

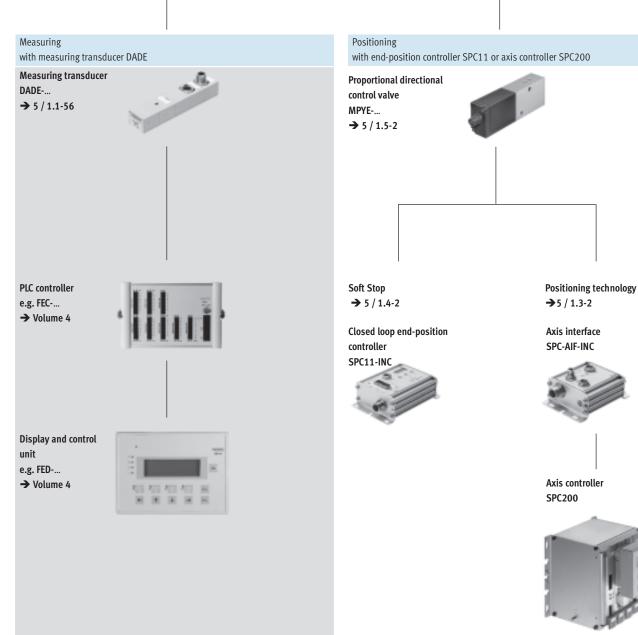
**FESTO** 

### Standard cylinders DNCI, with measuring transducer DADE

Key features

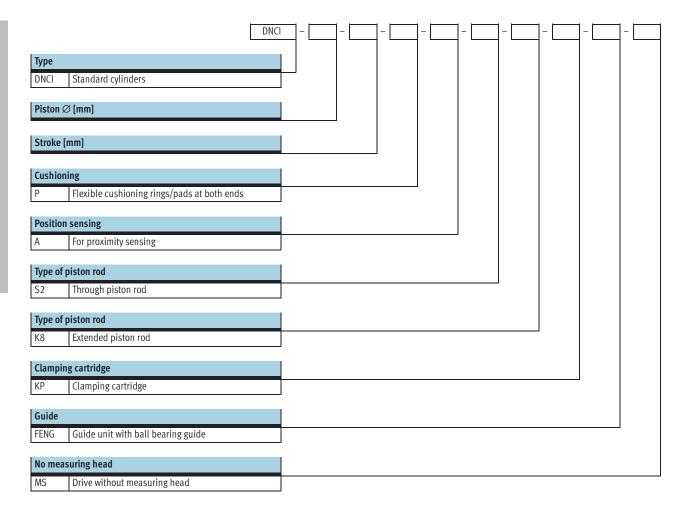




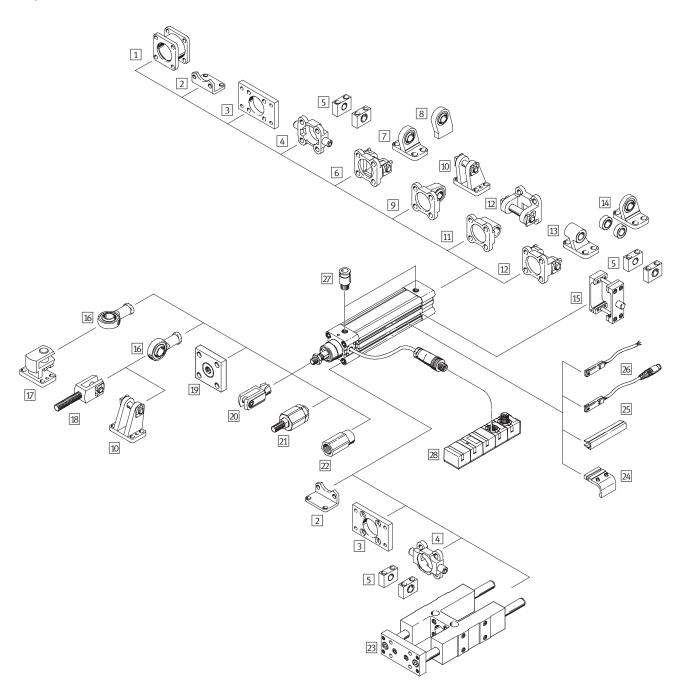


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Type code



## Standard cylinders DNCI, with measuring transducer DADE Peripherals overview



Acce	ccessories								
	Туре	Brief description	→ Page						
1	Adapter kit <sup>1)</sup> DPNC	For connecting two cylinders with identical piston $\varnothing$ to form a multi-position cylinder	Volume 1						
2	Foot mounting HNC	For mounting the drive on the bearing and end cap	Volume 1						
3	Flange mounting FNC	For mounting the drive on the bearing and end cap	Volume 1						
4	Trunnion mounting ZNCF/CRZNG	For swivelling movements of the drive on the bearing or end caps	Volume 1						
5	Trunnion support LNZG/CRLNZG	-	Volume 1						

## Standard cylinders DNCI, with measuring transducer DADE Peripherals overview

Acce	ssories		
	Туре	Brief description	→ Page
6	Swivel flange <sup>1)</sup>	For swivelling movements of the drive on the end cap	Volume 1
O	SNC	Tot swiveting movements of the drive on the end cap	volume 1
7	Clevis foot mounting <sup>1)</sup> LSNG	With spherical bearing	Volume 1
8	Clevis foot mounting <sup>1)</sup>	Weld-on, with spherical bearing	Volume 1
	LSNSG		
9	Swivel flange <sup>1)</sup> SNCS	For swivelling movements of the drive on the end cap, with spherical bearing	Volume 1
10	Clevis foot mounting <sup>1)</sup> LBG	-	Volume 1
11	Swivel flange <sup>1)</sup>	For swivelling movements of the drive on the end cap	Volume 1
40	SNCL	For any allian and an early of the dains on the said and	V-1 4
