



# Product range overview

Function	Туре	Description						
Drives	Rodless							
	DDLI	Without guide     With displacement encoder for contactless measurement     Based on linear drive DGC-K     Supply ports on end face     System product for handling and assembly technology						
	DGCI	With guide     With displacement encoder for contactless measurement     Based on linear drive DGC     Supply ports optionally on end face or front     System product for handling and assembly technology						
	With piston rod							
	DNCI	<ul> <li>With displacement encoder for contactless measurement</li> <li>Various piston rod variants</li> <li>Standards-based cylinder to ISO 15552</li> </ul>						
	DDPC	With displacement encoder for contactless measurement     Various piston rod variants     Standards-based cylinder to ISO 15552						
	DNC/DSBC	With attached potentiometer MLO-LWG     Various piston rod variants     Standards-based cylinder to ISO 15552						
Swivel modu	le Swivel module							
		<ul> <li>Based on swivel module DSM</li> <li>Integrated rotary potentiometer</li> <li>Compact design</li> <li>Wide range of mounting options</li> </ul>						

# Product range overview

Piston	Stroke/swivel angle	Suitable						
diameter		for positioning with	for end-position controlle	r	for use as a measuring			
	[mm/°]	CPX-CMAX	CPX-CMPX	SPC11	cylinder			
Rodless								
25, 32, 40, 63	100, 160, 225, 300, 360, 450, 500, 600, 750, 850, 1000, 1250, 1500, 1750, 2000		•	•	•			
18, 25, 32, 40, 63	100, 160, 225, 300, 360, 450, 500, 600, 750, 850, 1000, 1250, 1500, 1750, 2000	•	•	•	•			
With piston rod								
32, 40, 50, 63	10 2000	-	-	-	•			
	100 750	•		•				
80, 100	10 2000	-	-	-	•			
	100 750	•	•	•				
32, 40, 50, 63, 80	100, 150, 225, 300, 360, 450, 600, 750	•	•	•	•			
Swivel module								
25, 40, 63	270		•		•			

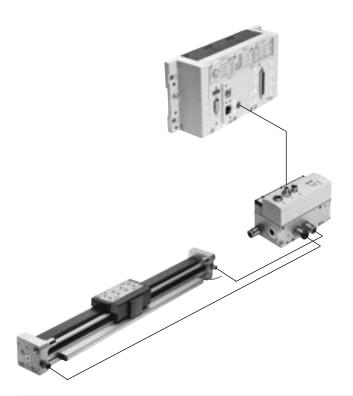
### Key features

### Servo-pneumatic drive technology

Positioning and Soft Stop applications as an integral component of the valve terminal CPX – the modular peripheral system for decentralised automation tasks. The modular design means that valves, digital inputs and outputs, positioning modules and end-position controllers, as appropriate to the application, can be combined in almost any way on the CPX terminal.

### Advantages:

- · Pneumatics and electrics control and positioning on one platform
- Innovative positioning technology piston rod drives, rodless drives, rotary drives
- Actuation via fieldbus
- Remote maintenance, remote diagnostics, web server, SMS and e-mail alerts are all possible via TCP/IP
- Modules can be quickly exchanged and expanded without altering the wiring



### Axis controller CPX-CMAX



### Free choice:

Position and force control, directly actuated or selected from one of 128 configurable position sets. If you are looking for something more: The configurable record sequencing function enables simple functional sequences to be realised in the axis controller CPX-CMAX.

Everything is recognisable: The auto-identification function identifies each participant with its device data on the controller CPX-CMAX.

### Also included:

Actuation of a brake or clamping unit via the proportional directional control valve VPWP is also part of the scope of performance of the controller CPX-CMAX.

Up to 8 modules (max. 8 axes) can be operated in parallel and independently of each other.

Commissioning via FCT (Festo configuration software) or via fieldbus: no programming, only configuration.

### Advantages:

- Greater flexibility
- OEM friendly commissioning also via fieldbus
- Easy installation and fast commissioning
- Cost-effective
- You program the system in your PLC environment

# Key features

### End-position controllers CPX-CMPX



Fast travel between the mechanical end stops of the cylinder, stopping gently and without impact in the end position.

Fast commissioning via control panel, fieldbus or handheld unit.

Improved standstill control.

Actuation of a brake or clamping unit via the proportional directional control valve VPWP is an integral part of the controller CMPX.

The 5/3-way proportional directional

control valve for applications with Soft

pressure sensors, with new diagnostic

Stop and pneumatic positioning.

Fully digitalised - with integrated

Flow rates of 350, 700, 1400 and

functions.

2000 l/min.

In sizes 4, 6, 8 and 10.

Depending on the fieldbus chosen, up to 9 end-position controllers can be actuated on the CPX terminal. All system data can be read and written via the fieldbus, including, for example, the mid-positions. Data sheets  $\rightarrow$  Internet: cpx-cmpx

Advantages:

- Greater flexibility
- OEM friendly commissioning also via fieldbus
- Easy installation and fast commissioning
- Cost-effective
- Up to 30% faster cycle ratesSignificantly reduced system
- vibration
  Improved work ergonomics thanks to significantly reduced noise level
- The extended diagnostics help to reduce the service time of the machine

Data sheets  $\rightarrow$  Internet: vpwp

### Proportional directional control valve VPWP



### Measuring module CPX-CMIX



Fully digital data acquisition and transmission means that pneumatic cylinders can be used as sensors. With very high repetition accuracy and incorporating both analogue and digital measuring sensors.

Suitable for the linear drive DGCI with displacement encoder for measuring absolute values, for the piston rod drive DNCI/DDPC with incremental displacement encoder or alternatively for a potentiometer of the type MLO.

With switching output for controlling a

Colour-coded supply ports.

Pre-assembled cables guarantee

faultless and fast connection with the

controllers CPX-CMPX and CPX-CMAX.

brake.

