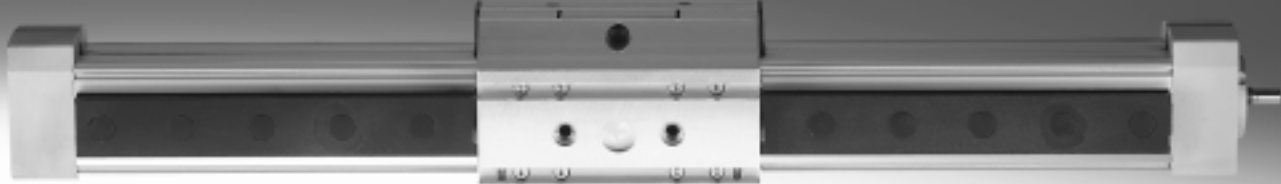


Positioning axes DMES



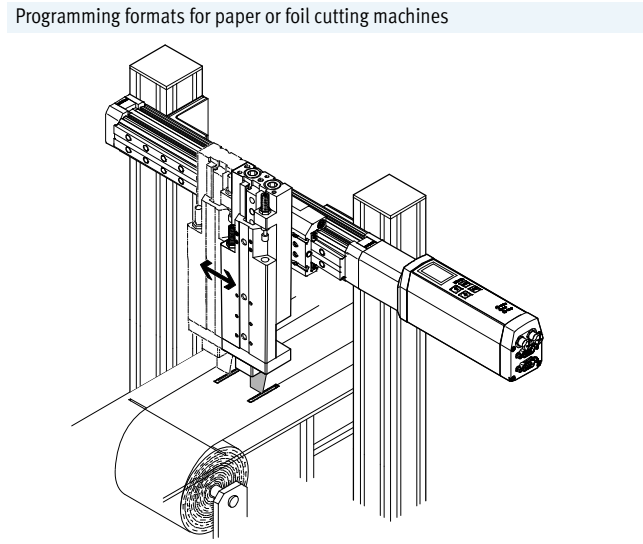
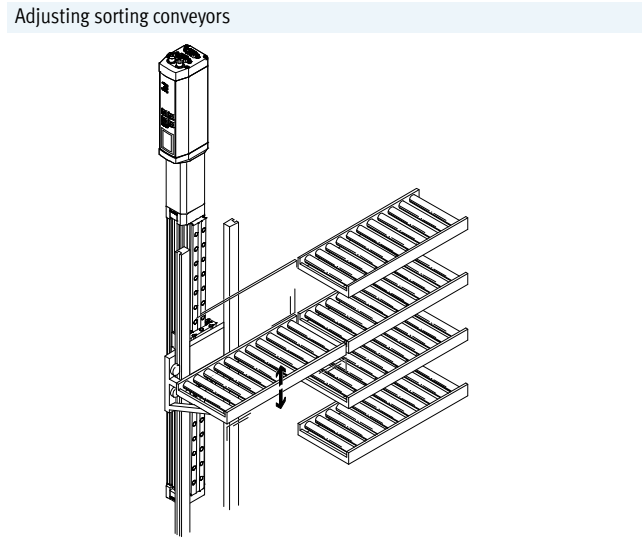
Positioning axes DMES

Key features

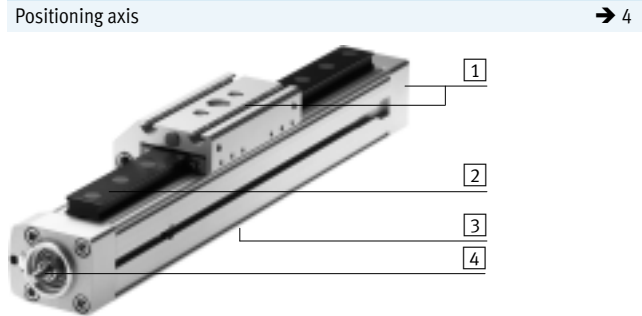
FESTO

At a glance		
General	Properties	Range of applications
<p>DMES positioning axes are mechanical linear drives that are specially designed for movements involving high forces.</p> <p>The mechanical interfaces are compatible with the spindle axis DGE-SP.</p>	<ul style="list-style-type: none"> • High mechanical torques • High feed forces up to 3000 N • Self-retarding lead-screw spindle • Compact dimensions • Cost optimised 	<ul style="list-style-type: none"> • Alternatively: <ul style="list-style-type: none"> – without guide – with recirculating ball bearing guide KF • For format adjustment: <ul style="list-style-type: none"> – in printing, paper and foil wrapping machines – in packaging machines – in feed technology

Application examples



The technology in detail



- 1 Mechanical interfaces are identical to spindle axes DGE-...-SP
- 2 KF: Recirculating ball bearing guide
- 3 Slot for proximity sensor
- 4 Lead-screw spindle, for use with high forces

The lead-screw spindle is self-retarding, which means that slow movements cannot be excluded in the event of vibration.

The entire system with intelligent motor unit MTR-DCI is self-locking.

A range of specially adapted complete solutions is available for the positioning axes DMES and the motors.

Two motor interfaces are available:

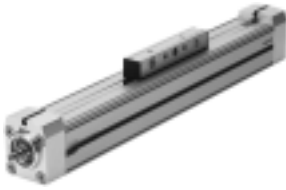
- Axial motor interface
- Parallel motor interface

Positioning axes DMES

Key features

Wide choice of variants

Basic design DMES, without guide



- For connection to an existing guide
- For small loads

Recirculating ball bearing guide DMES-KF



- With standard slide (GK) or extended slide (GV)
- For higher loads
- For high guide precision

Protected version DMES-GA

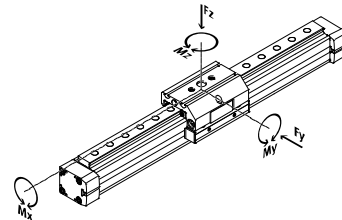
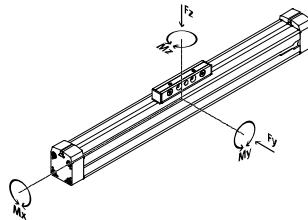


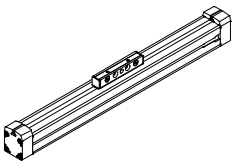
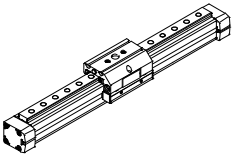
- With standard slide (GK)
- Guide and slide are fitted with a cover to protect against the ingress of particles from above and from the side

Guide characteristics

The specifications shown in the table are maximum values.

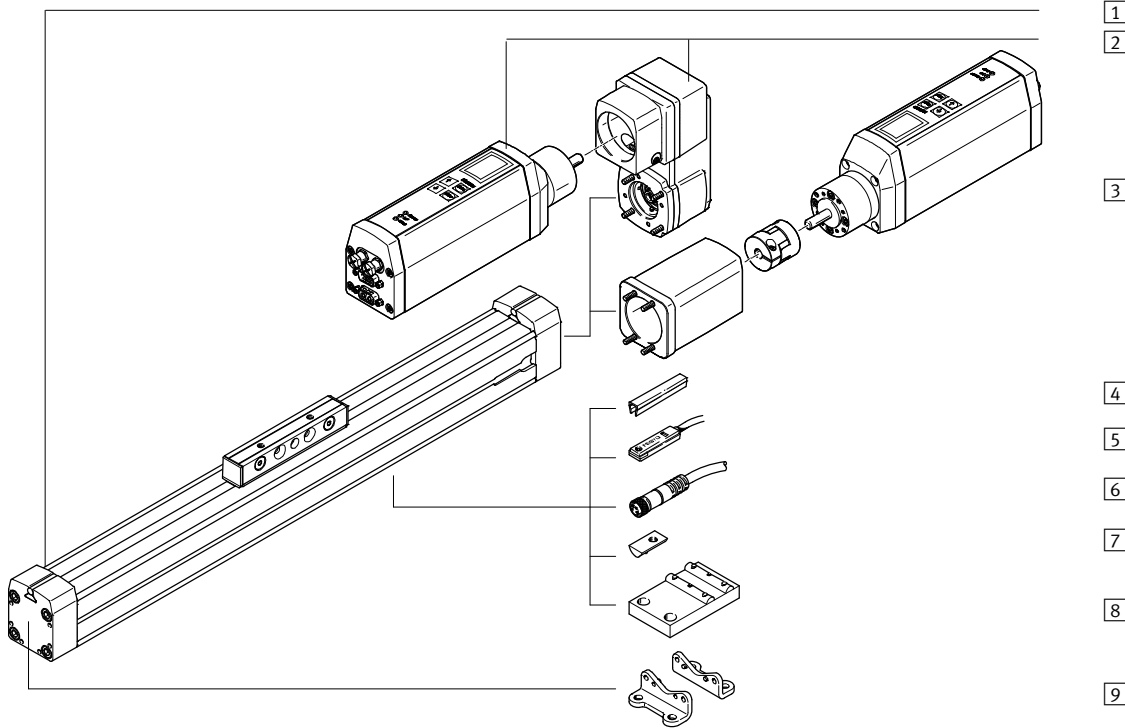
The precise values for each of the variants can be found in the relevant technical data in the catalogue.




	Size	Working stroke [mm]	Speed [m/s]	Repetition accuracy [mm]	Feed force [N]	Forces and torques					→ Page/ Internet
						Fy [N]	Fz [N]	Mx [Nm]	My [Nm]	Mz [Nm]	
Basic design DMES											
	18	50 ... 400	0.05	±0.05	240	36	80	0.4	2	0.7	6
	25	50 ... 700	0.05	±0.05	500	80	100	1.3	4	1.6	
	40	50 ... 1200	0.05	±0.05	1000	92	390	2.2	20	4.6	
	63	50 ... 1800	0.05	±0.07	3000	300	900	12	80	22	
Recirculating ball bearing guide DMES-KF											
	18	50 ... 400	0.05	±0.05	240	930	930	7	45	45	20
	25	50 ... 700	0.05	±0.05	500	3080	3080	45	170	170	
	40	50 ... 1200	0.05	±0.05	1000	7300	7300	170	660	660	
	63	50 ... 1800	0.05	±0.07	3000	13900	14050	580	1820	1820	

Positioning axes DMES, without guide

Peripherals overview



Variants and accessories		
Type/Order code	Description	→ Page/Internet
1 Positioning axis DMES	Electromechanical axis without guide	6
2 Intelligent servo unit and parallel kit U	Complete package for parallel motor attachment, comprising parallel kit and intelligent motor unit MTR-DCI	14
3 Intelligent servo unit and axial kit AX	Complete package for axial motor attachment, comprising axial kit and intelligent motor unit MTR-DCI	14
4 Slot cover B/S	For protecting against ingress of dirt	47
5 Proximity sensor SMT-8	For providing a proximity signal or safety sensing	46
6 Connecting cable KM8	For proximity sensor	46
7 Slot nut for mounting slot Y	For mounting attachments	47
8 Central support M	For mounting the axis	44
9 Foot mounting F	For mounting the axis (can only be attached to end cap, must be combined with central support)	44

-  - Note
 Servo, stepper motors and the corresponding mounting kits must be ordered separately → 40

Positioning axes DMES, without guide

Type code

DMES - 25 - 500 - AX : ZUB - 2Y 2M

Type

DMES	Positioning axis
------	------------------

Size

Stroke [mm]

Motor unit

AX	Intelligent servo unit and axial kit
----	--------------------------------------

U	Intelligent servo unit and parallel kit
---	---

Accessories

ZUB	Accessories supplied loose
-----	----------------------------

Slot cover

...S	Sensor slot
------	-------------

...B	Mounting slot
------	---------------

Slot nut

...Y	For mounting slot
------	-------------------

Central support

...M	Central support
------	-----------------

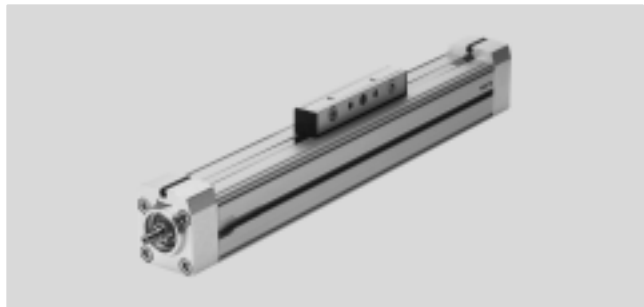
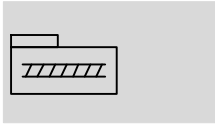
Foot mounting

...F	Foot mounting
------	---------------

Positioning axes DMES, without guide

Technical data

Function



- - Size
18 ... 63
- - Stroke length
50 ... 1800 mm

General technical data					
Size		18	25	40	63
Design		Electromechanical linear axis with lead-screw spindle			
Guide		None			
Assembly position		Any			
Working stroke	[mm]	50 ... 400	50 ... 700	50 ... 1200	50 ... 1800
Max. feed force F_x	[N]	240	500	1000	3000
Max. driving torque	[Nm]	0.3	0.9	3	14
Max. no-load driving torque ¹⁾	[Nm]	0.07	0.2	0.45	1.1
Max. radial force ²⁾	[N]	40	75	250	800
Max. speed	[m/s]	0.05			
Max. acceleration	[m/s ²]	2.5			
Repetition accuracy	[mm]	±0.05			±0.07
Positioning rigidity	[N/mm]	1700	2300	4200	5600
Duty cycle	[%]	100			
Reversing backlash ³⁾	[mm]	< 0.1			

- 1) Measured at a speed of 200 rpm.
- 2) On drive shaft
- 3) In new condition

Operating and environmental conditions	
Ambient temperature ¹⁾	[°C] 0 ... +50
Protection class	IP40

- 1) Note operating range of proximity sensors

Weights [kg]					
Size		18	25	40	63
Basic weight with 0 mm stroke ¹⁾		0.49	0.98	2.9	10.05
Additional weight per 100 mm stroke		0.2	0.36	0.74	1.97
Moving load		0.06	0.15	0.47	1.51

- 1) Without coupling housing

Positioning axes DMES, without guide

Technical data

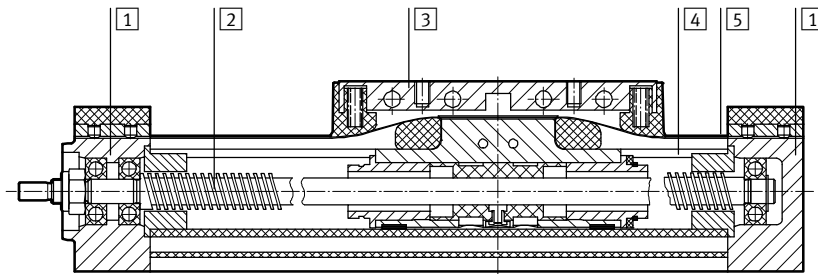
Mass moment of inertia					
Size		18	25	40	63
J_0	[kg cm ²]	0.0028	0.0147	0.1824	1.7747
j_H per metre stroke	[kg cm ² /m]	0.0210	0.0980	0.8400	5.5600
j_L per kg working load	[kg cm ² /Kg]	0.0006	0.0023	0.0041	0.0091

The mass moment of inertia J_A of the entire axis is calculated as follows: $J_A = J_0 + j_H \times \text{working stroke [m]} + j_L \times m_{\text{working load [kg]}}$

Spindle					
Size		18	25	40	63
Diameter	[mm]	8	12	20	32
Pitch	[mm/rev.]	1.5	2.5	4	6

Materials

Sectional view



Positioning axis		
1	Cover	Wrought aluminium alloy, anodised
2	Spindle	Steel
3	Piston, driver	Wrought aluminium alloy, anodised
4	Profile	Wrought aluminium alloy, anodised
5	Cover strip	High-alloy stainless steel

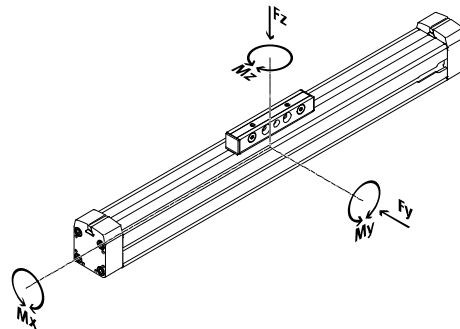
Positioning axes DMES, without guide

Technical data

Characteristic load values


The indicated forces refer to the centre line of the internal diameter of the profile.

