



FESTO

At a glance

With free, speed-controlled selection of the gripping positions, flexible access is no longer a problem with the parallel gripper HGPLE. Its long stroke

means it can be used with workpieces of different sizes. The option to adjust the gripping force makes the HGPLE

ideal for soft or very delicate workpieces. It also grips large and heavy workpieces reliably.

Economical

- A "pre-holding" position enables the HGPLE to stop its gripper fingers just short of the workpiece, thus reducing access times to an absolute minimum. Even when the size of the workpiece requires the entire
- stroke, the HGPLE still offers impressively short opening and closing times of 0.6 s.
- The installation complexity is minimal as only one cable is required (from the controller to the gripper).

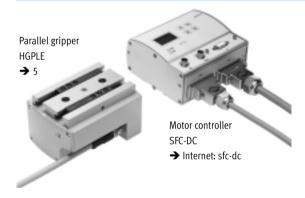
Sturdy

The T-slot gives the HGPLE very high torque resistance as well as very high precision.

Flexible

It is actuated on-site using the tried and tested motor controller SFC-DC.

Everything from a single source



The parallel gripper and motor controller SFC form one unit.

- Thanks to IP54 degree of protection, the SFC can be mounted close to the HGPLE, either:
 - via central supports or
 - via H-rail
- The motor controller SFC is available with or without control panel
- Easy actuation via:
 - PROFIBUS
 - CANopen
 - DeviceNet

Parameterisation possible via:

- · Control panel:
 - Suitable for easy positioning sequences
- FCT (Festo Configuration Tool) configuration package:
 - Parameterisation via RS 232 interface
 - Windows-based PC user interface, Festo Configuration Tool
 - Tool is included in scope of delivery





DeviceNet.



Note

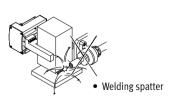
These grippers are not suitable for the following or similar applications:



- Aggressive media
 - Machining



Grinding dust



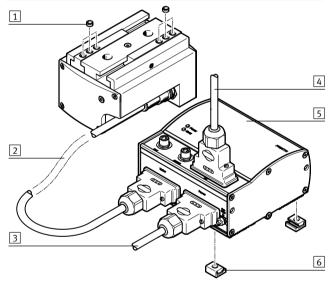
Parallel grippers HGPLE, sturdy with long stroke, electric Key features and peripherals overview

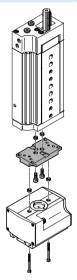
FESTO

Mounting options Direct mounting From above From underneath 1 2 2 1 1 Mounting screws 1 Mounting screws 2 Centring sleeves 2 Centring sleeves

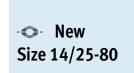
Peripherals overview

System product for handling and assembly technology



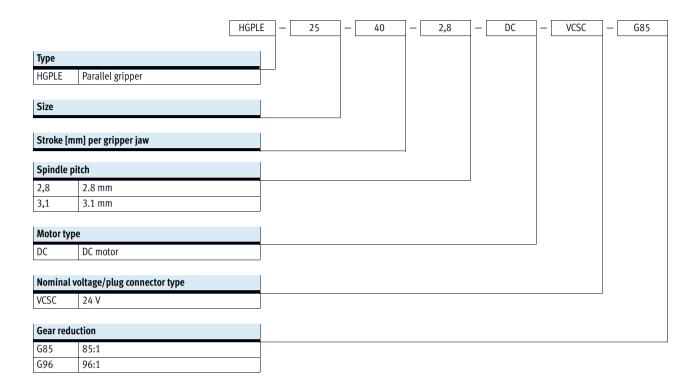


Acces	Accessories							
	Туре	Description	→ Page/Internet					
1	Centring sleeve	For centring attachments	11					
	ZBH							
2	Motor cable	Connecting cable between motor and motor controller	sfc-dc					
	KMTR							
3	Supply cable	Power supply cable; load and logic power supplies are separate	sfc-dc					
	KPWR							
4	Plug connector	For fieldbus interface	sfc-dc					
	FBS, FBA							
5	Motor controller	For parameterising and positioning the parallel gripper	sfc-dc					
	SFC							
6	Central support	- For mounting the motor controller	sfc-dc					
	MUP	- Motor controller can also be mounted on an H-rail						
-	Gripper jaw blank	Unmachined part specially matched to the gripper jaws for custom fabrication of gripper	11					
	BUB-HGPL	fingers						



