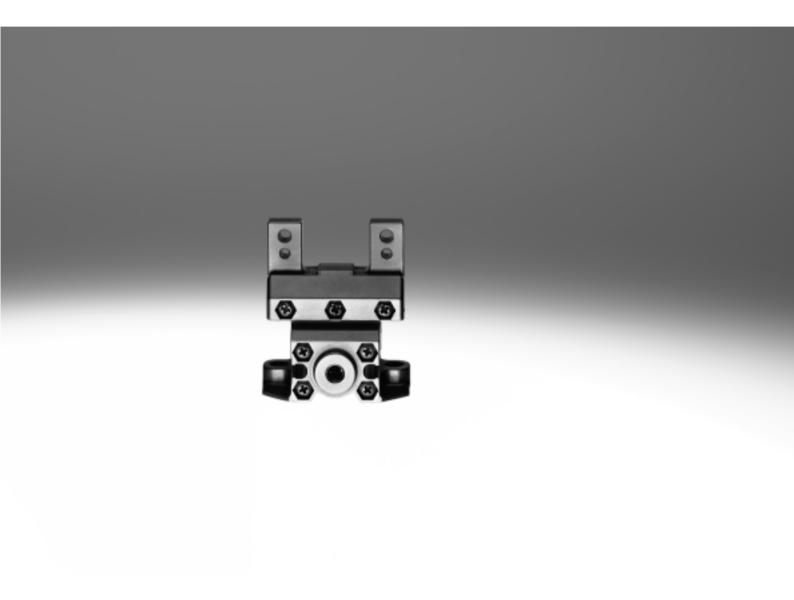
Parallel grippers HGPC

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Parallel grippers HGPC

Key features



At a glance

General

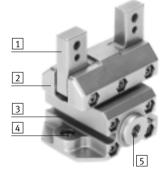
The compact and low-cost parallel gripper consists of a two-part symmetrical housing. The piston moves traverse to the half-shell casing in an optimum housing design that

guarantees reliable operation, long service life and convenient sensing. The gripper jaws move along the half shells in backlash-free, preloaded ball bearing guides.

- Double-acting gripper
- Compression spring for supplementary or retaining gripping forces
- Internal fixed flow control, does away with the need for external flow control in 80% of applications
- High force with minimal volume
- Suitable for external and internal gripping
- Wide range of options for attaching drive units
- Repetition accuracy of 0.05 mm
- Slot for proximity sensor SME/SMT-10

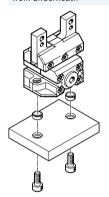


Details

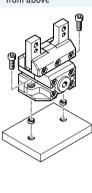


- 1 Gripper jaw with ball bearing
- 2 Housing based on half-shell principle
- 3 Slot for proximity sensor, for sensing the piston position
- 4 Mounting option
- 5 Supply port

Mounting option from underneath

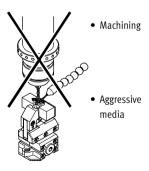


from above





Parallel grippers are not designed for the following applications:





Welding spatter



Parallel grippers HGPC Peripherals overview and type codes

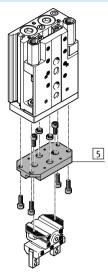
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3

Peripherals overview 1 2

3 4

System product for handling and assembly technology

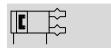


Acces	Accessories					
	Туре	Description	→ Page/Internet			
1	One-way flow control valve	For regulating speed	grla			
	GRLA					
2	Push-in fitting	For connecting compressed air tubing with standard O.D.	qs			
	QS					
3	Proximity sensor	For sensing the piston position	14			
	SME/SMT-10					
4	Centring sleeve	For centring when attaching to a drive	14			
	ZBH	(2 included in the scope of delivery)				
5	Adapter kit	Drive/gripper connections	12			
	HMSV, HAPG					

Type codes						
		HGPC —	12	_ A	-	G2
Туре						
	I					
HGPC	Parallel gripper					
Size						
Position sen	sing					
A	Via proximity sensor					
Gripping force	ce backup					
G2	Closing					

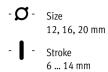
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Function Double-acting HGPC-...-A