### Advantages:

- Easy installation and fast commissioning
- Reduction of system downtimes thanks to the new diagnostic options
- With switching output for controlling a brake/clamping unit

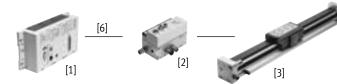
### Data sheets $\rightarrow$ Internet: cpx-cmix

Advantages:

- All process steps can be documented, which improves quality
- An adjustable contact force (via pressure regulator) increases the precision of the "displacement sensor"
- With displacement encoders for measuring absolute values, the actual position is immediately available after the system is switched on

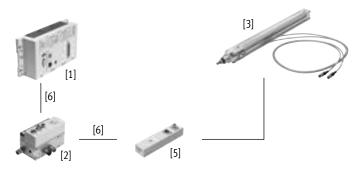
### Drive options

### System with linear drive DDLI, DGCI



- [1] Controller module CPX-CMPX or CPX-CMAX
- [2] Proportional directional control valve VPWP
- [3] Linear drive DDLI, DGCI with displacement encoder
- [6] Connecting cable KVI-CP-3-...

### System with standards-based cylinder DNCI, DDPC



- [1] Controller module CPX-CMPX or CPX-CMAX
- [2] Proportional directional control valve VPWP
- [3] Standards-based cylinder DNCI, DDPC with displacement encoder
- [5] Sensor interface CASM-S-D3-R7
- [6] Connecting cable KVI-CP-3-...

- Pneumatic rodless linear drive with displacement encoder, with or without recirculating ball bearing guide
- Displacement encoder with absolute and contactless measurement
- Diameter:
  - With DGCI: 18 ... 63 mm
  - With DDLI: 25 ... 63 mm
- Stroke: 100 ... 2000 mm in fixed lengths
- Range of applications: Soft Stop and pneumatic positioning
- Loads from 1 ... 180 kg
- No sensor interface required

· Standards-based cylinder with

conforms to DIN ISO 6432,

integrated displacement encoder,

### Data sheets → Internet: dnci

### Advantages:

Advantages:

CPX-CMAX)

• Complete drive unit

- Compact drive unit
- Can be used universally
- · Also with guide unit
- For fast and accurate positioning up to ±0.5 mm (only with axis controller CPX-CMAX)
- VDMA 24 562, NF E 49 003.1 and Uni 10 290
  Displacement encoder with contactless and incremental measurement
  Diameter: 32 ... 100 mm
  - Stroke: 100 ... 750 mm
  - Range of applications: Soft Stop and pneumatic positioning
  - Loads from 3 ... 450 kg and the corresponding sensor interface CASM-S-D3-R7
  - Pre-assembled cables guarantee faultless and fast electrical connection

# Data sheets → Internet: ddli or dgci

• DDLI for easy connection to the

• Excellent running characteristics

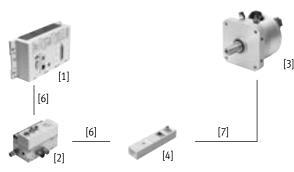
• For fast and accurate positioning up

to ±0.2 mm (only with axis controller

customer's guide system

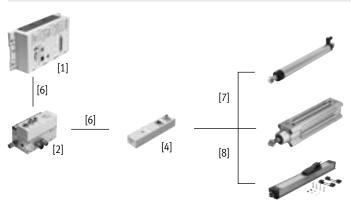
# Drive options

### System with swivel module DSMI



- [1] Controller module CPX-CMPX or CPX-CMAX
- [2] Proportional directional control valve VPWP
- [3] Swivel module DSMI with displacement encoder
- [4] Sensor interface CASM-S-D2-R3
- [6] Connecting cable KVI-CP-3-...
- [7] Connecting cable NEBC-P1W4-K-0.3-N-M12G5

### System with potentiometer



- [1] Controller module CPX-CMPX or CPX-CMAX
- [2] Proportional directional control valve VPWP
- [4] Sensor interface CASM-S-D2-R3
- [6] Connecting cable KVI-CP-3-...
- [7] Connecting cable NEBC-P1W4-K-0.3-N-M12G5
- [8] Connecting cable NEBC-A1W3-K-0.4-N-M12G5

- Swivel module DSMI with integrated displacement encoder
- Identical design to pneumatic swivel module DSM
- Absolute displacement encoder based on a potentiometer
- Swivel range from 0 ... 270°
- Size: 25, 40, 63
- Max. torque: 5 ... 40 Nm
  Range of applications: Soft Stop and pneumatic positioning
- Mass moments of inertia of 15 ... 6000 kgcm<sup>2</sup> and the corresponding sensor interface CASM-S-D2-R3
- Pre-assembled cables guarantee faultless and fast connection to the proportional directional control valve VPWP
- Attachable potentiometers with absolute measurement, with high degree of protection
- With connecting rod or moment compensator
- Measuring range: Connecting rod: 100 ... 750 mm Moment compensator: 225 ... 2000 mm
- Pre-assembled cables guarantee faultless and fast connection with the sensor interface CASM
- Range of applications: Soft Stop and pneumatic positioning with cylinder diameters of 25 ... 80 mm
- Loads from 1 ... 300 kg

### Data sheets $\rightarrow$ Internet: dsmi

### Advantages:

- Complete drive unit, compact, can be used immediately
- High angular acceleration
- With adjustable fixed stops
- For fast and accurate positioning down to ±0.2° (only with axis controller CPX-CMAX)

### Data sheets $\rightarrow$ Internet: casm

### Advantages:

- Easy installation and fast commissioning
- Cost-effective
- Can also be used in harsh ambient conditions
- Variety of drives: CPX-CMPX and CPX-CMAX also support cylinders with external displacement encoder