FESTO

Type codes



FESTO

Function





14 and 25 mm



Stroke 30 ... 80 mm



General technical data							
Size		14		25			
Stroke		30	60	40	80		
Design		Worm gear unit with integr	ated displacement encoder				
		Rack and pinion					
Guidance		Plain-bearing guide with T	-slot				
Mode of operation		Double-acting					
Gripper function		Parallel					
Number of gripper jaws		2					
Stroke per gripper jaw, adjustable	[mm]	0 30	0 60	0 40	0 80		
Max. load per gripper finger ¹⁾	[g]	150	150	500	500		
Repetition accuracy ²⁾	[mm]	≤ 0.05					
Max. interchangeability	[mm]	≤ 0.2					
Reversing backlash ³⁾	[mm]	≤ 0.35					
Rotational symmetry	[mm]	≤ 0.2					
Max. gripper jaw backlash	[mm]	≤ 0.05					
Max. gripper jaw angular backlash	[°]	≤ 0.2					
Homing		Negative fixed stop block					
		Positive fixed stop block					
Position sensing		Via integrated angular displacement encoder					
Type of mounting		Via through-holes and centring sleeves					
		Via female thread and centring sleeves					
Electrical connection		12-pin					
		M12x1					
		Plug connector					
Mounting position		Any					
Product weight	[g]	520	700	1680	2030		

- 2) End-position drift under constant operating conditions with 100 consecutive strokes in the direction of movement of the gripper jaws
 3) In new condition

Electrical data for motor						
Motor type		DC servo motor				
Nominal operating voltage	[V DC]	24				

Operating and environmental conditions					
Ambient temperature	[°C]	5 40			
Degree of protection		IP40			
Noise level	[db (A)]	≤60			
CE mark (see declaration of conformity) ¹⁾		To EU EMC Directive			
Corrosion resistance class CRC ²⁾		2			

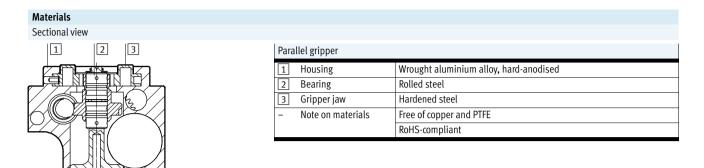
If the component is subject to restrictions on usage in residential, office or commercial environments or small businesses, further measures to reduce the emitted interference may be necessary.

²⁾ Corrosion resistance class CRC 2 to Festo standard FN 940070

Moderate corrosion stress. Indoor applications in which condensation may occur. External visible parts with primarily decorative requirements for the surface and which are in direct contact with the ambient atmospheric sphere typical for industrial applications.

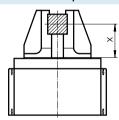
FESTO

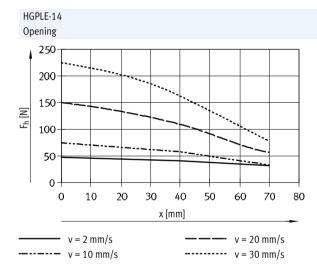
Technical data

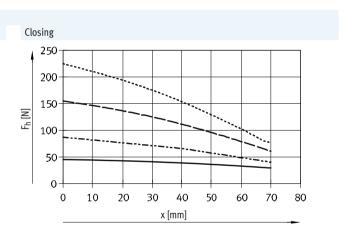


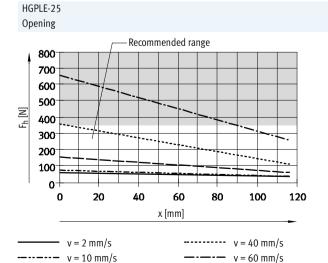
Gripping force F_h per gripper jaw as a function of travel speed v and lever arm x

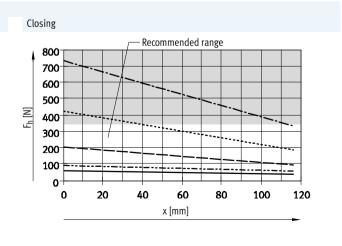
The gripping forces as a function of travel speed and lever arm can be determined using following graphs.









