

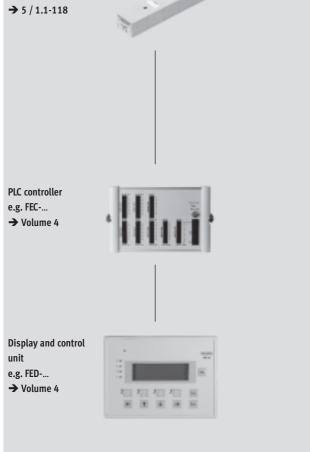
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Key features

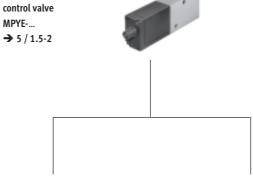
Components for positioning and measuring using the standard cylinder DNCI











→ 5 / 1.4-2 Closed loop end-position controller SPC11-INC

Soft Stop

Positioning technology **→**5 / 1.3-2



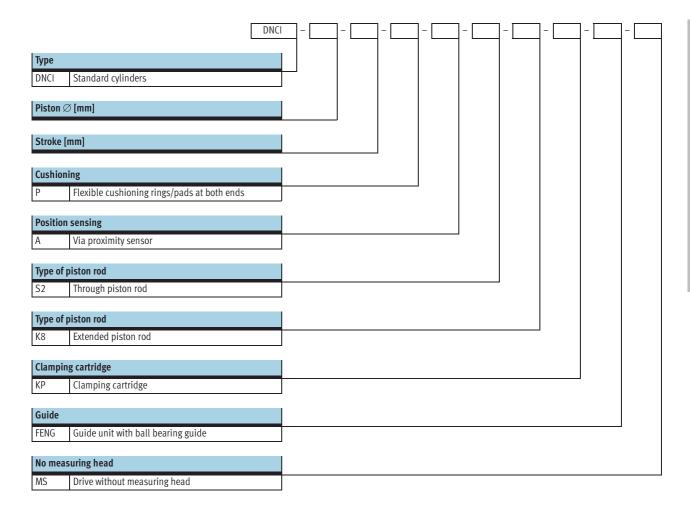


Axis controller SPC200

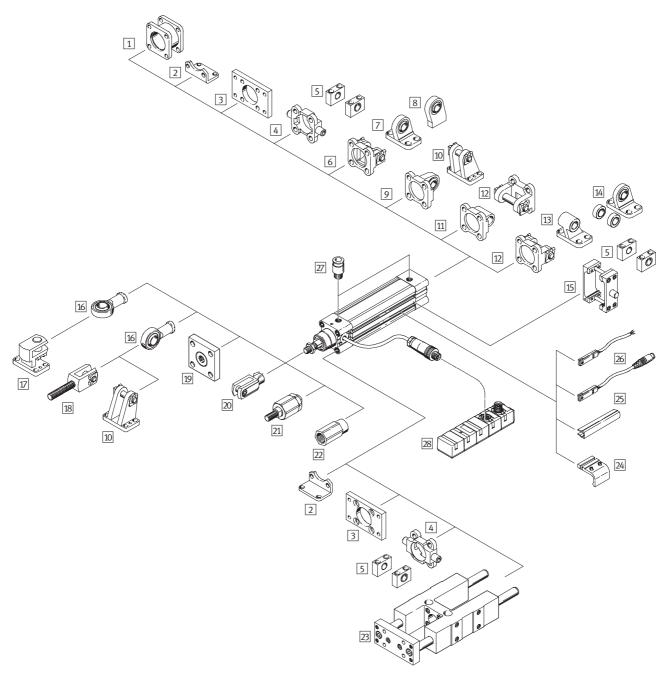


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Type cod



Standard cylinders DNCI, with measuring transducer DADE Peripherals overview



Accessories								
Туре	Brief description	→ Page						
1 Adapter kit ¹⁾ DPNC	For connecting two cylinders with identical piston \varnothing to form a multi-position cylinder	Volume 1						
2 Foot mounting HNC	For mounting the drive on the bearing and end cap	Volume 1						
3 Flange mounting FNC	For mounting the drive on the bearing and end cap	Volume 1						
4 Trunnion mounting ZNCF/CRZNG	For swivelling movements of the drive on the bearing or end caps	Volume 1						
5 Trunnion support LNZG/CRLNZG	-	Volume 1						