They must not be exceeded during dynamic operation. Special attention must be paid to the cushioning phase.



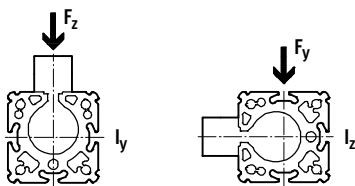
If the axis is subjected to more than two of the indicated forces simultaneously, the following equation must be satisfied in addition to the indicated maximum loads:

$$\frac{|F_y|}{F_{y_{max}}} + \frac{|F_z|}{F_{z_{max}}} + \frac{|M_x|}{M_{x_{max}}} + \frac{|M_y|}{M_{y_{max}}} + \frac{|M_z|}{M_{z_{max}}} \leq 1$$


 Note
Positioning axes DMES without guide are not designed to absorb lateral forces or torques on the slide.

Permissible forces and torques					
Size		18	25	40	63
F _y _{max.}	[N]	36	80	92	300
F _z _{max.}	[N]	80	100	390	900
M _x _{max.}	[Nm]	0.4	1.3	2.2	12
M _y _{max.}	[Nm]	2	4	20	80
M _z _{max.}	[Nm]	0.7	1.6	4.6	22

2nd moment of area



Size		18	25	40	63
I _y	[cm ⁴]	6.90	20.92	76.24	587.74
I _z	[cm ⁴]	6.83	21.20	71.01	464.30

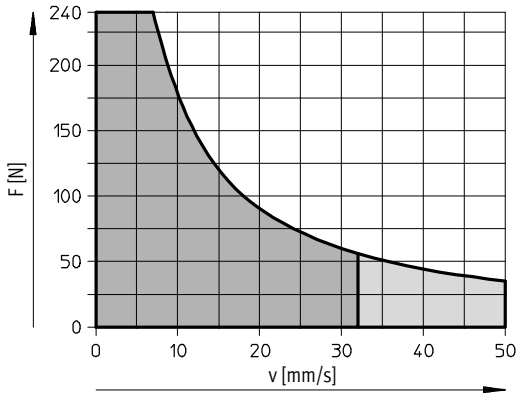
 Note
Sizing software
PositioningDrives
→ www.festo.com

Positioning axes DMES, without guide

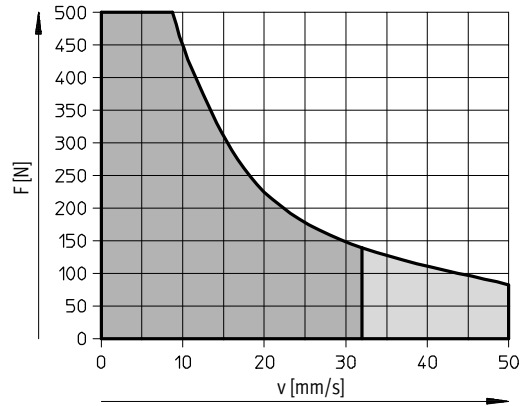
Technical data

Maximum permissible feed force F as a function of the feed speed v

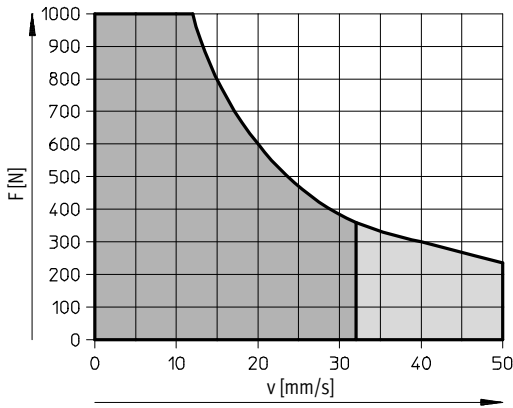
DMES-18



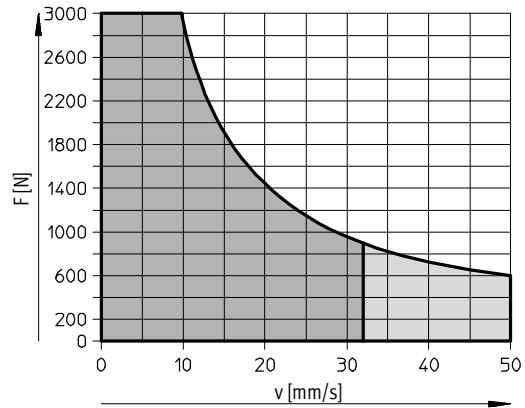
DMES-25



DMES-40



DMES-63



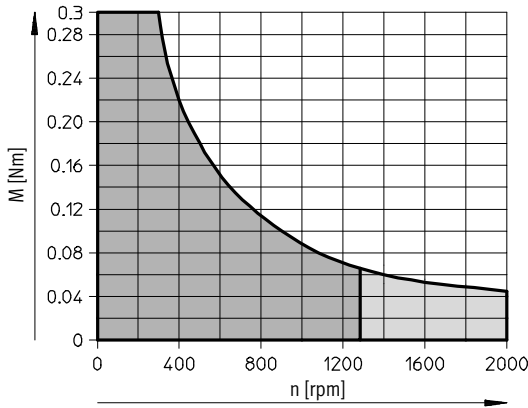
- Recommended operating range
- Permissible operating range (duty cycle < 50% recommended)

Positioning axes DMES, without guide

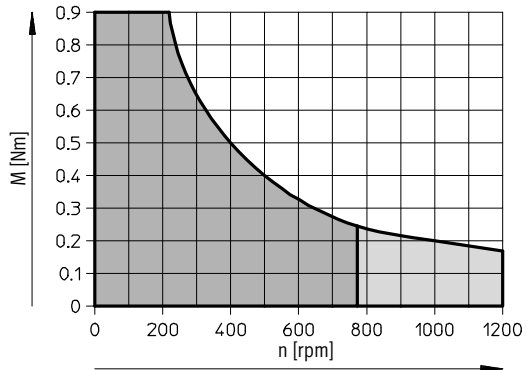
Technical data

Maximum permissible driving torque M as a function of n (rpm)

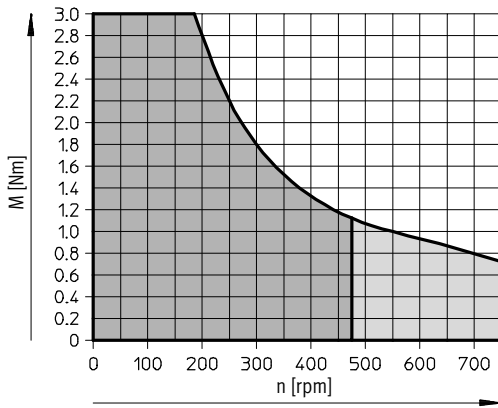
DMES-18



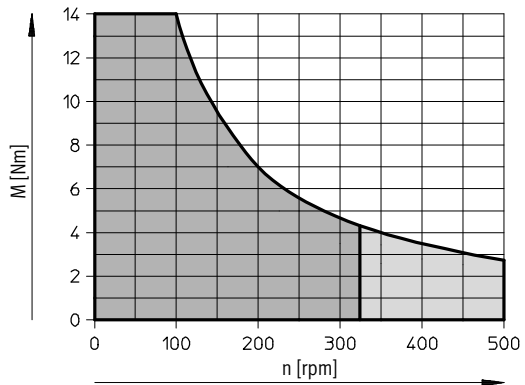
DMES-25



DMES-40

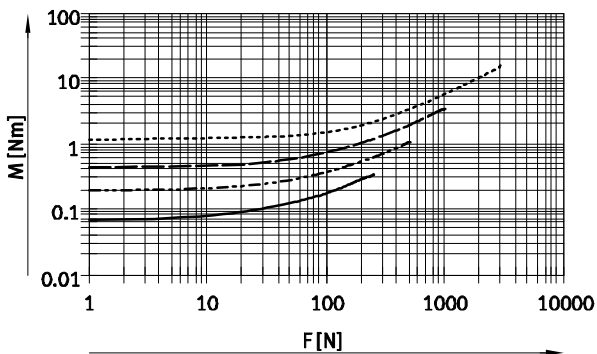


DMES-63

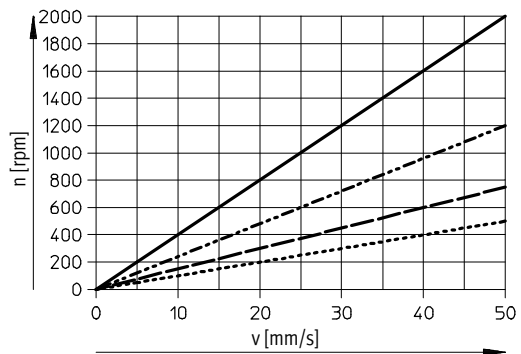


- Recommended operating range
- Permissible operating range (duty cycle < 50% recommended)

Driving torque M as a function of the feed force F



Speed as a function of the feed speed v



- DMES-18
- - - - - DMES-25
- · - · - DMES-40
- · · · · DMES-63

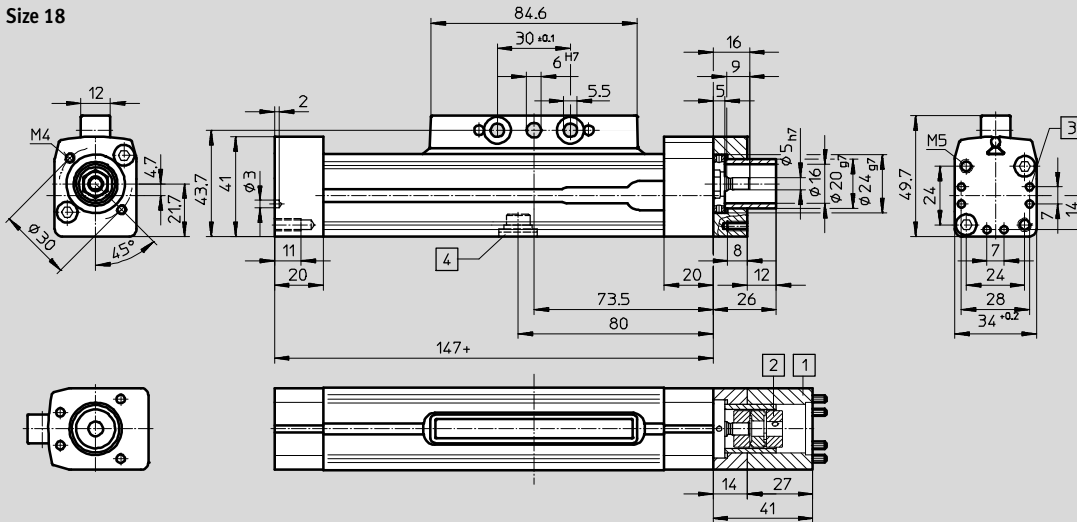
Positioning axes DMES, without guide

Technical data

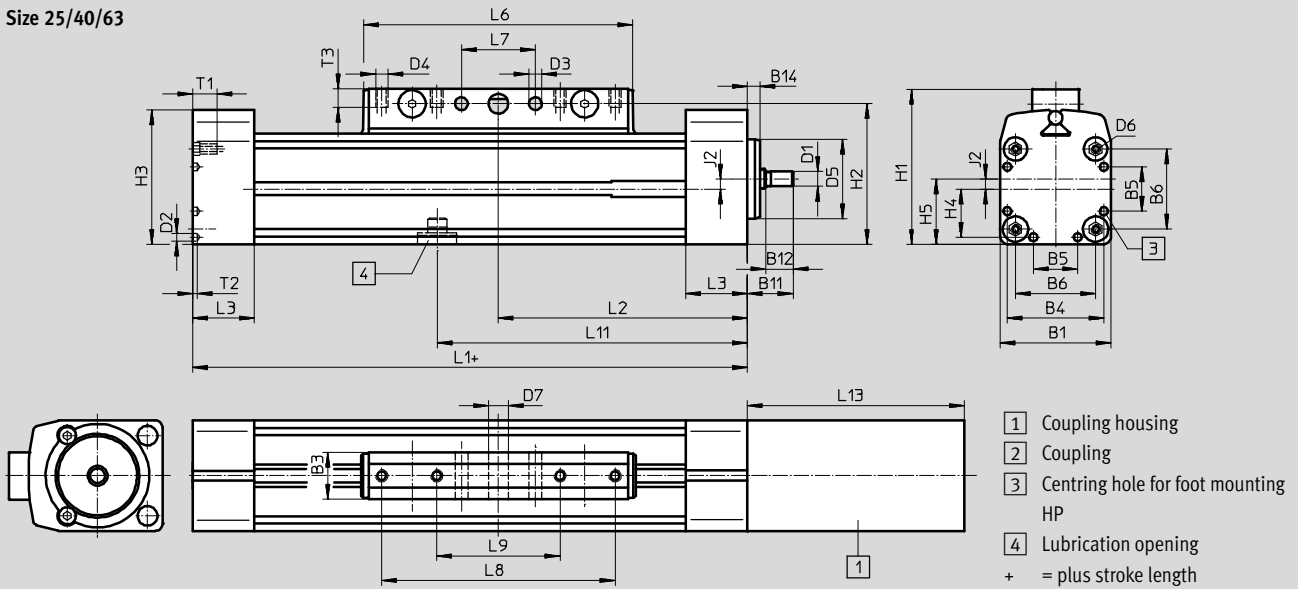
Dimensions

Download CAD data → www.festo.com

Size 18



Size 25/40/63



- 1) Coupling housing
- 2) Coupling
- 3) Centring hole for foot mounting HP
- 4) Lubrication opening
- + = plus stroke length

Size	B1	B3	B4	B5	B6	B11	B12	B14	D1	D2	D3	D4	D5	D6	D7	H1	H2	H3
	+0.4								∅ h7	∅	∅		∅ g7		∅ H10			
25	45	19	39.1	18	32.5	18.5	11	4	6	3.3	5.2	M5	32	M4	8	63	57	54.5
40	64	21	53	28	49	33.5	23	5	12	4.4	6.5	M6	48	M5	10	86	78	76.5
63	106	24	89	44	83	47.5	25	7	20	6.4	8.5	M8	72	M8	12	131	122	127.5

Size	H4	H5	J2	L1	L2	L3	L6	L7	L8	L9	L11	L13			T1	T2	T3
												1)	2)	3)			
25	19.6	26.5	4	175	87.5	25	108.8	30	±0.1	±0.1	±0.1	88	101	-	13	2	7.5
40	26.5	37	5	250	126	31	170.8	70	130	40	151	121	135	-	13	6	10
63	44.5	61	8	328	164	36	233.8	110	190	70	196	150	150	150	21	6	12.5

- 1) When combined with motor unit MTR-DCI with gear reduction 7:1.
- 2) When combined with motor unit MTR-DCI with gear reduction 14:1.
- 3) When combined with motor unit MTR-DCI with gear reduction 22:1.