Single-acting or with gripping force retention closing HGPC-...-G2







General technical data						
Size		12	16	20		
Constructional design		Wedge-shaped drive				
		Guided motion sequence				
Mode of operation		Double-acting				
Gripper function		Parallel				
Number of gripper jaws		2				
Max. load per external gripper finger ¹⁾	[g]	20	50	80		
Stroke per gripper jaw	[mm]	3	5	7		
Pneumatic connection		M5				
Repetition accuracy ²⁾	[mm]	≤ 0.05				
Max. interchangeability	[mm]	≤ 0.2				
Max. gripper jaw backlash ³⁾	[mm]	0				
Max. gripper jaw angular backlash ⁴⁾	[°]	0				
Max. operating frequency	[Hz]	4				
Rotational symmetry	[mm]	<∅0.2				
Position sensing		For proximity sensing				
Type of mounting		With female thread and centring sleeve				
Mounting position		Any				

- Valid for unthrottled operation
- End-position drift under constant conditions of use with 100 consecutive strokes in the direction of movement of the gripper jaws Perpendicular to the direction of motion of the gripper jaws Pretensioned, backlash-free ball bearing guide

Operating and environmental conditions						
Min. operating	HGPCA	[bar]	2			
pressure	HGPCG2	[bar]	4			
Max. operating pressure [bar]		[bar]	8			
Operating medium			Compressed air in accordance with ISO 8573-1:2010 [7:4:4]			
Note on operating/pilot medium			Operation with lubricated medium possible (in which case lubricated operation will always be required)			
Ambient temperature ¹⁾ [°C]		[°C]	+5 +60			
Corrosion resistance c	lass CRC ²⁾		2			

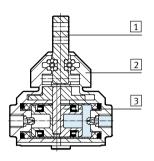
- 1) Note operating range of proximity sensors
- Corrosion resistance class 2 according to Festo standard 940 070 Components requiring moderate corrosion resistance. Externally visible parts with primarily decorative surface requirements which are in direct contact with a normal industrial environment or media such as coolants or lubricating agents

Weights [g]			
Size	12	16	20
HGPCA	152	241	473
HGPCG2	154	244	477



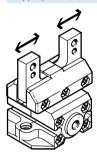
Materials

Sectional view



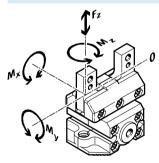
Para	Parallel gripper					
1	Gripper jaw	High-alloy steel				
2	Housing	Die-cast zinc				
3	Piston	Polyamide				
-	Seals	Polyurethane, nitrile rubber				
-	Note on materials	Copper, PTFE and silicone-free				
		Conforms to RoHS				

Gripping force [N] at 6 bar



Size	12	16	20				
Gripping force per gripper jaw	Gripping force per gripper jaw						
Opening	22	41.5	63				
Closing	22	41.5	63				
Total gripping force							
Opening	44	83	126				
Closing	44	83	126				

Static characteristic load values at the gripper jaws



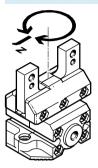
Indicated permissible forces and torques apply to a single gripper jaw. The indicated values include the lever arm, additional applied loads caused by the workpiece or external gripper

fingers, as well as forces which occur during movement.

The zero coordinate line (gripper finger guide) must be taken into consideration for the calculation of torques.

Size		12	16	20
Max. permissible force F _z	[N]	40	80	120
Max. permissible torque M_X	[Nm]	1	2,5	5
Max. permissible torque M _y	[Nm]	1	2,5	5
Max. permissible torque M _z	[Nm]	1	2,5	5

Mass moment of inertia [kgm²x10-4]



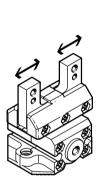
Mass moment of inertia $[kgm^2x10^{-4}]$ of the parallel gripper in relation to the central axis with no load.

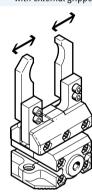
Size	12	16	20
HGPCA	0.272	0.679	2.095
HGPCG2	0.274	0.683	2.105

Opening and closing times [ms] at 6 bar

without external gripper fingers

with external gripper fingers





The indicated opening and closing times [ms] have been measured at room temperature and at 6 bar operating pressure with horizontally mounted gripper without additional

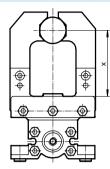
gripper fingers. The grippers must be throttled for greater loads [g]. Opening and closing times must then be adjusted correspondingly.

