

Toothed belt axes ELGR



# Electromechanical drives

Selection aid



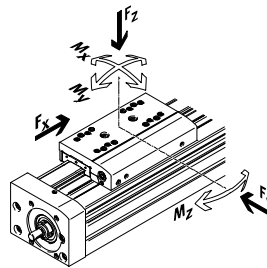
## Overview of toothed belt and spindle axes

### Toothed belt axes

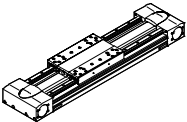
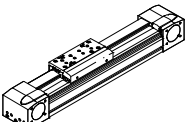
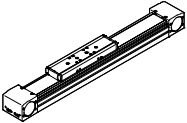
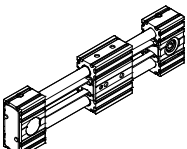
- Speeds of up to 10 m/s
- Acceleration of up to 50 m/s<sup>2</sup>
- Repetition accuracy of up to ±0.08 mm
- Strokes of up to 8500 mm (longer strokes on request)
- Flexible motor mounting

### Spindle axes

- Speeds of up to 2 m/s
- Acceleration of up to 20 m/s<sup>2</sup>
- Repetition accuracy of up to ±0.003 mm
- Strokes of up to 3000 mm



## Toothed belt axes

Type	$F_x$ [N]	$v$ [m/s]	$M_x$ [Nm]	$M_y$ [Nm]	$M_z$ [Nm]	Key features
<b>Heavy-duty recirculating ball bearing guide</b>						
<b>EGC-HD-TB</b>						
	450	3	140	275	275	<ul style="list-style-type: none"> <li>• Flat drive unit with rigid, closed profile</li> <li>• Precision DUO guide rail with high load capacity</li> <li>• Ideal as a basic axis for linear gantries and cantilever axes</li> </ul>
	1000	5	300	500	500	
	1800	5	900	1450	1450	
<b>Recirculating ball bearing guide</b>						
<b>EGC-TB-KF</b>						
	50	3	3.5	10	10	<ul style="list-style-type: none"> <li>• Rigid, closed profile</li> <li>• Precision guide rail with high load capacity</li> <li>• Small drive pinions reduce required driving torque</li> <li>• Space-saving position sensing</li> </ul>
	100	5	16	132	132	
	350	5	36	228	228	
	800	5	144	680	680	
	2500	5	529	1820	1820	
<b>ELGA-TB-KF</b>						
	350	5	16	132	132	<ul style="list-style-type: none"> <li>• Internal guide and toothed belt</li> <li>• Precision guide rail with high load capacity</li> <li>• Guide and toothed belt protected by cover band</li> <li>• High feed forces</li> </ul>
	800	5	36	228	228	
	1300	5	104	680	680	
	2000	5	167	1150	1150	
<b>ELGR-TB</b>						
	50	3	2.5	20	20	<ul style="list-style-type: none"> <li>• Cost-optimised rod guide</li> <li>• Ready-to-install unit</li> <li>• Ball bearings with high load capacity for dynamic operation</li> </ul>
	100	3	5	40	40	
	350	3	15	124	124	

# Electromechanical drives

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## Overview of toothed belt and spindle axes

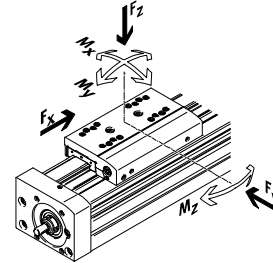
### Toothed belt axes

- Speeds of up to 10 m/s
- Acceleration of up to 50 m/s<sup>2</sup>
- Repetition accuracy of up to ±0.08 mm
- Strokes of up to 8500 mm (longer strokes on request)
- Flexible motor mounting

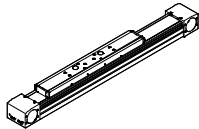
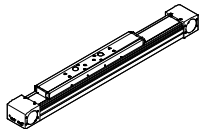
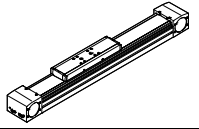
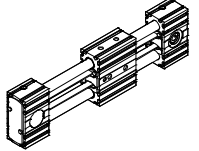
### Spindle axes

- Speeds of up to 2 m/s
- Acceleration of up to 20 m/s<sup>2</sup>
- Repetition accuracy of up to ±0.003 mm
- Strokes of up to 3000 mm

### Coordinate system



## Toothed belt axes

Type	$F_x$ [N]	$v$ [m/s]	$M_x$ [Nm]	$M_y$ [Nm]	$M_z$ [Nm]	Key features
<b>Roller bearing guide</b>						
<b>ELGA-TB-RF</b>						
	350 800 1300	10 10 10	11 30 100	40 180 640	40 180 640	<ul style="list-style-type: none"> <li>• Sturdy roller bearing guide</li> <li>• Guide and toothed belt protected by cover band</li> <li>• Speeds of up to 10 m/s</li> <li>• Lower weight than axes with guide rails</li> </ul>
<b>ELGA-TB-RF-F1</b>						
	260 600 1000	10 10 10	8.8 24 80	32 144 512	32 144 512	<ul style="list-style-type: none"> <li>• Suitable for use in the food zone</li> <li>• Sturdy roller bearing guide</li> <li>• Guide and toothed belt protected by cover band</li> <li>• Speeds of up to 10 m/s</li> <li>• Lower weight than axes with guide rails</li> </ul>
<b>Plain-bearing guide</b>						
<b>ELGA-TB-G</b>						
	350 800 1300	5 5 5	5 10 120	30 60 120	10 20 40	<ul style="list-style-type: none"> <li>• Guide and toothed belt protected by cover band</li> <li>• For simple handling tasks</li> <li>• As a drive component for external guides</li> <li>• Insensitive to harsh environmental conditions</li> </ul>
<b>ELGR-TB-GF</b>						
	50 100 350	1 1 1	1 2.5 1	10 20 40	10 20 40	<ul style="list-style-type: none"> <li>• Cost-optimised rod guide</li> <li>• Ready-to-install unit</li> <li>• Sturdy plain bearings for use in harsh environmental conditions</li> </ul>

# Electromechanical drives

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## Overview of toothed belt and spindle axes

Toothed belt axes	Spindle axes	Coordinate system
<ul style="list-style-type: none"> <li>• Speeds of up to 10 m/s</li> <li>• Acceleration of up to 50 m/s<sup>2</sup></li> <li>• Repetition accuracy of up to ±0.08 mm</li> <li>• Strokes of up to 8500 mm (longer strokes on request)</li> <li>• Flexible motor mounting</li> </ul>	<ul style="list-style-type: none"> <li>• Speeds of up to 2 m/s</li> <li>• Acceleration of up to 20 m/s<sup>2</sup></li> <li>• Repetition accuracy of up to ±0.003 mm</li> <li>• Strokes of up to 3000 mm</li> </ul>	

Spindle axes						
Type	$F_x$ [N]	$v$ [m/s]	$M_x$ [Nm]	$M_y$ [Nm]	$M_z$ [Nm]	Key features
<b>Heavy-duty recirculating ball bearing guide</b>						
EGC-HD-BS						
	300 600 1300	0.5 1.0 1.5	140 300 900	275 500 1450	275 500 1450	<ul style="list-style-type: none"> <li>• Flat drive unit with rigid, closed profile</li> <li>• Precision DUO guide rail with high load capacity</li> <li>• Ideal as a basic axis for linear gantries and cantilever axes</li> </ul>
<b>Recirculating ball bearing guide</b>						
EGC-BS-KF						
	300 600 1300 3000	0.5 1.0 1.5 2.0	16 36 144 529	132 228 680 1820	132 228 680 1820	<ul style="list-style-type: none"> <li>• Rigid, closed profile</li> <li>• Precision guide rail with high load capacity</li> <li>• For the highest requirements in terms of feed force and accuracy</li> <li>• Space-saving position sensing</li> </ul>
ELGA-BS-KF						
	300 600 1300 3000	0.5 1.0 1.5 2.0	16 36 104 167	132 228 680 1150	132 228 680 1150	<ul style="list-style-type: none"> <li>• Internal guide and ball screw</li> <li>• Precision guide rail with high load capacity</li> <li>• For the highest requirements for feed force and precision</li> <li>• Guide and ball screw protected by cover strip</li> <li>• Space-saving position sensing</li> </ul>
EGSK						
	57 133 184 239 392	0.33 1.10 0.83 1.10 1.48	13 28.7 60 79.5 231	3.7 9.2 20.4 26 77.3	3.7 9.2 20.4 26 77.3	<ul style="list-style-type: none"> <li>• Spindle axes with maximum precision, compactness and rigidity</li> <li>• Recirculating ball bearing guide and ball screw without caged ball bearings</li> <li>• Standard designs in stock</li> </ul>
EGSP						
	112 212 466 460	0.6 0.6 2.0 2.0	36.3 81.5 90.3 258	12.5 31.6 32.1 94	12.5 31.6 32.1 94	<ul style="list-style-type: none"> <li>• Spindle axes with maximum precision, compactness and rigidity</li> <li>• Recirculating ball bearing guide with caged ball bearings</li> <li>• Ball screw sizes 33, 46 with caged ball bearings</li> </ul>

# Toothed belt axes ELGR

## Key features

At a glance		
General	Properties	Range of applications
<ul style="list-style-type: none"> <li>• Optimum price/performance ratio</li> <li>• Ready-to-install unit for quick and easy design</li> <li>• High reliability thanks to tested service life of 5000 km</li> <li>• Complete module for a simple and space-saving solution for end-position sensing</li> </ul>	<ul style="list-style-type: none"> <li>• Plain-bearing guide                             <ul style="list-style-type: none"> <li>– For small loads</li> <li>– Restricted operating behaviour with torque load</li> <li>– Guide backlash = 0.05mm (on delivery)</li> </ul> </li> </ul>	<ul style="list-style-type: none"> <li>• Recirculating ball bearing guide                             <ul style="list-style-type: none"> <li>– For medium loads</li> <li>– Very good operating behaviour with torque load</li> <li>– Backlash-free guide (preloaded guide elements)</li> </ul> </li> </ul>
		<ul style="list-style-type: none"> <li>• Pick &amp; place with payloads of up to 15 kg</li> <li>• Positioning and handling with low process forces</li> <li>• Actuation of guard doors in processing machines</li> </ul>

### Modular axis system with open motor interface → 7

- Variable strokes
- Two guide variants
- Axial kits for servo and stepper motors
- The motor position can be freely selected on 4 sides and can be changed at any time.



### Optimised Motion Series (OMS) – Package solution with motor and motor controller → 20

A package that makes positioning easier than ever before. The Optimised Motion Series is as easy to handle as a pneumatic cylinder, but with the functionality of an electric drive.



Simple choice	Ordering and logistics	Quick to configure
<ul style="list-style-type: none"> <li>• Easy sizing and selection using cycle time charts</li> <li>• No specialist knowledge of electric drive technology required</li> </ul>	<ul style="list-style-type: none"> <li>• All the necessary component parts with a single part number</li> <li>• Motors preassembled on the axis mechanism</li> </ul>	<ul style="list-style-type: none"> <li>• Parameterisation and commissioning via web server/browser</li> <li>• Parameterise up to 7 freely definable positions directly on the PC</li> </ul>



### For simple positioning tasks

Toothed belt axis ELGR



Controller CMMO  
→ Internet: cmmo



# Toothed belt axes ELGR

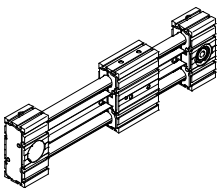
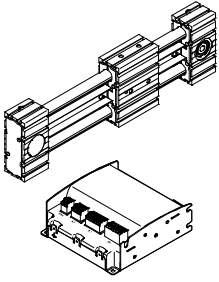
Features

## Characteristic values of the axes

The specifications shown in the table are maximum values.

The precise values for each of the variants can be found in the relevant technical data.

 Note  
PositioningDrives  
engineering software  
[www.festo.com](http://www.festo.com)

Design	Size	Working stroke [mm]	Speed [m/s]	Repetition accuracy [mm]	Feed force [N]	Guide characteristics					→ Page
						Forces and torques					
						Fy [N]	Fz [N]	Mx [Nm]	My [Nm]	Mz [Nm]	
<b>Toothed belt axis ELGR</b>											
	35	50 ... 800	3	±0.1	50	50	50	2.5	20	20	7
	45	50 ... 1000	3	±0.1	100	100	100	5	40	40	
	55	50 ... 1500	3	±0.1	350	300	300	15	124	124	
<b>Toothed belt axis ELGR in combination with Optimised Motion series (OMS)</b>											
	35	50 ... 800 <sup>1)</sup>	1.1	±0.1	50	20	20	2.5	20	20	20
	45	50 ... 1000 <sup>1)</sup>	1.1	±0.1	100	50	50	5	40	40	
	55	50 ... 1500 <sup>1)</sup>	0.35	±0.1	350	90	90	15	124	124	

