# **FESTO**



**FESTO** 

Key features

#### At a glance

- Gentle stopping without impact vibration or noise
- Single-acting or double-acting
- Powerful shock absorber for high energy absorption
- Wide range of applications thanks to adjustable shock absorber
- Supply ports at side or underneath
- Adjustable active direction thanks to rotatable toggle lever arrangement (90°, 180°, 270°)
- Position sensing via inductive proximity sensor SIEN on the toggle lever or via proximity sensor for T-slot SME-/SMT-8 on the piston
- Sturdy design for long service life
- Stable guide rod
- Seal for protection against dirt and moisture

#### The technology in detail

Cushioning adjustment

- Adaptable shock absorber depending on the load on the conveyed good
- Easy adjustment via knurled adjusting wheel 1
- Shock absorber can be replaced in the fitted position



#### Optional: toggle lever lock

- For locking the toggle lever 1
- The toggle lever lock 2 can be ordered as a variant of the stopper cylinder or as an accessory
- Simple design
- Reliable function

Piston  $\emptyset$  50:



Piston Ø 63, 80:











#### Toggle lever deactivator

- For deactivation of the stop function
- The toggle lever deactivator can be ordered as an accessory
- Simple design







#### Position sensing

2

- Sensing of the toggle lever position (conveyed good in stop position) via inductive proximity sensor SIEN-M8 1
- Sensing of the piston position (cylinder retracted or advanced) via proximity sensor SME-/SMT-8 in the slot 2

Sensing of the toggle lever position  $% \left\{ \left( 1\right) \right\} =\left\{ \left( 1\right) \right\} =\left\{$ 



Sensing of the piston position

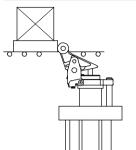


# **Stopper cylinders DFST** Key features

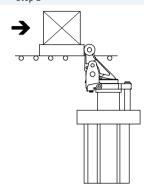
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### Functional sequence

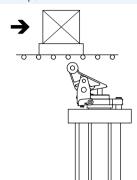
Step 1



Step 2



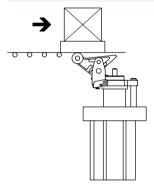
Step 3

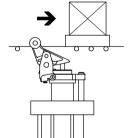


- 1. Gentle stopping of heavy masses via a hydraulic shock absorber in the piston rod.
- 2. The toggle lever (optional) is locked into the retracted end position so that the conveyed good cannot be pushed back by the shock absorber.
- 3. The conveyed good is released by means of compressed air, and the toggle lever is released simultaneously.

#### Step 4



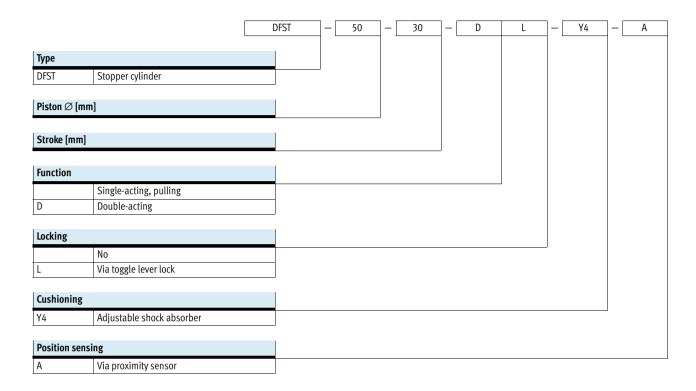




- 4. The piston is advanced by means of spring force or compressed air. The toggle lever tips back which prevents the conveyed good from being pushed up.
- The toggle lever is raised by means of spring force and stops  $% \left\{ \left( 1\right) \right\} =\left\{ \left( 1\right$ the next conveyed good.