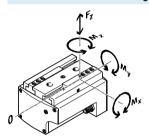


-- v = 20 mm/s

FESTO

Total gripping force F with a lever	arm X = 20 mm							
Travel speed v	[mm/s]	2	5	10	20	30	40	60
HGPLE-14								
Opening	[N]	92	93	149	300	450	-	_
Closing	[N]	88	104	173	305	445	-	_
HGPLE-25								
Opening	[N]	120	120	148	293	_	652	1150
Closing	[N]	121	120	176	376	_	771	1300

Characteristic load values at the gripper jaws

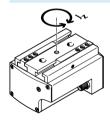


The indicated permissible forces and torques apply to a single gripper jaw. They include the lever arm, additional applied loads due to the workpiece or external gripper fingers and acceleration forces occurring during movement.

The zero co-ordinate line (gripper jaw guide groove) must be taken into consideration for the calculation of

Size	14		25	25	
Stroke		30	60	40	80
Max. permissible force F _z	[N]	500	500	1500	1500
Max. permissible torque M_X	[Nm]	25	35	100	140
Max. permissible torque M _y	[Nm]	25	35	60	90
Max. permissible torque M _z	[Nm]	25	35	70	100

Mass moment of inertia [kgcm²]

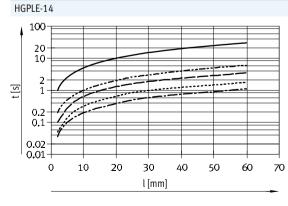


Under the following conditions:

- The reference point is the central
- Without external gripper fingers
- In a load-free state

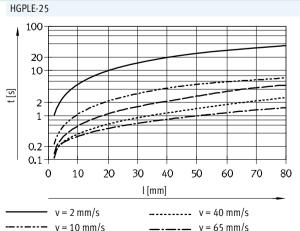
Size		14		25	
Stroke		30	60	40	80
Mass moment of inertia Jz	[kgcm ²]	4.24	11.64	28.32	72.72

Positioning time t as a function of stroke per gripper jaw l and travel speed v



v = 2 mm/s----- v = 10 mm/s -- v = 20 mm/s ----- v = 40 mm/s ---- v = 55 mm/s

100 20



____ v = 65 mm/s

-⊙- New Size 14/25-80

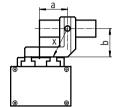
Parallel grippers HGPLE, sturdy with long stroke, electric

FESTO

Technical data

Gripping force F_h per gripper jaw as a function of lever arm x and eccentricity a and b

The following formula must be used to calculate the lever arm x with eccentric gripping:



 $x = \sqrt{60^2 + 70^2}$

x = 92 mm

$$x = \sqrt{a^2 + b^2}$$

The gripping force F_h can then be read from the graphs $(\rightarrow 6)$ using the calculated value x.

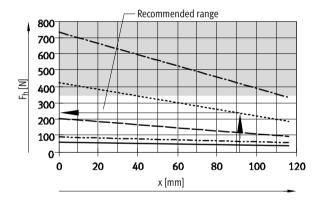
Calculation example

Given: Distance a = 60 mm

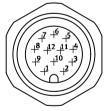
Distance b = 70 mm To be found:

The gripping force at 40 mm/s

with a HGPLE-25-40, used as an external gripper Approach: The graph (→ 6) gives a value for Calculating the lever arm x the gripping force F_h of approx. 245 N.