# Drive options

### System components for Soft Stop systems with end-position controller CPX-CMPX

	Linear drive	Standards-based cylinder	Swivel module	Displacement encode	er	→ Page/ Internet
	DDLI/DGCI	DNCI, DDPC	DSMI	MLO-LWG/-TLF	MME-MTS	
End-position controller	•					стрх
CPX-CMPX						
Proportional directional control valve						vpwp
VPWP						
Sensor interface	-	-	•	•	-	casm
CASM-S-D2-R3						
Sensor interface	-		-	-	-	casm
CASM-S-D3-R7						
Connecting cable						kvi
KVI-CP-3						
Connecting cable	-	-		■/-	-	nebc
NEBC-P1W4						
Connecting cable	-	-	-	- / =	-	nebc
NEBC-A1W3				,		
Connecting cable	-	-	-	-		vpwp
NEBP-M16W6						

### System components for pneumatic positioning systems with axis controller CPX-CMAX

	Linear drive	Standards-based cylinder	Swivel module	Displacement encode	er	→ Page/ Internet
	DDLI/DGCI	DNCI, DDPC	DSMI	MLO-LWG/-TLF	MME-MTS	
Axis controller CPX-CMAX			•	•	•	cmax
Proportional directional control valve VPWP	•		•			vpwp
Sensor interface CASM-S-D2-R3	-	-			-	casm
Sensor interface CASM-S-D3-R7	-		-	-	-	casm
Connecting cable KVI-CP-3						kvi
Connecting cable NEBC-P1W4	-	-		■ / -	-	nebc
Connecting cable NEBC-A1W3	-	-	-	- / ■	-	nebc
Connecting cable NEBP-M16W6	-	-	-	_		vpwp

### System components for measuring cylinders with measuring module CPX-CMIX

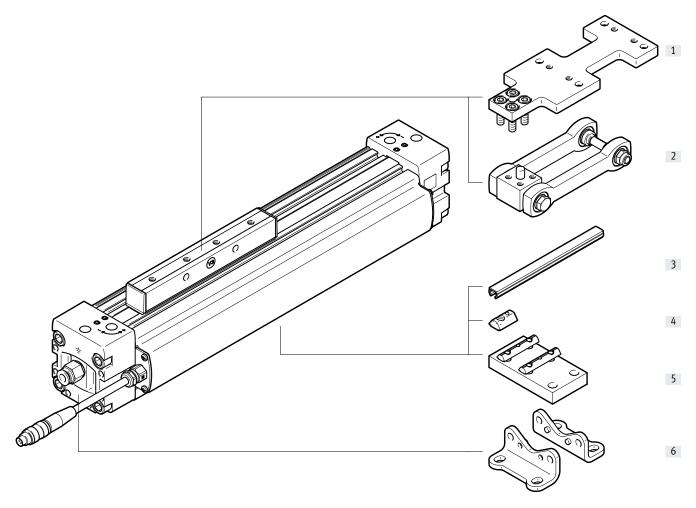
	Linear drive	Standards-based cylinder	Swivel module Displacement encoder			→ Page/ Internet
	DDLI/DGCI	DNCI, DDPC	DSMI	MLO-LWG/-TLF	MME-MTS	
Measuring module CPX-CMIX-M1-1	•	•				cmix
Sensor interface CASM-S-D2-R3	-	-	•		-	casm
Sensor interface CASM-S-D3-R7	-	•	-	-	-	casm
Connecting cable KVI-CP-3	(■) <sup>1)</sup>	•	•		(■)	kvi
Connecting cable NEBC-P1W4	-	-		■ / -	-	nebc
Connecting cable NEBC-A1W3	-	-	-	- / ■	-	nebc
Connecting cable NEBP-M16W6	-	-	-	-		vpwp

1) As an extension

# Type codes

001	Series	008	Cover, sensor slot	
DDLI	Linear drive, integrated displacement encoder		None	
		NS	1 record	
002	Piston diameter		1	
25	25	009	Cover, mounting slot	
32	32		None	
40	40	NC	1 record	
63	63			
002	Charles	010	Slot nut for mounting slot	
003	Stroke		None	
	100 2000	NM	1 50 units	
004	Cushioning	011	Moment compensator	
Р	Elastic cushioning rings/plates on both sides		None	
		T	Moment compensator coupling DARD	
005	Lubrication			
	Standard	012	Adapter plate	
H1	Food-safe lubrication		None	
006	Foot mounting	AP	FKP interface	
	None	013	Operating instructions	
MF	1 record		With operating instructions	
		DN	Without operating instructions	
007	Profile mounting			1
	None			
MA	1 10 units			

# Peripherals overview



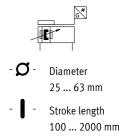
# Peripherals overview

Acce	ssories		
	Туре	Description	→ Page/Internet
[1]	Adapter plate DAMF	Has the same interface as the moment compensator FKP for the linear drive DGP	23
[2]	Moment compensator DARD	For compensating misalignments when using external guides	22
[3]	Slot cover ABP	For protection against contamination	24
[4]	Slot nut ABAN, NST	For mounting attachments	24
[5]	Central support MUP	For mounting the axis, particularly for long stroke lengths	21
[6]	Foot mounting HP	For mounting the axis. The foot mounting cannot be used when the bottom mounting position is used for the displacement encoder	21

# - 🖡 - Note

Allocation table of drives and associated proportional directional control valves → page 24

# Data sheet



www.festo.com

# A .....

### General technical data

Piston diameter		25	32	40	63		
Design	Rodless linear drive with slide and displacement encoder						
Mode of operation		Double-acting					
Moment compensator principle	Slotted cylinder, mechanical	ly coupled					
Mounting position		Any					
Type of mounting		Central support					
		Foot mounting					
		Direct mounting					
Cushioning		Elastic cushioning rings/pads at both ends					
Position sensing		Via integrated displacement encoder					
Measuring principle (displacement encoder)		Digital, magnetostrictive, contactless and absolute measurement					
Pneumatic connection <sup>1)</sup>		G1/8		G1/4	G3/8		
Stroke <sup>2)</sup>	[mm]	100, 160, 225, 300, 360, 4	50, 500, 600, 750, 850, 100	0, 1250, 1500, 1750, 2000			
Max. speed	[m/s]	3					

1) For pre-assembled push-in fittings, the tubing fittings  $\rightarrow$  page 15 apply

