Radial grippers DHRS

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Radial grippers DHRS

Key features

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At a glance

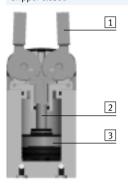
General information

- Lateral gripper jaw support for high torque loads
- Self-centring
- Gripper jaw centring options
- Max. repetition accuracy
- Gripping force retention
- Internal fixed flow control
- Wide range of options for mounting on drive units
- Sensor technology:
 - Adaptable position sensor for the small gripper sizes
 - Integratable proximity sensors for the medium and large gripper sizes

Flexible range of applications

- Can be used as a double-acting and single-acting gripper
- Compression spring for supplementary or retaining gripping forces
- Suitable for external and internal gripping

The technology in detail Gripper closed



Gripper open



- 1 Gripper jaw
- 2 Slotted guide plate
- 3 Piston with magnet



Position sensing/force control

With position transmitter SMAT-8M, SDAT



Analogue positional feedback possible

- Analogue output
 - 0 ... 10 V
- 4... 20 mA

With proportional pressure regulator VPPM



Infinite adjustment of the gripping force possible

- Setpoint input
 - 0 ... 10 V
 - 4 ... 20 mA

With proximity sensor SMT-8G $\,$



Multiple positions can be sensed:

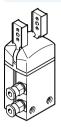
- Open
- Closed
- Workpiece gripped

Radial grippers DHRS Key features



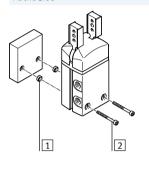
Supply ports

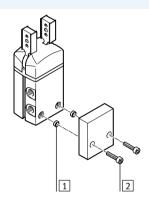
At the side



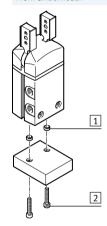
Mounting options

At the side



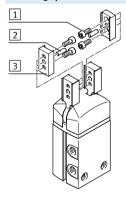






- 1 Centring sleeves
- 2 Mounting screws

Mounting options for external gripper fingers

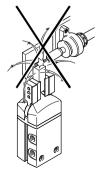


- 1 Mounting screws
- 2 Centring pins
- 3 Gripper fingers



Note

These grippers are not designed for the following or similar sample applications:



• Welding spatter



- Machining
- Aggressive media



• Grinding dust

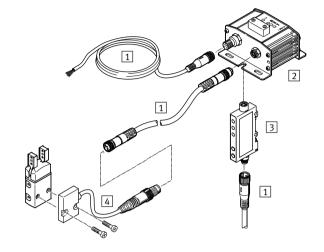
Radial grippers DHRS Peripherals overview

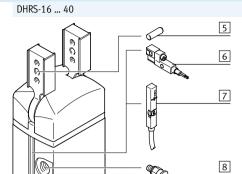


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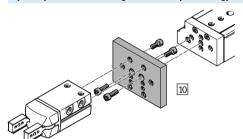
Peripherals overview

DHRS-10

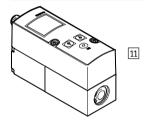




System product for handling and assembly technology



Proportional pressure regulator VPPM



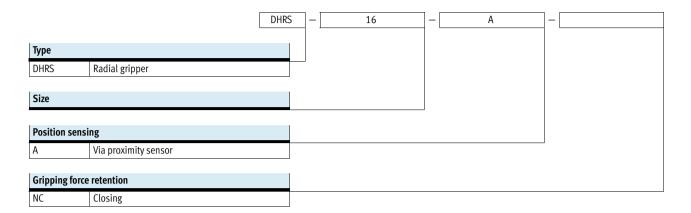
Radial grippers DHRS Peripherals overview