Positioning axes DMES, without guide

Technical data

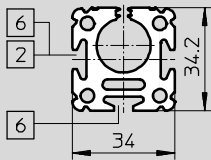


Dimensions

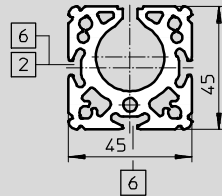
Download CAD data → www.festo.com

Profile

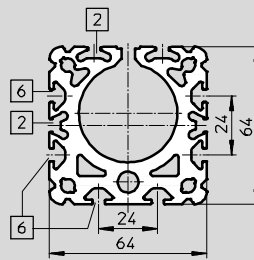
Size 18



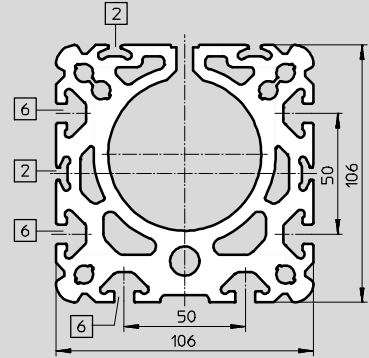
Size 25



Size 40



Size 63



2 Sensor slot for proximity sensor

6 Mounting slot for slot nut NST

Positioning axes DMES, without guide

Ordering data – Modular products

Order processing for positioning axis DMES in combination with intelligent motor unit MTR-DCI

1 Ordering positioning axis DMES [Ordering table → 15](#)

The drive unit and corresponding accessories are configured in the ordering table for the positioning axis DMES.

The code “AX” or “U” is used to specify whether an intelligent motor unit MTR-DCI and an axial or a parallel kit are required for the positioning axis.

The motor unit design must be defined separately.

3 Ordering intelligent motor unit MTR-DCI [Ordering table → LEERER MERKER](#)

The motor unit order code determined from table 2 must now be completed with the “gear unit” and “parameterisation interface” codes.

The module number of the intelligent motor unit must not be specified when ordering with order code “AX” or “U”. It is determined automatically.

1) Motor data				2) Options		
Module No.	Position	Size	Stroke	Motor unit	Accessories	Accessories supplied later
E33 400	DMES	25	70 - 1,200	42		25, 26, 27, 28, 29
E33 500		25				
E33 550		40				
E33 700		63				

Ordering table						
Size	25	40	63	Stroke	Stroke	Motor unit
Motor unit	E33 400	E33 500	E33 550	E33 700		DMES
Position	DMES					
Size	25	40	63			
Stroke	70 - 1,200	70 - 1,200	70 - 1,200			
Motor unit	Motor unit including electric interface motor unit					
Motor unit	E33 400					
Motor unit	E33 500					
Motor unit	E33 550					
Motor unit	E33 700					
Motor unit	E33 400					
Motor unit	E33 500					
Motor unit	E33 550					
Motor unit	E33 700					

3) Motor data										
Module No.	Motor unit	Type of motor	Range size	Length (mm)	Rated voltage	Rated torque	Rated speed (rpm)	Motor unit	Parameterisation interface	Electrical connection technology
E33 400	42	DC servo motor with integrated position controller	25	100	24V	0.2	1,500	E33	42	BT
E33 500	42	DC servo motor with integrated position controller	40	100	24V	0.4	1,500	E33	42	BT
E33 550	42	DC servo motor with integrated position controller	55	100	24V	0.6	1,500	E33	42	BT
E33 700	42	DC servo motor with integrated position controller	70	100	24V	1.0	1,500	E33	42	BT

Ordering table						
Size	25	40	55	70	Stroke	Motor unit
Motor unit						E33
Type of motor	DC servo motor with integrated position controller					
Parameterisation interface	42	42	50	50		42
Electrical connection technology	BT					
Rated torque	0.2	0.4	0.6	1.0		0.2
Rated speed	1,500					
Motor unit	E33 400					
Parameterisation interface	42					
Electrical connection technology	BT					

2 Permissible combinations with intelligent motor unit MTR-DCI

Positioning axis	Motor unit
DMES-18-...	MTR-DCI-32S-VCSC-E-...
DMES-25-...	MTR-DCI-42S-VCSC-E-...
DMES-40-...	MTR-DCI-52S-VCSC-E-...
DMES-63-...	MTR-DCI-62S-VDSC-E-...

4 Order example

Part No.	Type
	Positioning axis DMES
533700	DMES-25-700-AX:ZUB-2S2Y1M1F
	Intelligent motor unit MTR-DCI
-	MTR-DCI-42S-VCSC-EG7-R210

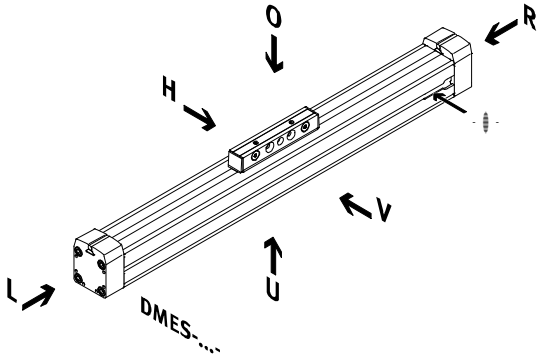
Note
 Servo, stepper motors and the corresponding mounting kits must be ordered separately → 40

Positioning axes DMES, without guide

Ordering data – Modular products

Order code

Mandatory data



<p>- - Note</p> <p>The insertion point for the proximity sensor is located on the right-hand side of the positioning axis.</p>	<p>O top U underneath V front H rear R right L left</p>
---	--

Order code

Options

Motor unit		U
Parallel kit		
Motor unit		AX
Axial kit		
B/S		
→ 47		
→ 47		
Y		
M		
F		

Positioning axes DMES, without guide

Ordering data – Modular products

M Mandatory data				O Options		
Module No.	Function	Size	Stroke	Motor unit	Accessories	Accessories supplied loose
533699	DMES	18	50 ... 1800	AX U		...S, ...B, ...Y, ...M, ...F
533700		25				
533701		40				
533702		63				
Order example						
533700	DMES	- 25	- 700		:	ZUB - 2S2Y2M
MTR-DCI-...S-...SC-E-...IO						

Ordering table							
Size	18	25	40	63	Condi-tions	Code	Enter code
M Module No.	533699	533700	533701	533702			
Function	Positioning axis without guided slide					DMES	DMES
Size	18	25	40	63		-...	
Stroke [mm]	50 ... 400	50 ... 700	50 ... 1200	50 ... 1800		-...	
O Motor unit	Axial kit and motor unit (enclosed separately)				1	-AX	
	Parallel kit and motor unit (enclosed separately)				-	U	
Accessories	Supplied separately					:ZUB-	:ZUB-
Slot cover	Sensor slot	1 ... 10				...S	
	Mounting slot	-	-	1 ... 10		...B	
Slot nut	Mounting slot	1 ... 10				...Y	
Central support	1 ... 10					...M	
Foot mounting	1 ... 10					...F	

1 **AX, U** Order processing for intelligent motor unit MTR-DCI → LEERER MERKER.

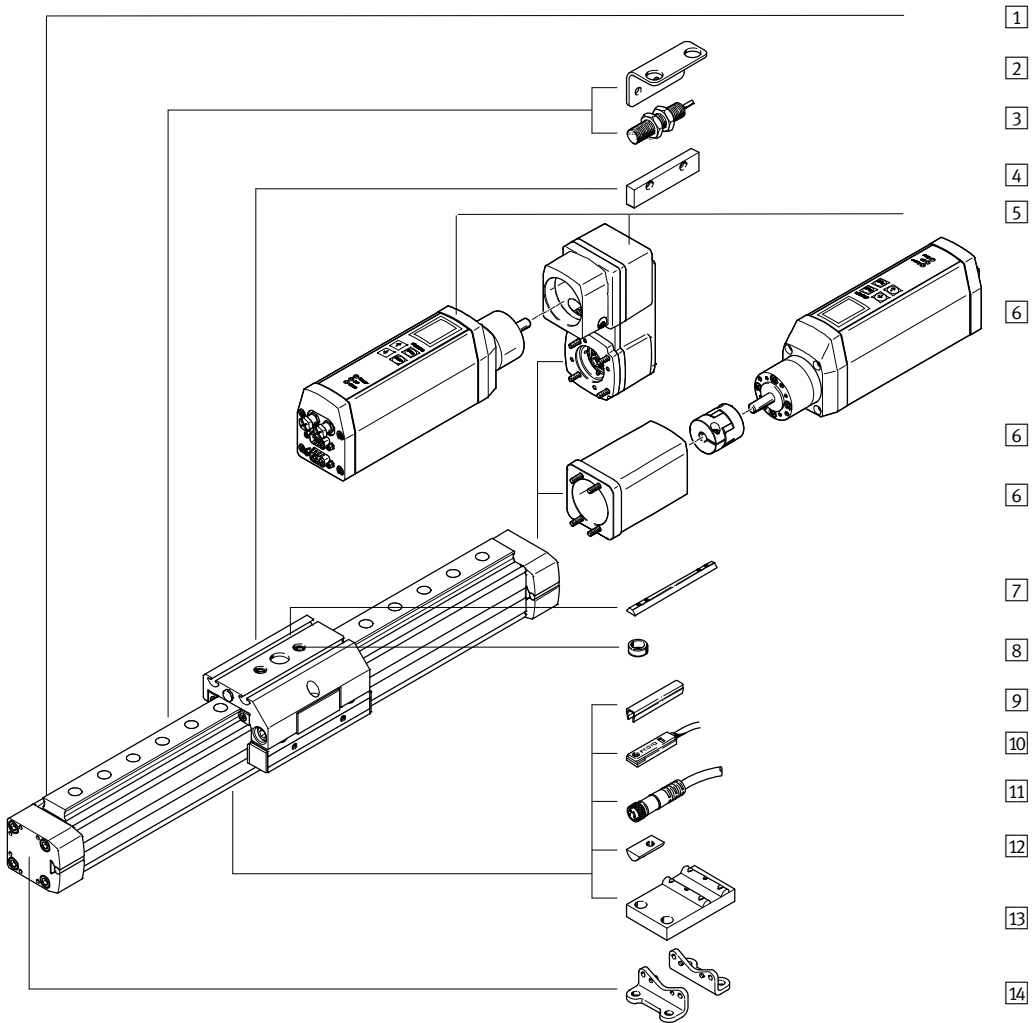
- M** Mandatory data
- O** Options

Transfer order code

	DMES	-		-		-		:	ZUB	-	
MTR-DCI-...S-...SC-E-...IO											

Positioning axes DMES-KF, with recirculating ball bearing guide

Peripherals overview




Positioning axes DMES-KF, with recirculating ball bearing guide

Peripherals overview

Variants and accessories				
Type/Order code	Description	GK/GV	GA	→ Page/Internet
1	Positioning axis DMES	■	■	20
2	Sensor retainer T	■	-	45
3	Inductive proximity sensor SIEN	■	-	46
4	Switching lug L	■	-	45
5	Motor unit and parallel kit U	■	■	37
6	Motor unit and axial kit AX	■	■	37
7	Slot nut for slide X	■	■	47
8	Centring sleeves Z	■	■	47
9	Slot cover B/S	■	■	47
10	Proximity sensor SMT-8	■	■	46
11	Connecting cable KM8	■	■	46
12	Slot nut for mounting slot Y	■	■	47
13	Central support M	■	■	44
14	Foot mounting F	■	■	44

GK: Standard slide
 GV: Extended slide
 GA: Protected version

 Note
 Servo, stepper motors and the corresponding mounting kits must be ordered separately → 40

Positioning axes DMES-KF, with recirculating ball bearing guide

Type code

DMES - 25 - 500 - KF - GK - SH - - AX

Type	
DMES	Positioning axis
Size	
Stroke [mm]	
Guide	
KF	Recirculating ball bearing guide
Slide	
GK	Standard slide
GV	Extended slide
GA	Protected version
Slide attachment position	
SV	Front
SH	Rear
Additional slide	
KL	Left
KR	Right
Motor unit	
AX	Motor unit and axial kit
U	Motor unit and parallel kit

Positioning axes DMES-KF, with recirculating ball bearing guide

Type code

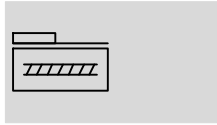
		:ZUB	-		2X	2M		Z	2T	L
Accessories										
ZUB	Accessories supplied loose									
Slot cover										
...S	Sensor slot									
...B	Mounting slot									
Slot nut										
...Y	For mounting slot									
...X	For slide									
Central support										
...M	Central support									
Foot mounting										
...F	Foot mounting									
Centring sleeves										
...Z	For slide									
Mounting bracket										
...T	For inductive proximity sensors									
Switching lug										
L	Switching lug									

Positioning axes DMES-KF, with recirculating ball bearing guide

FESTO



Technical data

Function



 www.festo.com



-  - Size
18 ... 63
-  - Stroke length
50 ... 1,800 mm

General technical data					
Size		18	25	40	63
Design		Electromechanical linear axis with lead-screw spindle			
Guide		With recirculating ball bearing guide			
Assembly position		Any			
Working stroke	[mm]	50 ... 400	50 ... 700	50 ... 1200	50 ... 1800
Max. feed force F_x	[N]	240	500	1000	3000
Max. driving torque	[Nm]	0.3	0.9	3	14
Max. no-load driving torque ¹⁾	[Nm]	0.07	0.2	0.45	1.1
Max. radial force ²⁾	[N]	40	75	250	800
Max. speed	[m/s]	0.05			
Max. acceleration	[m/s ²]	2.5			
Repetition accuracy	[mm]	±0.05			±0.07
Positioning rigidity	[N/mm]	1700	2300	4200	5600
Duty cycle	[%]	100			
Reversing backlash ³⁾	[mm]	< 0.1			

1) Measured at a speed of 200 rpm.