1) Only standard strokes can be ordered → 34

# Toothed belt axes ELGR

Type codes

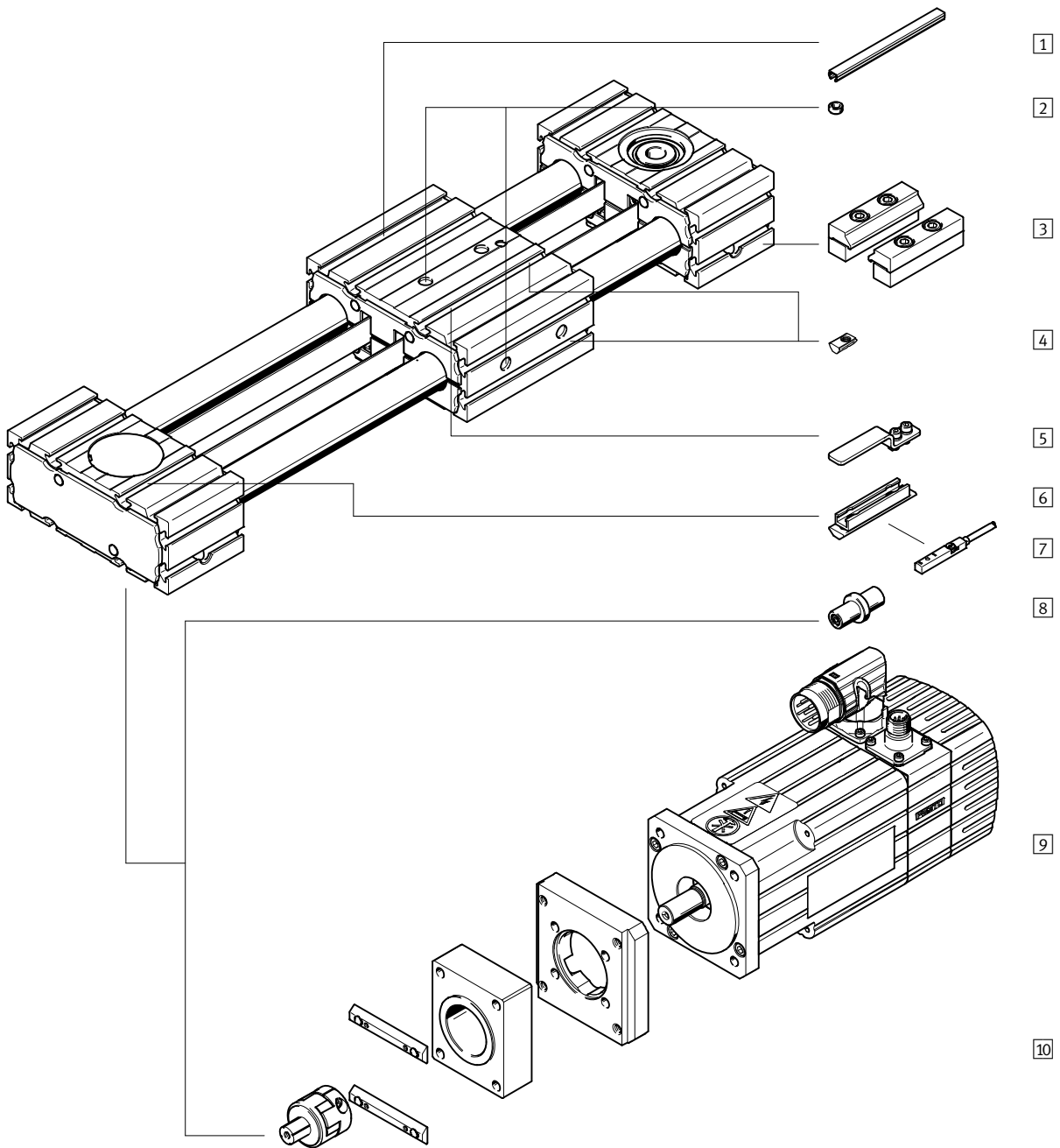
		ELGR	-	TB	-		-	45	-	500	-	30H	-	L	-	
<b>Type</b>																
ELGR	Linear axis															
<b>Drive function</b>																
TB	Toothed belt															
<b>Guide</b>																
-	Recirculating ball bearing guide															
GF	Plain-bearing guide															
<b>Size</b>																
<b>Stroke [mm]</b>																
<b>Stroke reserve</b>																
<b>Slide</b>																
-	Standard slide															
L	Long slide															
<b>Additional slide</b>																
-	No additional slide															
ZR	1 slide on right															
ZL	1 slide on left															
ZB	1 slide on right, 1 slide on left															

		→	+	2SA		4NM	EA	2MA	+	
<b>Proximity sensor</b>										
...SA	Proximity sensor (SIES), inductive, slot type 8, PNP, N/O contact, cable 7.5 m									
...SB	Proximity sensor (SIES), inductive, slot type 8, PNP, N/C contact, cable 7.5 m									
<b>Cover</b>										
...NC	For mounting slot									
<b>Slot nut</b>										
...NM	For mounting slot									
<b>Drive shaft</b>										
...EA	Drive shaft									
<b>Profile mounting</b>										
...MA	Profile mounting									
<b>Operating instructions</b>										
-	With operating instructions									
DN	Without operating instructions									

# Toothed belt axes ELGR

Peripherals overview

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# Toothed belt axes ELGR

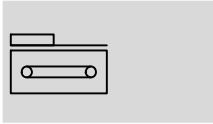
Peripherals overview




Accessories			
	Type/order code	Description	→ Page/Internet
1	Slot cover NC	<ul style="list-style-type: none"> <li>For protecting against ingress of dirt</li> </ul>	40
2	Centring sleeve ZBH	<ul style="list-style-type: none"> <li>For centring loads and attachments on the slide</li> <li>2 centring sleeves included in the scope of delivery of the axis</li> </ul>	40
3	Profile mounting MA	For mounting the axis on the bearing cap	39
4	Slot nut NM	For mounting attachments	40
5	Switch lug SA, SB	For sensing the slide position	39
6	Sensor bracket SA, SB	Adapter for mounting the inductive proximity sensors on the axis	39
7	Proximity sensor, T-slot SA, SB	<ul style="list-style-type: none"> <li>Inductive proximity sensor, for T-slot</li> <li>1 switching lug and 1 sensor bracket are included in the scope of delivery with the order code SA, SB</li> </ul>	41
8	Drive shaft EA	<ul style="list-style-type: none"> <li>Can, if required, be used as an alternative interface</li> <li>No drive shaft is required for the axis/motor combinations → 36</li> </ul>	40
9	Motor EMME, EMMS	Motors specially matched to the axis, with or without brake	36
10	Axial kit EAMM	For axial motor mounting (comprises: coupling, coupling housing and motor flange)	36
-	Connecting cable NEBU	For proximity sensor (order code SA and SB)	41

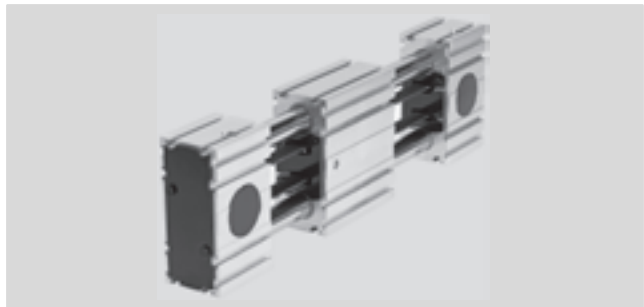
# Toothed belt axes ELGR

## Technical data

### Function



-  Size  
35 ... 55
-  Stroke length  
50 ... 1500 mm
-  [www.festo.com](http://www.festo.com)



General technical data				
Size		35	45	55
Design		Electromechanical linear axis with toothed belt		
Guide		Recirculating ball bearing guide		
		Plain-bearing guide		
Mounting position		Any		
Working stroke	[mm]	50 ... 800	50 ... 1000	50 ... 1500
Max. feed force $F_x$	[N]	50	100	350
Max. no-load torque	[Nm]	0.1	0.2	0.4
Max. driving torque	[Nm]	0.46	1.24	5
Max. no-load resistance to shifting	[N]	10.8	16.1	27.9
Max. speed				
Recirculating ball bearing guide	[m/s]	3		
Plain-bearing guide	[m/s]	1		
Max. acceleration <sup>1)</sup>	[m/s <sup>2</sup> ]	50		
Repetition accuracy	[mm]	±0.1		

1) The max. acceleration is dependent on the payload, the driving torque and the max. feed force → 13

Operating and environmental conditions			
Ambient temperature			
Recirculating ball bearing guide	[°C]	-10 ... +50	
Plain-bearing guide	[°C]	0 ... +40	
Degree of protection		IP20	
Duty cycle	[%]	100	

Weight [kg]				
Size		35	45	55
Recirculating ball bearing guide				
Basic weight with 0 mm stroke <sup>1)</sup>				
Standard slide		1.5	3.2	5.4
Long slide		1.9	4.3	7.4
Additional weight per 1000 mm stroke		2.5	5.0	7.8
Moving mass		0.5	1.1	1.9
Slide				
Standard slide		0.5	1.0	1.8
Long slide		0.8	1.7	3.0
Additional slide		0.4	0.9	1.7

1) Incl. slides

# Toothed belt axes ELGR

Technical data

Weight [kg]			
Size	35	45	55
Plain-bearing guide			
Basic weight with 0 mm stroke <sup>1)</sup>			
Standard slide	1.4	3.1	5.1
Long slide	1.9	4.3	7.3
Additional weight per 1000 mm stroke	2.5	5.0	7.8
Moving mass	0.4	0.9	1.5
Slide			
Standard slide	0.4	0.9	1.5
Long slide	0.7	1.6	2.8
Additional slide	0.3	0.7	1.3

1) Incl. slides

Toothed belt			
Size	35	45	55
Pitch [mm]	2	3	3
Expansion <sup>1)</sup> [%]	0.094	0.08	0.21
Width [mm]	10	15	19.3
Effective diameter [mm]	18.46	24.83	28.65
Feed constant [mm/rev]	58	78	90

1) At max. feed force

Mass moment of inertia			
Size	35	45	55
$J_0$			
Standard slide [kg mm <sup>2</sup> ]	40.26	155.13	360.48
Long slide [kg mm <sup>2</sup> ]	66.50	271.52	638.74
$J_S$ per metre stroke [kg mm <sup>2</sup> /m]	0.26	1.06	1.88
$J_L$ per kg payload [kg mm <sup>2</sup> /kg]	85.19	154.13	205.21
$J_W$ Additional slide [kg mm <sup>2</sup> ]	36.75	136.55	301.92

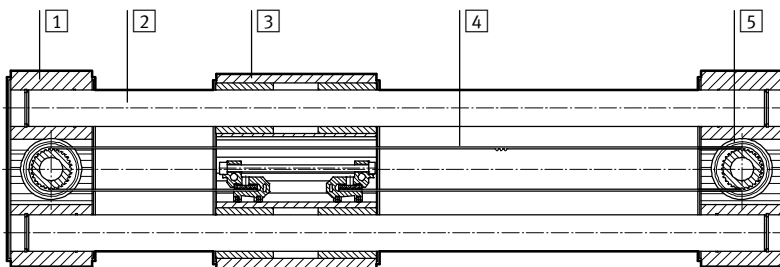
The mass moment of inertia  $J_A$  of the entire axis is calculated as follows:

$$J_A = J_0 + K \times J_W + J_H \times \text{working stroke [m]} + J_L \times m_{\text{payload [kg]}}$$

$K$  = Number of additional slides

## Materials

Sectional view



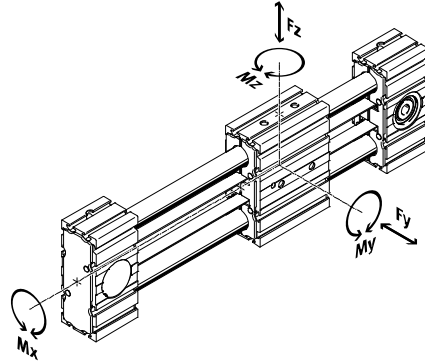
Axis		
1	Bearing cap, profile	Anodised wrought aluminium alloy
2	Guide rods	Tempered steel, hardened and hard-chromium plated
3	Slide, profile	Anodised wrought aluminium alloy
4	Toothed belt	Polychloroprene with glass cord and nylon coating
5	Belt pulley	High-alloy stainless steel
Note on materials		RoHS-compliant
		Contains paint-wetting impairment substances

# Toothed belt axes ELGR

Technical data

## Characteristic load values

The indicated forces and torques refer to the centre of the guide. The point of application of force is the point where the centre of the guide and the longitudinal centre of the slide intersect. These values must not be exceeded during dynamic operation. Special attention must be paid to the cushioning phase.



If the axis is subjected to two or more of the indicated forces and torques simultaneously, the following equation must be satisfied in addition to the indicated maximum loads:

Calculating the load comparison factor:

$$f_v = \frac{|F_{y,dyn}|}{F_{y,max.}} + \frac{|F_{z,dyn}|}{F_{z,max.}} + \frac{|M_{x,dyn}|}{M_{x,max.}} + \frac{|M_{y,dyn}|}{M_{y,max.}} + \frac{|M_{z,dyn}|}{M_{z,max.}} \leq 1$$

Permissible forces and torques for a service life of 5000 km							
Guide	Plain-bearing guide			Recirculating ball bearing guide			
Size	35	45	55	35	45	55	
$F_{y,max.}, F_{z,max.}$ [N]	50	100	300	50	100	300	
Standard slide							
$M_{x,max.}$ [Nm]	1	2.5	5	2.5	5	15	
$M_{y,max.}$ [Nm]	4	8	16	8	16	48	
$M_{z,max.}$ [Nm]	4	8	16	8	16	48	
Long slide							
$M_{x,max.}$ [Nm]	1	2.5	5	2.5	5	15	
$M_{y,max.}$ [Nm]	10	20	40	20	40	124	
$M_{z,max.}$ [Nm]	10	20	40	20	40	124	

## Service life

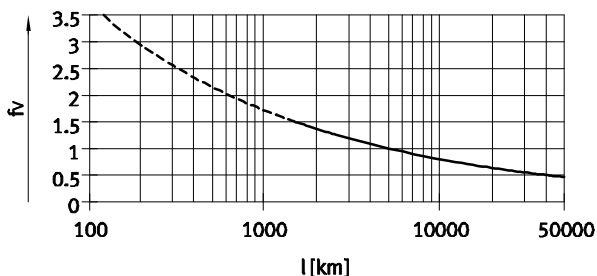
The service life of the guide depends on the load. To provide a rough indication of the service life of the guide,

the graph below plots the load comparison factor  $f_v$  against the service life.

These values are only theoretical. You must consult your local contact per-

son at Festo for load comparison factors  $f_v$  greater than 1.5.

Load comparison factor  $f_v$  as a function of service life



Example:

A user wants to move an X kg load. Using the above formula gives a value of 1.5 for the load comparison factor  $f_v$ . According to the graph, the guide would have a service life of

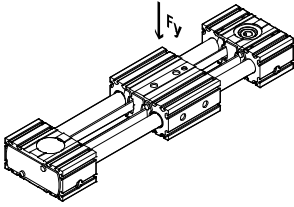
approx. 1500 km. Reducing the acceleration reduces the  $M_z$  and  $M_y$  values. A load comparison factor of 1 now gives a service life of 5000 km.