Acces	sories			
	Туре	Size	Description	→ Page/Internet
1	Connecting cable NEBU	10 40	For connecting evaluation unit and signal converter	21
2	Evaluation unit SMH-AE1	10	For evaluating signals for position sensor SMH-S1	21
3	Signal converter SVE4	10	For evaluating signals for position sensor SMH-S1	21
4	Position sensor SMH-S1	10	Adaptable and integratable sensor technology, for sensing the piston position	21
5	Centring pin	10 40	For centring the gripper fingers on the gripper jaws	-
6	Proximity sensor SMT-8G	16 40	For sensing the piston positionProximity sensor does not project past the housing at the bottom	22
7	Position transmitter SMAT-8M	16 40	Continuously senses the position of the piston. Has an analogue output with an output signal in proportion to the piston position	22
	Position transmitter SDAT	32, 40		
8	Push-in fitting QS	10 40	For connecting compressed air tubing with standard O.D.	quick star
9	Centring sleeve ZBH	10 40	 For centring the gripper during mounting The scope of delivery of the gripper includes 2 centring sleeves 	21
0	Adapter kit DHAA, HMSV, HAPG, HAPS, HMVA	10 40	Connecting plate between drive and gripper	16
11	Proportional pressure regulator VPPM	10 40	For infinite adjustment of the gripping force	vppm

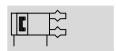
Radial grippers DHRS Type codes





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Function Double-acting DHRS-...-A



10 ... 40 mm



Opening angle



- www.festo.com

Function – Variants Single-acting or with gripping force retention \dots ... closing DHRS-...-NC





General technical data									
Size		10	16	25	32	40			
Design		Forced motion sequ	ience						
Mode of operation		Double-acting							
Gripper function		Radial							
Guide		Plain-bearing guide	Plain-bearing guide						
Gripping force retention		-	NC	NC	NC	NC			
Number of gripper jaws		2							
Opening angle per gripper jaw	90								
Pneumatic connection		M3	M3	M5	G ¹ /8	G1/8			
Repetition accuracy ¹⁾	[mm]	≤ 0.1							
Max. interchangeability	[mm]	≤ ±0.2							
Max. operating frequency	[Hz]	4		3		2			
Rotational symmetry	[mm]	≤ Ø 0.2							
Position sensing		Via position sensor	Via position sensor Via proximity sensor, position transmitter						
Type of mounting	Type of mounting Via t			Via through-hole and centring sleeve					
		Via female thread and centring sleeve							
Mounting position Any									

1) End-position drift under constant conditions of use with 100 consecutive strokes in the direction of movement of the gripper jaws

Operating and environmental condit	tions						
Size		10	16	25	32	40	
Min. operating pressure							
DHRSA	[bar]	2					
DHRSA-NC	[bar]	-	4				
Max. operating pressure	[bar]	8					
Operating medium		Compressed ai	r in accordance witl	n ISO 8573-1:2010	[7:4:4]		
Note on operating/pilot medium		Operation with	lubricated medium	possible (in which o	case lubricated operation	will always be required)	
Ambient temperature ¹⁾	[°C]	+5 +60					
Corrosion resistance class CRC ²⁾		1					

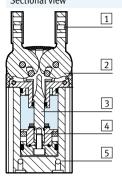
¹⁾ Note operating range of proximity sensors

¹⁾ Note Optimizing a large of proximal years of the Control of the

Weight [g]					
Size	10	16	25	32	40
DHRSA	44	114	270	480	829
DHRSA-NC	-	118	277	490	844

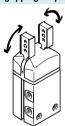
Materials

Sectional view



Radial gripper				
1 Gripper jaw	F	ligh-alloy stainless steel		
2 Cover cap	F	Polyamide		
3 Slotted guide	plate T	empered steel		
4 Piston	F	Polyacetal		
5 Housing	F	Hard anodised wrought aluminium alloy		
- Seals	N	litrile rubber		
 Note on mate 	erials F	Free of copper and PTFE		
	R	RoHS-compliant		

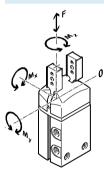
Total gripping torque [Ncm] at 6 bar



The gripping torque is not constant within the opening angle \rightarrow 12.