2) On drive shaft

3) In new condition

Operating and environmental conditions		
Ambient temperature ¹⁾	[°C]	0 ... +50
Protection class		IP40

1) Note operating range of proximity sensors

Weights [kg]					
Size		18	25	40	63
Basic weight with 0 mm stroke ¹⁾	GK	0.93	1.70	5.06	16.48
	GV	1.37	2.61	8.06	27.14
	GA	1.65	2.90	8.14	–
Additional weight per 100 mm stroke	GK	0.294	0.547	1.170	2.958
	GV	0.294	0.547	1.170	2.958
	GA	0.369	0.638	1.294	–
Moving load	GK	0.38	0.66	1.83	5.29
	GV	0.56	0.99	2.72	7.88
	GA	0.81	1.30	3.24	–
Additional slide	KL/KR	0.29	0.440	1.21	3.55

1) Without coupling housing

Positioning axes DMES-KF, with recirculating ball bearing guide

Technical data

Mass moment of inertia			18	25	40	63
Size						
J_0	GK	[kg cm ²]	0.0030	0.0158	0.1879	1.8093
	GV	[kg cm ²]	0.0049	0.0265	0.3340	3.2258
	GA	[kg cm ²]	0.0039	0.0212	0.2476	–
j_H per metre stroke		[kg cm ² /m]	0.0210	0.0980	0.8400	5.5600
j_L per kg working load		[kg cm ² /Kg]	0.0006	0.0023	0.0041	0.0091
j_W for additional slide		[kg cm ²]	0.0002	0.0010	0.0049	0.0324

The mass moment of inertia J_A of the entire axis is calculated as follows:

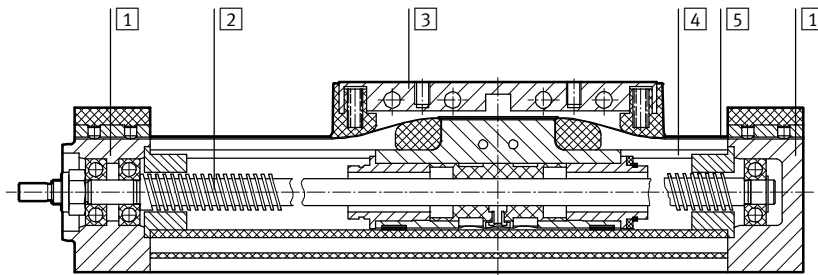
$$J_A = J_0 + j_H \times \text{working stroke [m]} + j_L \times m_{\text{working load [kg]}} + i \times j_W$$

i = Number of additional slides

Spindle			18	25	40	63
Size						
Diameter		[mm]	8	12	20	32
Pitch		[mm/rev.]	1.5	2.5	4	6

Materials

Sectional view



Positioning axis		
1	Cover	Wrought aluminium alloy, anodised
2	Spindle	Steel
3	Piston, driver	Wrought aluminium alloy, anodised
4	Profile	Wrought aluminium alloy, anodised
5	Cover strip	High-alloy stainless steel
–	Guide rail for KF	Hardened steel

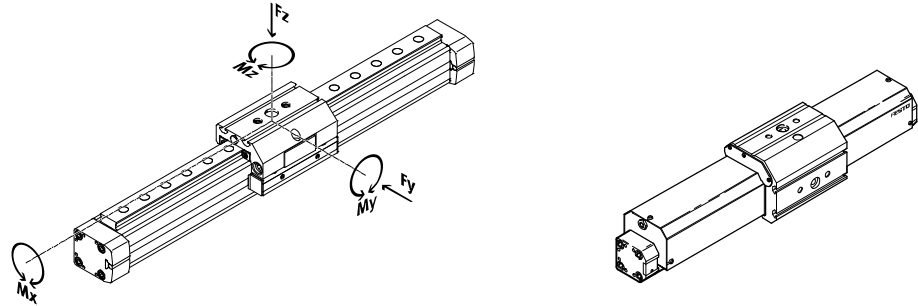
Positioning axes DMES-KF, with recirculating ball bearing guide

Technical data



Characteristic load values for axis with standard slide GK or protected version GA

The indicated forces and torques refer to the centre of the guide rail. They must not be exceeded during dynamic operation. Special attention must be paid to the cushioning phase.

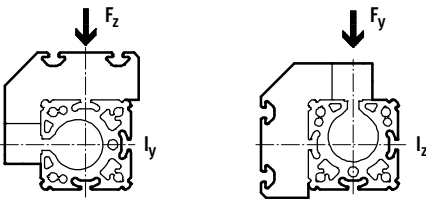


If the axis is subjected to more than two of the indicated forces and torques simultaneously, the following equation must be satisfied in addition to the indicated maximum loads:

$$\frac{|F_y|}{F_{y_{max}}} + \frac{|F_z|}{F_{z_{max}}} + \frac{|M_x|}{M_{x_{max}}} + \frac{|M_y|}{M_{y_{max}}} + \frac{|M_z|}{M_{z_{max}}} \leq 1$$

Permissible forces and torques					
Size		18	25	40	63
F _y _{max.}	[N]	930	2600	4300	6600
F _z _{max.}	[N]	930	2600	4300	6600
M _x _{max.}	[Nm]	7	45	160	400
M _y _{max.}	[Nm]	23	85	330	910
M _z _{max.}	[Nm]	23	85	330	910

2nd moment of area



Size		18	25	40	63
I _y	[cm ⁴]	14.37	47.60	176.24	992.06
I _z	[cm ⁴]	7.16	23.34	95.43	693.35

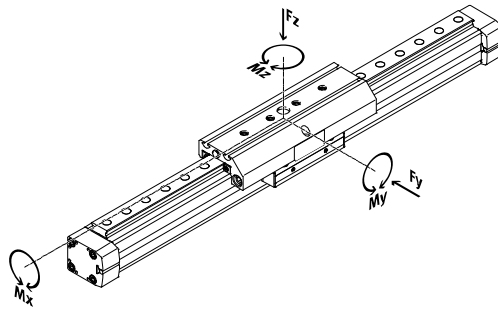
- - Note
Sizing software
PositioningDrives
→ www.festo.com

Positioning axes DMES-KF, with recirculating ball bearing guide

Technical data

Characteristic load values for axis with extended slide GV

The indicated forces and torques refer to the centre of the guide rail. They must not be exceeded during dynamic operation. Special attention must be paid to the cushioning phase.

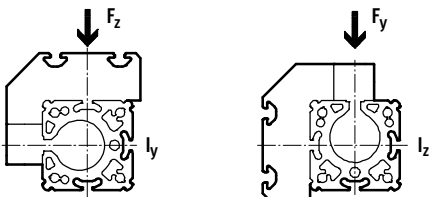


If the axis is subjected to more than two of the indicated forces and torques simultaneously, the following equation must be satisfied in addition to the indicated maximum loads:

$$\frac{|F_y|}{F_{y_{max}}} + \frac{|F_z|}{F_{z_{max}}} + \frac{|M_x|}{M_{x_{max}}} + \frac{|M_y|}{M_{y_{max}}} + \frac{|M_z|}{M_{z_{max}}} \leq 1$$

Permissible forces and torques					
Size		18	25	40	63
F _y _{max.}	[N]	930	3080	7300	13900
F _z _{max.}	[N]	930	3080	7300	14050
M _x _{max.}	[Nm]	7	45	170	580
M _y _{max.}	[Nm]	45	170	660	1820
M _z _{max.}	[Nm]	45	170	660	1820

2nd moment of area



Size		18	25	40	63
I _y	[cm ⁴]	14.37	47.60	176.24	992.06
I _z	[cm ⁴]	7.16	23.34	95.43	693.35

Positioning axes DMES-KF, with recirculating ball bearing guide

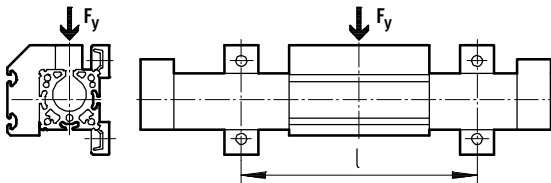
Technical data



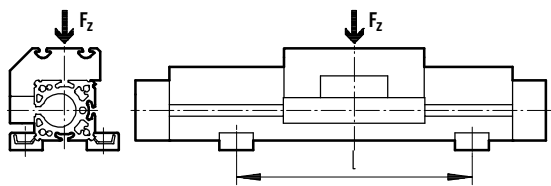
Deflection of the positioning axis as a function of the working load F and the support span l

The following diagrams can be used to determine the deflection of a positioning axis supported externally at both ends (see drawing below). A differentiation is made between two load directions. The axis may also need to be supported with central supports MUP in order to limit deflection in the case of large strokes.

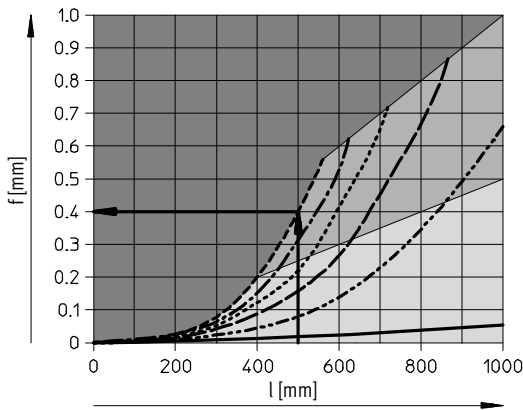
Deflection along the y-axis



Deflection along the z-axis



Example showing how to determine deflection



Given:

Positioning axis
DMES-25-700-KF-...

Working stroke = 700 mm
Total length of the positioning axis, dimensional drawing \rightarrow 29
700 mm + 175 mm = 875 mm
Working load F = 2500 N
Support span l = 500 mm

To be found:

Deflection f

Procedure:

A support span of 500 mm (see X-axis) and a working load of 2500 N (see characteristic curve) produces a deflection of 0.4 mm.

Note:

The slide may not be moved under this load as the operating point is in the static area of the diagram. In order to be able to operate the slide dynamically, the support span must be reduced to 400 mm.

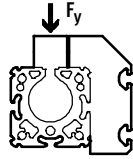
- Impermissible range:** The positioning axis may not be used.
- Static range:** The slide must not be moved under load.
- Static and dynamic range:** The slide must be moved under load.

Positioning axes DMES-KF, with recirculating ball bearing guide

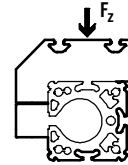
Technical data

Deflection of the positioning axis as a function of the working load F and the working stroke l

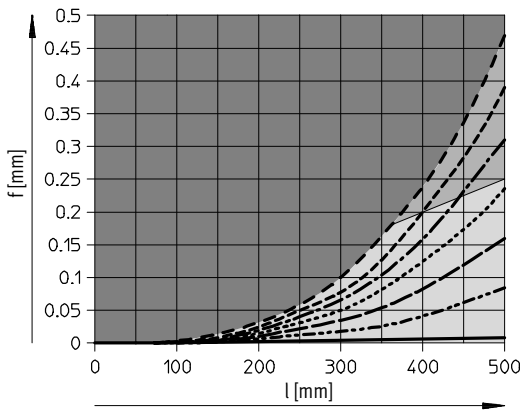
Along the y-axis



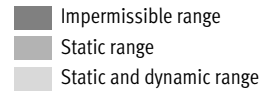
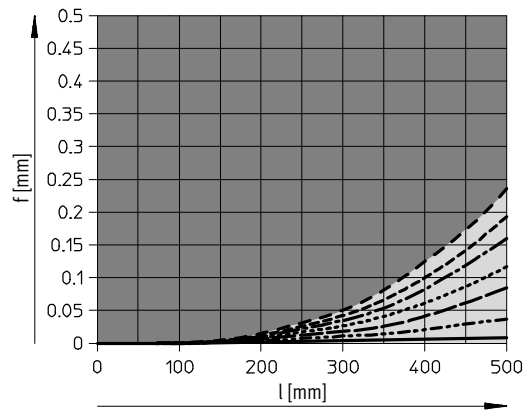
Along the z-axis



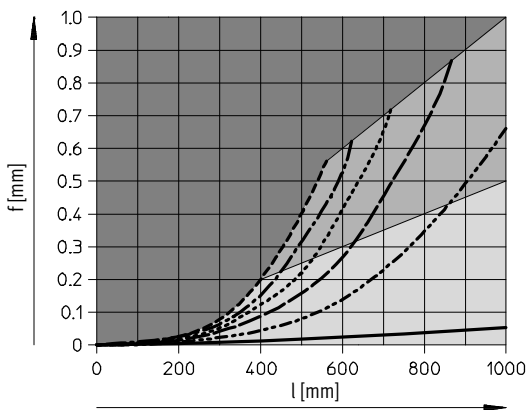
DMES-18



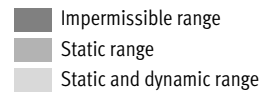
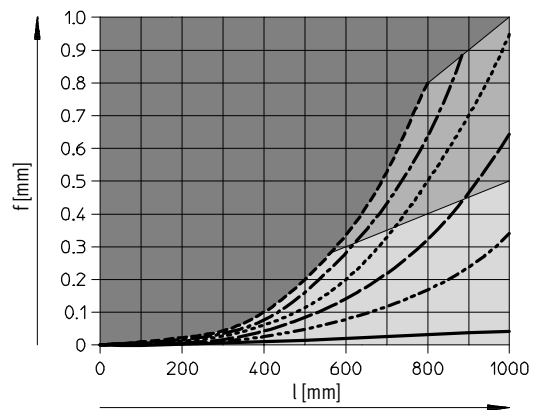
DMES-18



DMES-25



DMES-25



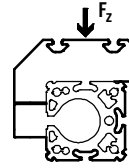
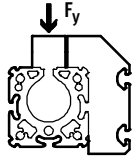
Positioning axes DMES-KF, with recirculating ball bearing guide

Technical data

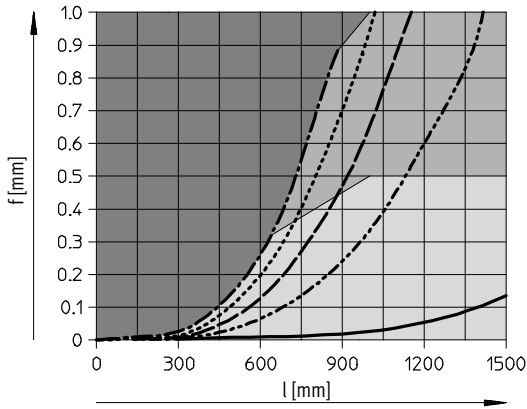
Deflection of the positioning axis as a function of the working load F and the working stroke l

Along the y-axis

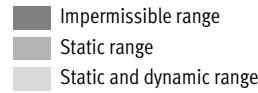
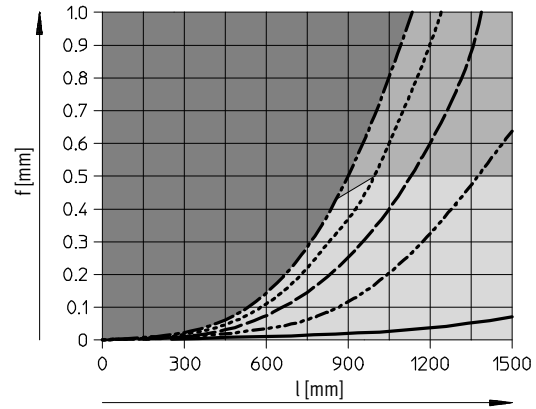
Along the z-axis



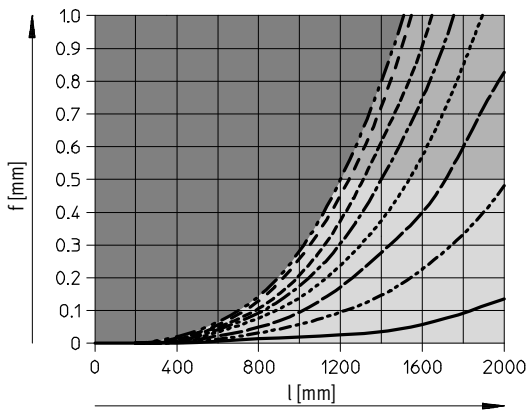
DMES-40



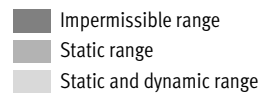
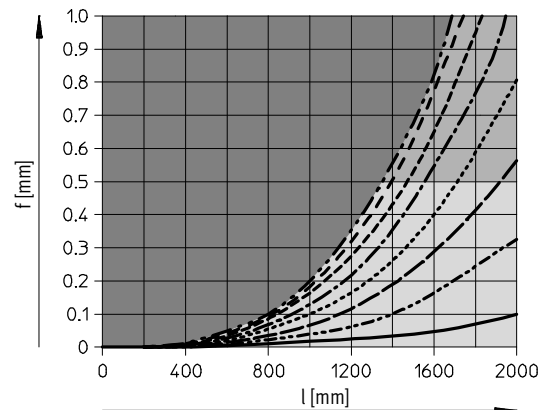
DMES-40