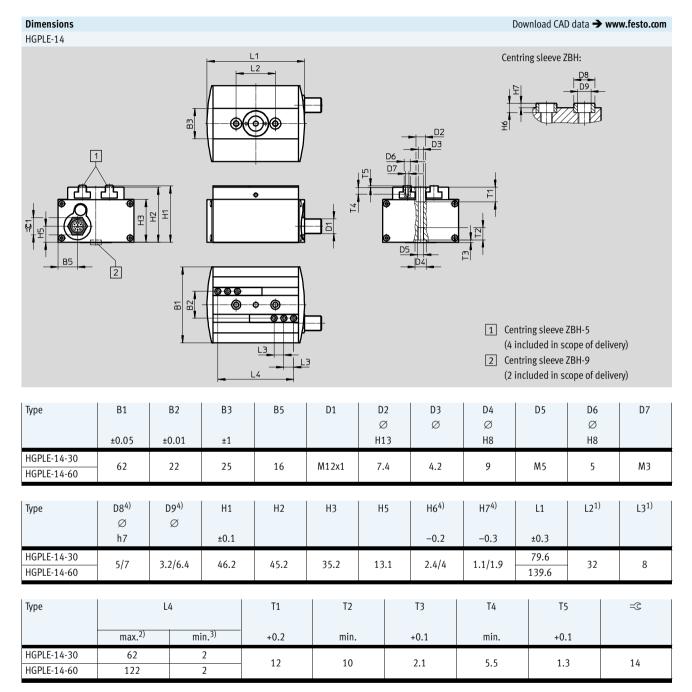
Pin allocation of plug connector



M12	plug connector	
Pin	Port	Function
1	Motor +	Motor conductor
2	Motor –	Motor conductor
3	A	Encoder signal RS 485
4	A/	Encoder signal RS 485
5	В	Encoder signal RS 485
6	B/	Encoder signal RS 485
7	1	Encoder signal RS 485
8	1/	Encoder signal RS 485
9	+5 V DC	Signal supply
10	0V	Signal ground
11	-	Preassigned
12	-	Preassigned

FESTO

Technical data



¹⁾ Tolerance for centring hole ±0.02 mm Tolerance for thread ±0.1 mm

²⁾ Gripper open

³⁾ Gripper closed

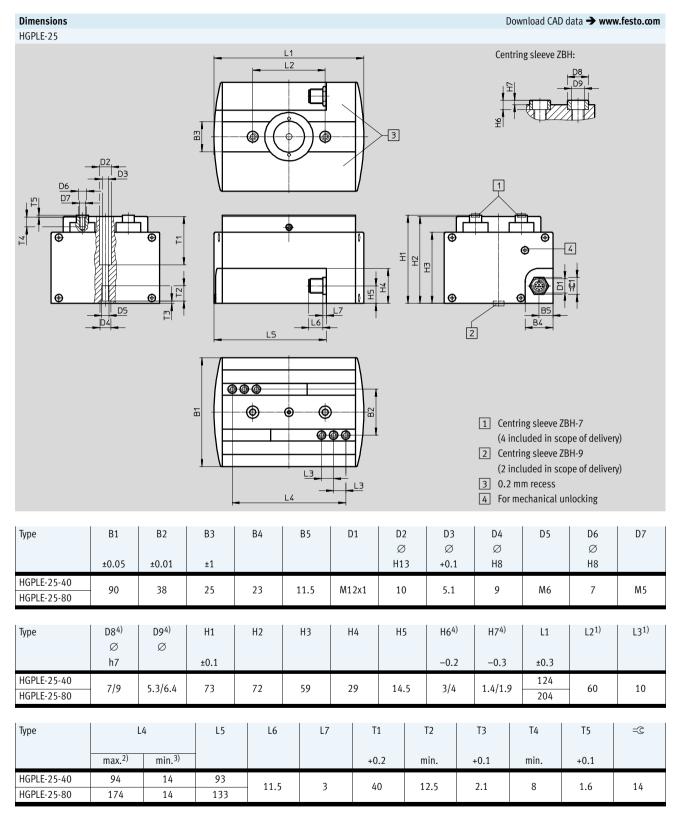
⁴⁾ On the gripper jaw/on the gripper

- New Size 14/25-80

Parallel grippers HGPLE, sturdy with long stroke, electric

FESTO

Technical data



Tolerance for centring hole ±0.02 mm
 Tolerance for thread ±0.1 mm

Gripper open

³⁾ Gripper closed

On the gripper jaw/on the gripper

Parallel grippers HGPLE, sturdy with long stroke, electric Technical data

FESTO

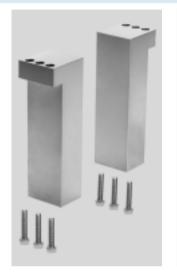
Ordering data		
	Part No.	Туре
\bigcirc	2342434	HGPLE-14-30-3,1-DC-VCSC-G96
	2342435	HGPLE-14-60-3,1-DC-VCSC-G96
	555563	HGPLE-25-40-2,8-DC-VCSC-G85
	2342436	HGPLE-25-80-2,8-DC-VCSC-G85