Size		12	16	20
without external gripper fingers				
HGPCA	Opening	30	60	90
	Closing	30	60	90
HGPCG2	Opening	30	70	105
	Closing	30	50	75
with external gripper fingers as a fun	ction of the loa	d		
HGPC	40 g	40	_	-
	50 g	60	-	-
	60 g	80	-	-
	70 g	-	80	-
	100 g	-	100	-
	120 g	-	-	100

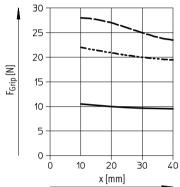
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Gripping force F_{Grip} per gripper jaw as a function of operating pressure and lever arm x

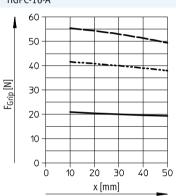
Gripping forces as a function of the operating pressure and the lever arm can be determined for the size using the following graph.



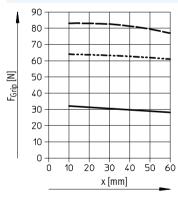
HGPC-12-A



HGPC-16-A



HGPC-20-A



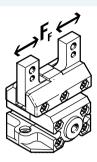


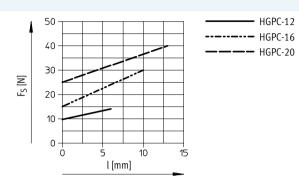
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Spring force F_S as a function of the gripper size and the overall stroke l

Gripping force retention for HGPC-...-G2

Spring forces F_S as a function of the gripper size and the overall stroke l for various gripper types (HGPC-...-G2) can be determined using the following graphs.





The lever arm x must be taken into consideration when determining the actual spring force F_{Stotal}. The formulae for calculating the spring force are provided in the table opposite.

Size	F _{Stotal} =
12	-0.02 * x +0.5 * F _S
16	-0.05 * x +0.5 * F _S
20	-0.05 * x +0.5 * F _S

Determination of the actual gripping forces F_{Gr} for HGPC-...-G2 depending on the application

Parallel grippers with integrated spring type HGPC-...-G2 (closing gripping force retention) can be used

single-acting grippers

- grippers with supplementary gripping force

- grippers with gripping force retention

In order to calculate available gripping forces F_{Gr} (per gripper jaw), the gripping force (F_{Grip}) and spring

force (F_{Stotal}) must be combined accordingly.

Application

Single-acting

• Gripping with spring force: $F_{Gr} = F_{Stotal}$

• Gripping with pressure force: $F_{Gr} = F_{Grip} - F_{Stotal}$

Supplementary gripping force

• Gripping with pressure and spring force:

$$F_{Gr} = F_{Grip} + F_{Stotal}$$

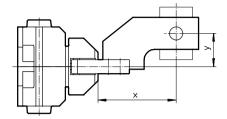
Gripping force retention

• Gripping with spring force:

$$F_{Gr} = F_{Stotal}$$

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Gripping force F_{Grip} per gripper jaw at 6 bar as a function of lever arm x and eccentricity y



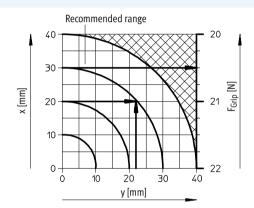
Gripping forces at 6 bar dependent upon eccentric application of force and the maximum permissible offcentre point of force application can be determined for the size using the $% \left(\frac{1}{2}\right) =\left(\frac{1}{2}\right) \left(\frac{1}{2}\right) \left($ following graph.

Calculation example

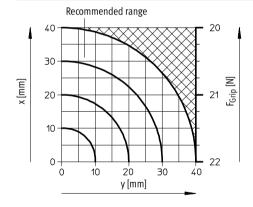
Lever arm x = 20 mmEccentricity y = 22 mm To be found: Gripping force at 6 bar

Procedure:

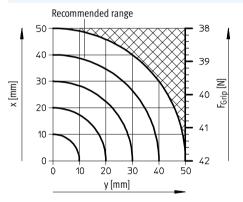
- Determine the intersection xy between lever arm x and eccentricity y in the graph for HGPC-12-A-...
- Draw an arc (with centre at origin) through intersection xy.
- Determine the intersection between the arc and the X axis.
- Read the gripping force. Result: Gripping force F = approx. 20.5 N