Standard cylinders DNCI, with measuring transducer DADE Peripherals overview

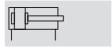
Acce	ssories		
	Туре	Brief description	→ Page
6	Swivel flange ¹⁾	For swivelling movements of the drive on the end cap	Volume 1
	SNC		
7	Clevis foot mounting ¹⁾	With spherical bearing	Volume 1
	LSNG		
8	Clevis foot mounting ¹⁾	Weld-on, with spherical bearing	Volume 1
	LSNSG		
9	Swivel flange ¹⁾	For swivelling movements of the drive on the end cap, with spherical bearing	Volume 1
	SNCS		
10	Clevis foot mounting ¹⁾	-	Volume 1
	LBG		
11	Swivel flange ¹⁾	For swivelling movements of the drive on the end cap	Volume 1
42	SNCL Swivel flange ¹⁾	Fax aviivalling mayoments of the drive on the and con	Volume 1
12	SNCB	For swivelling movements of the drive on the end cap	Volume 1
13	Clevis foot mounting ¹⁾	_	Volume 1
D	LNG/CRLNG		votume 1
14	Clevis foot mounting ¹⁾	With spherical bearing	Volume 1
٠	LSN		1.5.0
15	Trunnion mounting kit	For swivelling movements of the drive	Volume 1
	ZNCM		
16	Rod eye	With spherical bearing	Volume 1
	SGS/CRSGS		
17	Right-angle clevis foot	-	Volume 1
	LQG		
18	Rod clevis	With male thread	Volume 1
	SGA		
19	Coupling piece	For compensating radial deviations	Volume 1
	KSG		V 1 4
	Coupling piece KSZ	For cylinders with a non-rotating piston rod to compensate for radial deviations	Volume 1
20	Rod clevis	Permits a swivelling movement of the cylinder in one plane	Valuma 1
20	SG/CRSG	remits a swiveting movement of the cylinder in one plane	Volume 1
21	Self-aligning rod coupler	For compensating radial and angular deviations	Volume 1
21	FK	To compensating fadial and angular deviations	votume 1
22	Adapter	For a vacuum suction cup	Volume 1
	AD	'	
23	Guide unit	For protecting standard cylinders from torsion at high torque loads	5 / 1.1-116
	FENG		
24	Mounting kit	For mounting proximity sensors SME/SMT-8 in combination with guide unit FENG	Volume 1
	SMB-8-FENG		
25	Slot cover	To protect the sensor cable and keep dirt out of the sensor slots	Volume 1
	ABP-5-S		
26	Proximity sensor	Can be integrated in the cylinder profile barrel	Volume 1
	SME/SMT-8		14.1
27	Push-in fitting	For connecting compressed air tubing with standard external diameters	Volume 3
20	QS Measuring transducer	Converte concer signals of the standard culinder DNCI into an evaltage signal of 0. 40 V and 4.	F / 1 1 1 1 0
28	Measuring transducer DADE-MVC	Converts sensor signals of the standard cylinder DNCI into one voltage signal of 0 10 V and/or current signal of 0 20 mA	5 / 1.1-118
	DADE-IMINC	current signat of 0 20 IIIA	

Not with variants S2
 Guide unit FENG-KF must be attached to the piston rod such that backlash is eliminated

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Technical data

Function





32 ... 63 mm





General technical data								
Piston ∅		32	40	50	63			
Constructional design		Piston						
		Piston rod						
		Profile barrel						
Mode of operation		Double-acting						
Cushioning		Flexible cushio	ning rings/pads at botl	h ends				
Position sensing		Integrated disp	Integrated displacement encoder					
		For proximity sensor ¹⁾						
Measuring principle (displacement enco	der)	Digital						
Type of mounting		Foot mounting						
Stroke	[mm]	10 2,000	10 2,000					
Torsion protection/Guide ³⁾		Guide rod with	yoke, with ball bearing	g guide				
Stroke	[mm]	100 500						
Piston rod extension	[mm]	1 500						
Pneumatic connection		G1/8	G1/4	G1/4	G3/8			
Electrical connection		Cable with 8-pi	Cable with 8-pin plug, round type M12					
Cable length	[m]	1.5						

- Not included in the scope of delivery, can be ordered as an option
 Guide unit FENG-KF must be ordered as an option and will be supplied attached, the max. stroke is reduced

Forces [N] and impact energy [Nm]									
Piston ∅	32	40	50	63					
Theoretical force at 6 bar	483	754	1,178	1,870					
advancing									
Theoretical force at 6 bar	415	633	990	1,682					
retracting									
Impact energy at end positions	0.1	0.2	0.2	0.5					

Permissible impact velocity:

Maximum permissible load:

Note

This data represents the maximum values that can be achieved. Values fluctuate in practice relative to the size of the effective load. Allowance

must also be made for the limits of the cushioning capacity of the drive and the permissible impact energy.