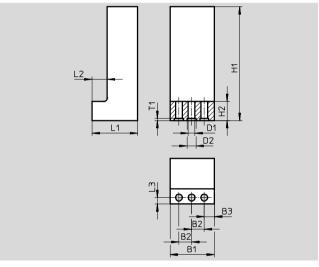
Accessories

Gripper jaw blank BUB-HGPL

(2 included in delivery)

Materials: Wrought aluminium alloy Free of copper and PTFE RoHS-compliant





Dimensions and ordering data									
For size	B1	B2	В3	D1	D2	H1	H2		
				Ø	Ø				
	+0.1	+0.02		+0.1	Н8	+0.1			
14	25	8	4	3.2	5	80	11		
25	35	10	8	5.3	7	120	15		

For size	L1	L2	L3	T1	Weight per	Part No.	Туре
					blank		
	+0.1	+0.1	+0.1	+0.1	[g]		
14	20.5	8	3.3	1.3	75	537316	BUB-HGPL-14
25	36	12	5	1.6	295	537317	BUB-HGPL-25

Ordering data –	Centring sleeve						
	For size	Part No. Type	PU ¹⁾				
For the gripper ja	For the gripper jaws Technical data → Internet: z						
	14	189652 ZBH-5	10				
	25	186717 ZBH-7					
For the gripper		Technical data → Inte	rnet: zbh				
	14, 25	150927 ZBH-9	10				

¹⁾ Packaging unit

- New Size 14/25-80

Parallel grippers HGPLE, sturdy with long stroke, electric

FESTO

Accessories

Adapter kit Materials:

DHAA, HAPG Wrought aluminium alloy Free of copper and PTFE

RoHS-compliant



The kit includes the individual mounting interface as well as the necessary mounting material.

Permissible drive/gripper com Combination						Download CAD data → www.festo.com		
	Drive	Gripper			Adapter kit			
	Size	Size	Mounting option		CRC ¹⁾	Part No.	Туре	
GSL/HGPLE	DGSL	HGPLE			DHAA/H.	APG		
DOSENIO EE	16	14		•	2	2519367	DHAA-G-G6-16-B17-14	
	20, 25	14			2	2515219	DHAA-G-G6-20-B17-14	
	25	25		•		539274	HAPG-90	
SLT/HGPLE	SLT	HGPLE			DHAA			
	16	14	•	-		2531838	DHAA-G-G3-16-B17-14	
	20	14		_	_	2516304	DHAA-G-G3-20-B17-14	
	25	14		-	2	2516252	DHAA-G-G3-25-B17-14	
	25	25		-		8033603	DHAA-G-G3-25-B17-25	
MP/HGPLE	HMP	HGPLE			HAPG			
TIMIT / TIOT LL	20, 25	25		-	2	539887	HAPG-92	
RQD/HGPLE								
RQD/HGPLE	DRQD	HGPLE			DHAA/H.			
RQD/HGPLE	16, 20	14		•		2534351	DHAA-G-Q5-16-B17-14	
RQD/HGPLE	16, 20 25, 32	14 25		•	2	2534351 537311	DHAA-G-Q5-16-B17-14 HAPG-SD2-29	
RQD/HGPLE	16, 20 25, 32 DRQD-E422	14 25 HGPL	•			2534351 537311 APG	HAPG-SD2-29	
RQD/HGPLE	16, 20 25, 32 DRQD-E422 16, 20	14 25 HGPL 14	-	•	2	2534351 537311 APG 2512383	HAPG-SD2-29 DHAA-G-Q5-16-B17-14-E	
RQD/HGPLE	16, 20 25, 32 DRQD-E422	14 25 HGPL	•		DHAA/H	2534351 537311 APG	HAPG-SD2-29	
	16, 20 25, 32 DRQD-E422 16, 20 25, 32	14 25 HGPL 14 25	-	•	DHAA/H	2534351 537311 APG 2512383 544645	HAPG-SD2-29 DHAA-G-Q5-16-B17-14-E HAPG-SD2-46	
	16, 20 25, 32 DRQD-E422 16, 20 25, 32 DRRD	14 25 HGPL 14 25 HGPLE 14		•	2 DHAA/H.	2534351 537311 APG 2512383 544645	HAPG-SD2-29 DHAA-G-Q5-16-B17-14-E HAPG-SD2-46 DHAA-G-Q11-16-B17-14	
	16, 20 25, 32 DRQD-E422 16, 20 25, 32 DRRD 16 20	14 25 HGPL 14 25 HGPLE 14 14		-	2 DHAA/H.	2534351 537311 APG 2512383 544645 8034057 8034058	DHAA-G-Q11-16-B17-14 DHAA-G-Q11-16-B17-14 DHAA-G-Q11-20-B17-14	
	16, 20 25, 32 DRQD-E422 16, 20 25, 32 DRRD 16 20 25	14 25 HGPL 14 25 HGPLE 14 14		•	2 DHAA/H. 2 DHAA	2534351 537311 APG 2512383 544645 8034057 8034058 3122168	DHAA-G-Q5-16-B17-14-E HAPG-SD2-46 DHAA-G-Q11-16-B17-14 DHAA-G-Q11-20-B17-14 DHAA-G-Q11-25-B17-14	
	16, 20 25, 32 DRQD-E422 16, 20 25, 32 DRRD 16 20 25 25	14 25 HGPL 14 25 HGPLE 14 14 14 14 25		•	2 DHAA/H.	2534351 537311 APG 2512383 544645 8034057 8034058 3122168 8033607	HAPG-SD2-29 DHAA-G-Q5-16-B17-14-E HAPG-SD2-46 DHAA-G-Q11-16-B17-14 DHAA-G-Q11-20-B17-14 DHAA-G-Q11-25-B17-14 DHAA-G-Q11-25-B17-25	
RQD/HGPLE RRD/HGPLE	16, 20 25, 32 DRQD-E422 16, 20 25, 32 DRRD 16 20 25	14 25 HGPL 14 25 HGPLE 14 14		•	2 DHAA/H. 2 DHAA	2534351 537311 APG 2512383 544645 8034057 8034058 3122168	DHAA-G-Q5-16-B17-14-E HAPG-SD2-46 DHAA-G-Q11-16-B17-14 DHAA-G-Q11-20-B17-14 DHAA-G-Q11-25-B17-14	