-  Note  
PositioningDrives  
engineering software  
www.festo.com

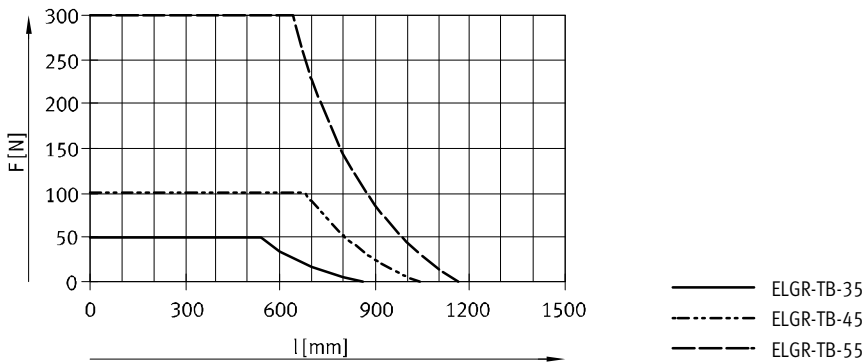
# Toothed belt axes ELGR

Technical data

## Max. load with flat mounting position

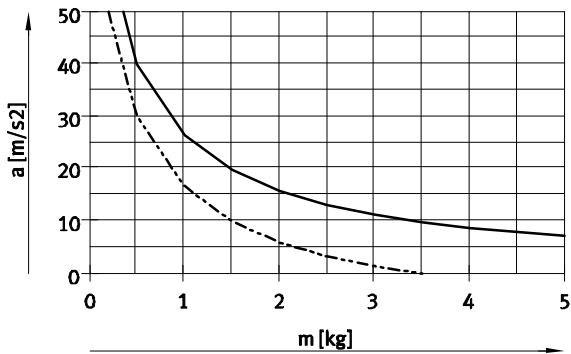


The characteristic curves in the graph correspond to the max. recommended deflection of 0.5 mm. In this case, the axis can no longer support the maximum load past a certain stroke length.

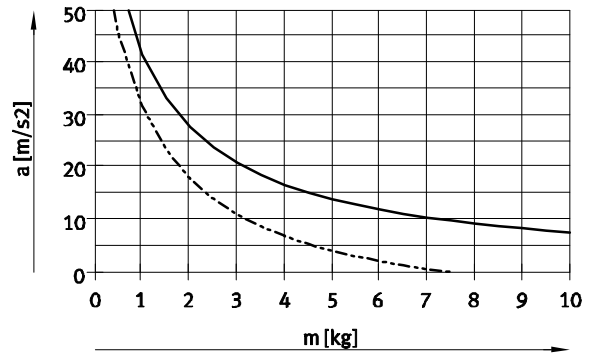


## Maximum acceleration a as a function of the payload m

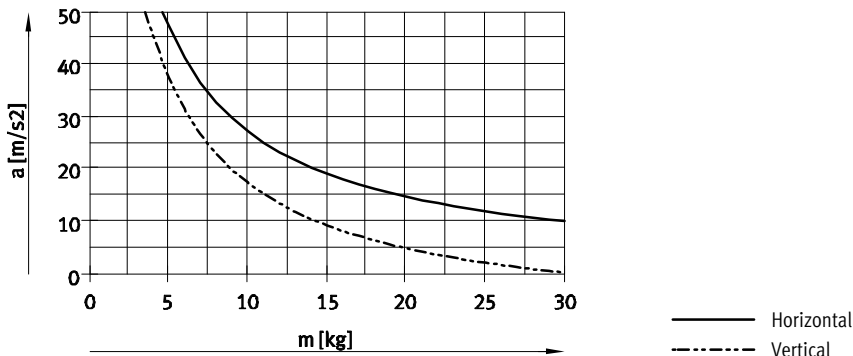
ELGR-35



ELGR-45



ELGR-55

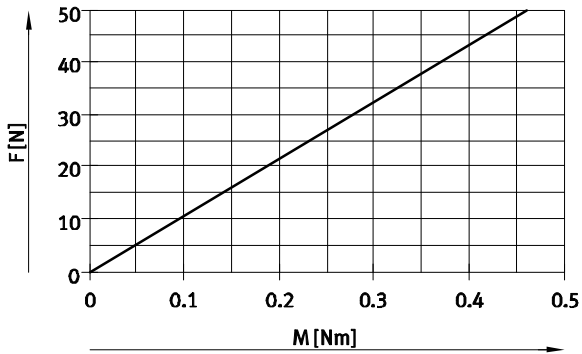


# Toothed belt axes ELGR

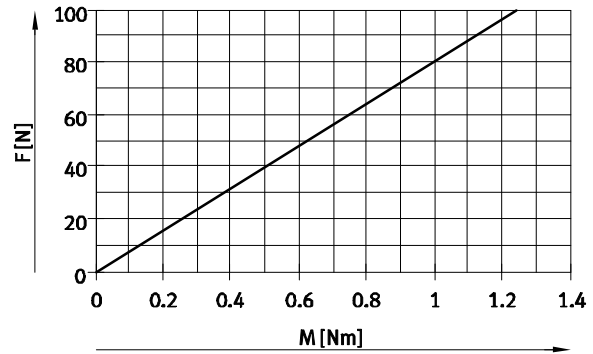
Technical data

## Feed force $F_x$ as a function of input torque M

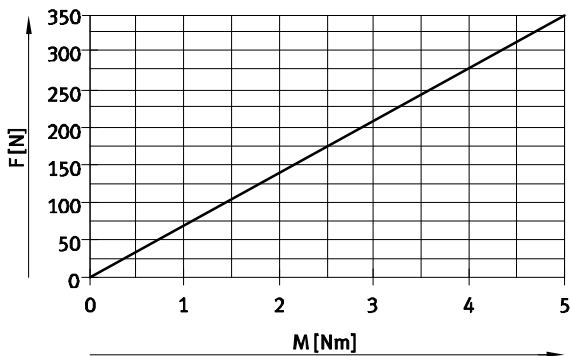
ELGR-35



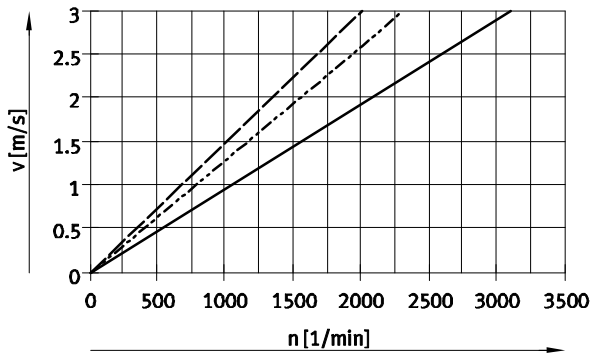
ELGR-45



ELGR-55



## Speed v as a function of rotational speed n



- ELGR-TB-35
- ELGR-TB-45
- - - ELGR-TB-55

# Toothed belt axes ELGR

Technical data

## Minimum nominal stroke

for variants with additional slide ELGR-...-ZR/ZL/ZB

Size	35		45		55	
ELGR-	ZR/ZL	ZB	ZR/ZL	ZB	ZR/ZL	ZB
Min. nominal stroke [mm]	126	202	146	242	166	282

## Stroke reserve



L18 = Nominal stroke  
L19 = Stroke reserve

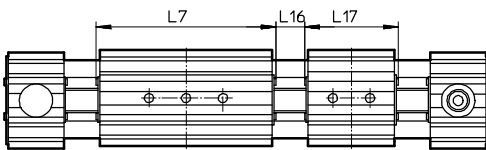
- The stroke reserve is a safety distance that can be available on both sides of the axis in addition to the nominal stroke
- The sum of the nominal stroke and 2x the stroke reserve must not exceed the maximum working stroke
- The stroke reserve length can be freely selected
- The stroke reserve is defined via the "stroke reserve" characteristic in the modular product system.

### Example:

Type ELGR-TB-45-500-20H-...  
 Nominal stroke = 500 mm  
 2x stroke reserve = 40 mm  
 Working stroke = 540 mm  
 (540 mm = 500 mm + 2 x 20 mm)

## Working stroke reduction

For standard slide or long slide with additional slide ELGR-...-ZR/ZL/ZB



L7 = Slide length  
L16 = Distance between the two slides  
L17 = Additional slide length

- For a toothed belt axis with additional slide, the working stroke is reduced by the length of the additional slide and the distance between the two slides
- If the long slide variant L is ordered, the additional slide is not extended

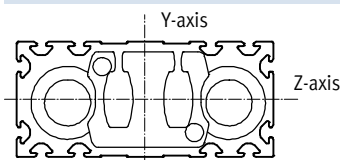
### Example:

Type ELGR-TB-35-500-...-ZR  
 Working stroke = 500 mm  
 L16 = 10 mm  
 L7, L17 = 76 mm  
 Working stroke with additional slide = 414 mm  
 (500 mm - 10 mm - 76 mm)

## Dimensions – Additional slide

Size	35	45	55
Length L17 [mm]	76	96	116
Distance between the slides L16 [mm]	≥ 0		

## Second moment of area



Size	35	45	55
ly [mm <sup>4</sup> ]	3.77x10 <sup>3</sup>	1.57x10 <sup>4</sup>	3.83x10 <sup>4</sup>
lz [mm <sup>4</sup> ]	1.89x10 <sup>5</sup>	8.08x10 <sup>5</sup>	1.85x10 <sup>6</sup>

## Recommended deflection limits

Adherence to a maximum deflection of 0.5 mm is recommended so as not to impair the functional performance of the axes. Greater deformation can result in increased friction, greater wear and reduced service life.

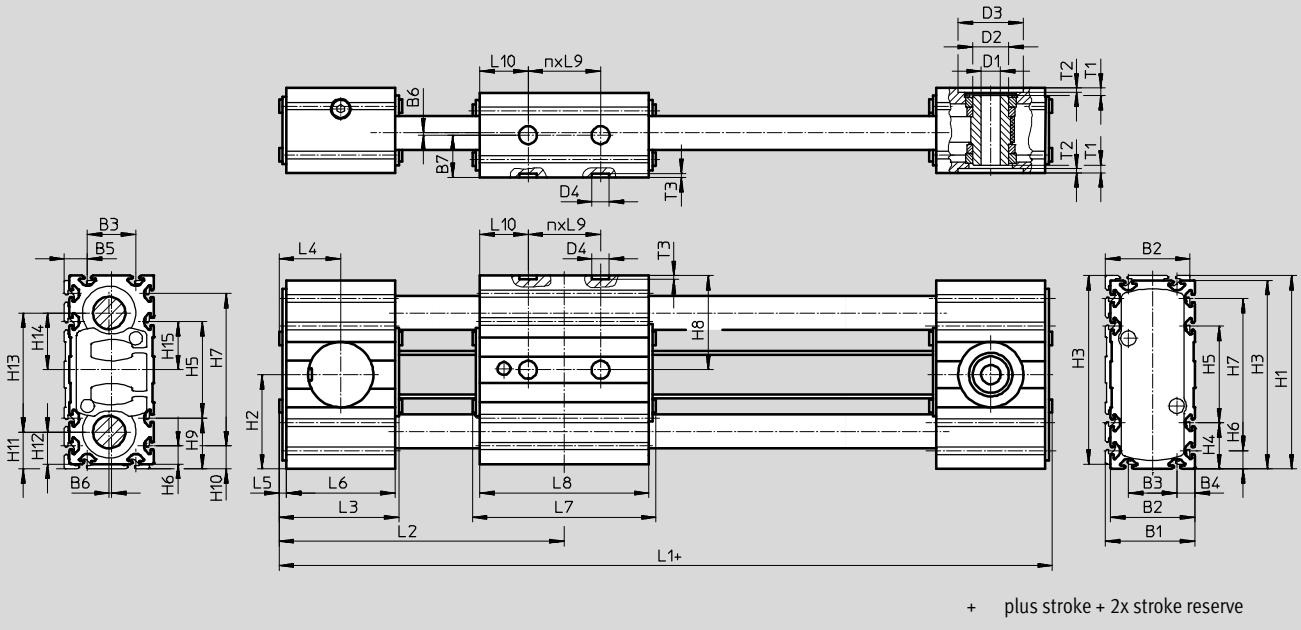
# Toothed belt axes ELGR

Technical data

FESTO

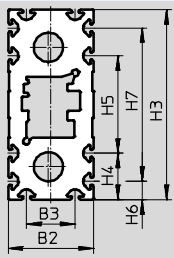
## Dimensions

Download CAD data → [www.festo.com](http://www.festo.com)

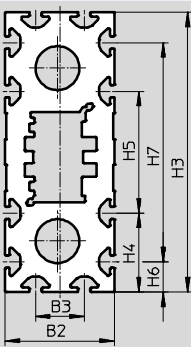


## Profile

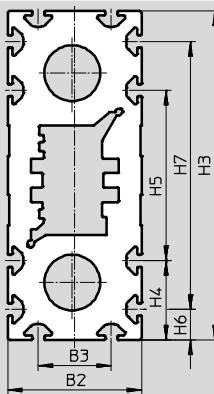
ELGR-35



ELGR-45



ELGR-55





# Toothed belt axes ELGR

Technical data

Size	B1	B2	B3	B4	B5	B6	B7	D1 ∅ H7	D2 ∅	D3 ∅ H7	D4 ∅ H7	H1	H2
35	37	35	20	7.5	9.5	1	17.5	8	15	27	7	80	39
45	47	45	20	12.5	14.5		22.5	10	20	38		117	57.5
55	57	55	30	12.5	14.5		27.5	16	25	48		137	67.5

Size	H3	H4	H5	H6	H7	H8	H9	H10	H11	H12	H13	H14
35	78	19	40	7.5	63	39	21	9.5	15.5	13.5	49	23.5
45	115	32.5	50	12.5	90	57.5	34.5	14.5	23	21	71	34.5
55	135	32.5	70	12.5	110	67.5	34.5	14.5	25.5	23.5	86	42

Size	H15	L3	L4	L5	L6	L9	T1	T2	T3
									+0.1
35	20	51	25.5	3	45	30	3.1	1.6	1.6
45	25	60	30		54	40	3	1.7	
55	35	62	31		56	40	4.5	2	

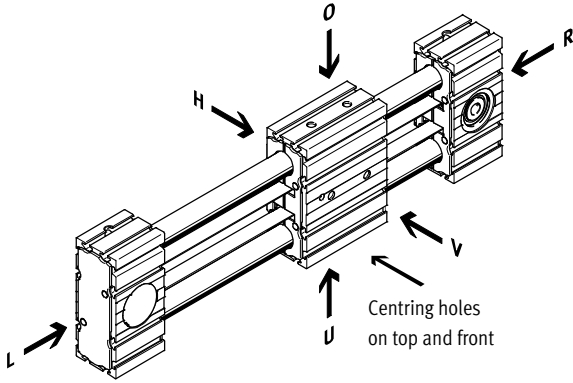
Size	L1		L2		L7		L8		L10		n	
ELGR...		-L		-L		-L		-L		-L		-L
35	178	248	89	124	76	146	70	140	20	40	1	2
45	219	309	108	153	96	186	90	180	25	50	1	2
55	243	353	120	175	116	226	110	220	35	70	1	2