12	Swivel flange <sup>1)</sup> SNCB	For swivelling movements of the drive on the end cap	Volume 1
13	Clevis foot mounting <sup>1)</sup> LNG/CRLNG	-	Volume 1
14	Clevis foot mounting <sup>1)</sup>	With spherical bearing	Volume 1
	LSN		
15	Trunnion mounting kit ZNCM	For swivelling movements of the drive	Volume 1
16	Rod eye	With spherical bearing	Volume 1
	SGS/CRSGS		1
17	Right-angle clevis foot	-	Volume 1
	LQG		
18	Rod clevis SGA	With male thread	Volume 1
19	Coupling piece KSG	For compensating radial deviations	Volume 1
	Coupling piece KSZ	For cylinders with a non-rotating piston rod to compensate for radial deviations	Volume 1
20	Rod clevis	Permits a swivelling movement of the cylinder in one plane	Volume 1
20	SG/CRSG	remits a switching movement of the cylinder in one plane	volume 1
21	Self-aligning rod coupler	For compensating radial and angular deviations	Volume 1
	FK		
22	Adapter AD	For a vacuum suction cup	Volume 1
23	Guide unit	For protecting standard cylinders from torsion at high torque loads	5 / 1.1-54
[a:	FENG	Franchiscon della constituta della const	\/-\
24	Mounting kit SMB-8-FENG	For mounting proximity sensors SME/SMT-8 in combination with guide unit FENG	Volume 1
25	Slot cover ABP-5-S	To protect the sensor cable and keep dirt out of the sensor slots	Volume 1
26	Proximity sensor	Can be integrated in the cylinder profile barrel	Volume 1
27	SME/SMT-8 Push-in fitting	For connecting compressed air tubing with standard external diameters	Volume 3
	QS		
28	Measuring transducer	Converts sensor signals of the standard cylinder DNCI into one voltage signal of 0 10 V and/or	5 / 1.1-56
	DADE-MVC	current signal of 0 20 mA	