### **Stopper cylinders DFST** Type codes

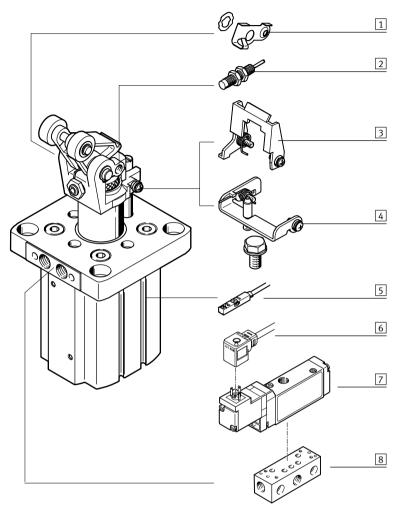




### **Stopper cylinders DFST** Peripherals overview







Varia	nts and accessories		
	Туре	Description	→ Page/Internet
1	Toggle lever deactivator	For deactivation of the stop function. The conveyed good is able to pass the stopper cylinder	15
	DADP-TF	without activating the cylinder	
2	Proximity sensor, inductive	For sensing of the toggle lever position	15
	SIEN-M8		
3	Toggle lever lock	For piston ∅ 50	15
	DADP-TL	For locking the toggle lever in the retracted position. With pressurisation, the conveyed good	
		and the toggle lever are released simultaneously	
4	Toggle lever lock	• For piston Ø 63, 80	15
	DADP-TL	For locking the toggle lever in the retracted position. With pressurisation, the conveyed good	
		and the toggle lever are released simultaneously	
5	Proximity sensor	For sensing the piston position	15
	SME-/SMT-8		
6	Plug socket with cable	-	14
	KMEB		
7	Solenoid valve	For quick and direct actuation of the stopper cylinder	14
	MEBH		
8	Intermediate plate	For attaching the valve	15
	ZVA-2		





Diameter 50 ... 80 mm

Stroke length 30 ... 40 mm



General technical data					
$Piston\varnothing$		50	63	80	
Pneumatic connection		G1/8			
Stroke	[mm]	30		40	
Constructional design		Piston rod with toggle lever			
Mode of operation		Double-acting Double-acting			
		Single-acting, pulling			
Protection against torsion/guide		Guide rod			
Type of mounting		Via through-holes			
Cushioning (of piston movement)		Flexible cushioning rings/pads at both	th ends		
Position sensing	on sensing Via proximity sensor				
Mounting position		Vertical			
Product weight	[g]	1800	3500	6850	

Operating and environmental conditions					
Operating medium		Compressed air in accordance with ISO 8573-1:2010 [7:-:-]			
Operating pressure <sup>1)</sup>	[bar]	2 10			
Ambient temperature	[°C]	5 60			
Corrosion resistance class CRC <sup>2)</sup>		1			

Min. operating pressure for piston Ø 50 with toggle lever lock is 3 bar
Corrosion resistance class 1 as per Festo standard 940 070
Components requiring low corrosion resistance. Transport and storage protection. Parts that do not have primarily decorative surface requirements, e.g. in internal areas that are not visible or behind covers.

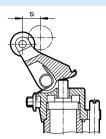
# Materials Sectional view 1 2 4

Stopper cylinder		
Piston ∅	50	63, 80
1 Rollers	Polyacetate	
2 Attachments	Nickel-plated cast steel	
3 Piston rod	High-alloy stainless stee	el
4 End cap	Die-cast aluminium	Wrought aluminium alloy
5 Housing	Wrought aluminium allo	by .
- Seals	Nitrile rubber	
Note on materials	RoHS-compliant	

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#### **Braking distance**

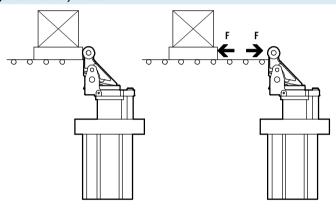
The braking distance refers to the distance from when contact is made with the toggle lever to the end stop.



Piston $\varnothing$		50	63	80
Braking distance	[mm]	14.75	14.75	20

#### Resetting force F<sub>R</sub> of the toggle lever against the delivery direction

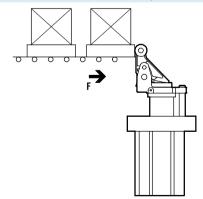
The resetting force refers to the minimum force that must be applied to press the toggle lever into the end position.