2) Note stroke reduction in combination with CPX-CMAX

### Operating and environmental conditions

Piston diameter		25	32	40	63	
Operating pressure	[bar]	28			1.5 8	
Operating pressure <sup>1)</sup>	[bar]	48				
Operating medium <sup>2)</sup>		Compressed air to ISO 857	3-1:2010 [6:4:4]			
Note on the operating/pilot medium		Operation with lubricated r	nedium not possible			
		Pressure dew point 10°C below ambient temperature/temperature of medium				
Ambient temperature	[°C]	-10 +60				
Vibration resistance to DIN/IEC 68 Part 2-6		At 1060 Hz: 0.15 mm				
		At 60150 Hz: 2G				
Continuous shock resistance to DIN/IEC 68, Part 2-2	7	Half sine 15 g, 11 ms				
CE marking (see declaration of conformity) <sup>3)</sup>		To EU EMC Directive				
Certification		C-Tick				
Corrosion resistance class CRC <sup>4)</sup>		1				

1) Only applies to applications with end-position controller CPX-CMPX, SPC11 and axis controller CPX-CMAX

2) The proportional directional control valve VPWP, MPYE used requires these characteristic values

3) For information about the area of use, see the EC declaration of conformity: www.festo.com/sp  $\rightarrow$  Certificates.

If the devices are subject to usage restrictions in residential, commercial or light-industrial environments, further measures for the reduction of the emitted interference may be necessary.

4) Corrosion resistance class CRC 1 to Festo standard FN 940070

Low corrosion stress. Dry indoor application or transport and storage protection. Also applies to parts behind coverings, in the non-visible interior area, and parts which are covered in the application (e.g. drive trunnions).

# Data sheet

Forces [N] and impact energy [Nm]					
Piston diameter		25	32	40	63
Theoretical force at 6 bar		295	483	754	1870
Impact energy at the end positions		0.05	0.12	0.25	0.5
Positioning characteristics with axis controlle	er CPX-CMAX				
Piston diameter		25	32	40	63
Mounting position		Any			
Resolution	[mm]	0.01			
Repetition accuracy		→ Page 15			
Minimum load, horizontal <sup>1)</sup>	[kg]	2	3	5	12
Maximum load, horizontal <sup>1)</sup>	[kg]	30	50	75	180
Minimum load, vertical <sup>1)</sup>	[kg]	2	3	5	12
Maximum load, vertical <sup>1)</sup>	[kg]	10	15	25	60
Min. travel speed	[m/s]	0.05	·		•
Max. travel speed	[m/s]	3			
Typical positioning time, long stroke <sup>2)</sup>	[s]	0.6 5/1.00	0.6 5/1.05	0.7 0/1.05	1.0 5/1.2
Typical positioning time, short stroke <sup>3)</sup>	[s]	0.38/0.60	0.38/0.60	0.38/0.60	0.6 5/0.65
Minimum positioning stroke4)	[%]	≤ 3			
Stroke reduction <sup>5)</sup>	[mm]	25	25	35	35
Recommended proportional directional contr	ol valve	· ·			·
For CPX-CMAX		→ Page 24			

1) Load = paytoad + toad of all moving parts of the drive

At 6 bar, horizontal mounting position, DDLI-XX-1000, 800 mm positioning travel at min./max. load
 At 6 bar, horizontal mounting position, DDLI-XX-1000, 100 mm positioning travel at min./max. load

4) In relation to the maximum stroke of the drive, but never more than 20 mm.

5) The stroke reduction must be maintained on each side of the drive, the max. positionable stroke is thus: stroke - 2x stroke reduction

### Force control characteristics with axis controller CPX-CMAX

Piston diameter		25	32	40	63
Mounting position		Any			
Maximum controllable force <sup>1)</sup>	[N]	266	435	679	1683
Typical friction forces <sup>2)</sup>	[N]	20	30	40	50
Repetition accuracy of pressure control <sup>3)4)</sup>	[%]	< ±2	-		

1) Advancing/retracting at 6 bar

2) These values can fluctuate greatly from cylinder to cylinder and are not guaranteed.

These friction forces must also be taken into consideration when using an external guide or when the cylinder is moving other components subject to friction

3) This value defines the repetition accuracy with which the internal differential pressure in the cylinder, which corresponds to the prescribed force setpoint value, is controlled and refers to the maximum controllable force

4) The effective force at the workpiece and its accuracy depend largely on the friction in the system as well as the repetition accuracy of the internal control system. Note that friction forces always work against the direction of movement of the piston. The following formula can be used as a rule of thumb to approximate the force F at the workpiece:

 $F = F_{setpoint} \pm F_{friction forces} \pm repetition accuracy of pressure control$ 

# Data sheet

### Positioning characteristics with Soft Stop end-position controller CPX-CMPX, SPC11

Positioning characteristics with Soft Stop	p end-position control	er CPX-CMPX, SPC11					
Piston diameter		25	32	40	63		
Mounting position		Any					
Repetition accuracy <sup>1)</sup>	[mm]	±2					
Minimum load, horizontal <sup>2)</sup>	[kg]	2	3	5	12		
Maximum load, horizontal <sup>2)</sup>	[kg]	30	50	75	180		
Minimum load, vertical <sup>2)</sup>	[kg]	2	3	5	12		
Maximum load, vertical <sup>2)</sup>	[kg]	10	15	25	60		
Travel time		→ SoftStop engi	→ SoftStop engineering software: → www.festo.com				
Recommended proportional directional of	control valve						
For CPX-CMPX		→ Page 25					
For SPC11		→ Page 26	→ Page 26				

1) One intermediate position. The accuracy in the end positions depends solely on the design of the end stops

2) Load = payload + load of all moving parts on the drive

### Electrical data – Displacement encoder

Output signal		Digital
Linearity error <sup>1)</sup>	[%]	< ±0.02, min. ±50 µm
Max. travel speed	[m/s]	3
Degree of protection		IP67
CE marking (see declaration of conformity)		To EU EMC Directive <sup>2)</sup>
Power supply	[V DC]	24 (±25%)
Current consumption	[mA]	Typically 100
Max. temperature coefficient	[ppm/°K]	15
Electrical connection		Cable with 5-pin plug, round type, M9
Cable length	[m]	1.5
Cable quality		Suitable for use with energy chains

1) Always refers to max. stroke.