¹⁾ Corrosion resistance class CRC 2 to Festo standard FN 940070 Moderate corrosion stress. Indoor applications in which condensation may occur. External visible parts with primarily decorative requirements for the surface and which are in direct contact with the ambient atmosphere typical for industrial applications.

FESTO

Accessories

Adapter kit

Material:

DHAA, HAPG Wrought aluminium alloy
Free of copper and PTFE

RoHS-compliant



The kit includes the individual mounting interface as well as the necessary mounting material.

Permissible drive/gripper co	Download CAD data → www.festo.com						
Combination	Drive						
	Size	Size	Mounting option		CRC ¹⁾	Part No.	Туре
DGEA/HGPLE	DGEA	HGPLE			DHAA		
	25	14			2	2786045	DHAA-G-E2-25-B17-14
	40	14	•		2	2806354	DHAA-G-E2-40-B17-14
EGC/HGPLE	EGC	HGPLE			DHAA		
ECC/HOPEL	70	14		•	Dillot	2808960	DHAA-G-E7-70-B17-14
	80	14	_			2810619	DHAA-G-E7-80-B17-14
	120	25	•		2	8033604	DHAA-G-E7-120-B17-25
	185	25		•		8033605	DHAA-G-E7-185-B17-25
EGSL/HGPLE	EGSL 45, 55 75	HGPLE 14 14		•	DHAA 2	2519367 2515219	DHAA-G-G6-16-B17-14 DHAA-G-G6-20-B17-14
ERMB/HGPLE	ERMB	HGPLE			DHAA		
	20	14	•	•		2807590	DHAA-G-R1-20-B17-14
	25	14			2	2812698	DHAA-G-R1-25-B17-14
	32	25				8033606	DHAA-G-R1-32-B17-25
EHMB/HGPLE	EHMB	HGPLE			HAPG		
	20	25	-		2	537311	HAPG-SD2-29

¹⁾ Corrosion resistance class CRC 2 to Festo standard FN 940070 Moderate corrosion stress. Indoor applications in which condensation may occur. External visible parts with primarily decorative requirements for the surface and which are in direct contact with the ambient atmosphere typical for industrial applications.