Standard cylinders DNCI, with measuring transducer DADETechnical data

Operating and environmental conditions							
Operating pressure	[bar]	0.6 12					
Operating medium ²⁾		Compressed air, filtered and unlubricated, filter unit 5 µm					
Ambient temperature ³⁾	[°C]	-20 +80					
Vibration resistance		To DIN/IEC 68 Parts 2 – 6, severity level 2					
Continuous shock resistance		To DIN/IEC 68 Parts 2 – 82, severity level 2					
CE symbol (declaration of conformance)		In accordance with EU EMC Directive					
Protection class (displacement encoder)		IP65 to IEC 60 529					
Corrosion resistance class CRC ⁴⁾		1					

- $2) \quad \text{The proportional directional control valve MPYE used requires the characteristic values} \\$

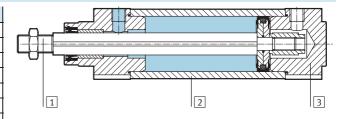
Note operating range of proximity sensors
 Corrosion resistance class 1 according to Festo standard 940 070
 Components requiring low corrosion resistance. Transport and storage protection. Parts that do not have primarily decorative surface requirements, e.g. in internal areas that are not visible or behind covers.

Piston Ø	32	40	50	63
	32	40	30	0,7
Basic drive DNCI				
Product weight with 0 mm stroke	521	853	1,319	1,914
Additional weight per 10 mm stroke	30	44	62	71
Moving load with 0 mm stroke	95	175	316	383
Additional weight per 10 mm stroke	8	14	23	23
Drive with through piston rod DNCIS2				
Product weight with 0 mm stroke	586	981	1,553	2,165
Additional weight per 10 mm stroke	39	60	87	96
Moving load with 0 mm stroke	155	164	297	364
Additional weight per 10 mm stroke	17	30	48	48
Additional weight with extended piston rod K8				
Additional weight per 10 mm stroke	8	14	23	23
		<u>'</u>	'	I.
Additional weight with clamping cartridge KP				
Product weight	234	394	700	1,147
Additional weight with guide unit FENG				
Product weight with 0 mm stroke	1,530	2,370	4,030	5,410
				62
Additional weight per 10 mm stroke	18	32	50	62

Materials

Sectional view

Stan	Standard cylinders								
1	Piston rod	High-alloy steel							
2	Cylinder barrel	Anodised aluminium							
3	Bearing/end caps	Die-cast aluminium							
-	Dynamic seals	Polyurethane TPE-U							
-	Static seals	Nitrile rubber							
-	Lubricant	Klüberplex BE31-102							
Disp	lacement encoder								
-	Sensor housing	Polyacetate							
-	Cable sheath	Polyurethane							
-	Plug housing	Polybuteneterephthalate							
-	Wall mounting plate	Polyacetate							
-	Screws for mounting plate	Steel							



Standard cylinders DNCI, with measuring transducer DADE Technical data



Electrical data, displacement encoder		
Measuring accuracy	[mm]	±(0.07±0.02/m)
Resolution	[mm]	0.02
Max. speed of travel	[m/s]	1.5
Ambient temperature	[°C]	-20 +80
Max. temperature coefficient	[ppm/°K]	30
Protection class		IP65
CE symbol (declaration of conformance)		In accordance with EU EMC Directive
Max. permitted magnetic disruption field at	[kA/m]	10
100 mm interval from the sensor ¹⁾		
Output signal		Analogue
Electrical connection		Cable with 8-pin plug, round type M12
Cable length	[m]	1.5

¹⁾ See also mounting conditions

Standard cylinders DNCI, with measuring transducer DADE

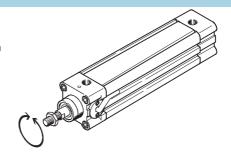
Technical data

Torques and lateral forces

The piston rod must not absorb any torque. We therefore recommend that an external guide FENG-KF be used with the drive DNCI. The guide unit is delivered installed.