<sup>2)</sup> Guide unit FENG-KF must be attached to the piston rod such that backlash is eliminated

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Technical data

Function







32 ... 63 mm



Stroke length 10 ... 2,000 mm



General technical data								
Piston $\varnothing$		32	40	50	63			
Constructional design		Piston						
		Piston rod						
		Profile barrel						
Mode of operation		Double-acting						
Cushioning		Flexible cushion	ing rings/pads at both	ends				
Position sensing		Integrated displ	acement encoder					
		For proximity se	For proximity sensing <sup>1)</sup>					
Measuring principle (displacement encode	der)	Digital						
Type of mounting		Foot mounting						
Stroke	[mm]	10 2,000	10 2,000					
Torsion protection/Guide <sup>3)</sup>		Guide rod with y	Guide rod with yoke, with ball bearing guide					
Stroke	[mm]	100 500						
Piston rod extension	[mm]	1 500						
Pneumatic connection	G1/8	G1/4	G1/4	G3/8				
Electrical connection		Cable with 8-pir	Cable with 8-pin plug, round type M12					
Cable length	[m]	1.5						

- Not included in the scope of delivery, can be ordered as an option
   Guide unit FENG-KF must be ordered as an option and will be supplied attached, the max. stroke is reduced

Forces [N] and impact energy [Nm]										
Piston Ø	32	40	50	63						
Theoretical force at 6 bar	483	754	1,178	1,870						
advancing										
Theoretical force at 6 bar	415	633	990	1,682						
retracting										
Impact energy at end positions	0.1	0.2	0.2	0.5						

Permissible impact velocity:

$$v_{perm.} = \sqrt{\frac{2 \times E_{perm.}}{m_{dead} + m_{load}}}$$

Permissible impact velocity  $v_{\text{perm.}} \\$ Max. impact energy E<sub>perm</sub>. Moving load (drive)  $\mathsf{m}_{\mathsf{dead}}$  $\mathsf{m}_{load}$ Moving work load

- Note

Maximum permissible load:

$$m_{load} \ = \frac{2 \ x \ E_{perm.}}{v^2} \ - \ m_{dead}$$

These specifications represent the maximum values which can be reached. Note the maximum permitted impact energy.

### **Standard cylinders DNCI, with measuring transducer DADE**Technical data

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Operating and environmental conditions							
Operating pressure	[bar]	0.6 12					
Operating medium <sup>2)</sup>		Compressed air, filtered and unlubricated, filter unit 5 µm					
Ambient temperature <sup>3)</sup>	[°C]	-20 +80					
Vibration resistance		To DIN/IEC 68 Parts 2 – 6, severity level 2					
Continuous shock resistance		To DIN/IEC 68 Parts 2 – 82, severity level 2					
CE symbol (declaration of conformance)		In accordance with EU EMC Directive					
Protection class (displacement encoder)		IP65 to IEC 60 529					
Corrosion resistance class CRC <sup>4)</sup>		1					

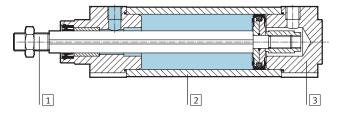
The proportional directional control valve MPYE used requires the characteristic values
 Note operating range of proximity sensors
 Corrosion resistance class 1 according to Festo standard 940 070
 Components requiring low corrosion resistance. Transport and storage protection. Parts that do not have primarily decorative surface requirements, e.g. in internal areas that are not visible or behind covers.