DMES-63



DMES-63

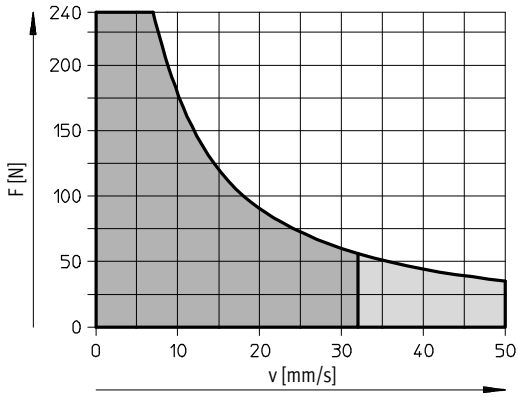


Positioning axes DMES-KF, with recirculating ball bearing guide

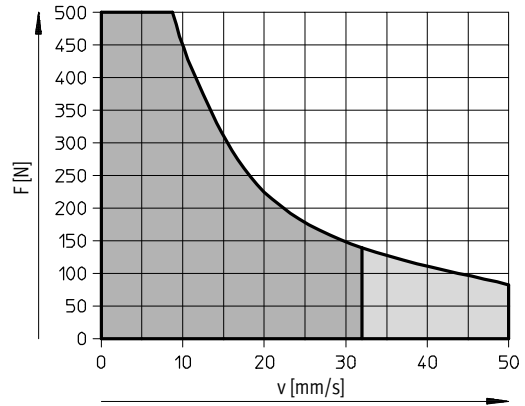
Technical data

Maximum permissible feed force F as a function of the feed speed v

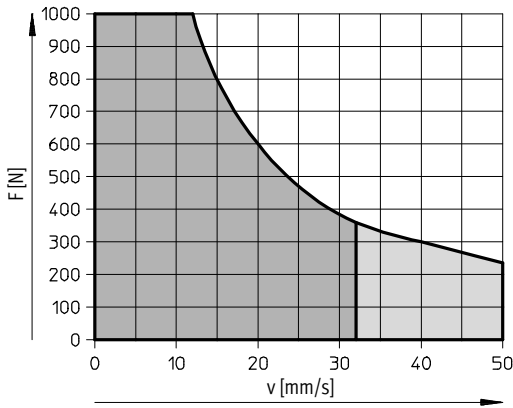
DMES-18



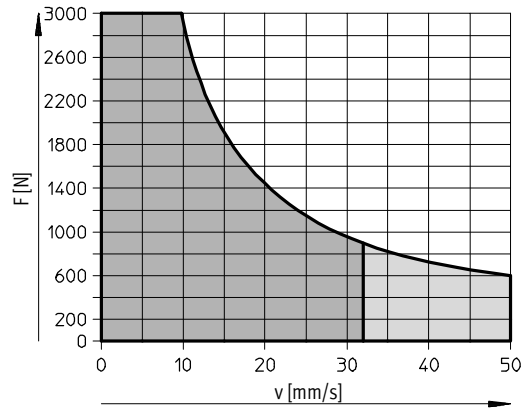
DMES-25



DMES-40



DMES-63



- Recommended operating range
- Permissible operating range (duty cycle < 50% recommended)

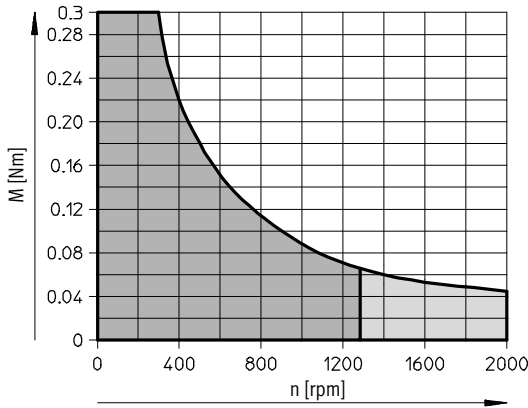
Positioning axes DMES-KF, with recirculating ball bearing guide

Technical data

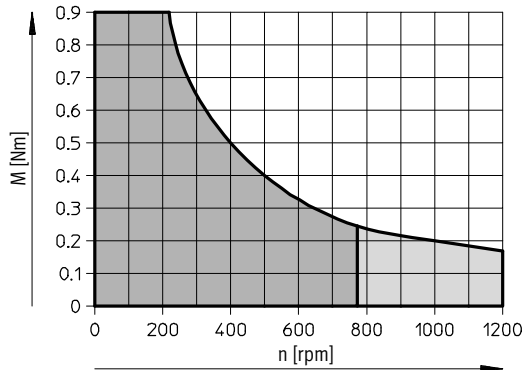


Maximum permissible driving torque M as a function of n (rpm)

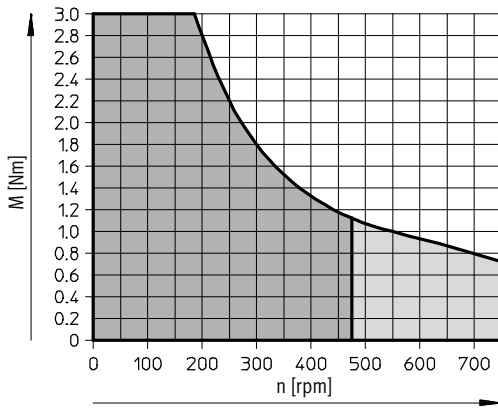
DMES-18



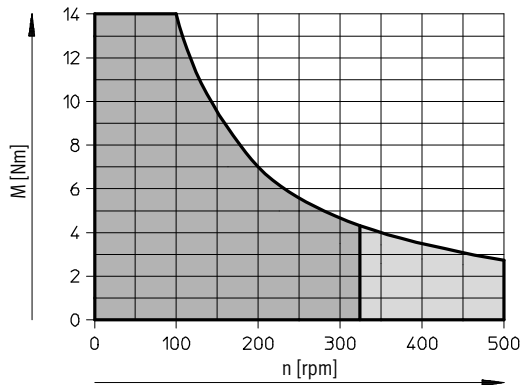
DMES-25



DMES-40

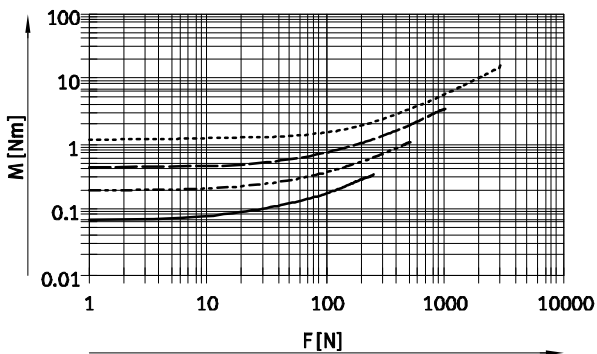


DMES-63

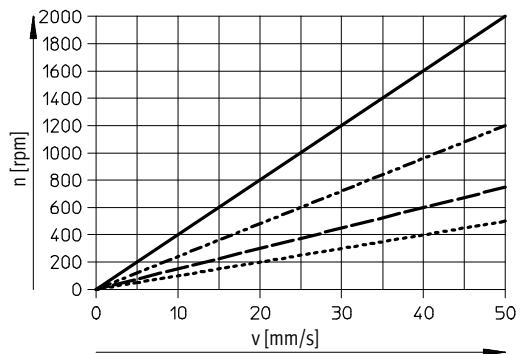


- Recommended operating range
- Permissible operating range (duty cycle < 50% recommended)

Driving torque M as a function of the feed force F



Speed as a function of the feed speed v



- DMES-18
- - - - - DMES-25
- · - · - DMES-40
- · · · · DMES-63

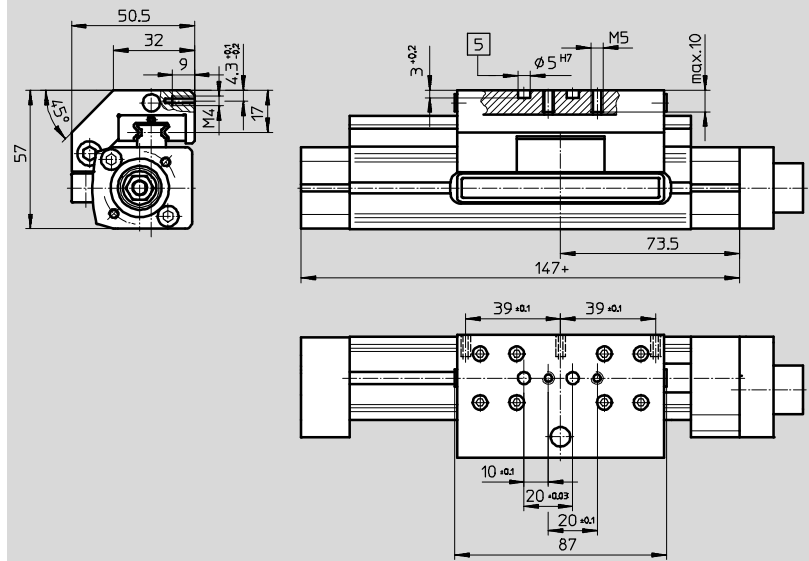
Positioning axes DMES-KF, with recirculating ball bearing guide

Technical data

Dimensions Download CAD data → www.festo.com

Standard slide GK

Size 18

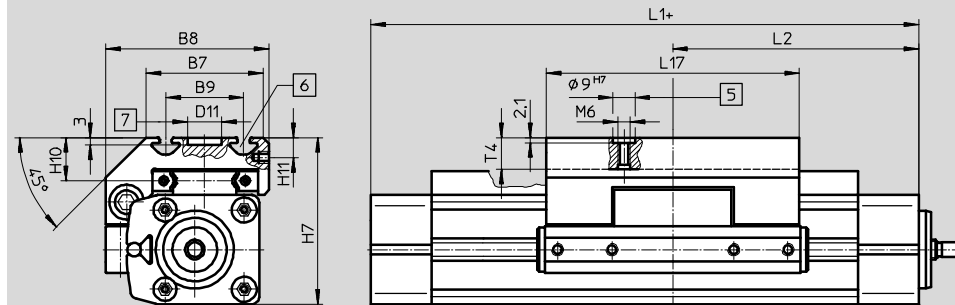


5 Hole for centring pin ZBS-5

Basic dimensions

→ 11

Size 25/40/63



5 Hole for centring pin ZBH-9

6 Mounting slot for slot nut NSTL

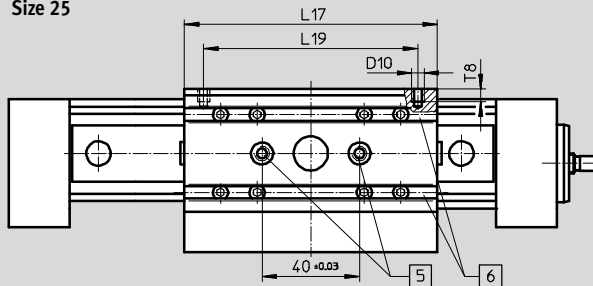
7 Hole for central mounting SLZZ

+ = plus stroke length

Basic dimensions

→ 11

Size 25



Size	B7	B8	B9	D10	D11	H7	H10	H11	L1	L2	L17	L19	T4	T8
			±0.2		∅ G7			+0.3					±0.1	max.
25	48	67	32	M5	14	68.5	18.5	8.2	175	87.5	105	88	12.5	8.5
40	78.5	96.5	55	M5	25	90.5	20	7	250	126	167	150	12.5	8.5
63	121	142	90	M8	25	144.5	30	12.5	328	164	230	200	20.5	10.5

Positioning axes DMES-KF, with recirculating ball bearing guide

Technical data

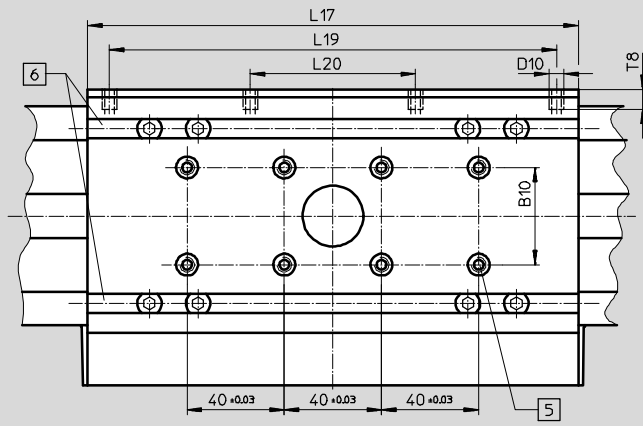


Dimensions

Download CAD data → www.festo.com

Standard slide GK

Size 40/63



- 5 Hole for centring pin ZBH-9
- 6 Mounting slot for slot nut NSTL
- + = plus stroke length

Size	D10	L17	L19	L20	T8
			±0.1	±0.1	
25	M5	105	88	-	8.5
40	M5	167	150	58	8.5
63	M8	230	200	72	10.5

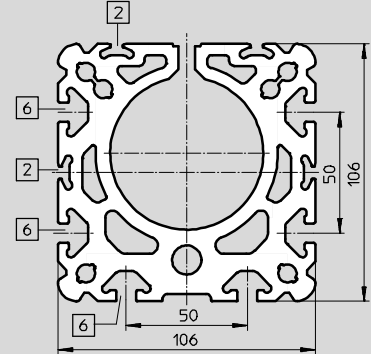
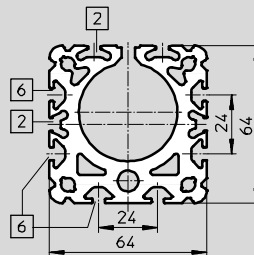
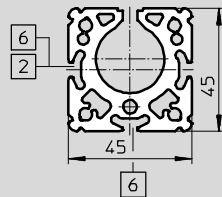
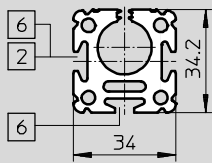
Profile

Size 18

Size 25

Size 40

Size 63



- 2 Sensor slot for proximity sensor

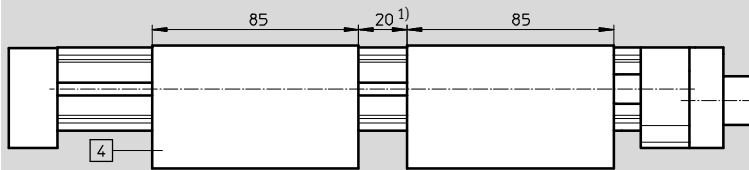
- 6 Mounting slot for slot nut NST

Positioning axes DMES-KF, with recirculating ball bearing guide

Technical data

Additional slide KL/KR

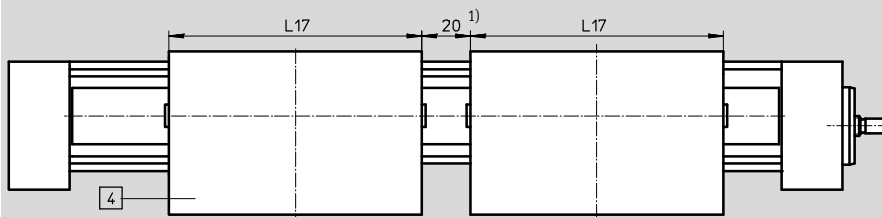
Size 18



4 Additional slide
DMES-...-KL/KR

1) Recommended minimum distance for access to lubrication nipple

Size 25/40/63



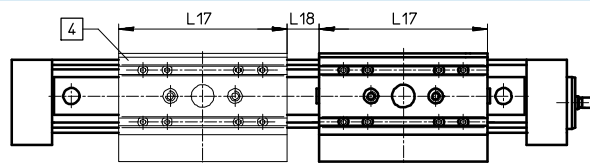
4 Additional slide
DMES-...-KL/KR

1) Recommended minimum distance for access to lubrication nipple

Size	L17
18	85
25	105
40	167
63	230

Working stroke reduction with standard slide GK or extended slide GV and additional slide KL/KR

- L17 = Slide/additional slide length
- L18 = Distance between both slides
- 4 Additional slide



For a toothed belt axis with additional slide, the working stroke is reduced by the length of the additional slide and the distance between both slides.