The permissible static and dynamic characteristic load values with and without attached guide as well as with regard to the technical data of the variants (S2, S8, S9)

→ Volume 1 (standard cylinder DNC)



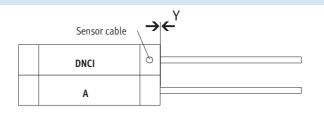
Mounting conditions

When mounting a drive A with magnet (for position sensing), in addition to a standard cylinder DNCI, the following conditions must be observed:

- X Minimum distance between the drives
- Y Offset between the drives on the bearing cap

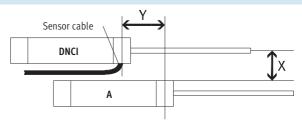
Parallel assembly

If the offset Y = 0 mm, the drives can be assembled directly next to one another.



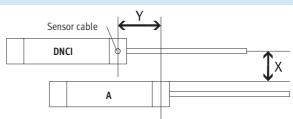
Offset assembly, cable outlet between the drives

If the offset Y > 0 mm and the cable outlet is between the drives, the distance from X > 70 mm must be observed.



Offset assembly, cable outlet upwards or downwards

If the offset Y > 0 mm and the cable outlet is up or down, the distance from X > 60 mm must be observed.



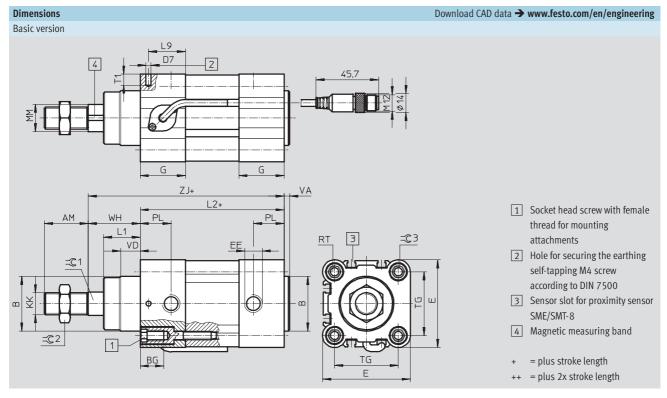
Pin assignment of plug, view of plug

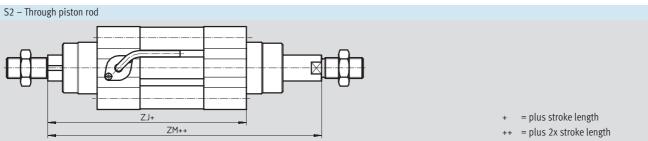
Pin	Function	Colour
1	5 V	black
2	GND	brown
3	sin+	red
4	sin-	orange
5	cos-	green
6	COS+	yellow
7	Screening	Screening
8	-	-

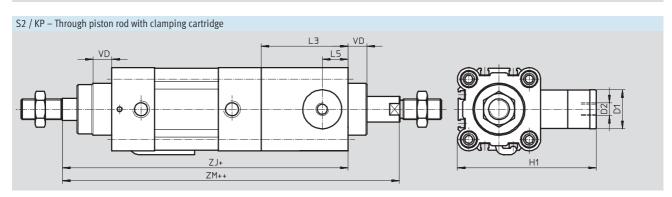


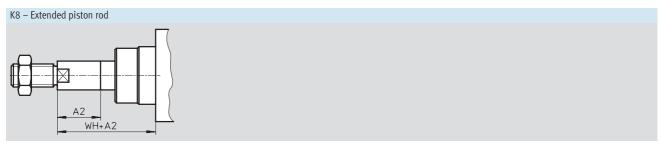
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Technical data