Piston Ø	with displacement encoder	32	40	50	63
		32	40	30	0)
Basic drive D					
	Product weight with 0 mm stroke	521	853	1,319	1,914
	Additional weight per 10 mm stroke	30	44	62	71
	Moving load with 0 mm stroke	95	175	316	383
	Additional weight per 10 mm stroke	8	14	23	23
Drive with th	rough piston rod DNCIS2				
	Product weight with 0 mm stroke	586	981	1,553	2,165
	Additional weight per 10 mm stroke	39	60	87	96
	Moving load with 0 mm stroke	155	164	297	364
	Additional weight per 10 mm stroke	17	30	48	48
Additional w	eight with extended piston rod K8				
	Additional weight per 10 mm stroke	8	14	23	23
		•	•	•	
Additional w	eight with clamping cartridge KP				
	Product weight	234	394	700	1,147
Additional w	eight with guide unit FENG				
riaditional W	Product weight with 0 mm stroke	1,530	2,370	4,030	5,410
	r roudet weight with o min Stroke	1,550	32	4,000	3,410

#### Materials

Sectional view

Stan	dard cylinders					
1	Piston rod	High-alloy steel				
2	Cylinder barrel	Anodised aluminium				
3	Bearing/end caps	Die-cast aluminium				
-	Dynamic seals	Polyurethane TPE-U				
-	Static seals	Nitrile rubber				
-	Lubricant	Klüberplex BE31-102				
Disp	lacement encoder					
-	Sensor housing	Polyacetate				
-	Cable sheath	Polyurethane				
-	Plug housing	Polybuteneterephthalate				
-	Wall mounting plate	Polyacetate				
-	Screws for mounting plate	Steel				



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# Standard cylinders DNCI, with measuring transducer DADE Technical data

Electrical data, displacement encoder		
Linearity error <sup>1)</sup>	[mm]	±(0.07±0.02xL)
Max. speed of travel	[m/s]	1.5
Ambient temperature	[°C]	-20 +80
Max. temperature coefficient	[ppm/°K]	30
Protection class		IP65
CE symbol (declaration of conformance)		In accordance with EU EMC Directive
Max. permitted magnetic disruption field at	[kA/m]	10
100 mm interval from the sensor <sup>2)</sup>		
Electrical connection		Cable with 8-pin plug, round type M12
Cable length	[m]	1.5

Maximum deviation of the output signal from "best fit" line (characteristic curve with nominal gradient).
 L = Length of measuring system in meters
 See also mounting conditions

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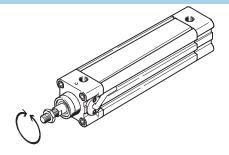
Technical data

#### Torques and lateral forces

The piston rod must not absorb any torque. We therefore recommend that an external guide FENG-KF be used with the drive DNCI. The guide unit is delivered installed.

The permissible static and dynamic characteristic load values with and without attached guide as well as with regard to the technical data of the variants (S2, S8, S9)

→ Volume 1 (standard cylinder DNC)



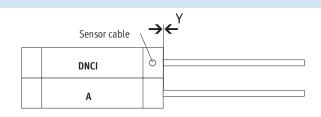
#### **Mounting conditions**

When mounting a drive A with magnet (for position sensing), in addition to a standard cylinder DNCI, the following conditions must be observed:

- X Minimum distance between the drives
- Y Offset between the drives on the bearing cap

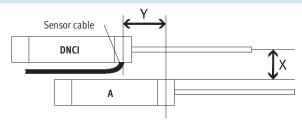
#### Parallel assembly

If the offset Y = 0 mm, the drives can be assembled directly next to one another.



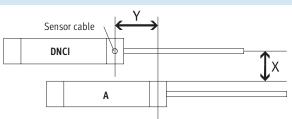
#### Offset assembly, cable outlet between the drives

If the offset Y > 0 mm and the cable outlet is between the drives, the distance from X > 70 mm must be observed.



#### Offset assembly, cable outlet upwards or downwards

If the offset Y > 0 mm and the cable outlet is up or down, the distance from X > 60 mm must be observed.