2) For information about the area of use, see the EC declaration of conformity at: www.festo.com/sp  $\rightarrow$  Certificates.

If the devices are subject to usage restrictions in residential, commercial or light-industrial environments, further measures for the reduction of the emitted interference may be necessary.

### Pin allocation

Plugs



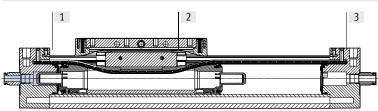
Pin	Function
1	+24 V
2	-
3	0 V
4	CAN_H
5	CAN_L
Housing	Cable shielding

# Data sheet

Weight [g]				
Piston diameter	25	32	40	63
Basic weight with 0 mm stroke	1103	1716	2580	8730
Additional weight per 10 mm stroke	34	43	58	139
Moving mass	130	227	350	1669

### Materials

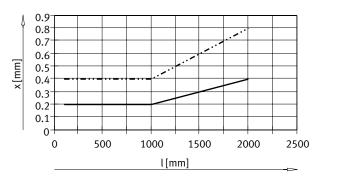
Sectional view



Linear actuators

[1]	Cylinder profile, housing	Anodised aluminium
[2]	Slide	Anodised aluminium
[3]	End cap	Painted aluminium
-	Seals	NBR, TPE-U(PU)
-	Cable	PUR
-	Note on materials	Free of copper and PTFE
		RoHS-compliant

### Repetition accuracy x as a function of stroke l



 Horizontal
 Vertical

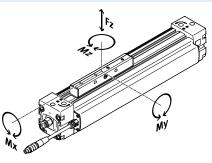
# Tubing O.D. of pre-assembled push-in fittings

Size	Stroke	Ø in [mm]	Ø in [mm]						
	[mm]	6	8	10	12				
DDLI-25	100 160	•	-	-	-				
	225 2000	6 8 10	-						
DDLI-32 100 160 2000	100		-	-	-				
	160 2000	-		_	_				
DDLI-40	100 750	-		-	_				
	850 2000	-	-		-				
DDLI-63	100 300	-		_	_				
	360 450	-	-		-				
	500 2000	_	-	_					

# Data sheet

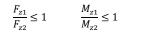
### Characteristic load values

The indicated forces and torques refer to the surface of the slide. These values must not be exceeded during dynamic operation. Special attention must be paid to the deceleration phase.



If the drive is subjected to two or more of the indicated forces and torques simultaneously, the following equation must be satisfied in addition to the indicated maximum loads:

$0.4 \cdot \frac{F_{z1}}{F_{z1}} +$	$M_{x1}$	$M_{y1}$ + (	$12.\frac{M_{z1}}{M_{z1}} < 1$	
$F_{z2}^{++}$	$M_{x2}$	$M_{y2} + C$	$0,2 \cdot \frac{M_{z1}}{M_{z2}} \le 1$	



F1/M1 = dynamic value F2/M2 = maximum value

### Permissible forces and torques

Permissible forces and torques						
Piston diameter		25	32	40	63	
Fz <sub>max.</sub>	[N]	330	480	800	1600	
Mx <sub>max.</sub>	[Nm]	1.2	1.9	3.8	5.7	
My <sub>max.</sub>	[Nm]	20	40	60	150	
Mz <sub>max.</sub>	[Nm]	3	5	8	24	

# Data sheet

### Number of central supports MUP as a function of overall length

Excessive distances between the central supports can reduce the positioning accuracy. The following table shows the required minimum number of central supports and foot mountings.

Stroke [mm]	Number of mounting components		
	Order code MA	Order code MF	
	Central support	Foot mounting + central support	
100 400	2	2	0
401 600	2	2	1
601 1200	3	2	1
1201 1400	3	2	2
1401 2000	4	2	2

Μ5

Μ6

M8

H5

22.5

27

32

53

5.2

6.5

8.5

H4

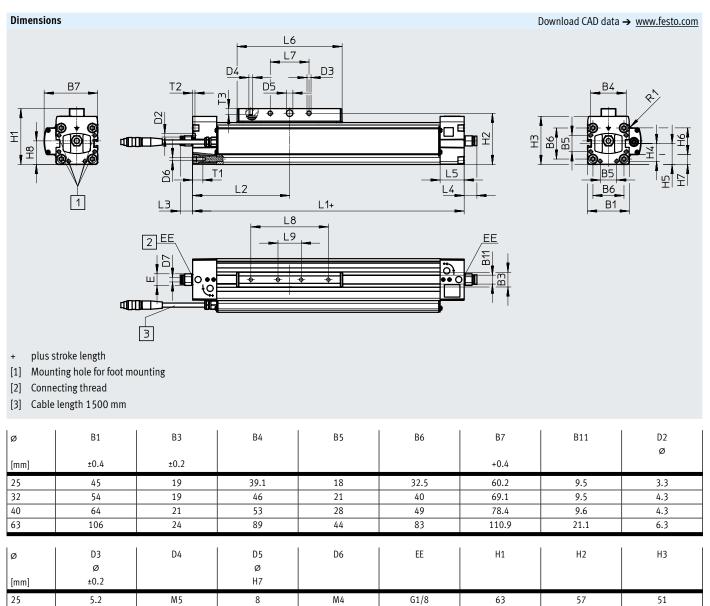
19.55

23

26.5

44.5

## Data sheet



Μ5

Μ5

M8

H7

5.15

12.65

16.25

43.25

G1/8

G1/4

G3/8

H8

28.7

30.4

35.5

61

72

86

131

R1

2.5

3.5

5

2

66

78

122

L1

200

250

300

400

61.8

71.8

115.2

L2

100

125

150

200

8

10

12

Η6

34.5

34.5

34.5

34.5

32

40

63

ø

[mm]