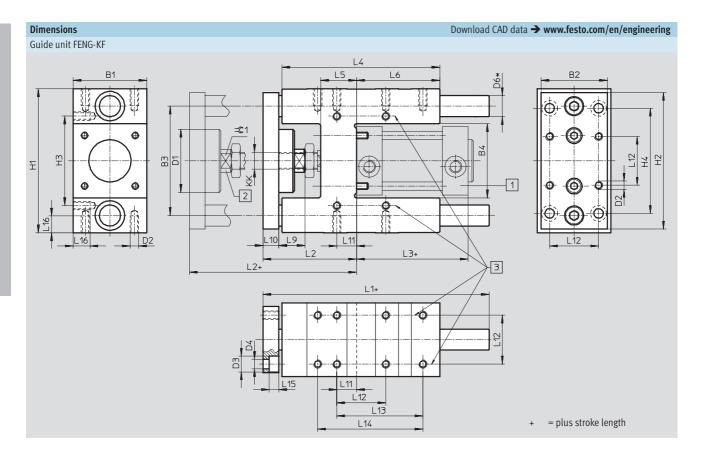




Standard cylinders DNCI, with measuring transducer DADE Technical data

Ø [mm]	AM	A2 max.	B ∅ d11	BG	D1 ∅ f9	D2	D7 ∅	E	EE	G	H1
32	22	500	30	16	20	M5	3.7	45	G1/8	28	67
40	24	500	35	16	24	G1/8	3.7	54	G1/4	33	88
50	32	500	40	17	30	G1/8	3.7	64	G1/4	33	107
63	32	500	45	17	38	G1/8	3.7	75	G3/8	40.5	123
Ø	KK	L1	L2	L3	L5	L9	MM Ø	PL	RT	T1	TG
[mm]							f8				
32	M10x1.25	18	94	45	14	22.5	12	15.6	M6	8	32.5
40	M12x1.25	21.3	105	53	16	27	16	14	M6	8	38
50	M16x1.5	26.8	106	67	20	27	20	14	M8	8	46.5
63	M16x1.5	27	121	76	24	33	20	17	M8	8	56.5
Ø	PI	VD	WH	Z,	J	ZI	M	=©1	=©2	=3	3
[mm]					KP		KP				
32	4	10	26	120	165	148	193	10	16	6	
40	4	10.8	30	135	188	167	220	13	18	6	,
50	4	14.3	37	143	210	183	250	17	24	8	}
63	4	14.5	37	158	234	199	275	17	24	8	}

Standard cylinders DNCI, with measuring transducer DADE Technical data



Standard cylinders DNCI, with measuring transducer DADE Technical data

For Ø	B1	B2	В3	B4	D1	D2	D3	D4	D6	H1
					Ø		Ø	Ø	Ø	
[mm]	-0.3		±0.2	±0.3					h6	
32	50	45	74	50.5	44	M6	11	6.6	12	97 _{-0.4}
40	58	54	87	58.5	44	M6	11	6.6	16	115-0.4
50	70	63	104	70.5	60	M8	15	9	20	137 _{-0.5}
63	85	80	119	85.5	60	M8	15	9	20	152 _{-0.5}

For Ø	H2	Н3	H4	KK	L1	L2	L3	L4	L5	L6
[mm]		±0.2	±0.2							
32	90	61	78	M10x1.25	155	67+5	94	125	24	76
40	110	69	84	M12x1.25	170	75 ₊₅	105	140	28	81
50	130	85	100	M16x1	188	89+10	106	150	34	79
63	145	100	105	M16x1	220	89+10	121	182	34	111

For Ø	L9	L10	L11	L12	L13	L14	L15	L16	=©1
[mm]				±0.2	±0.2	±0.2			
32	20	12	4.3	32.5	70.3	78	6.5	12	15
40	22	12	11	38	84	-	6.5	14	15
50	25	15	18.8	46.5	81.8	100	9	16	19

Standard cylinders DNCI, with measuring transducer DADE Ordering data – Modular products



M Mandate	ory data							→
Module No.	Function	Piston	Ø	Stroke		ing	Position sen	sing
535 411	DNCI	32		10 2,000	Р		A	
535 412		40						
535 413		50						
535 414		63						
Order								
example								
535 411	DNCI	- 32		- 100	- P	_	A	-
Ordering table								
Piston Ø		32	40	50	63	Condi-	Code	Enter
1131011 2		32	10	30		tions	Couc	code
M Module No.		535 411	535 412	535 413	535 414			
Function		Standard cylinder v	vith integrated dis	placement encoder, non	-rotating piston r	od	DNCI	DNCI
Piston Ø	[mm]	32	40		63			
Stroke	[mm]	10 2,000						
Cushioning		Flexible cushioning	rings/pads at bot	h ends			-P	-P
◆ Position se	nsing	Via proximity senso	or				-A	-A

Iransfer order code							
DNCI	 -	-[-	P	-	Α	-

Standard cylinders DNCI, with measuring transducer DADE Ordering data – Modular products