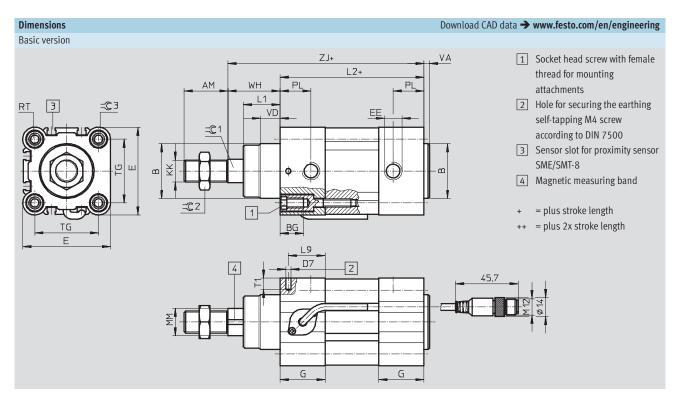
#### Pin assignment of plug, view of plug

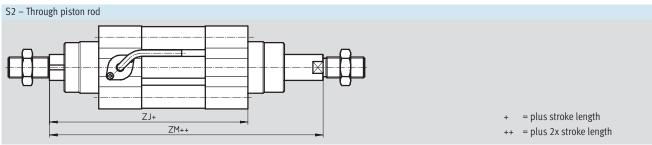
Pin	Function	Colour
1	5 V	black
2	GND	brown
3	sin+	red
4	sin-	orange
5	cos-	green
6	COS+	yellow
7	Screening	Screening
8	-	-

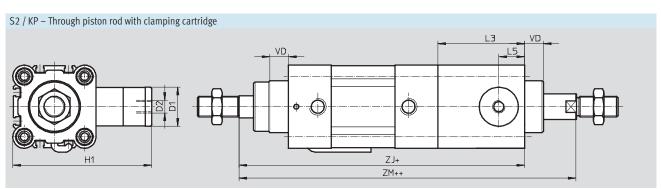


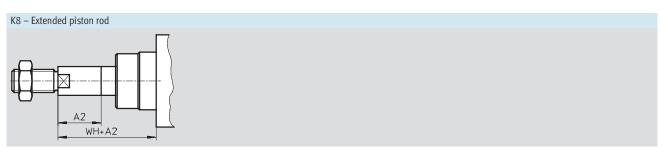
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Technical data