25

32

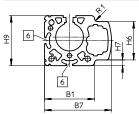
40

# Data sheet

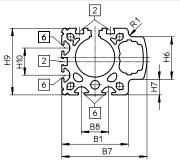
Ø	L5	L6	L7	L8	L9	T1	T2	T3
[mm]			±0.1	±0.1	±0.1			
25	25	109	30	50	-	13	2	7.5
32	31	135	50	100	30	13.2	3	7.5
40	31	171	70	130	40	13.2	3	7.5
63	34	234	110	190	70	21.2	6	12.5
Ø [mm]	Stroke [mm]	D	7	E		L3		L4
25	100 160	6		15		15.9		16.4
	225 2000	8		16		21.1		21.6
32	100	6		15		15.9		16.4
	160 2000	8		16		21.1		21.6
40	100 750	8		19		16.6		17.2
	850 2000	10	0	19		23.6		24.3
63	100 300	8		22		15.8		16.3
	360 500	10	0	22		19.6		20.2
	600 2000	1	2	24		25.7		26.3

### Profile barrel

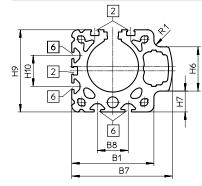


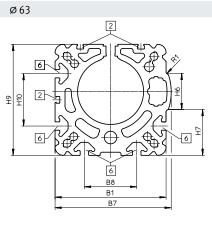


Ø 32



Ø 40





Ø	B1	B7	B8	H6	H7	H9	H10	R1
[mm]	+0.4	+0.4				+0.4		
25	45	60.2	-	34.5	5.15	45	-	2.5
32	54	69.1	22	34.5	12.65	54	22	3.5
40	64	78.4	24	34.5	16.25	64	24	5
63	106	110.9	50	34.5	43.3	106	50	2

# Ordering data – Modular product system

### Ordering table

Piston diameter		25	32	40	63	Condi- tions	Code	Enter code
Module no.		1315779	1344778	1463452	1572299			
Function		Linear drive with	integrated displacemen	t encoder			DDLI	DDLI
Piston diameter	[mm]	25	32	40	63			
Stroke	[mm]	100, 160, 225, 3	00, 160, 225, 300, 360, 450, 500, 600, 750, 850, 1000, 1250, 1500, 1750, 2000					
Cushioning		Elastic cushioning	astic cushioning rings/pads at both ends					-P
Lubrication		Standard		-	-			
		Food-safe lubrication					-H1	
Foot mounting		None						
		1 set					-MF	
Profile mounting		None						
		110					MA	
Sensor slot cover		None						
		- 1 set (for the entire drive length and all slots)					NS	
Mounting slot cover		None						
		1 set (for the entire drive length and all slots)					NC	
Slot nut for the mounting slot		None						
		150				[1]	NM	
Moment compensator		None						
		Moment compensator coupling					Т	
Adapter plate		None				[2]		
		FKP interface					AP	
Operating instructions		With operating in	structions					
		Without operating instructions					DN	

[1] NM For size 25: Entry "1NM" = delivery quantity 4 pieces

[2] AP Only with moment compensator T

# Accessories

Foot mounting HP (Order code: MF)

### Material:

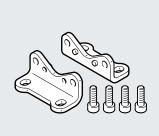
Galvanised steel

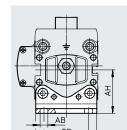
Free of copper and PTFE

### \_ Note -

Central supports MUP are additionally required for strokes above 400 mm → page 17

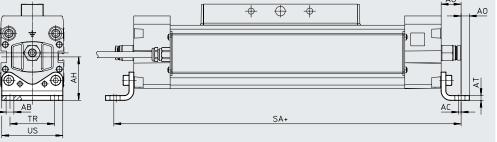
The foot mounting cannot be used when the bottom mounting position is used for the displacement encoder.





plus stroke length

+



### Dimensions and ordering data

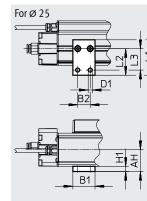
For Ø	AB	AC	AH	AO	AT	AU	SA	TR	US	Weight	Part no.	Туре
	ø											
[mm]										[g]		
25	5.5	2	29.5	6	3	13	226	32.5	44	61	150731	HP-25
32	6.6	2	37	7	4	17	284	38	52	117	150732	HP-32
40	6.6	2	46	8.5	5	17.5	335	45	62	188	150733	HP-40
63	11	3	69	13.5	6	28	456	75	102	305	150735	HP-63

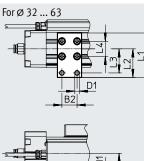
### Central support MUP

(Order code: MA)

### Material:

Anodised aluminium





B1

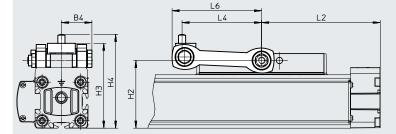
Free of copper and PTFE

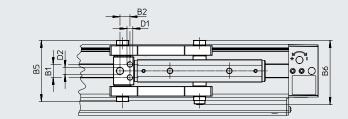
Dimensions and	ordering d	ata										
For Ø	AH	B1	B2	D1	H1	L1	L2	L3	L4	Weight	Part no.	Туре
				ø								
[mm]										[g]		
25	29.5	30	17	5.5	7	48	36	29	-	33	1711704	MUP-18/25-P
32	37	35	22	6.6	10	64.5	41.5	35	22	89	150737	MUP-32
40	46	35	22	6.6	14	75	47	40	24	126	150738	MUP-40
63	69	50	26	11	16	125	77	65	50	340	150800	MUP-63

# Accessories

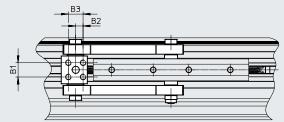
Moment compensator DARD (Order code: T) Material: Galvanised steel







DARD-32/40/63-...