# Toothed belt axes ELGR

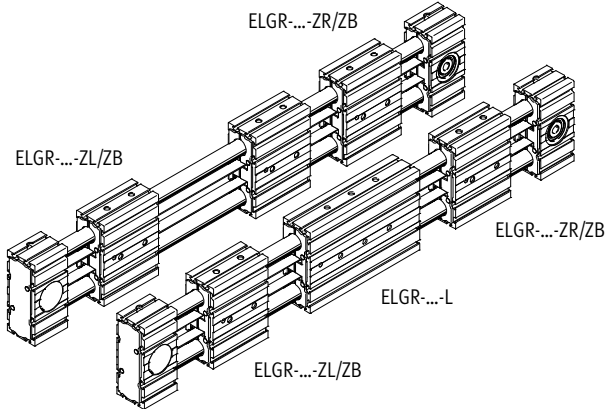
Ordering data – Modular products



**Order code**  
Mandatory data Additional slide



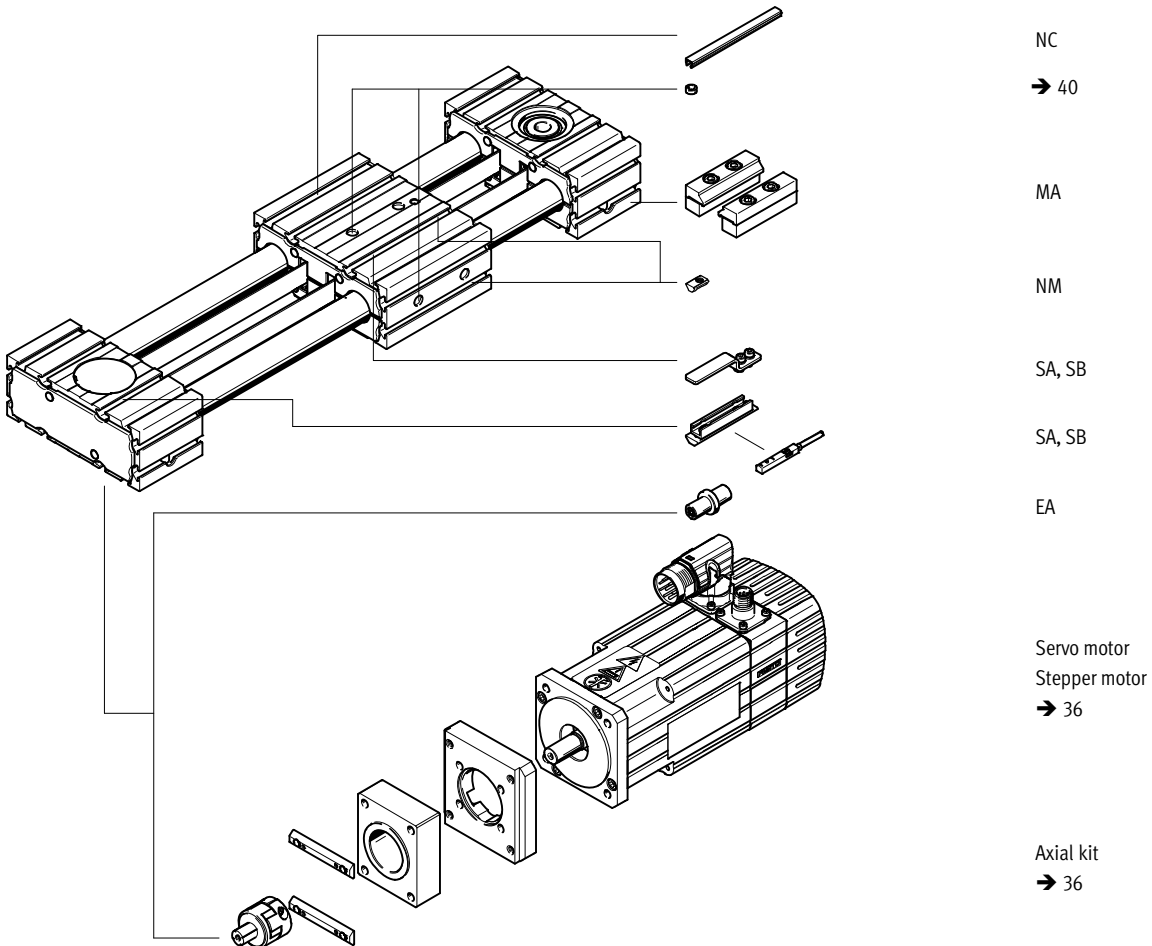
O top L left  
U underneath V front  
R right H rear



Minimum order stroke in combination with additional slide ELGR-...-ZR/ZL/ZB

Size	35		45		55	
ELGR-...	-ZR/ZL	-ZB	-ZR/ZL	-ZB	-ZR/ZL	-ZB
Min. nominal stroke [mm]	126	202	146	242	166	282

Accessories



# Toothed belt axes ELGR

Ordering data – Modular products

Ordering table							
Size	35	45	55	Condi- tions	Code		Entry code
<b>M</b> Module no.	<b>560505</b>	<b>560506</b>	<b>560507</b>				
Design	Linear axis				<b>ELGR</b>		ELGR
Drive system	Toothed belt				<b>-TB</b>		-TB
<b>O</b> Guide	Recirculating ball bearing guide						
	Plain-bearing guide				<b>-GF</b>		
<b>M</b> Sizes	35	45	55		-...		
Stroke length [mm]	1 ... 800	1 ... 1000	1 ... 1500	<b>1</b>	-...		
Stroke reserve [mm]	0 ... 999 (0 = no stroke reserve)			<b>1</b>	<b>-...H</b>		
<b>O</b> Slide design	Standard slide						
	Long slide				<b>-L</b>		
Additional slide	No additional slide						
	1 slide on right			<b>2</b>	<b>-ZR</b>		
	1 slide on left			<b>2</b>	<b>-ZL</b>		
	1 slide on right, 1 slide on left			<b>2</b>	<b>-ZB</b>		
Accessories	Accessories enclosed separately				<b>+</b>		<b>+</b>
Proximity sensor (SIES), inductive, slot type 8, PNP, N/O contact, cable 7.5 m, incl. switch lug and sensor bracket	1 ... 6				<b>...SA</b>		
Proximity sensor (SIES), inductive, slot type 8, PNP, N/C contact, cable 7.5 m, incl. switch lug and sensor bracket	1 ... 6				<b>...SB</b>		
Mounting slot cover	-	1 ... 50 (1=2pc. 500 mm long)			<b>...NC</b>		
Slot nut for mounting slot	1 ... 99				<b>...NM</b>		
Drive shaft	1 ... 4				<b>...EA</b>		
Profile mounting	1 ... 2				<b>...MA</b>		
Operating instructions	With operating instructions						
	Without operating instructions				<b>+DN</b>		

**1** ... The sum of the stroke length and 2x the stroke reserve must not exceed the maximum stroke length or be less than the minimum stroke length of 50 mm  
**2** ZR, ZL, ZB Working stroke reduction → 15

- M** Mandatory data
- O** Options

Transfer order code

**ELGR** - **TB** -  -  -  -  -  -  -  +

# Toothed belt axes ELGR, for Optimised Motion Series (OMS)

Type codes

ELGR - TB - [ ] - 45 - 500 - 0H - [ ] - ST - E - B - AT - FR

**Type**

ELGR	Linear axis
------	-------------

**Drive function**

TB	Toothed belt
----	--------------

**Guide**

-	Recirculating ball bearing guide
---	----------------------------------

**Size**

**Stroke [mm]**

**Stroke reserve**

**Slide**

-	Standard slide
---	----------------

**Motor type**

ST	Stepper motor
----	---------------

**Measuring unit**

E	Encoder
---	---------

**Brake**

-	Without
B	With brake

**Cable outlet direction**

AT	Top (standard)
AD	Underneath
AL	Left
AR	Right

**Motor position**

FR	Front right (standard)
FL	Front left
RL	Rear left
RR	Rear right

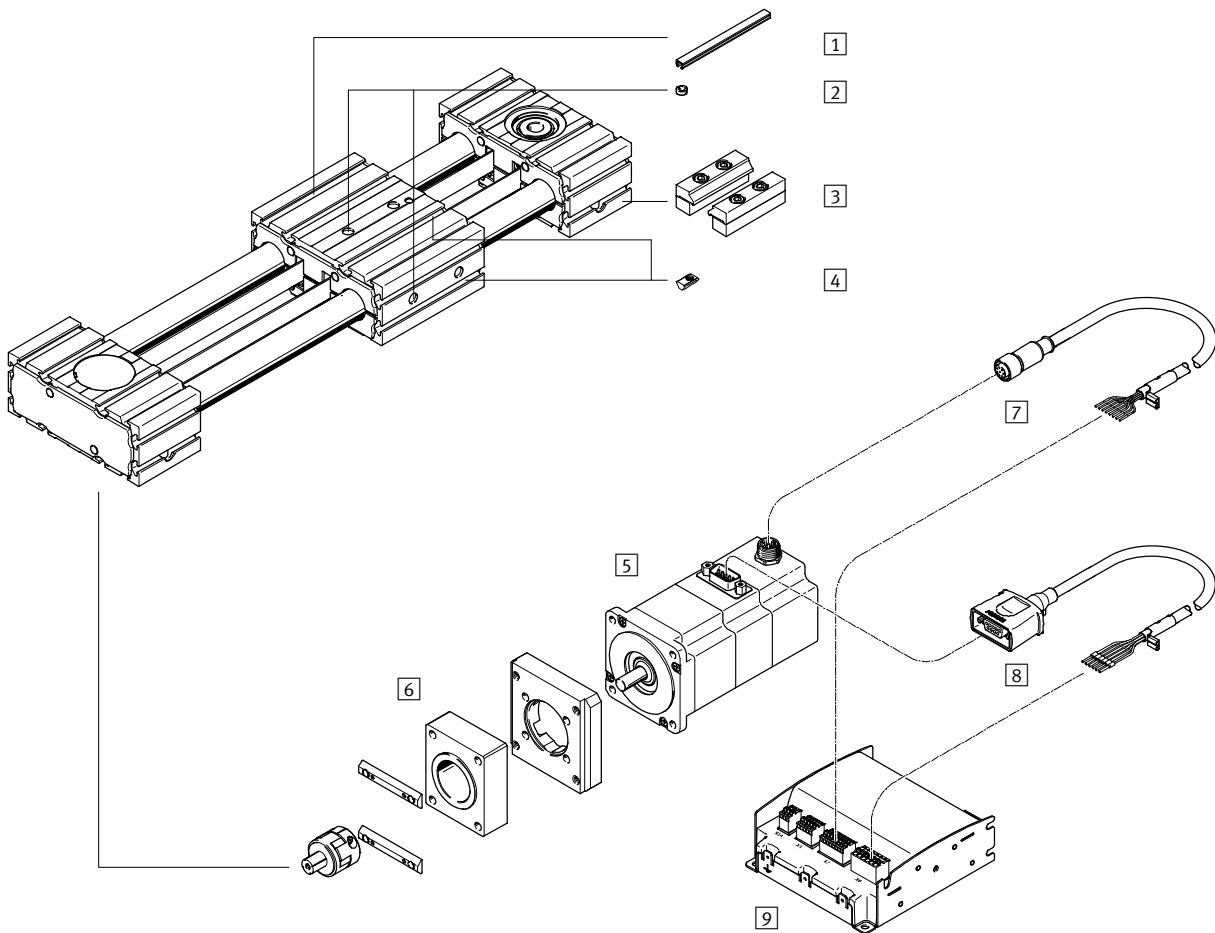
# Toothed belt axes ELGR, for Optimised Motion Series (OMS)

Type codes

→	+			2MA	+	2.5E	+	C5		DIO		N	+	DN	
<b>Cover</b>															
...NC	For mounting slot														
<b>Slot nut</b>															
...NM	For mounting slot														
<b>Profile mounting</b>															
...MA	Profile mounting														
<b>Connecting cable to motor controller</b>															
1.5E	1.5 m, straight plug connector														
2.5E	2.5 m, straight plug connector														
5E	5 m, straight plug connector														
7E	7 m, straight plug connector														
10E	10 m, straight plug connector														
<b>Controller type</b>															
C5	CMMO, 5 A														
<b>Bus protocol/activation</b>															
DIO	Digital I/O interface														
LK	IO-Link														
<b>Switching input/output</b>															
N	NPN														
P	PNP														
<b>Operating instructions</b>															
-	With operating instructions														
DN	Without operating instructions														

# Toothed belt axes ELGR, for Optimised Motion Series (OMS)

Peripherals overview



## Toothed belt axes ELGR, for Optimised Motion Series (OMS)

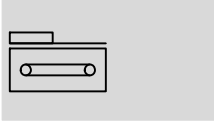
Peripherals overview




Accessories			
	Type/order code	Description	→ Page/Internet
1	Slot cover NC	<ul style="list-style-type: none"> <li>For protecting against ingress of dirt</li> </ul>	40
2	Centring sleeve ZBH	<ul style="list-style-type: none"> <li>For centring loads and attachments on the slide</li> <li>2 centring sleeves included in the scope of delivery of the axis</li> </ul>	40
3	Profile mounting MA	For mounting the axis on the bearing cap	39
4	Slot nut NM	For mounting attachments	40
5	Motor EMMS-ST	Motors specially matched to the axis, with or without brake	36
6	Axial kit EAMM	For axial motor mounting (comprises: coupling, coupling housing and motor flange)	36
7	Encoder cable NEBM	For connecting the encoder and controller	41
8	Motor cable NEBM	For connecting the motor and controller	41
9	Motor controller CMMO	For parameterising and positioning the toothed belt axis	41

# Toothed belt axes ELGR, for Optimised Motion Series (OMS)

Technical data

Function



-  - Size  
35 ... 55
-  - Stroke length  
50 ... 1 500 mm
-  - [www.festo.com](http://www.festo.com)



General technical data				
Size		35	45	55
Design		Electromechanical linear axis with toothed belt		
Guide		Recirculating ball bearing guide		
Mounting position		Any		
Standard stroke	[mm]	50, 100, 150, 200, 250, 300, 350, 400, 450, 500, 550, 600, 650, 700, 750, 800	50, 100, 150, 200, 250, 300, 350, 400, 450, 500, 550, 600, 650, 700, 750, 800, 900, 1000	50, 100, 150, 200, 250, 300, 350, 400, 450, 500, 550, 600, 650, 700, 750, 800, 900, 1000, 1100, 1200, 1300, 1400, 1500
Max. working load	[kg]	2.8	5.0	6.8
Max. feed force $F_x$	[N]	50	100	350
Max. driving torque	[Nm]	0.46	1.24	5
Max. speed	[m/s]	1.1	1.1	0.35
Max. acceleration <sup>1)</sup>	[m/s <sup>2</sup> ]	15		
Repetition accuracy	[mm]	±0.1		