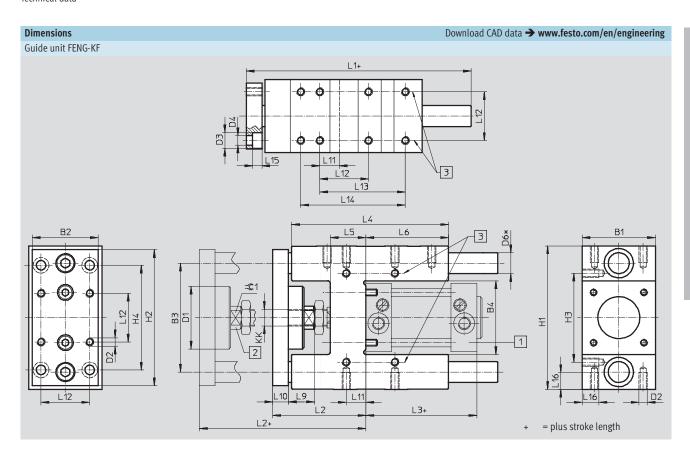




# Standard cylinders DNCI, with measuring transducer DADE Technical data

Ø [mm]	AM	A2 max.	B ∅ d11	BG	D1 Ø f9	D2	D7 ∅	E	EE	G	H1
32	22	500	30	16	20	M5	3.7	45	G1/8	28	67
40	24	500	35	16	24	G1/8	3.7	54	G1/4	33	88
50	32	500	40	17	30	G1/8	3.7	64	G1/4	33	107
63	32	500	45	17	38	G1/8	3.7	75	G3/8	40.5	123
										_	
Ø	KK	L1	L2	L3	L5	L9	MM ~	PL	RT	T1	TG
							Ø				
[mm]							f8				
32	M10x1.25	18	94	45	14	22.5	12	15.6	M6	8	32.5
40	M12x1.25	21.3	105	53	16	27	16	14	M6	8	38
50	M16x1.5	26.8	106	67	20	27	20	14	M8	8	46.5
63	M16x1.5	27	121	76	24	33	20	17	M8	8	56.5
Ø	PI	VD	WH	Z	J	ZI	M	<b>=</b> ©1	<b>=</b> ©2	=3	3
[mm]					KP		KP				
32	4	10	26	120	165	148	193	10	16	$\epsilon$	ó
40	4	10.8	30	135	188	167	220	13	18	$\epsilon$	5
50	4	14.3	37	143	210	183	250	17	24	8	3
63	4	14.5	37	158	234	199	275	17	24	8	3

### **Standard cylinders DNCI, with measuring transducer DADE**Technical data



# Standard cylinders DNCI, with measuring transducer DADE Technical data

For $\varnothing$	B1	B2	В3	B4	D1	D2	D3	D4	D6	H1
					Ø		Ø	Ø	Ø	
[mm]	-0.3		±0.2	±0.3					h6	
32	50	45	74	50.5	44	M6	11	6.6	12	97 <sub>-0.4</sub>
40	58	54	87	58.5	44	M6	11	6.6	16	115-0.4
50	70	63	104	70.5	60	M8	15	9	20	137 <sub>-0.5</sub>
63	85	80	119	85.5	60	M8	15	9	20	152-0.5

For Ø	H2	Н3	H4	KK	L1	L2	L3	L4	L5	L6
[mm]		±0.2	±0.2							
32	90	61	78	M10x1.25	155	67+5	94	125	24	76
40	110	69	84	M12x1.25	170	75+5	105	140	28	81
50	130	85	100	M16x1	188	89+10	106	150	34	79
63	145	100	105	M16x1	220	89+10	121	182	34	111

For Ø	L9	L10	L11	L12	L13	L14	L15	L16	<b>=</b> ©1
[mm]				±0.2	±0.2	±0.2			
32	20	12	4.3	32.5	70.3	78	6.5	12	15
40	22	12	11	38	84	-	6.5	14	15
	2.5	4.5	40.0	165	04.0	400	0	4.6	10
50	25	15	18.8	46.5	81.8	100	9	16	19

# Standard cylinders DNCI, with measuring transducer DADE Ordering data – Modular products

Module No.	Function	Pistor	ıØ	Stroke	Cushioning		Position sen	sing
535 411	DNCI	32		10 2,000	P		A	
535 412		40						
535 413		50						
535 414		63						
Order								
example								
535 411	DNCI	- 32		- 100	- P	-	Α	
rdering table								
iston Ø		32	40	50	63	Condi- tions	Code	Ente code
Module No.		535 411	535 412	535 413	535 414			
Function		Standard cylinder	with integrated di	splacement encoder, non	-rotating piston rod		DNCI	DNC
Piston Ø	[mm]	32	40	50	63			
Stroke	[mm]	10 2,000						
Cushioning		Flexible cushioning	ng rings/pads at bo	oth ends			-P	-P
Position sensing For proximity sensing							-A	-A



## Standard cylinders DNCI, with measuring transducer DADE Ordering data – Modular products

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-MS

Measuring head

O Options												
Type of piston rod		Piston rod extended at front		Clamping uni	t		Guide		Measi	uring hea	d	
52		K8	<b>-</b>	КР		1-	FENG		MS			
davina tabla			<u></u>									
dering table ston ∅		32	40		50		63	Contion		Code		Enter code
Type of piston rod		Through piston rod								-S2		
Piston rod extended	[mm]	1 500						2		K8		
Clamping unit		Clamping cartridge						3		-KP		
Guide	Guide unit with ball bearing guide on the sensor head side									FENG		

2 <b>K8</b>	In combination with piston rod type S2, the piston rod is only extended at the front	3 <b>K9</b>	Only with piston rod type S2
	(the side facing the measuring head)	/ FENG	Maximum stroke length 500 mm

No measuring head

	Transfer order code						
-		-	-	-	-	-	

### Standard cylinder DNCI, with transducer DADE

Technical data

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Measuring transducer DADE-MVC-010 DADE-MVC-420

The transducer converts sensor signals of the DNCI standard cylinder into a voltage signal of 0 ... 10 V or a current signal of 0 ... 20 mA. These signals can be evaluated by a PLC with an appropriate signal input.