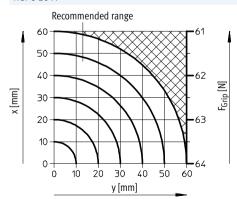
HGPC-12-A



HGPC-16-A



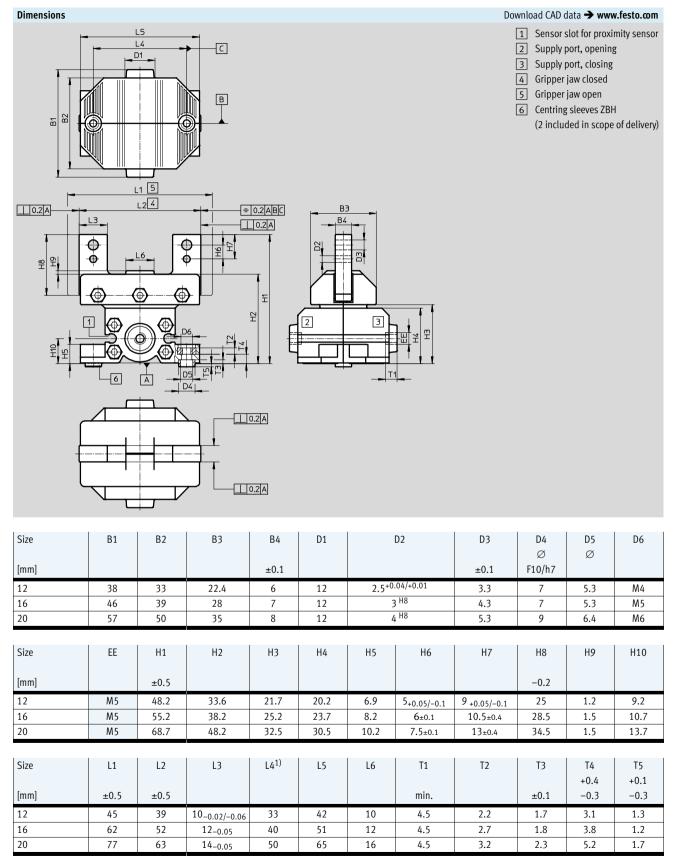
HGPC-20-A



Parallel grippers HGPC

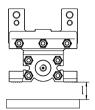
Technical data





Tolerance for centring hole ±0.03
 Tolerance for thread ±0.1





Minimum distance I between gripper and ferritic object							
12 16 20							
Distance	[mm]	10					

Ordering data					
	Size	Double-acting	Single-acting or with gripping force retention Closing		
		Without compression spring			
	[mm]	Part No. Type	Part No. Type		
\Diamond	12	539 267 HGPC-12-A	539 268 HGPC-12-A-G2		
	16	539 269 HGPC-16-A	539 270 HGPC-16-A-G2		
	20	539 271 HGPC-20-A	539 272 HGPC-20-A-G2		

Parallel grippers HGPC Accessories

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Adapter kit HAPG

Material:

Wrought aluminium alloy Free of copper and PTFE RoHS-compliant



The kit includes the individual mounting interface as well as the necessary mounting material.

	Gripper			Adapter kit			
Size	Size			CRC ¹⁾	Part No.	Туре	
DGSL	HGPC			HAPG			
12, 16	12				529018	HAPG-58	
20, 25	16			2	191267	HAPG-49	
20, 25	20				191269	HAPG-51	
				•			
CIT	HCDC			HADC			
				ПАРС	5/(2670	HAPG-100	
				\dashv		HAPG-58	
				\dashv		HAPG-101	
				2		HAPG-49	
						HAPG-102	
						HAPG-51	
23	20				171207	imi o 71	
НМР	HGPC			HAPG			
16	16	_			191263	HAPG-45	
20, 25	20	_	•	2	191264	HAPG-46	
НЅР	HGPC			HAPG			
				TIAFG	191901	HAPG-55	
		•	-			HAPG-71-B	
25	20			2	191901	HAPG-55	
1 -	-		-		540883	HAPG-72-B	
	12, 16 20, 25 20, 25 SLT 10 16 16 20 20 25 HMP 16 20, 25	12, 16	12, 16 12 20, 25 16 20, 25 20 SLT HGPC 10 12 16 12 16 16 20 20 25 20 HMP HGPC 16 16 20, 25 20 - - HSP HGPC 16 16 16 16 16 16 16 16	DGSL HGPC 12, 16 12 ■ ■ 20, 25 16 ■ ■ 20, 25 20 ■ ■ SLT HGPC HGPC ■ - 16 12 ■ - - 16 16 ■ - - - 20 20 ■ - - - HMP HGPC HGPC ■ ■ - ■ HSP HGPC HGPC ■ ■ - ■ HSP HGPC HGPC ■ ■ - ■	DGSL	DGSL HGPC HAPG 12, 16 12	

Corrosion resistance class 2 according to Festo standard 940 070 Components subject to moderate corrosion stress. Externally visible parts with primarily decorative surface requirements which are in direct contact with a normal industrial environment or media such as coolants or lubricating agents.