1) In combination with Optimised Motion Series (OMS).  
The max. acceleration is dependent on the payload, the driving torque and the max. feed force → 27

Operating and environmental conditions		
Ambient temperature	[°C]	-10 ... +50
Degree of protection		IP20
Duty cycle	[%]	100



# Toothed belt axes ELGR, for Optimised Motion Series (OMS)

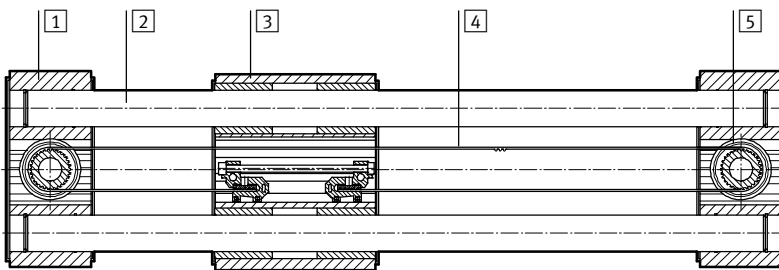
Technical data

Weight of axis/axial kit/motor [kg]			
Size	35	45	55
Basic weight with 0 mm stroke <sup>1)</sup>			
Axis/axial kit/motor	3.9	8.0	13.2
Additional weight per 1000 mm stroke	2.5	5.0	7.8
Moving mass	0.5	1.1	1.9
Slide			
Standard slide	0.5	1.0	1.8

1) Incl. slide

## Materials

Sectional view



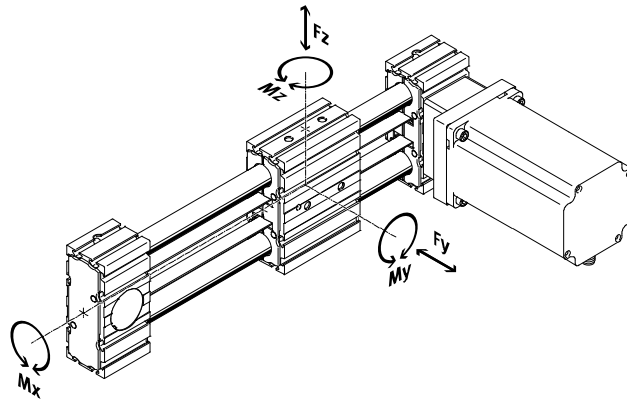
Axis		
1	Bearing cap, profile	Anodised wrought aluminium alloy
2	Guide rods	Steel
3	Slide, profile	Anodised wrought aluminium alloy
4	Toothed belt	Polychloroprene with glass cord and nylon coating
5	Belt pulley	High-alloy stainless steel
Note on materials		RoHS-compliant
		Contains paint-wetting impairment substances

# Toothed belt axes ELGR, for Optimised Motion Series (OMS)

Technical data

## Characteristic load values

The indicated forces and torques refer to the centre of the guide. The point of application of force is the point where the centre of the guide and the longitudinal centre of the slide intersect. These values must not be exceeded during dynamic operation. Special attention must be paid to the cushioning phase.



If the axis is subjected to two or more of the indicated forces and torques simultaneously, the following equation must be satisfied in addition to the indicated maximum loads:

Calculating the load comparison factor:

$$f_v = \frac{|F_{y,dyn}|}{F_{y,max.}} + \frac{|F_{z,dyn}|}{F_{z,max.}} + \frac{|M_{x,dyn}|}{M_{x,max.}} + \frac{|M_{y,dyn}|}{M_{y,max.}} + \frac{|M_{z,dyn}|}{M_{z,max.}} \leq 1$$

Permissible forces and torques for a service life of 5000 km				
Guide		Recirculating ball bearing guide		
Size		35	45	55
$F_{y,max.}, F_{z,max.}^{1)}$	[N]	50	100	300
Standard slide				
$M_{x,max.}$	[Nm]	2.5	5	15
$M_{y,max.}$	[Nm]	8	16	48
$M_{z,max.}$	[Nm]	8	16	48

1) In combination with Optimised Motion Series (OMS) max. working load limited only by drive system

## Service life

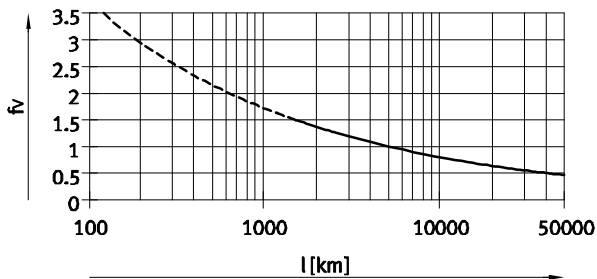
The service life of the guide depends on the load. To provide a rough indication of the service life of the guide,

the graph below plots the load comparison factor  $f_v$  against the service life.

These values are only theoretical. You must consult your local contact per-

son at Festo for load comparison factors  $f_v$  greater than 1.5.

Load comparison factor  $f_v$  as a function of service life



Example:

A user wants to move an X kg load. Using the above formula gives a value of 1.5 for the load comparison factor  $f_v$ . According to the graph, the guide would have a service life of

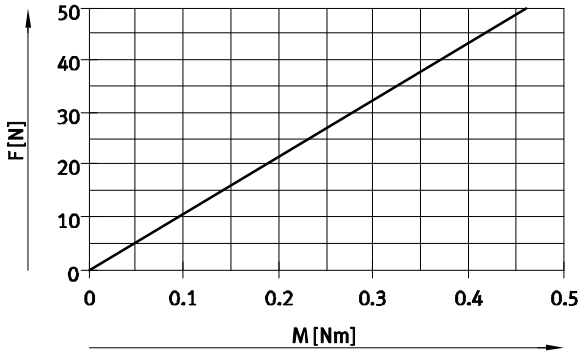
approx. 1500 km. Reducing the acceleration reduces the  $M_z$  and  $M_y$  values. A load comparison factor of 1 now gives a service life of 5000 km.

# Toothed belt axes ELGR, for Optimised Motion Series (OMS)

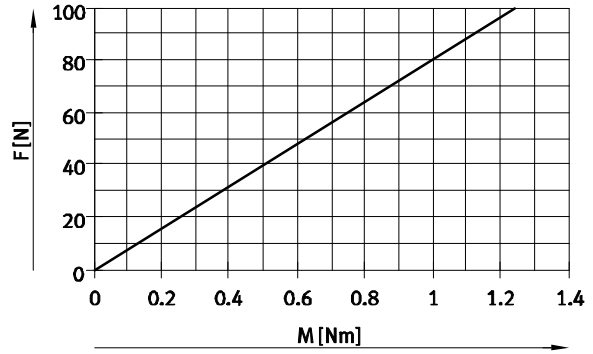
Technical data

Feed force  $F_x$  as a function of input torque  $M$

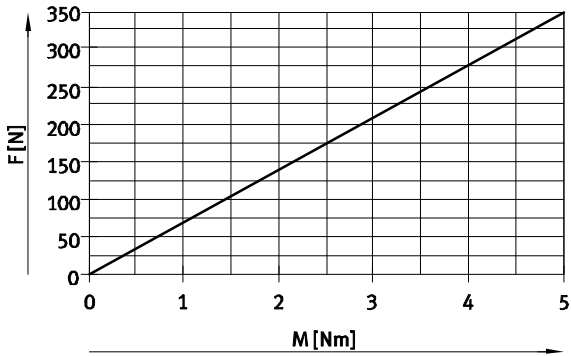
ELGR-35



ELGR-45

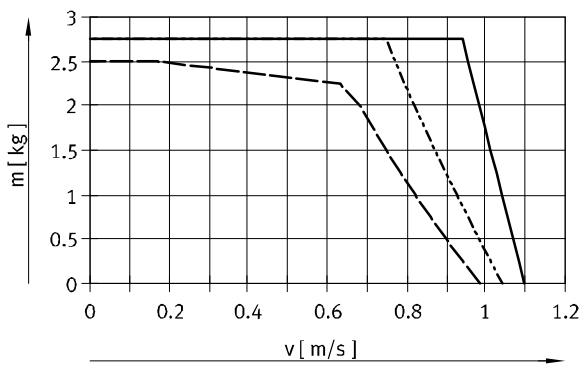


ELGR-55

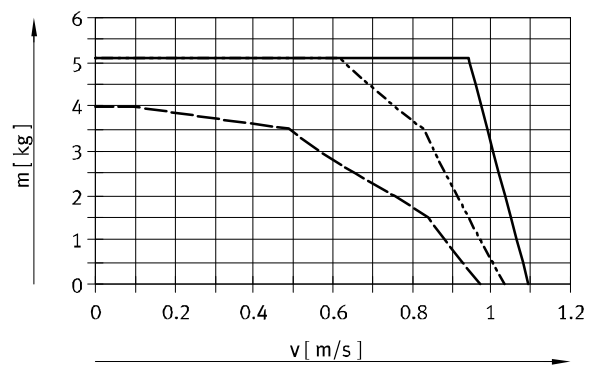


Max. payload  $m$  as a function of acceleration  $a$  and speed  $v^1$

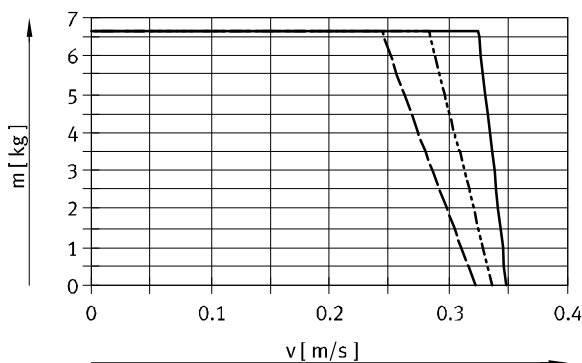
ELGR-35



ELGR-45



ELGR-55



- 5 m/s<sup>2</sup>
- - - 10 m/s<sup>2</sup>
- · - 15 m/s<sup>2</sup>

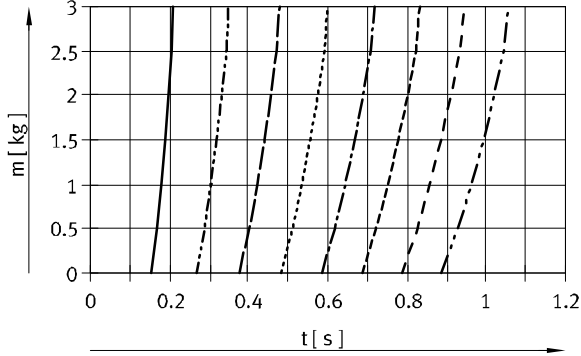
1) In combination with Optimised Motion Series (OMS)

# Toothed belt axes ELGR, for Optimised Motion Series (OMS)

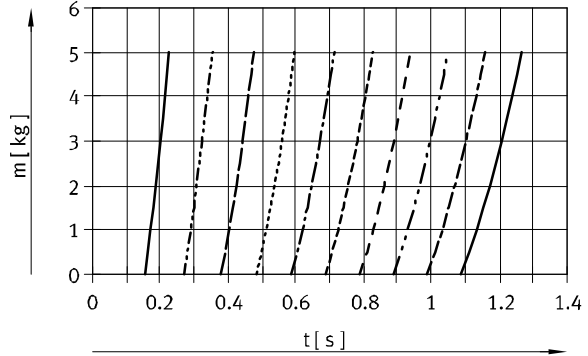
Technical data

## Max. payload $m$ as a function of stroke $l$ and positioning time $t^1)$

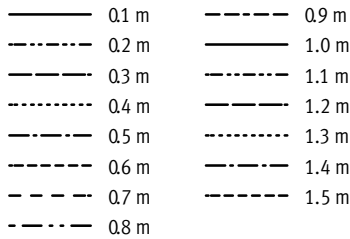
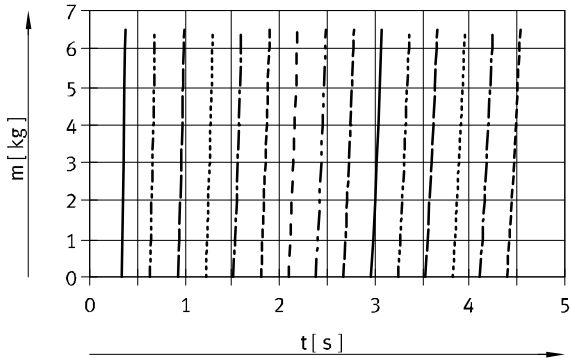
ELGR-35



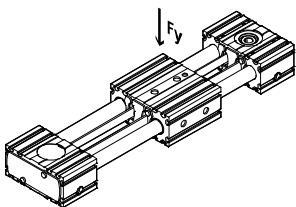
ELGR-45



ELGR-55

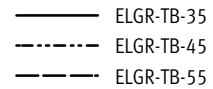
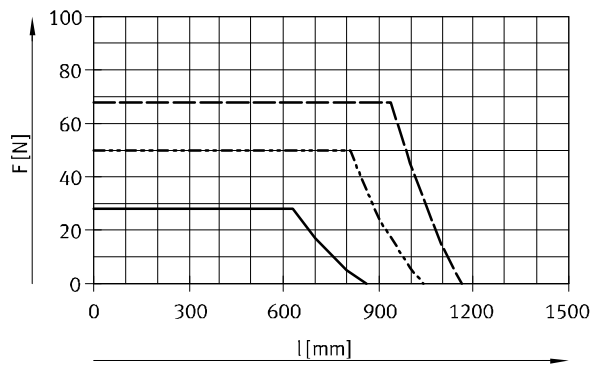


## Max. load with flat mounting position<sup>1)</sup>



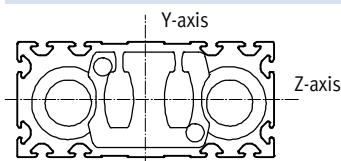
The characteristic curves in the graph correspond to the max. recommended deflection of 0.5 mm.

In this case, the axis can no longer support the maximum load past a certain stroke length.