Piston Ø	50	63	80
Resetting force at the toggle lever [N]	11	23	36

#### Permissible impact force F<sub>Impact</sub> on the rollers of the toggle lever when the piston rod is advanced and the toggle lever is pushed into its end position

The permissible impact force refers to the momentary force that may act on the toggle lever when it is already pushed into its end position without damaging the rod bearing or the toggle lever mechanism.

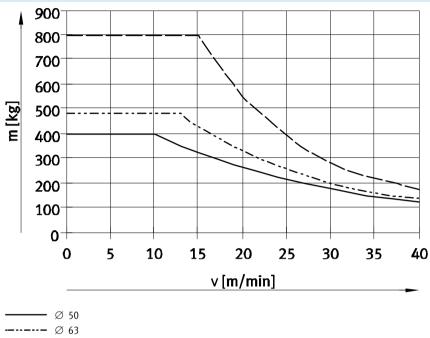


Piston Ø		50	63	80
Impact force	[N]	3000	5000	6000

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#### Permissible mass m as a function of the conveyor speed v

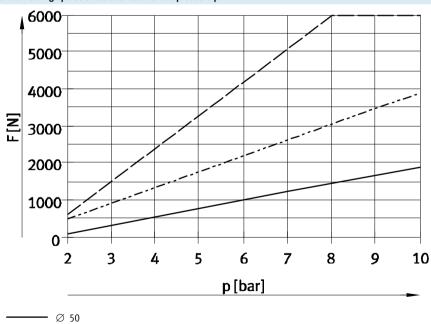
The values in the graph opposite take into account a friction value of  $\mu = 0.1$ .



Permissible transverse force F<sub>Q</sub> during the switching operation as a function of the pressure p

-- Ø 80

The applied load causes a transverse force to act on the piston rod. To ensure the function of the cylinder, a certain minimum pressure must be applied.



---- Ø 63 -- Ø 80

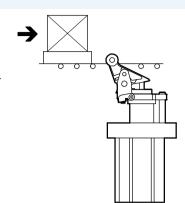
Technical data

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#### Selection aid

Stopping a workpiece carrier

The stopper cylinder is used to brake an individual workpiece carrier, without or without end position locking. The toggle lever and oil damper are pushed into the end position again for each new workpiece carrier.



#### Example

Given:

Friction value  $\mu = 0.1$ 

Delivery speed v = 20 m/min

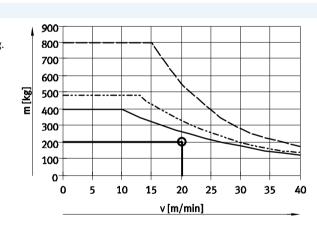
Workpiece carrier with workpiece m = 200 kg

Operating pressure p = 6 bar

Choice: Stopper cylinder DFST-50

#### 1. Checking the permissible mass

The maximum permissible mass at a delivery speed of 20 m/min is 250 kg. This means that the total mass of the workpiece carrier and workpiece of 200 kg is permissible.





#### 2. Checking the permissible transverse force during the switching operation

Transverse force  $F_Q$  = friction force

F<sub>Friction</sub>

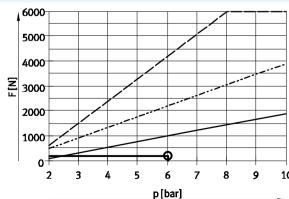
 $F_{Friction} = \mu x m x g$ 

 $= 0.1 \times 200 \text{ kg} \times 9.81 \text{ m/s}^2$ 

= approx. 200 N

The maximum permissible transverse force at an operating pressure of 6 bar is 1000 N.

This means that the transverse force of 200 N is permissible.





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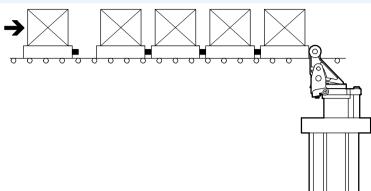
Technical data

#### Selection aid

Stopping or separating several workpiece carriers

The stopper cylinder is used to separate workpiece carriers. Further workpiece carriers accumulate behind carriers that have already pushed the toggle lever into its end position.