Example:
 Type DMES-25-500-KF-GK ... KL
 Working stroke without additional slide = 500 mm
 L18 = 20 mm
 L17 = 105 mm
 Working stroke with additional slide = 375 mm
 (500 mm – 20 mm – 105 mm)

Positioning axes DMES-KF, with recirculating ball bearing guide

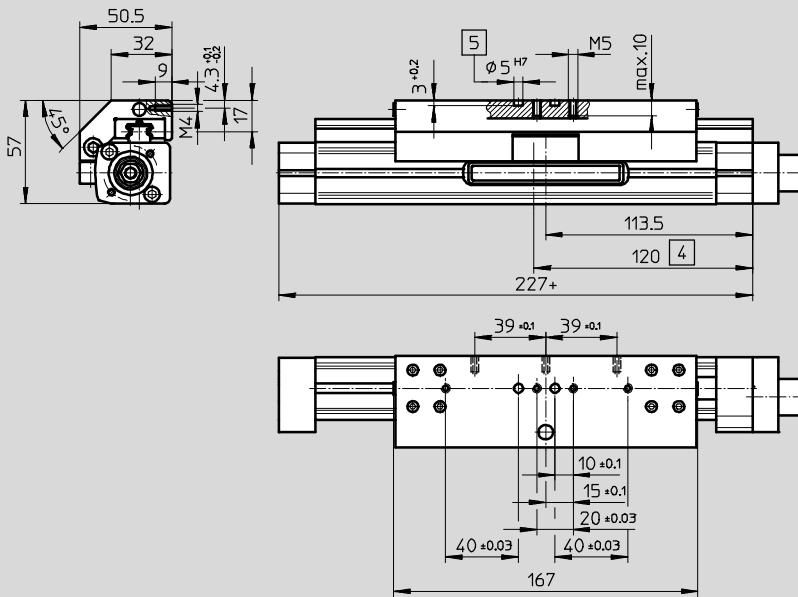
Technical data

Dimensions

Download CAD data → www.festo.com

Extended slide GV

Size 18



- 4 Lubrication opening
- 5 Hole for centring pin ZBS-5
- + = plus stroke length

Basic dimensions

→ 11

Positioning axes DMES-KF, with recirculating ball bearing guide

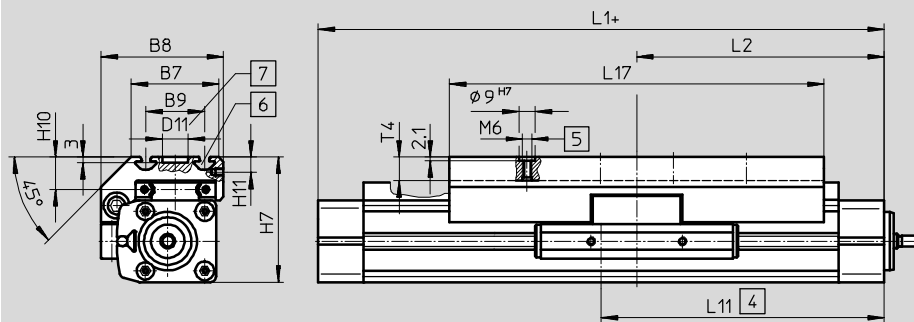
Technical data

Dimensions

Download CAD data → www.festo.com

Extended slide GV

Size 25/40/63

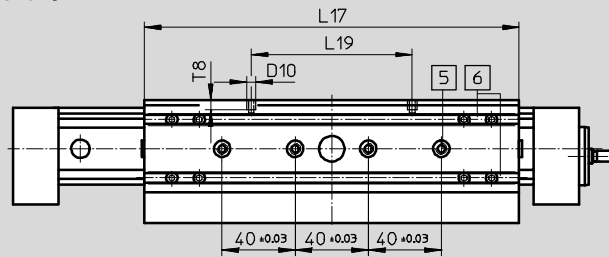


- 4 Lubrication opening
- 5 Hole for centring pin ZBS-9
- 6 Slot for slot nut NSTL
- 7 Hole for central mounting SLZZ
- + = plus stroke length

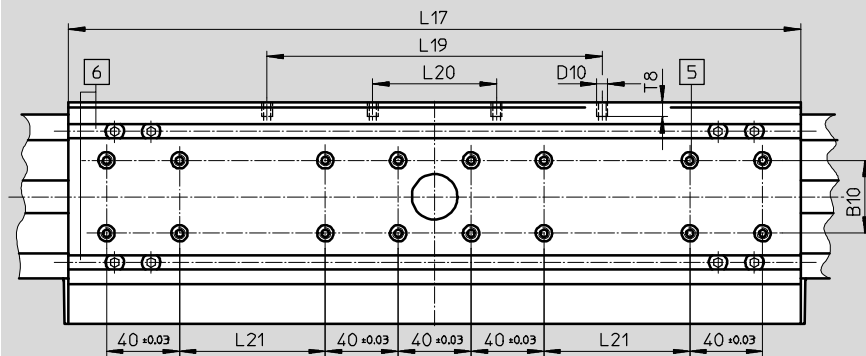
Basic dimensions

→ 11

Size 25



Size 40



- 5 Hole for centring pin ZBH-9
- 6 Mounting slot for slot nut NSTL

Size	B7	B8	B9	B10	D10	D11	H7	H10	H11
			±0.2			∅ G7			+0.3
25	48	67	32	–	M5	14	68.5	18.5	8.2
40	78.5	96.5	55	20	M5	25	90.5	20	7
63	121	142	90	40	M8	25	144.5	30	12.5

Size	L1	L2	L11	L17	L19	L20	L21	T4	T8
				±0.1	±0.1	±0.1	±0.1	max.	
25	275	137.5	155	205	88	–	–	12.5	8.5
40	420	211	236	337	150	58	40	12.5	8.5
63	578	289	321	480	200	72	120	20.5	10.5

Positioning axes DMES-KF, with recirculating ball bearing guide

Technical data

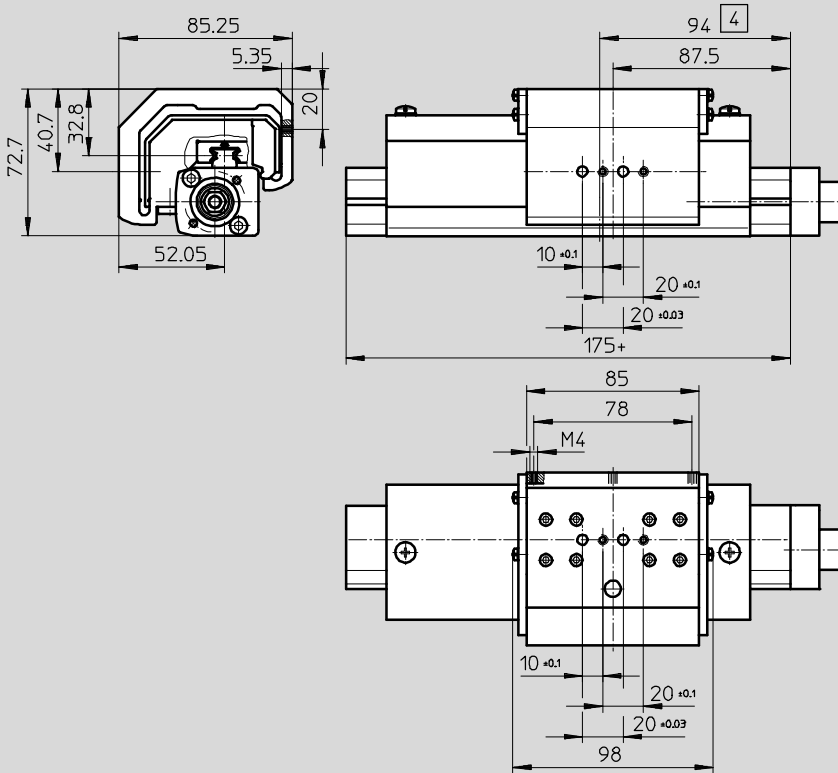
FESTO

Dimensions

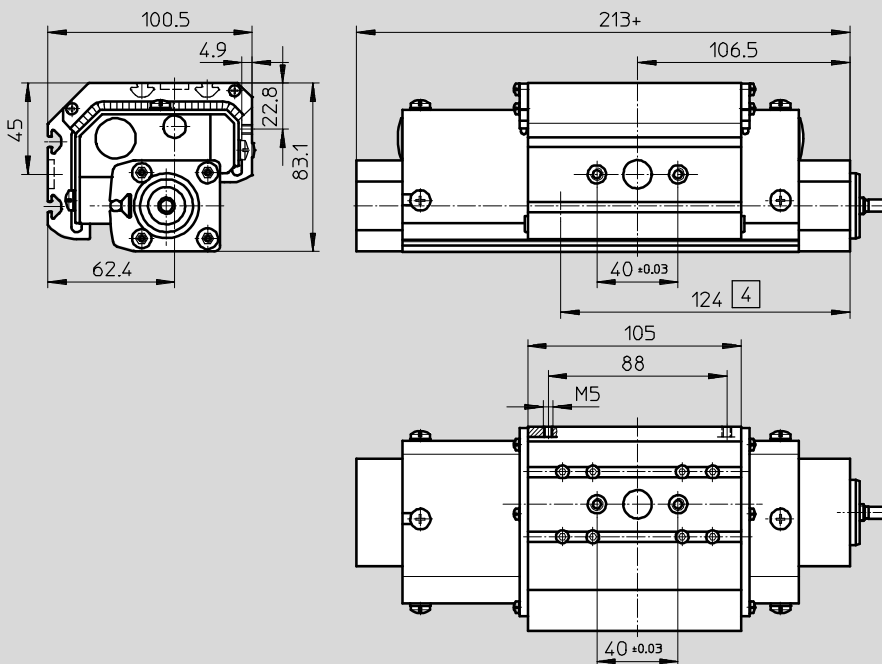
Download CAD data → www.festo.com

Protected version GA

Size 18



Size 25



Positioning axes DMES-KF, with recirculating ball bearing guide

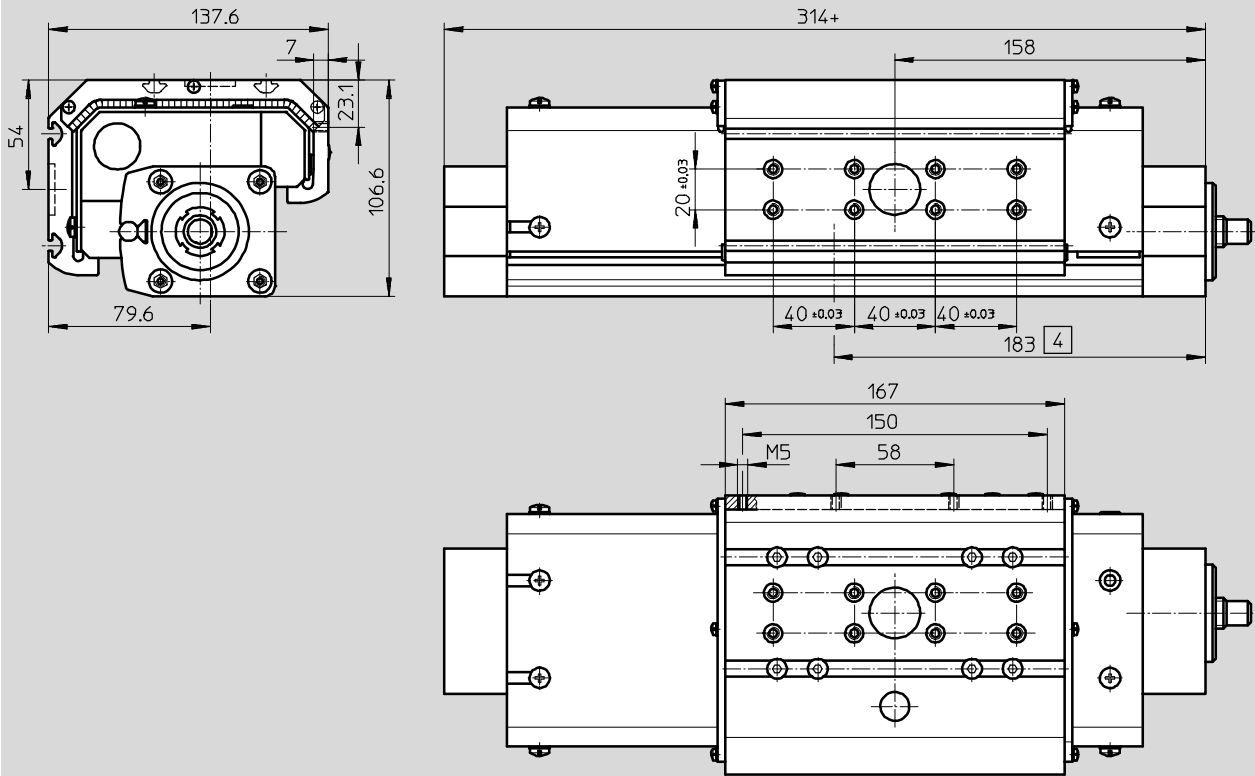
Technical data

Dimensions

Download CAD data → www.festo.com

Protected version GA

Size 40



4 Lubrication opening
+ = plus stroke length

Positioning axes DMES-KF, with recirculating ball bearing guide

Ordering data – Modular products

Order processing for positioning axis DMES in combination with intelligent motor unit MTR-DCI

- 1 Ordering positioning axis DMES [Ordering table → 38](#)
- 3 Ordering intelligent motor unit MTR-DCI [Ordering table → LEERER MERKER](#)

The drive unit and corresponding accessories are configured in the ordering table for the positioning axis DMES.

The code “AX” or “U” is used to specify whether an intelligent motor unit MTR-DCI and an axial or a parallel kit are required for the positioning axis.

The motor unit design must be defined separately.

The motor unit order code determined from table 2 must now be completed with the “gear unit” and “parameterisation interface” codes.

The module number of the intelligent motor unit must not be specified when ordering with order code “AX” or “U”. It is determined automatically.

DMES-18...				DMES-25...				DMES-40...				DMES-63...				
Module No.	Motor unit	Drive	Shaft	Mounting kit	Motor unit	Drive	Shaft	Mounting kit	Motor unit	Drive	Shaft	Mounting kit	Motor unit	Drive	Shaft	Mounting kit
533 449	MTR-DCI	25	25 ... 3,800	63	63	63	70	63	63	63	63	63	63	63	63	63
533 798	MTR-DCI	25	25 ... 3,800	63	63	63	70	63	63	63	63	63	63	63	63	63
533 794	MTR-DCI	40	40 ... 5,000	63	63	63	70	63	63	63	63	63	63	63	63	63
533 794	MTR-DCI	40	40 ... 5,000	63	63	63	70	63	63	63	63	63	63	63	63	63
533 794	MTR-DCI	40	40 ... 5,000	63	63	63	70	63	63	63	63	63	63	63	63	63
533 794	MTR-DCI	40	40 ... 5,000	63	63	63	70	63	63	63	63	63	63	63	63	63

MTR-DCI												
Module No.	Motor unit	Type of motor	Range size	Range class	Motor voltage	Plug design	Regulation method	Gear unit	Parameterisation interface	ES-2002 connection technology		
533 798	MTR-DCI	25	S	VC	2C	E	07	024	42	01		
533 794	MTR-DCI	40	S	VC	2C	E	07	024	42	01		
533 794	MTR-DCI	40	S	VC	2C	E	07	024	42	01		

Ordering table													
Type	30	40	50	60	Smallest motor	Code	Enter code						
Motor unit	MTR-DCI						533	798					
Type of motor	25	40	50	60			533	794					
Range size	S	S	S	S			533	794					
Range class	VC	VC	VC	VC			533	794					
Motor voltage	2C	2C	2C	2C			533	794					
Plug design	E	E	E	E			533	794					
Regulation method	07	07	07	07			533	794					
Gear unit	024	024	024	024			533	794					
Parameterisation interface	42	42	42	42			533	794					
ES-2002 connection technology	01	01	01	01			533	794					

2 Permissible combinations with intelligent motor unit MTR-DCI

Positioning axis	Motor unit
DMES-18-...	MTR-DCI-32S-VCSC-E...
DMES-25-...	MTR-DCI-42S-VCSC-E...
DMES-40-...	MTR-DCI-52S-VCSC-E...
DMES-63-...	MTR-DCI-62S-VDSC-E...