<sup>1)</sup> In combination with Optimised Motion Series (OMS) max. working load limited only by drive system

## Second moment of area



Size	35	45	55
$I_y$ [mm <sup>4</sup> ]	$3.77 \times 10^3$	$1.57 \times 10^4$	$3.83 \times 10^4$
$I_z$ [mm <sup>4</sup> ]	$1.89 \times 10^5$	$8.08 \times 10^5$	$1.85 \times 10^6$

## Recommended deflection limits

Adherence to a maximum deflection of 0.5 mm is recommended so as not to impair the functional performance of

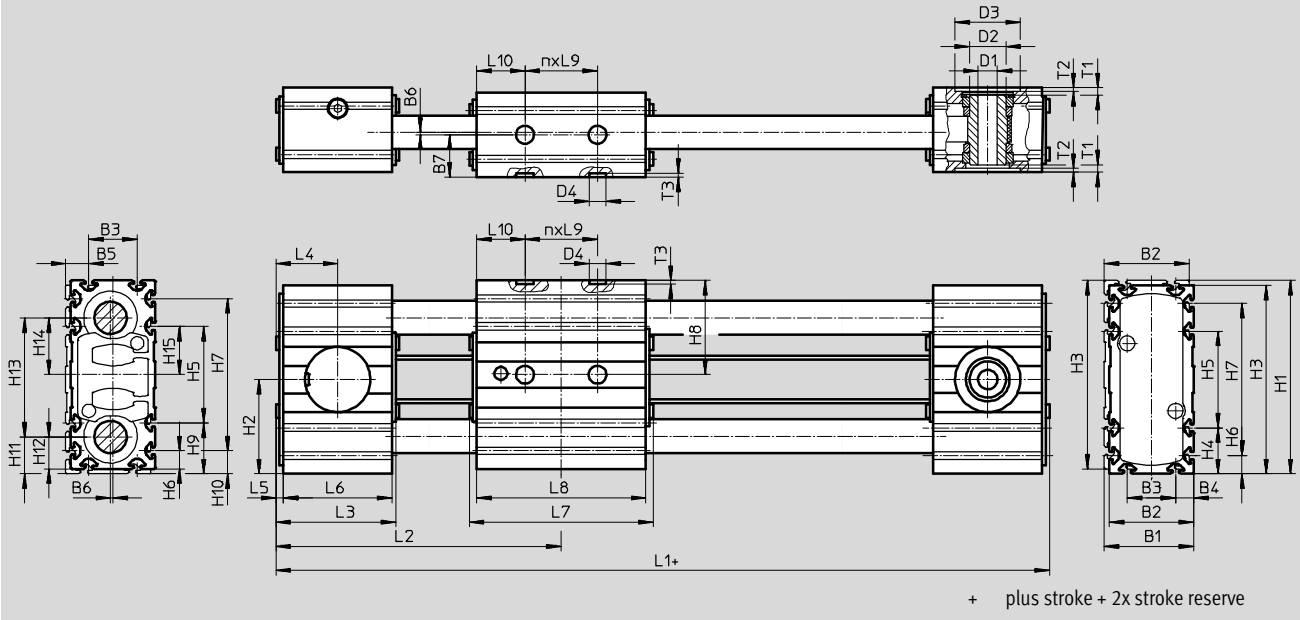
the axes. Greater deformation can result in increased friction, greater wear and reduced service life.

# Toothed belt axes ELGR, for Optimised Motion Series (OMS)

Technical data

**Dimensions**

Download CAD data → [www.festo.com](http://www.festo.com)



Size	B1	B2	B3	B4	B5	B6	B7	D1 ∅ H7	D2 ∅	D3 ∅ H7
35	37	35	20	7.5	9.5	1	17.5	8	15	27
45	47	45	20	12.5	14.5		22.5	10	20	38
55	57	55	30	12.5	14.5		27.5	16	25	48

Size	D4 ∅ H7	H1	H2	H3	H4	H5	H6	H7	H8	H9
35	7	80	39	78	19	40	7.5	63	39	21
45		117	57.5	115	32.5	50	12.5	90	57.5	34.5
55		137	67.5	135	32.5	70	12.5	110	67.5	34.5

Size	H10	H11	H12	H13	H14	H15	L1	L2	L3	L4
35	9.5	15.5	13.5	49	23.5	20	178	89	51	25.5
45	14.5	23	21	71	34.5	25	219	108	60	30
55	14.5	25.5	23.5	86	42	35	243	120	62	31

Size	L5	L6	L7	L8	L9	L10	T1	T2	T3	n
									+0.1	
35	3	45	76	70	30	20	3.1	1.6	1.6	1
45		54	96	90	40	25	3	1.7		1
55		56	116	110	40	35	4.5	2		1

# Toothed belt axes ELGR, for Optimised Motion Series (OMS)

Technical data

**Dimensions**

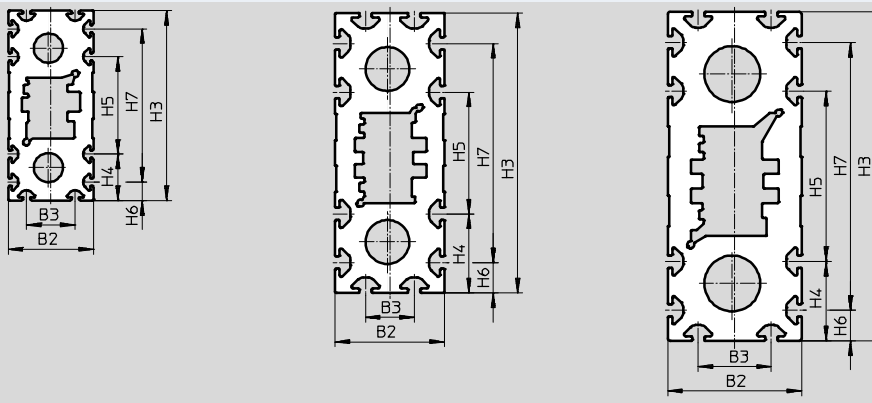
Download CAD data → [www.festo.com](http://www.festo.com)

Profile

ELGR-35

ELGR-45

ELGR-55



Size	B2	B3	H3	H4
35	35	20	78	19
45	45	20	115	32.5
55	55	30	135	32.5

Size	H5	H6	H7
35	40	7.5	63
45	50	12.5	90
55	70	12.5	110

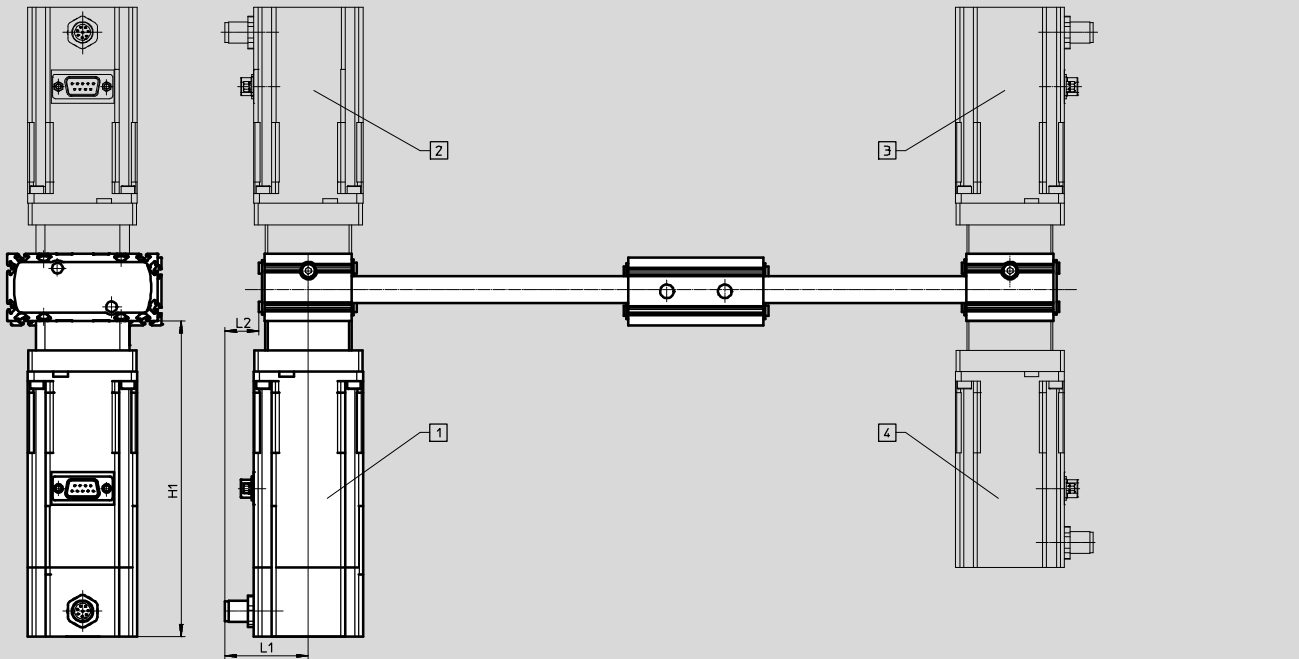
# Toothed belt axes ELGR, for Optimised Motion Series (OMS)

Technical data

**Dimensions**

Download CAD data → [www.festo.com](http://www.festo.com)

Motor attachment variants



- 1 ELGR-...-FL (motor at front left)
- 2 ELGR-...-RL (motor at rear left)
- 3 ELGR-...-RR (motor at rear right)
- 4 ELGR-...-FR (motor at front right)

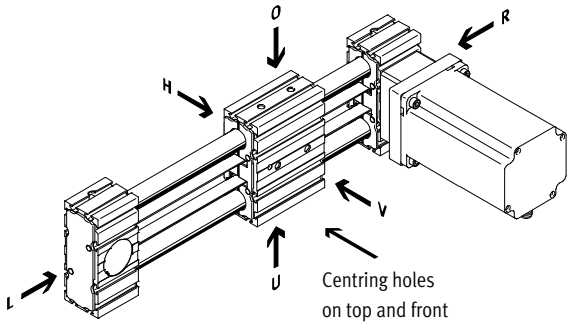
Size	H1		L1		L2	
	ELGR-...	-B	ELGR-...	-B	ELGR-...	-B
35	127.5	163	43.2	44	17.7	18
45	152.4	192.5	58	58	28	28
55	190	230	58	58	27	27

# Toothed belt axes ELGR, for Optimised Motion Series (OMS)

Ordering data – Modular products

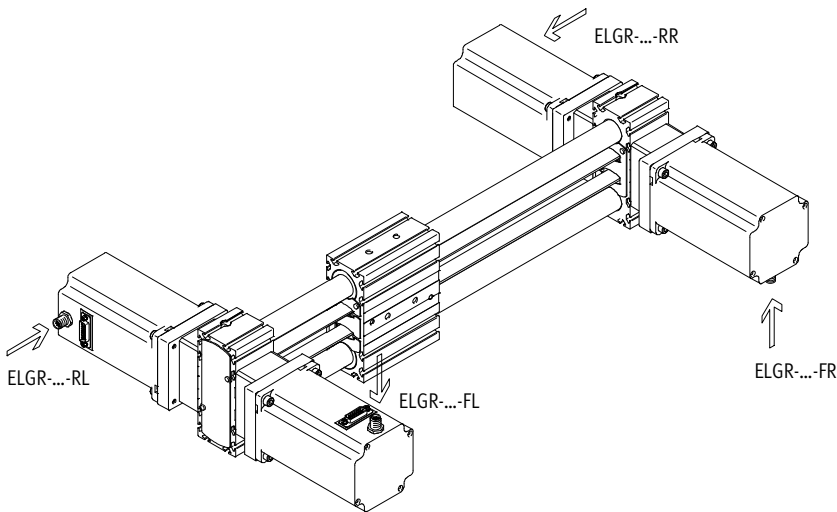
**Order code**

Mandatory data



O	top	L	left
U	underneath	V	front
R	right	H	rear

**Motor attachment variants**

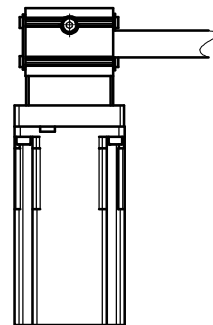
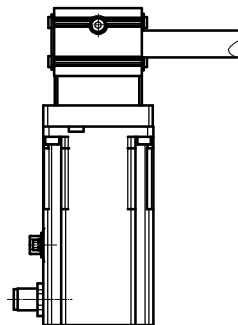
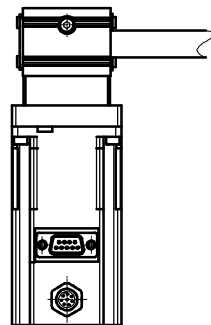
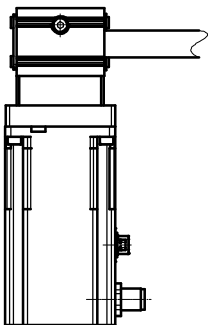
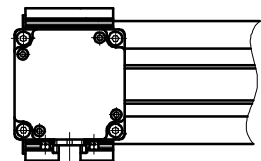
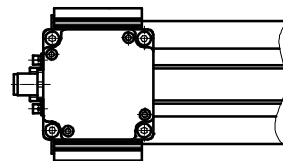
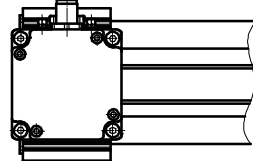
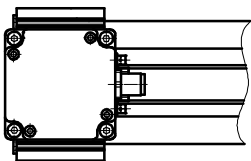