Parallel grippers HGPC Accessories



Adapter kit HAPG

Material:

Wrought aluminium alloy Free of copper and PTFE RoHS-compliant



The kit includes the individual mounting interface as well as the necessary mounting material.

		adapter kit					Oownload CAD data → www.festo.co		
Combination	Drive					Adapter kit			
	Size	Size Mounting option			CRC ¹⁾	Part No.	Туре		
HSW/HGPC	HSW	HGPC	•		HAPG				
	12, 16	16				191901	HAPG-55		
			•	-	2	540882	HAPG-71-B		
***	ERMB	HGPC			HAPG				
40	ERMB 20	HGPC	—	•	HAPG	542668	HAPG-SD2-42		
40			-	•	HAPG 2	542668 542669	HAPG-SD2-42 HAPG-SD2-43		
ERMB/HGPC	20	16							

¹⁾ Corrosion resistance class 2 according to Festo standard 940 070 Components subject to moderate corrosion stress. Externally visible parts with primarily decorative surface requirements which are in direct contact with a normal industrial environment or media such as coolants or lubricating agents.

Parallel grippers HGPC Accessories



Ordering data	- Centring sleeves			Technical data → Intern	et: zbh
	For size	Weight	Part No.	Туре	PU ¹⁾
	[mm]	[g]			
	12, 16	1	186717	ZBH-7	10
(1)	20	1	150927	ZBH-9	10

¹⁾ Packaging unit

Ordering data	rdering data – Proximity sensors for C-slot								
	Type of mounting	Electrical connection,	Switching	Cable length	Part No.	Туре			
		connection direction	output	[m]					
	N/O contact, magneto-resistive Technical data → Interne								
	Insertable in the slot from	Cable, 3-wire, in-line	PNP	2.5	551373	SMT-10M-PS-24V-E-2,5-L-0E			
	above	Plug M8x1, 3-pin, in-line		0.3	551375	SMT-10M-PS-24V-E-0,3-L-M8D			
	N/O contact, magnetic reed Technical data → Internet: sr								
	Insertable in the slot	Cable, 3-wire, in-line	Contacting	2.5	173210	SME-10-KL-LED-24			
	lengthwise	Plug M8x1, 3-pin, in-line		0.3	173212	SME-10-SL-LED-24			

Ordering data	– Proximity sensors for C-sl	ot							
	Type of mounting	Electrical connection,	Switching	Cable length	Part No.	Туре			
		connection direction	output	[m]					
Î	N/O contact, magneto-resistive Technical data → Internet:								
	Insertable in the slot from	Cable, 3-wire, lateral	PNP	2.5	551374	SMT-10M-PS-24V-E-2,5-Q-0E			
	above	Plug M8x1, 3-pin, lateral		0.3	551376	SMT-10M-PS-24V-E-0,3-Q-M8D			
	N/O contact, magnetic reed Technical data → Interne								
	Insertable in the slot	Cable, 3-wire, lateral	Contacting	2.5	173211	SME-10-KQ-LED-24			
	lengthwise	Plug M8x1, 3-pin, lateral		0.3	173213	SME-10-SQ-LED-24			

Ordering data	Technical data → Internet: nebu				
	Electrical connection, left	Electrical connection, right	Cable length	Part No.	Туре
			[m]		
	Straight socket, M8x1, 3-pin	Cable, open end, 3-wire	2.5	541333	NEBU-M8G3-K-2.5-LE3
			5	541334	NEBU-M8G3-K-5-LE3
	Angled socket, M8x1, 3-pin	Cable, open end, 3-wire	2.5	541338	NEBU-M8W3-K-2.5-LE3
			5	541341	NEBU-M8W3-K-5-LE3