### Dimensions and ordering data

Dimensions and									
For Ø	Max. offset between linear drive and external guide <sup>1)</sup>	Max. permissible load in direction of force	Ambient temperature	Weight					
[mm]	[mm]	[N]	[°C]	[g]					
25	±2.5	800	-10 +60	240					
32	±2.5	1300	-10 +60	275					
40	±2.5	2000	-10 +60	580					
63	±4	5000	-10 +60	1000					

1) Laterally and vertically.

For Ø	B1	B2	B3	B4	B5	B6	D1	D2	H2
[mm]							ø	ø	
25	11	8.4	-	25.7±2.5	51.4	54	M5x17	6	57
32	12	6.2	12.4	25.7±2.5	51.4	54	M5x13	6 6	66
40	18	11	17	36±2.5	72	75.3	M6x16	6	78
63	26	12.6	19	44±4	88	96.4	M8x18	3 10	122
For Ø	H3	H4	Li	2	L4	L6	Part no.	Туре	
[mm]						max.			
25	71.5±2.5	79±2.5	10	0	67.1	75.5	2349275	DARD-L1-25-M	

80.3

104

138

91

117

153

2349276

2349277

2349279

DARD-L1-32-M

DARD-L1-40-M

DARD-L1-63-M

125

150

200

32

40

63

80.5±2.5

94.5±2.5

142±4

88±2.5

104.5±2.5

152±4

# Accessories

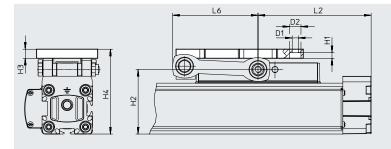
Adapter plate DAMF (Order code: AP)

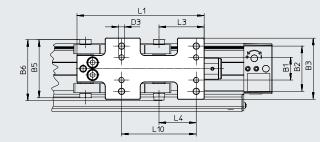
1111

### Material:

Galvanised steel

The adapter plate DAMF has the same interface as the moment compensator FKP for linear drive DGP.





DAME-32/40/63-...

(

⊕ ⊕	⊕ ∳	
<b>⊕</b>	⊕ ⊕	B4

1042

102

2349286

DAMF-63-FKP

Dimensions	and ordering data	a										
For Ø	B1	B2	B3	B4	B5	B6	D1	D2	D3	H1	H2	H3
							ø	ø				
[mm]												
25	20	40	54	27±2.5	51.4	54	5.5	10	M5	5	57	8
32	20	40	54	27±2.5	51.4	54	5.5	10	M5	5	66	8
40	24	44	58	29±2.5	72	75.3	6.6	11	M6	6	78	10
63	23	51	71	35.5±4	88.1	96.4	9	15	M8	8	122	10
	-											
For Ø	H4	L1	L2	L3	L4	L6	L10	Weight	Part no.	Туре		
[mm]						max.						
25	75±2.5	112.4	100	40	33	75.5	66	265	2349282	DAMF-25-FKP		
32	84±2.5	133	125	40.5	33	91	66	308	2349283	DAMF-32-FKP	1	
40	99±2.5	162	150	45	38	117	76	593	2349284	DAMF-40-FKP	1	

153

63

146±4

214

200

61

# Accessories

Ordering data									
	For Ø	Description	Order code	Part no.	Туре	PU <sup>1)</sup>			
Slot nut ABAN, NST Data sheets → Internet: hmbn									
Ø	25	For mounting slot	NM	8003032	ABAN-1M4-5	4			
	32, 40			150914	NST-5-M5	1			
	63			150915	NST-8-M6				
Slot cover ABP					Data sheets → Interr	net: abp			
	25	For mounting slot	NC	563360	ABP-5-S1	2			
	32,40	Each 0.5 m		151681	ABP-5				
6	63			151682	ABP-8				
	25, 32, 40, 63	For sensor slot	NS	563360	ABP-5-S1	2			
		Each 0.5 m							

1) Packaging unit

### Ordering data – Proportional directional control valves

Ordering data – Proportional dire	ctional control val	ves		
	For Ø	Stroke		directional control valve → Internet: vpwp
	[mm]	[mm]	Part no.	Туре
	For application	ons with axis controller CPX-CMAX		
	25	100 160	550170	VPWP-4-L-5-Q6-10-E
		225 600	550170	VPWP-4-L-5-Q8-10-E
		750 2000	550171	VPWP-6-L-5-Q8-10-E
OP OP COR	32	100	550170	VPWP-4-L-5-Q6-10-E
a a se		160 360	550170	VPWP-4-L-5-Q8-10-E
		450 2000	550171	VPWP-6-L-5-Q8-10-E
	40	100 300	550170	VPWP-4-L-5-Q8-10-E
		360 750	550171	VPWP-6-L-5-Q8-10-E
		850 2000	550172	VPWP-8-L-5-Q10-10-E
	63	100 300	550171	VPWP-6-L-5-Q8-10-E
		360 450	550172	VPWP-8-L-5-Q10-10-E
		500 750	550172	VPWP-8-L-5-Q-10-E <sup>1)</sup>
		850 2000	1552544	VPWP-10-L-5-Q-10-E-G-EX1 <sup>1)</sup>

1) Push-in fittings for a tubing O.D. of 12 mm must be used for these stroke ranges.