ELGR...-AR – right

ELGR...-AT – top

ELGR...-AL – left

ELGR...-AD – underneath

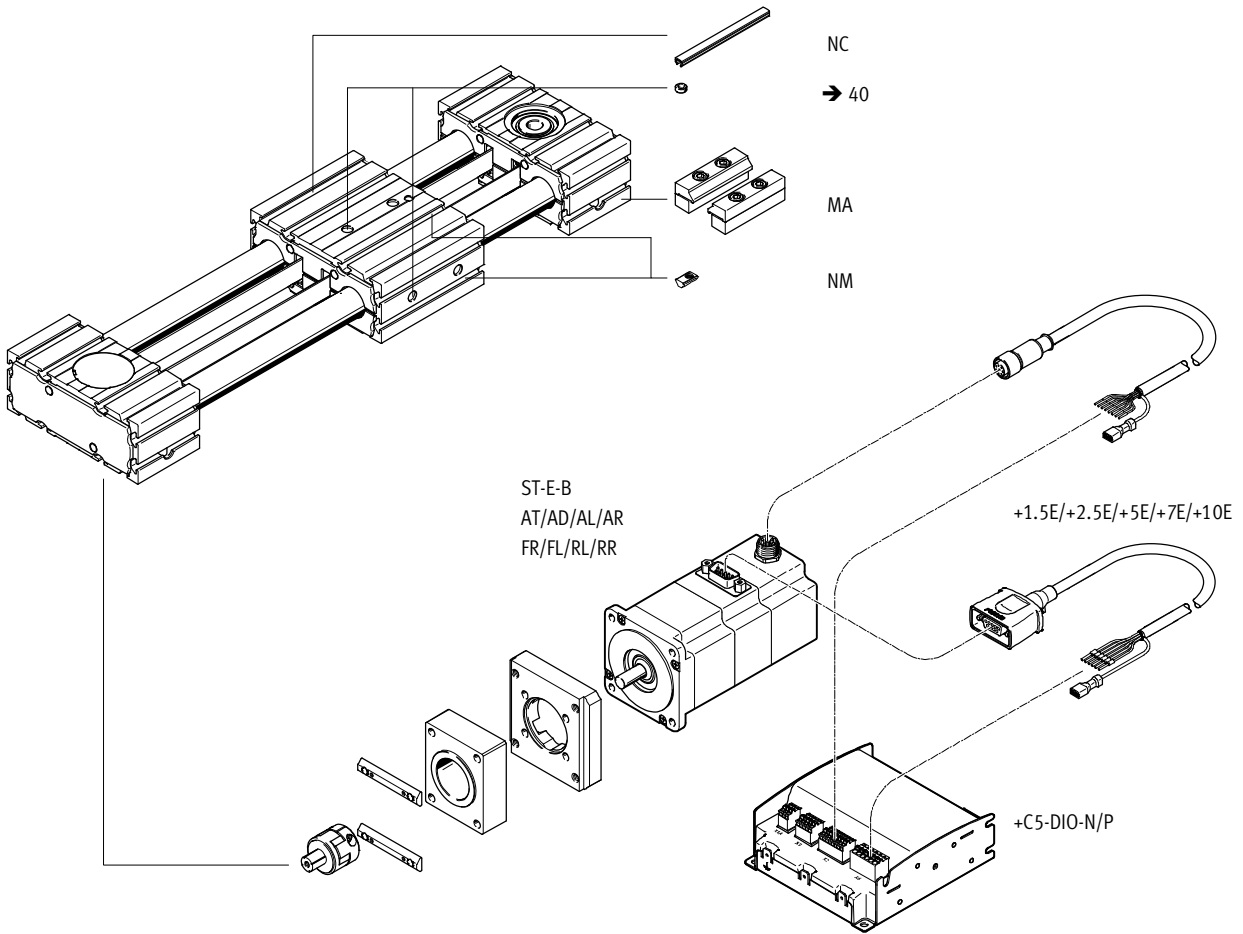





# Toothed belt axes ELGR, for Optimised Motion Series (OMS)

Ordering data – Modular product system

Accessories



 Note  
 The associated axial kit (→ 36) is automatically included in the scope of delivery.  
 Motor and axial kit are installed on delivery.

## Toothed belt axes ELGR, for Optimised Motion Series (OMS)

Ordering data – Modular product system

Ordering table						
Size	35	45	55	Condi- tions	Code	Entry code
<b>M</b> Module no.	<b>560505</b>	<b>560506</b>	<b>560507</b>			
Design	Linear axis				<b>ELGR</b>	ELGR
Drive system	Toothed belt				<b>-TB</b>	-TB
Sizes	35	45	55		-...	
Standard stroke [mm]	50, 100, 150, 200, 250, 300, 350, 400, 450, 500, 550, 600, 650, 700, 750, 800	50, 100, 150, 200, 250, 300, 350, 400, 450, 500, 550, 600, 650, 700, 750, 800, 900, 1000	50, 100, 150, 200, 250, 300, 350, 400, 450, 500, 550, 600, 650, 700, 750, 800, 900, 1000, 1100, 1200, 1300, 1400, 1500			
Stroke reserve [mm]	0 mm				<b>-OH</b>	-OH
Slide design	Standard slide					
Motor type	Stepper motor				<b>-ST</b>	-ST
Measuring unit	Encoder				<b>-E</b>	-E
Brake	Without					
	With brake				<b>B</b>	
Cable outlet direction	Top (standard)				<b>-AT</b>	
	Underneath				<b>-AD</b>	
	Left				<b>-AL</b>	
	Right				<b>-AR</b>	
Motor position	Front right (standard)				<b>-FR</b>	
	Front left				<b>-FL</b>	
	Rear left				<b>-RL</b>	
	Rear right				<b>-RR</b>	

**M** Mandatory data

**O** Options

Transfer order code

**ELGR** -  **TB** -  -  -  **OH** -  **ST** -  **E** -  -  -

# Toothed belt axes ELGR, for Optimised Motion Series (OMS)

Ordering data – Modular product system

Ordering table						
Size	35	45	55	Condi- tions	Code	Entry code
Accessories	Accessories enclosed separately				+	+
<input type="checkbox"/> Mounting slot cover	–	1 ... 50 (1=2pc. 500 mm long)			...NC	
Slot nut for mounting slot	1 ... 99				...NM	
Profile mounting	1 ... 2				...MA	
<input type="checkbox"/> Connecting cable to motor controller, suitable for use with energy chains	Without					
	1.5 m, straight plug connector				+1.5E	
	2.5 m, straight plug connector				+2.5E	
	5 m, straight plug connector				+5E	
	7 m, straight plug connector				+7E	
	10 m, straight plug connector				+10E	
Controller type	CMMO, 5 A				+C5	+C5
Bus protocol/activation	Digital I/O interface				DIO	
	IO-Link				LK	
Switching input/output	NPN			<input type="checkbox"/>	N	
	PNP				P	
Operating instructions	With operating instructions					
	Without operating instructions				+DN	

N Not with LK

- Mandatory data
- Options

Transfer order code

+  -  -  -  + C5 -  -  +

# Toothed belt axes ELGR

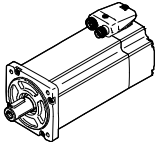
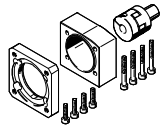



Accessories

FESTO



Note

Depending on the combination of motor and drive, it may not be possible to reach the maximum feed force of the drive.

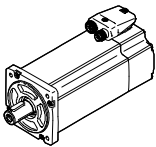
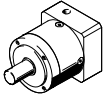
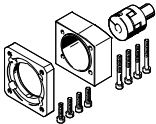

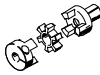

Permissible axis/motor combinations with axial kit – Without gear unit					Technical data → Internet: eamm-a
Motor <sup>1)</sup>	Axial kit	Axial kit comprises:			
		Motor flange	Coupling	Coupling housing	
					
Type	Part No. Type	Part No. Type	Part No. Type	Part No. Type	
<b>ELGR-35</b>					
With servo motor					
<b>EMMS-AS-55-...</b>	<b>1133400</b> <b>EAMM-A-R27-55A</b>	<b>558176</b> <b>EAMF-A-38A-55A</b>	<b>557999</b> <b>EAMD-19-15-9-8X10</b>	<b>1133397</b> <b>EAMK-A-R27-38A</b>	
With stepper motor					
<b>EMMS-ST-57-...<sup>2)</sup></b>	<b>1133403</b> <b>EAMM-A-R27-57A</b>	<b>560692</b> <b>EAMF-A-38A-57A</b>	<b>561292</b> <b>EAMD-16-15-6.35-8X10</b>	<b>1133397</b> <b>EAMK-A-R27-38A</b>	
With integrated drive					
<b>EMCA-EC-67-...</b>	<b>1456619</b> <b>EAMM-A-R27-67A</b>	<b>1490100</b> <b>EAMF-A-38A-67A</b>	<b>557999</b> <b>EAMD-19-15-9-8X10</b>	<b>1133397</b> <b>EAMK-A-R27-38A</b>	
<b>ELGR-45</b>					
With servo motor					
<b>EMME-AS-60-...</b>	<b>2224996</b> <b>EAMM-A-R38-60P</b>	<b>1987412</b> <b>EAMF-A-38A-60P</b>	<b>1453861</b> <b>EAMD-28-22-14-10X12</b>	<b>1133398</b> <b>EAMK-A-R38-38A</b>	
<b>EMMS-AS-70-...</b>	<b>1133401</b> <b>EAMM-A-R38-70A</b>	<b>558018</b> <b>EAMF-A-38A-70A</b>	<b>558000</b> <b>EAMD-25-22-11-10X12</b>	<b>1133398</b> <b>EAMK-A-R38-38A</b>	
With stepper motor					
<b>EMMS-ST-57-...</b>	<b>1578138</b> <b>EAMM-A-R38-57A</b>	<b>560692</b> <b>EAMF-A-38A-57A</b>	<b>561293</b> <b>EAMD-25-22-6.35-10X12</b>	<b>1133398</b> <b>EAMK-A-R38-38A</b>	
<b>EMMS-ST-87-...<sup>2)</sup></b>	<b>1133404</b> <b>EAMM-A-R38-87A</b>	<b>560693</b> <b>EAMF-A-38A-87A</b>	<b>558000</b> <b>EAMD-25-22-11-10X12</b>	<b>1133398</b> <b>EAMK-A-R38-38A</b>	
<b>ELGR-55</b>					
With servo motor					
<b>EMMS-AS-70-...</b>	<b>1578139</b> <b>EAMM-A-R48-70A</b>	<b>558025</b> <b>EAMF-A-48A-70A</b>	<b>558001</b> <b>EAMD-32-32-11-16X20</b>	<b>1133399</b> <b>EAMK-A-R48-48A</b>	
<b>EMME-AS-80-...</b>	<b>2225090</b> <b>EAMM-A-R48-80P</b>	<b>2043427</b> <b>EAMF-A-48A-80P</b>	<b>558002</b> <b>EAMD-42-40-19-16X25</b>	<b>1133399</b> <b>EAMK-A-R48-48A</b>	
<b>EMMS-AS-100-...</b>	<b>1133402</b> <b>EAMM-A-R48-100A</b>	<b>558020</b> <b>EAMF-A-48A-100A</b>	<b>558002</b> <b>EAMD-42-40-19-16X25</b>	<b>1133399</b> <b>EAMK-A-R48-48A</b>	
With stepper motor					
<b>EMMS-ST-87-...<sup>2)</sup></b>	<b>1133405</b> <b>EAMM-A-R48-87A</b>	<b>560695</b> <b>EAMF-A-48A-87A</b>	<b>558001</b> <b>EAMD-32-32-11-16X20</b>	<b>1133399</b> <b>EAMK-A-R48-48A</b>	

1) The input torque must not exceed the maximum permissible transferable torque of the axial kit

2) Motors used in combination with Optimised Motion Series (OMS)

# Toothed belt axes ELGR

Accessories

Permissible axis/motor combinations with axial kit – With gear unit						Technical data → Internet: eamm-a
Motor <sup>1)</sup>	Gear unit	Axial kit	Axial kit comprises:			
			Motor flange	Coupling	Coupling housing	
						
Type		Part No. Type	Part No.. Type	Part No. Type	Part No. Type	
<b>ELGR-35</b>						
With servo motor						
EMME-AS-40-...	EMGA-40-P-G...-EAS-40	1456622 EAMM-A-R27-40G	1460097 EAMF-A-38A-40G	557998 EAMD-19-15-10-8X10	1133397 EAMK-A-R27-38A	
EMMS-AS-40-...	EMGA-40-P-G...-SAS-40	1456622 EAMM-A-R27-40G	1460097 EAMF-A-38A-40G	557998 EAMD-19-15-10-8X10	1133397 EAMK-A-R27-38A	
With stepper motor						
EMMS-ST-42-...	EMGA-40-P-G...-SST-42	1456622 EAMM-A-R27-40G	1460097 EAMF-A-38A-40G	557998 EAMD-19-15-10-8X10	1133397 EAMK-A-R27-38A	
With integrated drive						
EMCA-EC-67-...	EMGC-40-...	1456622 EAMM-A-R27-40G	1460097 EAMF-A-38A-40G	557998 EAMD-19-15-10-8X10	1133397 EAMK-A-R27-38A	
<b>ELGR-45</b>						
With servo motor						
EMME-AS-40-...	EMGA-40-P-G...-EAS-40	1456623 EAMM-A-R38-40G	1460097 EAMF-A-38A-40G	1453860 EAMD-25-22-10-10X12	1133398 EAMK-A-R38-38A	
EMMS-AS-40-...	EMGA-40-P-G...-SAS-40	1456623 EAMM-A-R38-40G	1460097 EAMF-A-38A-40G	1453860 EAMD-25-22-10-10X12	1133398 EAMK-A-R38-38A	
EMMS-AS-55-...	EMGA-60-P-G...-SAS-55	2310075 EAMM-A-R38-60G	558017 EAMF-A-38A-60G/H	558000 EAMD-25-22-11-10X12	1133398 EAMK-A-R38-38A	
EMME-AS-60-...	EMGA-60-P-G...-EAS-60	1456630 EAMM-A-R38-60H	558017 EAMF-A-38A-60G/H	1453861 EAMD-28-22-14-10X12	1133398 EAMK-A-R38-38A	
EMMS-AS-70-...	EMGA-60-P-G...-SAS-70	2310075 EAMM-A-R38-60G	558017 EAMF-A-38A-60G/H	558000 EAMD-25-22-11-10X12	1133398 EAMK-A-R38-38A	
With stepper motor						
EMMS-ST-42-...	EMGA-40-P-G...-SST-42	1456623 EAMM-A-R38-40G	1460097 EAMF-A-38A-40G	1453860 EAMD-25-22-10-10X12	1133398 EAMK-A-R38-38A	
EMMS-ST-57-...	EMGA-60-P-G...-SST-57	2310075 EAMM-A-R38-60G	558017 EAMF-A-38A-60G/H	558000 EAMD-25-22-11-10X12	1133398 EAMK-A-R38-38A	
With integrated drive						
EMCA-EC-67-...	EMGC-40-...	1456623 EAMM-A-R38-40G	1460097 EAMF-A-38A-40G	1453860 EAMD-25-22-10-10X12	1133398 EAMK-A-R38-38A	
	EMGC-60-...	1456630 EAMM-A-R38-60H	558017 EAMF-A-38A-60G/H	1453861 EAMD-28-22-14-10X12	1133398 EAMK-A-R38-38A	

1) The input torque must not exceed the maximum permissible transferable torque of the axial kit