Since the oil damper in the stopper cylinder is inoperative in this case, a certain amount of cushioning between the workpiece carriers must be guaranteed (e.g. elastomer elements).



#### Example

Given:

Friction value  $\mu = 0.1$ 

Delivery speed v = 15 m/min

Workpiece carrier with workpiece m = 100 kg

Operating pressure p = 6 bar

Maximum number of workpiece carriers accumulating simultaneously n<sub>Group</sub> = 1

Maximum number of all queued workpiece carriers  $n_{Queue} = 5$ 

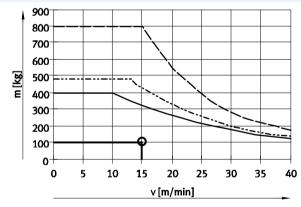
Maximum number of all advancing workpiece carriers  $n_{Queue-1} = 4$ 

Spring travel of the workpiece carrier buffer  $s_F = 10 \text{ mm}$ 

Choice: Stopper cylinder DFST-50

#### 1. Checking the permissible mass of the first workpiece carrier

The maximum permissible mass at a delivery speed of 15 m/min is 320 kg. This means that the total mass of the workpiece carrier and workpiece of 100 kg is permissible.



\_\_\_\_ Ø 50 ---- Ø 63 ---- Ø 80

#### 2a. Calculation of the maximum permissible impact force when workpiece carriers accumulate behind a carrier at the stopper cylinder

With the DFST-50, the maximum permissible impact force is 3000 N. This means that at a total force of 1,150 N, the number of workpiece carriers is permissible.

Impact force calculation:

$$F_{Impact} = \frac{(n_{Group} \times m) \times v^2}{s_F} = \frac{(1 \times 100 \text{kg}) \times (15 \text{m}/60 \text{s})^2}{0.01 \text{m}} = \text{ca.650N}$$

Friction force:

$$F_{Friction} = \mu \times (n_{Queue} \times m) \times g = 0.1 \times (5 \times 100 kg) \times 9.81 m/s^2 = ca.500 N$$

Max. total force:

$$F_{Total force} = F_{Impact} + F_{Friction} = 650N + 500N = 1150N$$

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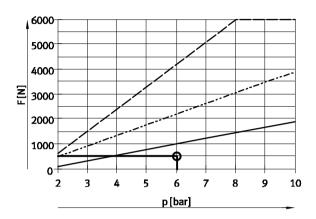
#### Selection aid

#### 2b. Checking the permissible transverse force during the switching operation

Transverse force  $F_Q =$ friction force F<sub>Friction</sub>  $F_{Friction} = 500 \text{ N}$ 

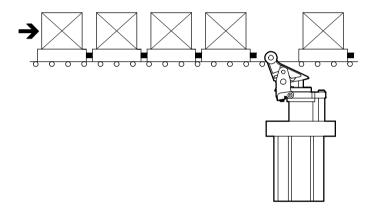
The maximum permissible transverse force at an operating pressure of 6 bar is 1000 N.

This means that the transverse force of 500 N is permissible.

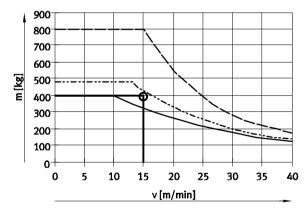


Ø 50 Ø 63 Ø 80

#### 3. Separating and advancing the workpiece carriers



The maximum permissible mass with the DFST-50 at a delivery speed of 15 m/min is 320 kg. Since the total mass of the four workpiece carriers advancing on the stopper cylinder is 400 kg, the next largest stopper cylinder must be selected for separating.