4 Order example

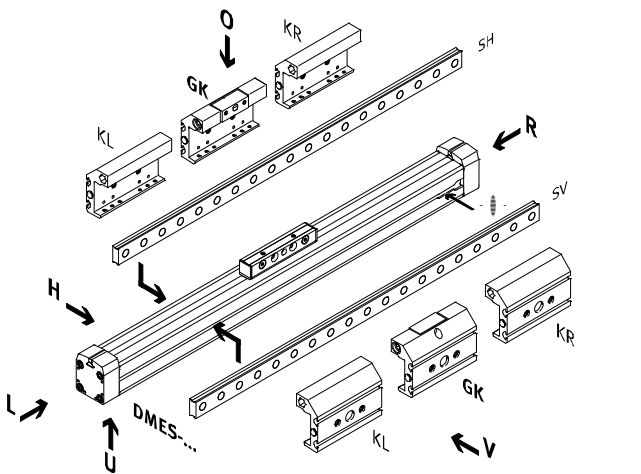
Part No.	Type
	Positioning axis DMES
533700	DMES-25-700-KF-GK-SH-AX:ZUB-2S2Y1M1F
	Intelligent motor unit MTR-DCI
-	MTR-DCI-42S-VCSC-EG7-R210

Note
Servo, stepper motors and the corresponding mounting kits must be ordered separately → 40

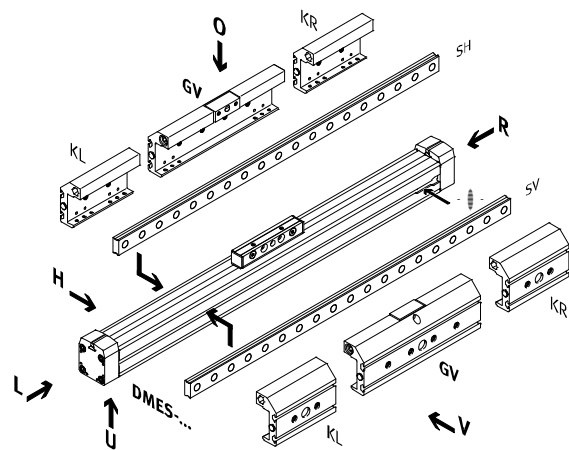
Positioning axes DMES-KF, with recirculating ball bearing guide

Ordering data – Modular products

Order code
Mandatory data
DMES-...-GK



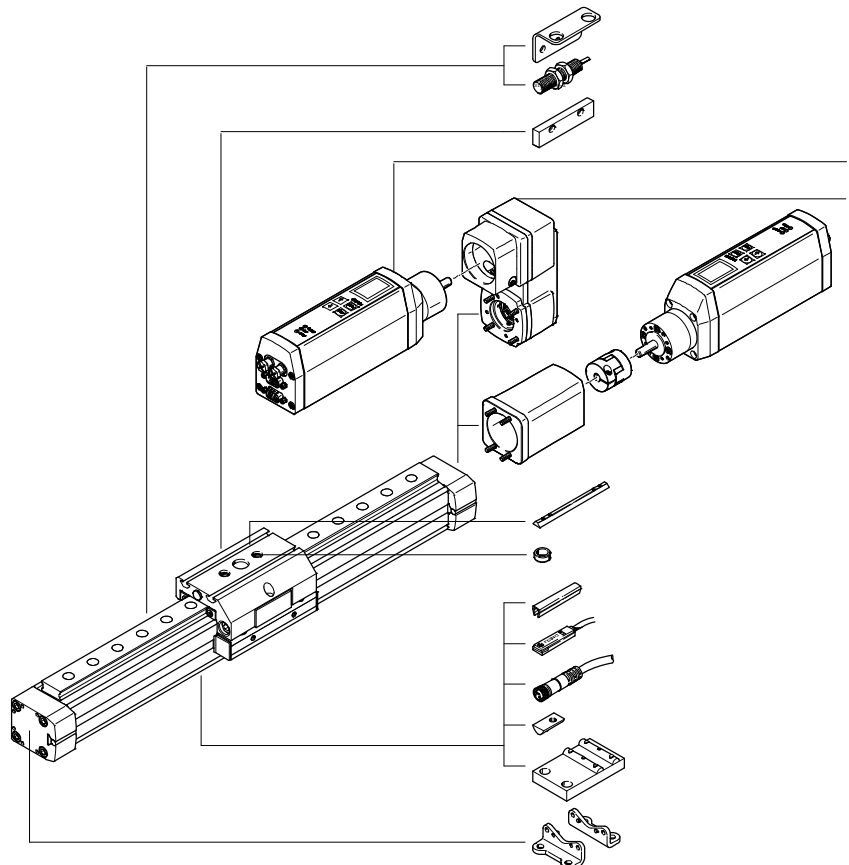
DMES-...-GV



- Note
The insertion point for the proximity sensor is located on the right-hand side of the positioning axis.

O top
U underneath
V front
H rear
R right
L left

Order code
Options



- T
- 47
- L
- Motor unit
- Parallel kit
- Motor unit
- Axial kit
- X
- Z
- B/S
- 47
- 47
- Y
- M
- F

Positioning axes DMES-KF, with recirculating ball bearing guide

Ordering data – Modular products

M Mandatory data			O Options						
Module No.	Function	Stroke	Guide		Slide attachment position		Motor unit	Accessories	
	Size		Slide		Additional slide			Accessories supplied loose	
533699	DMES 18	50 ... 1800	KF	GK	SV	KL	AX	...S, ...B, ...Y, ...X, ...M, ...F, ...Z, ...T, L	
533700	25			GV	SH	KR	U		
533701	40			GA					
533702	63								
Order example									
533701	DMES	- 40	- 800	- KF	- GV	- SV	- KL	- ZUB	- 2X2M20Z
MTR-DCI-...S-VCSC-E...-...IO									

Ordering table								
Size	18	25	40	63	Condi- tions	Code	Enter code	
M Module No.	533699	533700	533701	533702				
Function	Positioning axis with slide					DMES		DMES
Size	18	25	40	63		-...		
Stroke [mm]	50 ... 400	50 ... 700	50 ... 1200	50 ... 1800		-...		
Guide	Recirculating ball bearing guide				1	-KF		-KF
Slide	Standard slide				2	-GK		
	Extended slide				2	-GV		
	Protected version				-	-GA		
Slide attachment position	Slide at front				2	-SV		
	Slide at rear				2	-SH		
Additional slide	Additional slide, standard, at left				3	-KL		
	Additional slide, standard, at right				3	-KR		
Motor unit	Axial kit and motor unit (enclosed separately)				4	-AX		
	Parallel kit and motor unit (enclosed separately)				-	-U		
Accessories	Supplied separately					:ZUB-		:ZUB-
Slot cover	Sensor slot 1 ... 10					...S		
	Mounting slot -		1 ... 10			...B		
Slot nut	Mounting slot 1 ... 10					...Y		
	Slide -		1 ... 10		2	...X		
Central support	1 ... 10					...M		
Foot mounting	1 ... 10					...F		
Centring sleeve (pack of 10)	10 ... 90				2	...Z		
Mounting bracket for inductive proximity sensors	1 ... 5				5	...T		
Switching lug	1				5	L		

1 KF Only with slide GK, GV or GA and with slide attachment position SV or SH.

2 GK, GV, GA, SV, SH, X, Z

Only with guide KF

M Mandatory data

3 KL, KR

Only with guide KF (recirculating ball bearing guide) and with slide GK or GV

O Options

4 AX, U

Order processing for intelligent motor unit MTR-DCI → LEERER MERKER

5 T, L

Only with slide GK or GV

Transfer order code

DMES - **KF** - - - - - - : **ZUB** -

MTR-DCI-...S-VCSC-E...-...IO

Positioning axes DMES

Accessories – Motor units MTR-DCI



M Mandatory data										
Module No.	Motor unit		Flange/size		Nominal voltage		Measuring system		Parameterisation interface	
Order example	Motor type		Torque class		Plug design		Gearing unit		Electrical connection technology	
		MTR	DCI	32 42 52 62	S	VC VD	SC	E	G7 G14 G22	R2 H2
533742	MTR	- DCI	- 42	S	- VC	SC	- E	G7	- R2	IO

Ordering table											
Size	32		42		52		62		Condi- tions	Code	Enter code
M	Module No.	533 736				533 754					
	Motor unit	Motor unit									MTR
	Motor type	DC servo motor with integrated position controller									-DCI
	Flange/size	32	42	52	62	-				-...	
	Torque class	Standard torque class									S
	Nominal voltage	24 DC				-				-VC	
		-				48 DC				-VD	
	Plug design	Straight plug									SC
	Measuring system	Encoder									-E
	Gearing unit	Integrated planetary gearing i = 6.75									G7
		Integrated planetary gearing i = 13.73									G14
		-				Integrated planetary gearing i = 22.21					G22
	Parameterisation interface	RS232 interface									-R2
		RS232 interface + control panel									-H2
	Electrical connection technology	I/O interface									IO
		CANopen									CO
		Profibus DP									PB
		DeviceNet									DN

Transfer order code


	MTR	- DCI		S		SC	- E		-	
--	------------	--------------	--	----------	--	-----------	------------	--	----------	--

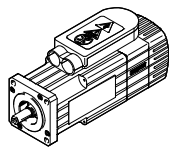
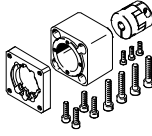


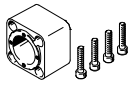
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Positioning axes DMES

Accessories

FESTO

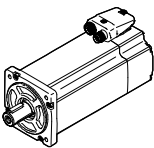
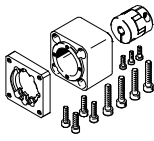


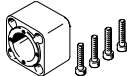
-  - Note
 Depending on the combination of motor and drive, it may not be possible to reach the maximum feed force of the drive.
 The respective no-load driving torque of the kit must be taken into consideration when using parallel kits.

Permissible axis/motor combinations with axial kit – Without gear unit					Technical data → Internet: eamm-a
Motor ¹⁾	Axial kit	Axial kit comprises:			
		Motor flange	Coupling	Coupling housing	
					
Type	Part No. Type	Part No. Type	Part No. Type	Part No. Type	
DMES-18					
With servo motor					
EMMS-AS-40-...	550961 EAMM-A-E20-40A	552163 EAMF-A-28B-40A	540751 EAMC-B-15-22-5-6	170374 EAMK-A-E20-28B	
EMMS-AS-55-...	550963 EAMM-A-E20-55A	529946 EAMF-A-28A/B-55A	529953 EAMC-B-15-22-5-9	170374 EAMK-A-E20-28B	
With stepper motor					
EMMS-ST-42-...	550962 EAMM-A-E20-42A	552164 EAMF-A-28B-42A	530085 EAMC-B-15-22-5-5	170374 EAMK-A-E20-28B	
With motor unit					
MTR-DCI-32S-...	556991 EAMM-A-E20-32B	–	533707 EAMC-15-20-5-6	533703 EAMK-A-E20-32B	
DMES-25					
With servo motor					
EMMS-AS-40-...	550964 EAMM-A-E32-40A	550985 EAMF-A-44A/B-40A	123040 EAMC-30-35-6-6	124631 EAMK-A-E32-44A	
EMMS-AS-55-...	550965 EAMM-A-E32-55A	529942 EAMF-A-44A/B-55A	530941 EAMC-30-35-6-9	124631 EAMK-A-E32-44A	
With stepper motor					
EMMS-ST-57-...	550966 EAMM-A-E32-57A	530081 EAMF-A-44A/B-57A	530087 EAMC-30-35-6-6.35	124631 EAMK-A-E32-44A	
With integrated drive					
EMCA-EC-67-...	1454246 EAMM-A-E32-67A	1476305 EAMF-A-44A/B/C-67A-S1	530941 EAMC-30-35-6-9	124631 EAMK-A-E32-44A	
With motor unit					
MTR-DCI-42S-...G7	556992 EAMM-A-E32-42B	–	533708 EAMC-30-32-6-8	533704 EAMK-A-E32-42B	
MTR-DCI-42S-...G14	556993 EAMM-A-E32-42C	–	533708 EAMC-30-32-6-8	538578 EAMK-A-E32-42C	

1) The input torque must not exceed the maximum permissible transferable torque of the axial kit.

Positioning axes DMES

Accessories

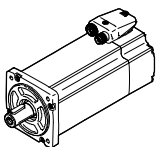
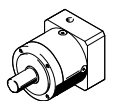
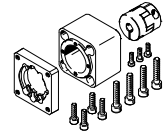
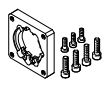

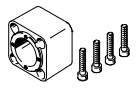
Permissible axis/motor combinations with axial kit – Without gear unit					Technical data → Internet: eamm-a
Motor ¹⁾	Axial kit	Axial kit comprises:			
		Motor flange	Coupling	Coupling housing	
					
Type	Part No. Type	Part No. Type	Part No. Type	Part No. Type	
DMES-40					
With servo motor					
EMMS-AS-70-...	557448 EAMM-A-E48-64A-70A	529945 EAMF-A-64A/B-70A	525864 EAMC-40-66-11-12	529940 EAMK-A-E48-64A	
EMME-AS-100-...	550973 EAMM-A-E48-100A	529947 EAMF-A-64A/C/D-100A	529952 EAMC-40-66-12-19	529940 EAMK-A-E48-64A	
EMMS-AS-100-...	550973 EAMM-A-E48-100A	529947 EAMF-A-64A/C/D-100A	529952 EAMC-40-66-12-19	529940 EAMK-A-E48-64A	
With stepper motor					
EMMS-ST-57-...	550970 EAMM-A-E48-57A	530081 EAMF-A-44A/B-57A	550995 EAMC-30-35-6.35-12	124632 EAMK-A-E48-44A	
EMMS-ST-87-...	550972 EAMM-A-E48-87A	533140 EAMF-A-64A/B-87A	525864 EAMC-40-66-11-12	529940 EAMK-A-E48-64A	
With integrated drive					
EMCA-EC-67-...	1454248 EAMM-A-E48-67A	1460114 EAMF-A-64A/B-67A-S1	1731999 EAMC-40-66-9-12	529940 EAMK-A-E48-64A	
With motor unit					
MTR-DCI-52S-...-G7	556994 EAMM-A-E48-52B	–	533709 EAMC-42-50-12-12	533705 EAMK-A-E48-52B	
MTR-DCI-52S-...-G14	556995 EAMM-A-E48-52C	–	533709 EAMC-42-50-12-12	538579 EAMK-A-E48-52C	
DMES-63					
With servo motor					
EMMS-AS-70-...	550975 EAMM-A-E72-70A	529945 EAMF-A-64A/B-70A	550999 EAMC-40-66-11-20	529941 EAMK-A-E72-64A	
EMME-AS-100-...	550978 EAMM-A-E72-100A	529947 EAMF-A-64A/C/D-100A	132847 EAMC-40-66-19-20	529941 EAMK-A-E72-64A	
EMMS-AS-100-...	550978 EAMM-A-E72-100A	529947 EAMF-A-64A/C/D-100A	132847 EAMC-40-66-19-20	529941 EAMK-A-E72-64A	
With stepper motor					
EMMS-ST-87-...	550977 EAMM-A-E72-87A	533140 EAMF-A-64A/B-87A	550999 EAMC-40-66-11-20	529941 EAMK-A-E72-64A	
With motor unit					
MTR-DCI-62S-...	556996 EAMM-A-E72-62B	–	533710 EAMC-42-50-14-20	533706 EAMK-A-E72-62B	

1) The input torque must not exceed the maximum permissible transferable torque of the axial kit.