# Toothed belt axes ELGR

Accessories

FESTO

Permissible axis/motor combinations with axial kit – With gear unit						Technical data → Internet: eamm-a
Motor <sup>1)</sup>	Gear unit	Axial kit	Axial kit comprises:			
			Motor flange	Coupling	Coupling housing	
Type		Part No. Type	Part No.. Type	Part No. Type	Part No. Type	
<b>ELGR-55</b>						
With servo motor						
EMMS-AS-55-...	EMGA-60-P-G...-SAS-55	2374780 EAMM-A-R48-60G	558019 EAMF-A-48A-60G/H	558001 EAMD-32-32-11-16X20	1133399 EAMK-A-R48-48A	
EMME-AS-60-...	EMGA-60-P-G...-EAS-60	1456633 EAMM-A-R48-60H	558019 EAMF-A-48A-60G/H	1377840 EAMD-32-32-14-16X20	1133399 EAMK-A-R48-48A	
EMMS-AS-70-...	EMGA-60-P-G...-SAS-70	2374780 EAMM-A-R48-60G	558019 EAMF-A-48A-60G/H	558001 EAMD-32-32-11-16X20	1133399 EAMK-A-R48-48A	
With stepper motor						
EMMS-ST-57-...	EMGA-60-P-G...-SST-57	2374780 EAMM-A-R48-60G	558019 EAMF-A-48A-60G/H	558001 EAMD-32-32-11-16X20	1133399 EAMK-A-R48-48A	
With integrated drive						
EMCA-EC-67-...	EMGC-60-...	1456633 EAMM-A-R48-60H	558019 EAMF-A-48A-60G/H	1377840 EAMD-32-32-14-16X20	1133399 EAMK-A-R48-48A	

1) The input torque must not exceed the maximum permissible transferable torque of the axial kit

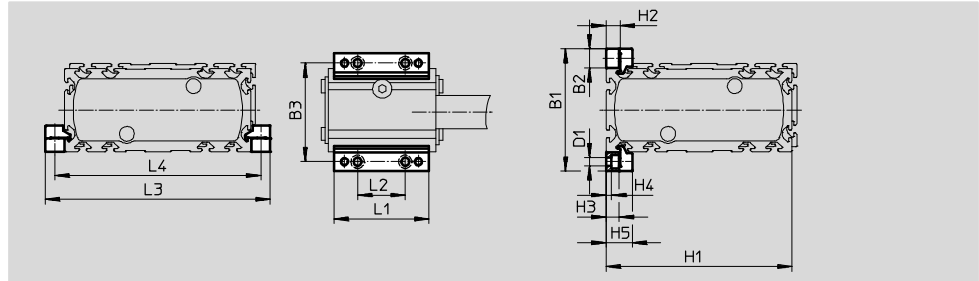
# Toothed belt axes ELGR

Accessories



**Profile mounting MUE**  
(Order code MA)

Materials:  
Anodised aluminium  
RoHS-compliant

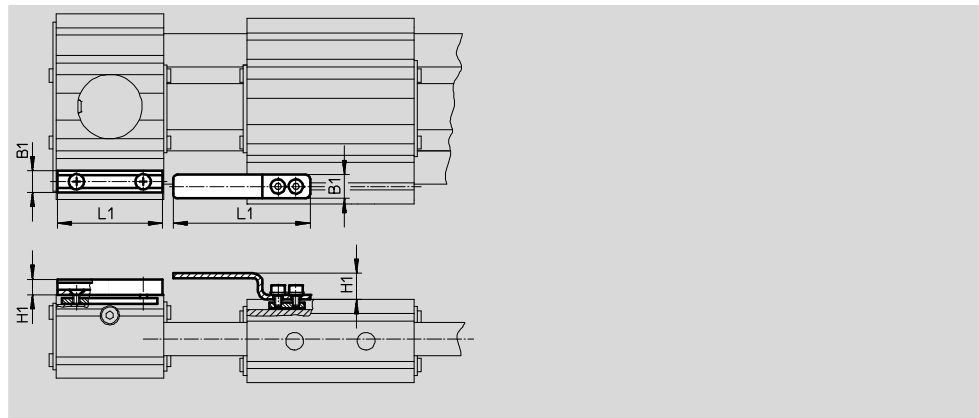


Dimensions and ordering data								
For size	B1	B2	B3	D1 ∅	H1	H2	H3	H4
35	51	8	43	3.4	78	6	5.5	2.3
45	69	12	57	5.5	115	10	9	3.2
55	79	12	67	5.5	135	10	9	3.2

For size	H5	L1	L2	L3	L4	Weight [g]	Part No.	Type
35	11	40	20	94	86	20	<b>558042</b>	<b>MUE-50</b>
45	17.5	52	40	139	127	32	<b>562238</b>	<b>MUE-45</b>
55	17.5	52	40	159	147	32	<b>562238</b>	<b>MUE-45</b>

**Sensor bracket EAPM-...-SHS,**  
**switch lug EAPM-...-SLS**  
(Order code SA/SB)

Materials:  
Switch lug: Galvanised steel  
Sensor bracket: Wrought aluminium  
alloy, anodised  
RoHS-compliant



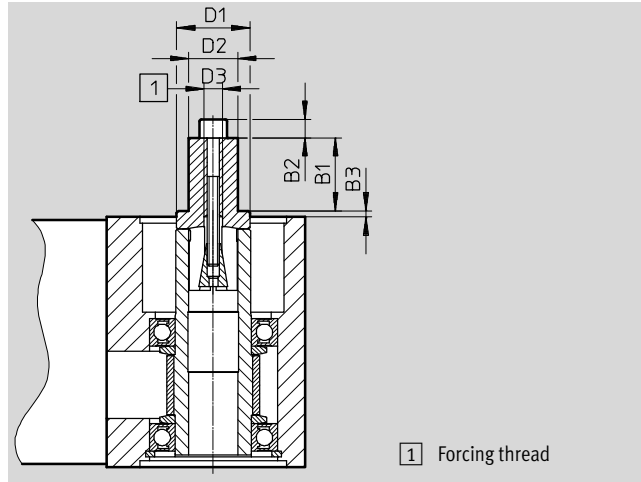
Dimensions and ordering data							
For size	B1	H1	L1	Weight [g]	Part No.	Type	
Sensor bracket							
35, 45, 55	9	6.5	44	20	<b>567537</b>	<b>EAPM-L4-SHS</b>	
Switch lug							
35, 45, 55	10	11	57.5	15	<b>567538</b>	<b>EAPM-L4-SLS</b>	

# Toothed belt axes ELGR



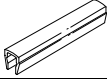
Accessories

FESTO

**Drive shaft EAMB**  
Alternative interface  
(Order code EA)



Dimensions and ordering data									
For size	B1	B2	B3	D1 ∅	D2 ∅	D3	Weight [g]	Part No.	Type
35	12	3	3.9	16	8	M4	20	558034	EAMB-16-7-8X15-8X10
45	12	4	6	18	8	M5	29	558035	EAMB-18-9-8X16-10X12
55	21	-	1.5	24	15	M6	70	558036	EAMB-24-6-15X21-16X20

Ordering data						
	For size	Comment	Order code	Part No.	Type	PU <sup>1)</sup>
<b>Slot nut NST</b>						
	35	For mounting slot	NM	558045	NST-3-M3	1
	45, 55			150914	NST-5-M5	
<b>Centring sleeve ZBH<sup>2)</sup></b>						
	35, 45, 55	For slide	-	186717	ZBH-7	10
<b>Slot cover ABP</b>						
	45, 55	For mounting slot Every 0.5 m	NC	151681	ABP-5	2

1) Packaging unit

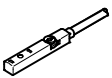
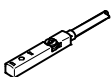
2) 2 centring sleeves included in the scope of delivery of the axis





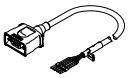
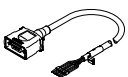
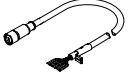
# Toothed belt axes ELGR

Accessories

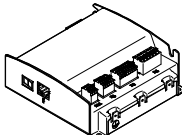
FESTO

Ordering data – Proximity sensor for T-slot, inductive							Technical data → Internet: sies	
	Type of mounting	Electrical connection	Switching output	Cable length [m]	Order code	Part No.	Type	
N/O contact								
	Insertable in the slot from above, flush with the cylinder profile	Cable, 3-wire	PNP	7.5	SA	551386	SIES-8M-PS-24V-K-7,5-OE	
		Plug connector M8x1, 3-pin		0.3	–	551387	SIES-8M-PS-24V-K-0,3-M8D	
		Cable, 3-wire	NPN	7.5	–	551396	SIES-8M-NS-24V-K-7,5-OE	
		Plug connector M8x1, 3-pin		0.3	–	551397	SIES-8M-NS-24V-K-0,3-M8D	
N/C contact								
	Insertable in the slot from above, flush with the cylinder profile	Cable, 3-wire	PNP	7.5	SB	551391	SIES-8M-PO-24V-K-7,5-OE	
		Plug connector M8x1, 3-pin		0.3	–	551392	SIES-8M-PO-24V-K-0,3-M8D	
		Cable, 3-wire	NPN	7.5	–	551401	SIES-8M-NO-24V-K-7,5-OE	
		Plug connector M8x1, 3-pin		0.3	–	551402	SIES-8M-NO-24V-K-0,3-M8D	

Ordering data – Connecting cables					Technical data → Internet: nebu	
	Electrical connection, left	Electrical connection, right	Cable length [m]	Part No.	Type	
	Straight socket, M8x1, 3-pin	Cable, open end, 3-wire	2.5	541333	NEBU-M8G3-K-2.5-LE3	
			5.0	541334	NEBU-M8G3-K-5-LE3	
	Angled socket, M8x1, 3-pin	Cable, open end, 3-wire	2.5	541338	NEBU-M8W3-K-2.5-LE3	
			5.0	541341	NEBU-M8W3-K-5-LE3	

Ordering data – Cables <sup>1)</sup>						
	For size	Description	Cable length [m]	Part No.	Type	
Motor cable						
	35	Straight plug connector – Min. bending radius: 62 mm – Suitability for energy chains – Ambient temp.: –40 ... +80°C	1.5	1450368	NEBM-S1G9-E-1.5-Q5-LE6	
			2.5	1450369	NEBM-S1G9-E-2.5-Q5-LE6	
			5.0	1450370	NEBM-S1G9-E-5-Q5-LE6	
			7.0	1450371	NEBM-S1G9-E-7-Q5-LE6	
			10.0	1450372	NEBM-S1G9-E-10-Q5-LE6	
	45, 55	Straight plug connector – Min. bending radius: 80 mm – Suitability for energy chains – Ambient temp.: –40 ... +80°C	1.5	1450834	NEBM-S1G15-E-1.5-Q7-LE6	
			2.5	1450835	NEBM-S1G15-E-2.5-Q7-LE6	
			5.0	1450836	NEBM-S1G15-E-5-Q7-LE6	
			7.0	1450837	NEBM-S1G15-E-7-Q7-LE6	
			10.0	1450838	NEBM-S1G15-E-10-Q7-LE6	
Encoder cable						
	35, 45, 55	Straight plug connector – Min. bending radius: 68 mm – Suitable for use with energy chains – Ambient temp.: –40 ... +80°C	1.5	1451586	NEBM-M12G8-E-1.5-LE8	
			2.5	1451587	NEBM-M12G8-E-2.5-LE8	
			5.0	1451588	NEBM-M12G8-E-5-LE8	
			7.0	1451589	NEBM-M12G8-E-7-LE8	
			10.0	1451590	NEBM-M12G8-E-10-LE8	

1) Other cable lengths on request.

Ordering data				Technical data → Internet: cmmo	
Motor controller	Description	Part No.	Type		
	With I/O interface				
	Switching input/output PNP	1512316	CMMO-ST-C5-1-DIOP		
	Switching input/output NPN	1512317	CMMO-ST-C5-1-DION		
	With IO-Link				
	Switching input/output PNP	1512320	CMMO-ST-C5-1-LKP		

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To meet this commitment, we strive to ensure a consistent, integrated, and systematic approach to management that will meet or exceed the requirements of the ISO 9001 standard for Quality Management and the ISO 14001 standard for Environmental Management.

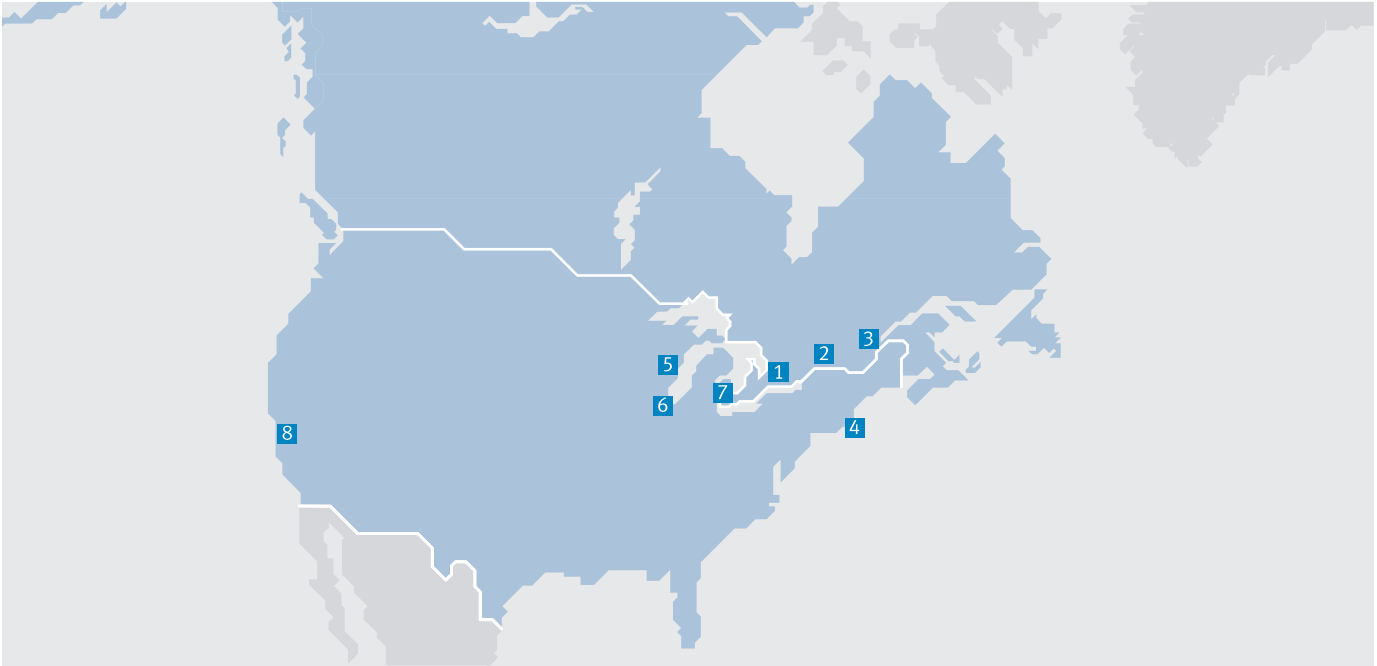


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