O Options									
Type of piston rod	Piston rod extended at front	C	lamping unit		Guide		Measuri	ing head	
S2	K8	KI	P .] -	FENG		MS		
dering table									
ston Ø	32	40	50		63	Cond		ode	Enter code
Type of piston rod	Through piston rod						-S	2	
Piston rod extended [mn	1] 1 500					2		.K8	
Clamping unit	Clamping cartridge	lamping cartridge						P	
Guide	Guide unit with ball b	earing guid	de on the sensor head side			4	-FE	ENG	
Measuring head	No measuring head						-M	IS	

2 K8	In combination with piston rod type S2, the piston rod is only extended at the front	3	К9	Only with piston rod type S2
	(the side facing the measuring head)	4	FENG	Maximum stroke length 500 mm

	Transfer order code						
-[-	-	-	-	-	

Standard cylinder DNCI, with transducer DADE

Technical data

DADE-MVC-010

DADE-MVC-420

Measuring transducer The transducer converts sensor

> current signal of 0 ... 20 mA. These signals can be evaluated by a PLC with an appropriate signal input.

signals of the DNCI standard cylinder into a voltage signal of 0 ... 10 V or a

General technical data							
Type of mounting		ia through holes					
Mounting position		Any					
Repetition accuracy in relation to	≤ 400	±0.1 mm					
effective stroke	≤ 750	±0.2 mm					
	≤ 1 , 200	±0.3 mm					
	≤ 1,600	±0.4 mm					
	≤ 2 , 000	±0.5 mm					
Protection against short circuit		Yes					
Protection against polarity reversal		Yes					
Diagnostic function		Display via LED					

General electrical data		
Analogue output	[V]	0 10 (as per EN 61131-2)
	[mA]	0 20 (as per EN 61131-2)
Nominal operating voltage	[V DC]	24 ±25%
Residual ripple	[%]	4 (at 50 Hz)
Current consumption at nominal	[mA]	20 30
operating voltage		
Switching logic at outputs		PNP
Switching logic at inputs		PNP
Debounce time at inputs	[ms]	3
Linearity error FS		0,2%

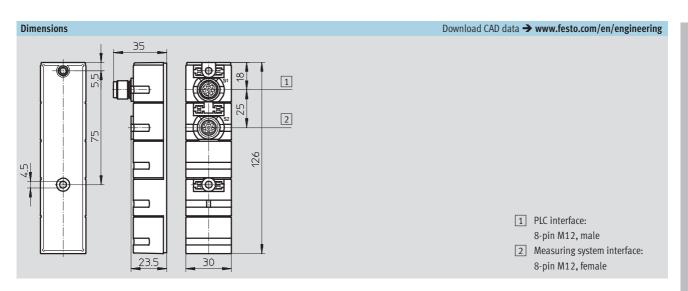
Operating and environmental conditions					
Ambient temperature	[°C]	0 55			
Protection class		IP65			
Relative air humidity		95% non-condensing			
CE symbol (see conformity declaration)		As per EU EMC directive			
Corrosion resistance class CRC ¹⁾		1			
Product weight	[g]	128			
Note on material for housing		Polybutylene terephthalate			

¹⁾ Corrosion resistance class 1 as per Festo standard 940 070 Components requiring low corrosion resistance Transport and storage protection. Parts that do not have primarily decorative surface requirements, e.g. in internal areas that are not visible or behind covers

Standard cylinder DNCI, with transducer DADE

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Technical data



Pin allocation

PLC interface



outputs

4	2
	F+X 8
3 	++/
6	

Pin	Function	Cable colour
1	24 V	white
2	Measured signal (analogue)	brown
3	Reference output	green
4	0 V measured signal	yellow
5	Reference input	grey
6	Calibration input	pink
7	Ready output	blue
8	0 V power supply and inputs/	red

7
6 1
\0°0 \0\
5 10 0 6 8

Measuring system interface

Pin	Function
1	Ub
2	0 V
3	Signal sine +
4	Signal sine -
5	Signal cosine -
6	Signal cosine +
7	Screening / earth
8	-

Ordering data						
		Description	Part No.	Туре		
Measuring transducer						
	With voltage signal	0 10 V	542 117	DADE-MVC-010		
	With current signal	0 20 mA	542 118	DADE-MVC-420		
Accessories						
Accessories	Plug socket with cable	Connecting cable to PLC (length 2 m)	525 616	SIM-M12-8GD-2-PU		
	riug sockei with cable	Connecting capie to PLC (tength 2 m)	525 616	31W-W12-0UD-2-PU		
		Connecting cable to PLC (length 5 m)	525 618	SIM-M12-8GD-5-PU		