Ø 50 ----- Ø 63 **--**- ∅ 80

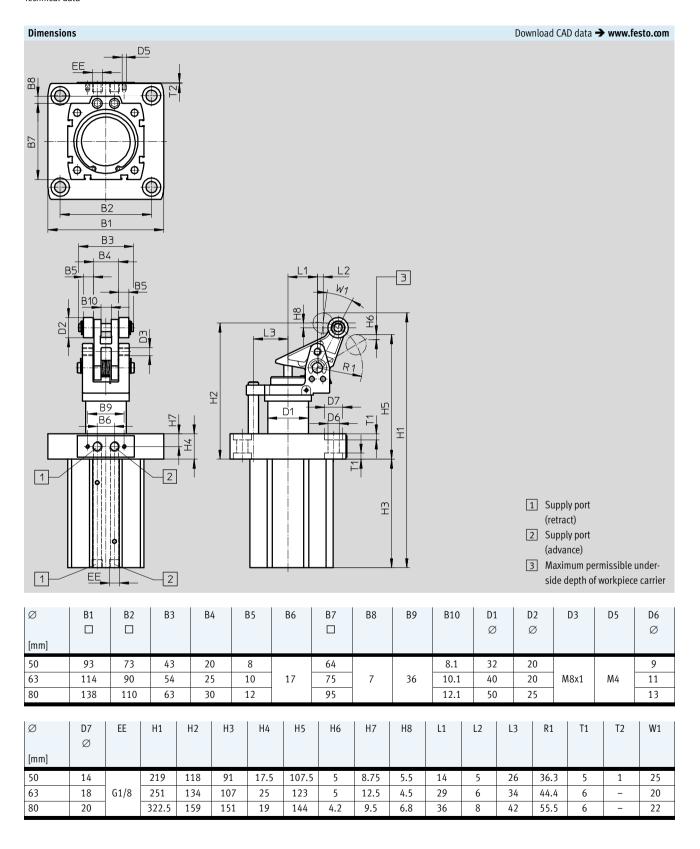
Max. total mass:

 $m_{Total\:force}\,=\,n_{Queue\,-\,1}\,\times\,m\,=\,4\,\times\,100kg\,=\,400kg$ 

#### Result

The stopper cylinder DFST-63 must be selected for separating five workpiece carriers.







Ordering data						
	Piston Ø	with spring	without spring	with toggle lever lock	Part No.	Туре
<u></u>	50				543 729	DFST-50-30-Y4-A
				•	555 572	DFST-50-30-L-Y4-A
					543 730	DFST-50-30-D-Y4-A
				-	555 573	DFST-50-30-DL-Y4-A
	63				543 744	DFST-63-30-Y4-A
				-	555 574	DFST-63-30-L-Y4-A
					543 745	DFST-63-30-D-Y4-A
				•	555 575	DFST-63-30-DL-Y4-A
	80				543 747	DFST-80-40-Y4-A
				•	555 576	DFST-80-40-L-Y4-A
					543 748	DFST-80-40-D-Y4-A
					555 577	DFST-80-40-DL-Y4-A

### **Stopper cylinders DFST** Accessories



#### Mounting options for solenoid valves and valve functions

A solenoid valve MEH, MEBH, MOEH or MOEBH can be mounted on the stopper cylinder for quick, direct

actuation of the cylinder. The valve must be connected to the cylinder via an intermediate plate ZVA. The position of the piston rod when the solenoid valve is in the normal position

depends on the valve type and the position of the valve on the cylinder.

Ordering data – Solenoid valve				Technical data → Internet: meh
Mounting options for the solenoid valve with	Position of the piston rod in normal position	Part No.	Туре	
intermediate plate ZVA				
Single-acting				
	12 2 2	173125 172999	MEH-3/2-5,0-B MEBH-3/2-5,0-B	
	82 $\sqrt{3}$			
		173429 173002	MOEH-3/2-5,0-B MOEBH-3/2-5,0-B	
	12 Z Z Z Z Z Z Z Z Z Z Z Z Z Z Z Z Z Z Z			
Double-acting				
Q Q	<u>— Пілала</u>	173128	MEH-5/2-5,0-B	
	12 2 2 W 3 3 9 9 9 9 9 9 9 9 9 9 9 9 9 9 9 9 9	173005	MEBH-5/2-5,0-B	
		173128 173005	MEH-5/2-5,0-B MEBH-5/2-5,0-B	
	14 2 WW 3 V 9 3	2,3003		
	•			