Positioning axes DMES

Accessories

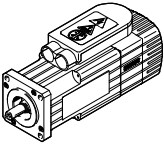
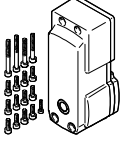
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Permissible axis/motor combinations with axial kit – With gear unit						Technical data → Internet: eamm-a
Motor ¹⁾	Gear unit	Axial kit	Axial kit comprises:			
			Motor flange	Coupling	Coupling housing	
						
Type	Type	Part No. Type	Part No. Type	Part No. Type	Part No. Type	
DMES-25						
With servo motor						
EMME-AS-40-...	EMGA-40-P-G...-EAS-40	1454247 EAMM-A-E32-40G	550986 EAMF-A-44A/B-40G	1453062 EAMC-30-35-6-10	124631 EAMK-A-E32-44A	
EMMS-AS-40-...	EMGA-40-P-G...-SAS-40	1454247 EAMM-A-E32-40G	550986 EAMF-A-44A/B-40G	1453062 EAMC-30-35-6-10	124631 EAMK-A-E32-44A	
With stepper motor						
EMMS-ST-42-...	EMGA-40-P-G...-SST-42	1454247 EAMM-A-E32-40G	550986 EAMF-A-44A/B-40G	1453062 EAMC-30-35-6-10	124631 EAMK-A-E32-44A	
With integrated drive						
EMCA-EC-67-...	EMGC-40-...	1454247 EAMM-A-E32-40G	550986 EAMF-A-44A/B-40G	1453062 EAMC-30-35-6-10	124631 EAMK-A-E32-44A	
DMES-40						
With motor unit						
EMCA-EC-67-...	EMGC-60-...	1454249 EAMM-A-E48-60H	550987 EAMF-A-64A/B-60G/H	1452803 EAMC-40-66-12-14	529940 EAMK-A-E48-64A	
DMES-63						
With servo motor						
EMMS-AS-55-...	EMGA-60-P-G...-SAS-55	550974 EAMM-A-E72-60G	550987 EAMF-A-64A/B-60G/H	550999 EAMC-40-66-11-20	529941 EAMK-A-E72-64A	
EMME-AS-60-...	EMGA-60-P-G...-EAS-60	1454250 EAMM-A-E72-60H	550987 EAMF-A-64A/B-60G/H	1452809 EAMC-40-66-14-20	529941 EAMK-A-E72-64A	
EMMS-AS-70-...	EMGA-60-P-G...-SAS-70	550974 EAMM-A-E72-60G	550987 EAMF-A-64A/B-60G/H	550999 EAMC-40-66-11-20	529941 EAMK-A-E72-64A	
EMMS-AS-70-...	EMGA-80-P-G...-SAS-70	550976 EAMM-A-E72-80G	533139 EAMF-A-64A/C-80G	123849 EAMC-40-66-20-20	529941 EAMK-A-E72-64A	
EMME-AS-80-...	EMGA-80-P-G...-EAS-80	550976 EAMM-A-E72-80G	533139 EAMF-A-64A/C-80G	123849 EAMC-40-66-20-20	529941 EAMK-A-E72-64A	
EMMS-AS-100-...	EMGA-80-P-G...-SAS-100	550976 EAMM-A-E72-80G	533139 EAMF-A-64A/C-80G	123849 EAMC-40-66-20-20	529941 EAMK-A-E72-64A	
With stepper motor						
EMMS-ST-57-...	EMGA-60-P-G...-SST-57	550974 EAMM-A-E72-60G	550987 EAMF-A-64A/B-60G/H	550999 EAMC-40-66-11-20	529941 EAMK-A-E72-64A	
EMMS-ST-87-...	EMGA-80-P-G...-SST-87	550976 EAMM-A-E72-80G	533139 EAMF-A-64A/C-80G	123849 EAMC-40-66-20-20	529941 EAMK-A-E72-64A	
With integrated drive						
EMCA-EC-67-...	EMGC-60-...	1454250 EAMM-A-E72-60H	550987 EAMF-A-64A/B-60G/H	1452809 EAMC-40-66-14-20	529941 EAMK-A-E72-64A	

1) The input torque must not exceed the maximum permissible transferable torque of the axial kit.

Positioning axes DMES

Accessories

Permissible axis/motor combinations with parallel kit – Without gear unit		Technical data → Internet: eamm-u
Motor ¹⁾	Parallel kit	
		<ul style="list-style-type: none"> • Space-saving gravity die-cast housing • Components can be mounted to the kit facing any direction
Type	Part No.	Type
DMES-18		
With servo motor		
EMMS-AS-40-...	543226	EAMM-U-E24-40A
With motor unit		
MTR-DCI-32S-...	543225	EAMM-U-E24-32B
DMES-25		
With servo motor		
EMMS-AS-55-...	543230	EAMM-U-E32-55A
With motor unit		
MTR-DCI-42S-...-G7	543228	EAMM-U-E32-42B
MTR-DCI-42S-...-G14	543229	EAMM-U-E32-42C
DMES-40		
With servo motor		
EMMS-AS-70-...	543234	EAMM-U-E48-70A
With motor unit		
MTR-DCI-52S-...-G7	543232	EAMM-U-E48-52B
MTR-DCI-52S-...-G14	543233	EAMM-U-E48-52C

1) The input torque must not exceed the maximum permissible transferable torque of the parallel kit.

Positioning axes DMES

Accessories

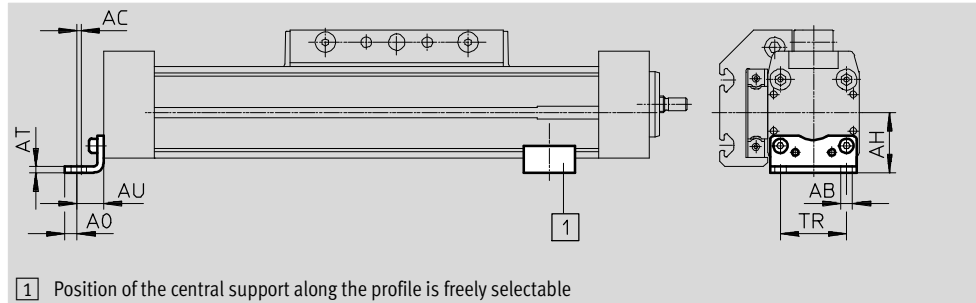


Foot mounting HP (order code F)

Materials:
Galvanised steel
Free of copper and PTFE



HP-25



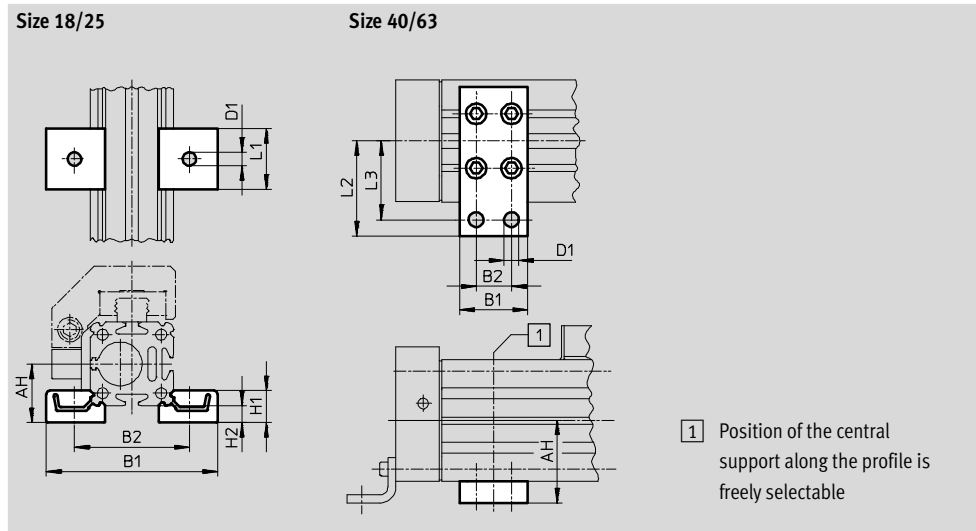
Dimensions and ordering data										
For size	AB ∅	AC	AH	AO	AT	AU	TR	Weight [g]	Part No.	Type
18	5.5	2	24	4.8	3	13.2	24	59	158472	HP-18
25	5.5	2	29.5	6	3	13	32.5	61	150731	HP-25
40	6.6	2	46	8.5	5	17.5	45	188	150733	HP-40
63	11	3	69	13.5	6	28	75	305	150735	HP-63

Central support MUP (order code M)

Materials:
Anodised aluminium
Free of copper and PTFE



MUP-40



Dimensions and ordering data												
For size	AH	B1	B2	D1 ∅	H1	H2	L1	L2	L3	Weight [g]	Part No.	Type
18	24	70.5	47	5.5	13	7	25	-	-	33	150736	MUP-18/25
25	29.5	81	58	5.5	13	7	25	-	-	33	150736	MUP-18/25
40	46	35	22	6.6	-	-	-	47	40	126	150738	MUP-40
63	69	50	26	11	-	-	-	77	65	340	150800	MUP-63

Positioning axes DMES

Accessories

Sensor bracket HWS

For inductive proximity sensors
(order code: T)

Materials:
Galvanised steel



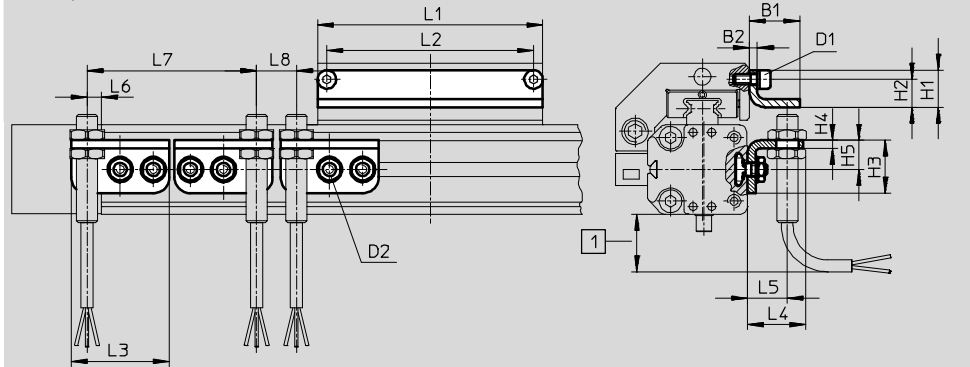
Switch lug SF

(order code: L)

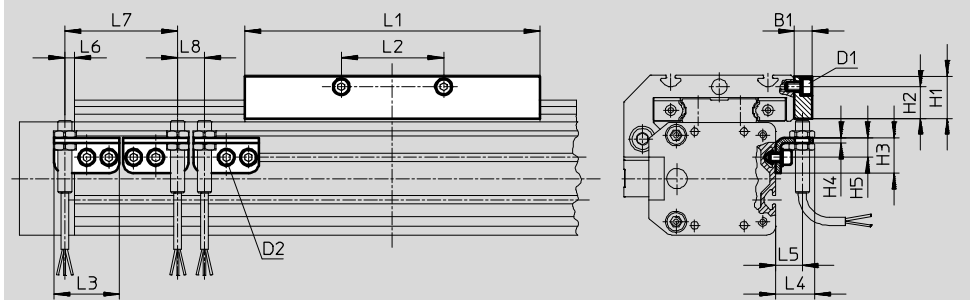
Material:
Galvanised steel



Size 18/25



Size 40/63



1 Protruding sensor cable, ensure sufficient installation space

Dimensions and ordering data





For size	D1	D2	B1	B2	H1	H2	H3	H4	H5	L1	L2	L3	L4	L5
18	M4	M5	19	3	14	10.5	20	3	11	85	78	37	22.5	15
25	M5	M5	27	3	20.5	15.3	20	3	11	105	88	37	34.5	27
40	M5	M5	10	-	24	18	20	3	11	167	58	37	22.5	15
63	M8	M5	10	-	35	25	20	3	11	230	72	37	22.5	15

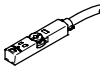
For size	L6	L7	L8	Weight [g]	Part No.	Type
	Max.	Min.	Min.			
18	5.5	64	15	34	188968	HWS-18/25-M8
				59	188964	SF-18
25	5.5	64	15	34	188968	HWS-18/25-M8
				75	188965	SF-25
40	5.5	64	15	37	188969	HWS-40-M8
				328	188966	SF-40
63	5.5	64	15	45	188970	HWS-63-M8
				630	188967	SF-63

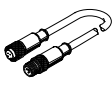
Positioning axes DMES

Accessories

FESTO

Ordering data – Inductive proximity sensors M8						Technical data → Internet: sien	
	Electrical connection		Switching output	LED	Cable length [m]	Part No.	Type
	Cable	M8 plug connector					
N/O contact							
	3-wire	–	PNP	■	2.5	150386	SIEN-M8B-PS-K-L
	–	3-pin	PNP	■	–	150387	SIEN-M8B-PS-S-L
N/C contact							
	3-wire	–	PNP	■	2.5	150390	SIEN-M8B-PO-K-L
	–	3-pin	PNP	■	–	150391	SIEN-M8B-PO-S-L


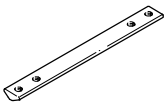



Ordering data – Proximity sensors for T-slot, magneto-resistive					Technical data → Internet: smt		
	Type of mounting	Switching output	Electrical connection	Cable length [m]	Part No.	Type	
N/O contact							
	Insertable in the slot from above, flush with the cylinder profile, short design	PNP	Plug connector M8x1, 3-pin	0.3	574334	SMT-8M-A-PS-24V-E-0,3-M8D	
			Cable, 3-wire	2.5	574335	SMT-8M-A-PS-24V-E-2,5-OE	

Ordering data – Connecting cable				Technical data → Internet: km8		
	Assembly	Connection	Cable length [m]	Part No.	Type	
Straight socket						
	Union nut M8, both ends	3-pin	0.5	175488	KM8-M8-GSGD-0,5	
			1	175489	KM8-M8-GSGD-1	
			2.5	165610	KM8-M8-GSGD-2,5	
			5	165611	KM8-M8-GSGD-5	

Positioning axes DMES

Accessories



Ordering data				Technical data → Internet: mounting component		
	For size	Comment	Order code	Part No.	Type	PU ¹⁾
Slot nut NST						
	18/25	For mounting slot	Y	526091	NST-HMV-M4	10
	40			150914	NST-5-M5	1
	63			150915	NST-8-M6	1
Slot nut NSTL						
	25	For slide	X	158410	NSTL-25	1
	40			158412	NSTL-40	1
	63			158414	NSTL-63	1
Centring pin ZBS/centring sleeve ZBH						
	18	For slide	Z	150928	ZBS-5	10
	25/40/63			150927	ZBH-9	10
Slot cover ABP						
	40	For mounting slot Every 0.5 m	B	151681	ABP-5	2
	63			151682	ABP-8	2
Slot cover ABP-S						
	18/25/40/63	For sensor slot Every 0.5 m	S	151680	ABP-5-S	2

1) Packaging unit quantity