7.0	1450371	NEBM-S1G9-E-7-Q5-LE6
			10.0	1450372	NEBM-S1G9-E-10-Q5-LE6
Encoder cable					
	16/-25/-40	Straight plug - Min. bending radius: 68 mm - Suitable for energy chains - Ambient temp.: –40 ... +80°C	1.5	1451586	NEBM-M12G8-E-1.5-LE8
			2.5	1451587	NEBM-M12G8-E-2.5-LE8
			5.0	1451588	NEBM-M12G8-E-5-LE8
			7.0	1451589	NEBM-M12G8-E-7-LE8
			10.0	1451590	NEBM-M12G8-E-10-LE8
	25/-40	Angled plug - Min. bending radius: 68 mm - Suitable for energy chains - Ambient temp.: –40 ... +80°C	1.5	1451674	NEBM-M12W8-E-1.5-LE8
			2.5	1451675	NEBM-M12W8-E-2.5-LE8
			5.0	1451676	NEBM-M12W8-E-5-LE8
			7.0	1451677	NEBM-M12W8-E-7-LE8
			10.0	1451678	NEBM-M12W8-E-10-LE8

1) Other cable lengths on request.

Ordering data – Motor controller			Data sheets → Internet: cmmo
	Description	Part no.	Type
	With I/O interface		
	Switching input/output PNP	1512316	CMMO-ST-C5-1-DIOP
	Switching input/output NPN	1512317	CMMO-ST-C5-1-DION
	With IO-Link		
	Switching input/output PNP	1512320	CMMO-ST-C5-1-LKP