General technical data						
Type of mounting		Via through holes				
Mounting position		Any				
Repetition accuracy in relation to	≤ 400	±0.1 mm				
effective stroke	≤ 750	±0.2 mm				
	≤ 1,200	±0.3 mm				
	≤ 1,600	±0.4 mm				
	≤ 2,000	±0.5 mm				
Protection against short circuit		Yes				
Protection against polarity reversal		Yes				
Diagnostic function		Display via LED				

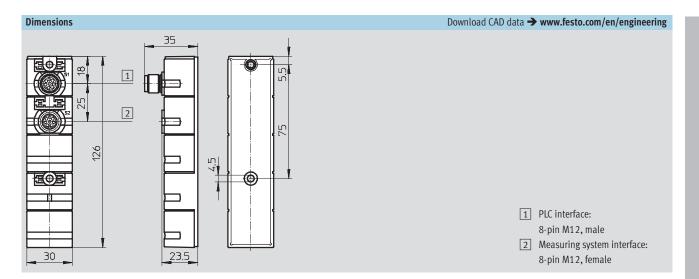
General electrical data		
Analogue output	[V]	0 10 (as per EN 61131-2)
	[mA]	0 20 (as per EN 61131-2)
Nominal operating voltage	[V DC]	24 ±25%
Residual ripple [%]		4 (at 50 Hz)
Current consumption at nominal	[mA]	20 30
operating voltage		
Switching logic at outputs		PNP
Switching logic at inputs		PNP
Debounce time at inputs	[ms]	3
Linearity error FS		0,2%

Operating and environmental conditions						
Ambient temperature [ºd	C]	0 55				
Protection class		IP65				
Relative air humidity		95% non-condensing				
CE symbol (see conformity declaration)		As per EU EMC directive				
Corrosion resistance class CRC <sup>1)</sup>		1				
Product weight [g	g]	128				
Note on material for housing		Polybutylene terephthalate				

<sup>1)</sup> Corrosion resistance class 1 as per Festo standard 940 070 Components requiring low corrosion resistance Transport and storage protection. Parts that do not have primarily decorative surface requirements, e.g. in internal areas that are not visible or behind covers

### **Standard cylinder DNCI, with transducer DADE** Technical data





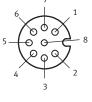
#### Pin allocation

PLC interface



	7
6,	_ 1
$\sim$	5 X

Measuring system interface



Pin	Function	Cable colour
1	24 V	white
2	Measured signal (analogue)	brown
3	Reference output	green
4	0 V measured signal	yellow
5	Reference input	grey
6	Calibration input	pink
7	Ready output	blue
8	0 V power supply and inputs/ outputs	red

Pin	Function
1	Ub
2	0 V
3	Signal sine +
4	Signal sine -
5	Signal cosine -
6	Signal cosine +
7	Screening / earth
8	-

Ordering data				
		Description	Part No.	Туре
Measuring transducer				
	With voltage signal	0 10 V	542 117	DADE-MVC-010
	With current signal	0 20 mA	542 118	DADE-MVC-420
Accessories			Technical c	lata → www.festo.com/catalogue/sim
	Cable with socket	Connecting cable to PLC (length 2 m)	525 616	SIM-M12-8GD-2-PU
		Connecting cable to PLC (length 5 m)	525 618	SIM-M12-8GD-5-PU