Ordering data - Plug socket with cable				Technical data → Internet: kmeb
	For Ø	Part N	o. Type	
	50, 63, 80	15168	8 KMEB-1-24-2,5	i-LED
		15168	9 KMEB-1-24-5-L	ED
		19345	7 KMEB-1-24-10-	-LED

# Stopper cylinders DFST Accessories



Ordering data – Intermediate plate			
	For Ø	Part No.	Type
	50, 63, 80	164897	ZVA-2

Ordering data			
	For Ø	Part No.	Туре
Lever locking mechanism DADP-TL			
	50	543751	DADP-TL-F3-50
Soo - A	63	543752	DADP-TL-F3-63
	80	543753	DADP-TL-F3-80
Free pass mechanism DADP-TF			
A	50	543755	DADP-TF-F3-50
	63	543756	DADP-TF-F3-63
OF-	80	543757	DADP-TF-F3-80

Ordering data	Technical data → Internet: sien				
	For Ø	Contact	Electrical connection	Part No.	Туре
-6 <b>0</b>	50, 63, 80	N/O contact	Cable, 2.5 m	150386	SIEN-M8B-PS-K-L
			Plug	150387	SIEN-M8B-PS-S-L
		N/C contact	Cable, 2.5 m	150390	SIEN-M8B-PO-K-L
			Plug	150391	SIEN-M8B-PO-S-L

Ordering data	- Proximity sensors for T-slot, magneto-r	Technical data → Internet: smt					
	Type of mounting	Switch	Electrical connection	Cable length	Part No.	Туре	
		output		[m]			
N/O contact							
~	Insertable in the slot from above, flush	PNP	Cable, 3-wire	2.5	574335	SMT-8M-A-PS-24V-E-2,5-0E	
THE STATE OF THE S	with cylinder profile, short design		Plug M8x1, 3-pin	0.3	574334	SMT-8M-A-PS-24V-E-0,3-M8D	
			Plug M12x1, 3-pin	0.3	574337	SMT-8M-A-PS-24V-E-0,3-M12	
		NPN	Cable, 3-wire	2.5	574338	SMT-8M-A-NS-24V-E-2,5-OE	
			Plug M8x1, 3-pin	0.3	574339	SMT-8M-A-NS-24V-E-0,3-M8D	
N/C contact							
THE WAY	Insertable in the slot from above, flush with cylinder profile, short design	PNP	Cable, 3-wire	7.5	574340	SMT-8M-A-PO-24V-E-7,5-OE	

### **Stopper cylinders DFST** Accessories



Ordering data	- Proximity sensor for T-slot, magnetic re	Technical data → Internet: sme					
	Type of mounting	Switching	Electrical connection	Cable length	Part No.	Туре	
		output		[m]			
N/O contact							
	Insertable in slot from above, flush with	Contacting	Cable, 3-wire	2.5	543862	SME-8M-DS-24V-K-2,5-0E	
CT ST	cylinder profile			5.0	543863	SME-8M-DS-24V-K-5,0-OE	
			Cable, 2-wire	2.5	543872	SME-8M-ZS-24V-K-2,5-0E	
			Plug M8x1, 3-pin	0.3	543861	SME-8M-DS-24V-K-0,3-M8D	
N. C.	Insertable in slot lengthwise, flush with	Contacting	Cable, 3-wire	2.5	150855	SME-8-K-LED-24	
	cylinder profile		Plug M8x1, 3-pin	0.3	150857	SME-8-S-LED-24	
N/C contact							
	Insertable in slot lengthwise, flush with	Contacting	Cable, 3-wire	7.5	160251	SME-8-O-K-LED-24	
	cylinder profile						

Ordering data	Technical data → Internet: nebu				
	Electrical connection, left	Electrical connection, right	Cable length [m]	Part No.	Type
	Straight socket, M8x1, 3-pin	Cable, open end, 3-wire	2.5	541333	NEBU-M8G3-K-2.5-LE3
<b>6</b>			5	541334	NEBU-M8G3-K-5-LE3
	Angled socket, M8x1, 3-pin	Cable, open end, 3-wire	2.5	541338	NEBU-M8W3-K-2.5-LE3
			5	541341	NEBU-M8W3-K-5-LE3