# Accessories

Ordering data – Proportional direction	onal control valves							
	For Ø	Stroke	· ·	directional control valve				
			Data sheets -	Internet: vpwp				
	[mm]	[mm]	Part no.	Туре				
	For applications with Soft Stop end-position controller CPX-CMPX, horizontal							
	25	100 160	550170	VPWP-4-L-5-Q6-10-E				
		225 300	550170	VPWP-4-L-5-Q8-10-E				
		360 2000	550171	VPWP-6-L-5-Q8-10-E				
R C & Cale	32	100	550170	VPWP-4-L-5-Q6-10-E				
		160 1000	550171	VPWP-6-L-5-Q8-10-E				
		1250 2000	550172	VPWP-8-L-5-Q-10-E <sup>1)</sup>				
	40	100 500	550171	VPWP-6-L-5-Q8-10-E				
		600 750	550172	VPWP-8-L-5-Q-10-E <sup>1)</sup>				
		850 2000	550172	VPWP-8-L-5-Q10-10-E				
	63	100 300	550171	VPWP-6-L-5-Q8-10-E				
		360 400	550172	VPWP-8-L-5-Q10-10-E				
		450	1552544	VPWP-10-L-5-Q-10-E-G-EX1 2)				
		500 2000	1552544	VPWP-10-L-5-Q-10-E-G-EX1 <sup>3)</sup>				

1) Push-in fittings for a tubing O.D. of 8 mm must be used for these stroke ranges.

2) Push-in fittings for a tubing O.D. of 10 mm must be used for this stroke range.

Push-in fittings for a tubing O.D. of 12 mm must be used for these stroke ranges.

### Ordering data – Proportional directional control valves

Ordering data - Proportional directi	Unat control valves								
	For Ø	Stroke	Proportional	directional control valve					
			Data sheets -	→ Internet: vpwp					
	[mm]	[mm]	Part no.	Туре					
	For applications with Soft Stop end-position controller CPX-CMPX, vertical								
	25	100 160	550170	VPWP-4-L-5-Q6-10-E					
		225 750	550170	VPWP-4-L-5-Q8-10-E					
		850 2000	550171	VPWP-6-L-5-Q8-10-E					
OP OP GOODE	32	100	550170	VPWP-4-L-5-Q6-10-E					
a a a a		160 300	550170	VPWP-4-L-5-Q8-10-E					
		360 1750	550171	VPWP-6-L-5-Q8-10-E					
		2000	550172	VPWP-8-L-5-Q-10-E <sup>1)</sup>					
	40	100 225	550170	VPWP-4-L-5-Q8-10-E					
		300 750	550171	VPWP-6-L-5-Q8-10-E					
		850 1000	550171	VPWP-6-L-5-Q-10-E <sup>2)</sup>					
		1250 2000	550172	VPWP-8-L-5-Q10-10-E					
	63	100 225	550170	VPWP-4-L-5-Q8-10-E					
		300	550171	VPWP-6-L-5-Q8-10-E					
		360 450	550172	VPWP-8-L-5-Q10-10-E					
		500 2000	1552544	VPWP-10-L-5-Q-10-E-G-EX1 <sup>3)</sup>					

1) Push-in fittings for a tubing 0.D. of 8 mm must be used for these stroke ranges.

2) Push-in fittings for a tubing 0.D. of 10 mm must be used for these stroke ranges.

3) Push-in fittings for a tubing 0.D. of 12 mm must be used for these stroke ranges.

I

# Accessories

# Ordering data – Proportional directional control valves

ordering data - r roportional directio	mat control valves							
	For Ø	Stroke	Proportional of	directional control valve				
			Data sheets -	➤ Internet: mpye				
	[mm]	[mm]	Part no.	Туре				
	For applications with Soft Stop end-position controller SPC11-MTS-AIF-2, horizontal							
6	25	100 160	151692	MPYE-5-1/8-LF-010-B				
		225 300	151692	MPYE-5-1/8-LF-010-B				
		360 2000	151693	MPYE-5-1/8-HF-010-B				
	32	100	151692	MPYE-5-1/8-LF-010-B				
		160 1000	151693	MPYE-5-1/8-HF-010-B				
		1250 2000	151694	MPYE-5-1/4-010-B				
	40	100 500	151693	MPYE-5-1/8-HF-010-B				
		600 750	151694	MPYE-5-1/4-010-B				
		850 2000	151694	MPYE-5-1/4-010-B				
	63	100 300	151693	MPYE-5-1/8-HF-010-B				
		360 400	151694	MPYE-5-1/4-010-B				
		450 2000	151695	MPYE-5-3/8-010-B				

### Ordering data – Proportional directional control valves

	For Ø	Stroke		directional control valve						
			Data sheets	→ Internet: mpye						
	[mm]	[mm]	Part no.	Туре						
$\square$	For applicati	For applications with Soft Stop end-position controller SPC11-MTS-AIF-2, vertical								
0	25	100 160	151692	MPYE-5-1/8-LF-010-B						
		225 750	151692	MPYE-5-1/8-LF-010-B						
		850 2000	151693	MPYE-5-1/8-HF-010-B						
	32	100	151692	MPYE-5-1/8-LF-010-B						
		160 300	151692	MPYE-5-1/8-LF-010-B						
		360 1750	151693	MPYE-5-1/8-HF-010-B						
		2000	151694	MPYE-5-1/8-010-B						
	40	100 225	151692	MPYE-5-1/8-LF-010-B						
		300 750	151693	MPYE-5-1/8-HF-010-B						
		850 1000	151693	MPYE-5-1/8-HF-010-B						
		1250 2000	151694	MPYE-5-1/4-010-B						
	63	100 225	151692	MPYE-5-1/8-LF-010-B						
		300	151693	MPYE-5-1/8-HF-010-B						
		360 450	151694	MPYE-5-1/4-010-B						
		500 2000	151695	MPYE-5-3/8-010-B						

Ordering data – Connecting cables				
	Description	Cable length	Part no.	Туре
		[m]		
Connection between axis controller CPX-CMAX/end-position controller CPX-CMPX and proportional directional control valve VPWP				
	Angled plug and angled socket	0.25	540327	KVI-CP-3-WS-WD-0.25
		0.5	540328	KVI-CP-3-WS-WD-0.5
		2	540329	KVI-CP-3-WS-WD-2
		5	540330	KVI-CP-3-WS-WD-5
		8	540331	KVI-CP-3-WS-WD-8
	Straight plug and straight socket	2	540332	KVI-CP-3-GS-GD-2
		5	540333	KVI-CP-3-GS-GD-5
		8	540334	KVI-CP-3-GS-GD-8