Size		10	16	25	32	40
DHRSA	Opening	21	62	233	423	725
	Closing	15	55	215	390	660

Static characteristic load values at the gripper jaws

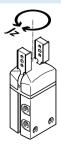


The indicated permissible forces and torques apply to a single gripper jaw. They include the lever arm, additional applied loads due to the workpiece or external gripper fingers and acceleration forces occurring during move-

The zero coordinate line (gripper jaw guide) must be taken into consideration for the calculation of torques.

Size		10	16	25	32	40
Max. permissible force F _z	[N]	30	40	75	120	200
Max. permissible torque M _x	[Nm]	0.8	1.3	3.2	6.2	14
Max. permissible torque M _y	[Nm]	0.8	1.3	3.2	6.2	14
Max. permissible torque M _z	[Nm]	0.8	1.3	3.2	6.2	14

Mass moment of inertia $[kgm^2x10^{-4}]$



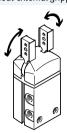
Mass moment of inertia of the radial gripper in relation to the central axis, without external gripper fingers, without load.

Size	10	16	25	32	40
DHRSA	0.03	0.14	0.69	1.66	4.18
DHRSA-NC	_	0.15	0.71	1.69	4.24

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Opening and closing times [ms] at 6 bar

Without external gripper fingers

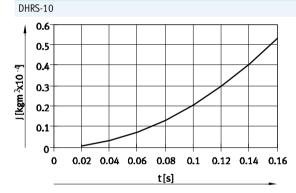


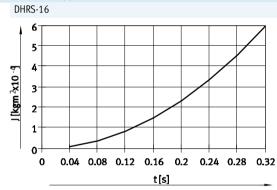
The indicated opening and closing times [ms] were measured at room temperature at an operating pressure of 6 bar with horizontally mounted grippers without additional gripper

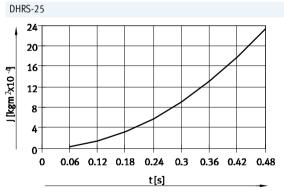
fingers (average values). The grippers must be throttled for greater applied loads. Opening and closing times must then be adjusted accordingly.

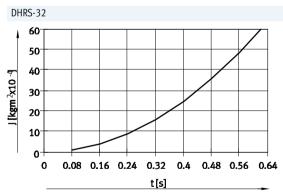
Size		10	16	25	32	40
Without external gripper fingers						
DHRSA	Opening	35	61	102	111	113
	Closing	91	63	105	119	142
DHRSA-NC	Opening	-	75	150	131	151
	Closing	-	43	96	88	110

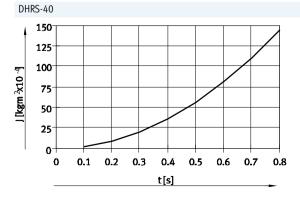
Opening and closing times t to be set at 6 bar as a function of mass moment of inertia of the gripper fingers









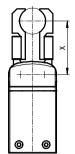




Gripping force F_H per gripper jaw as a function of operating pressure and lever arm x

The gripping forces as a function of operating pressure and lever arm can be determined from the following graphs.

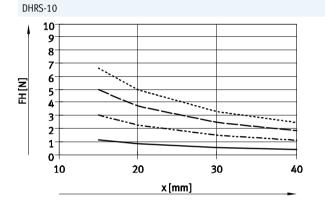
The gripping torque is not constant within the opening angle \rightarrow 12.

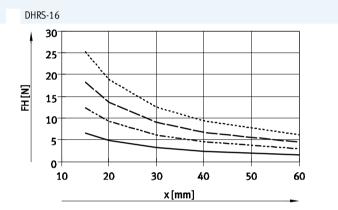


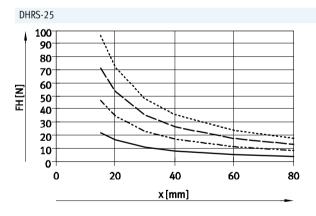
2 bar 4 bar 6 bar ----- 8 bar

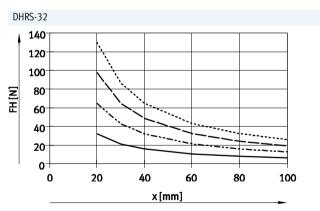


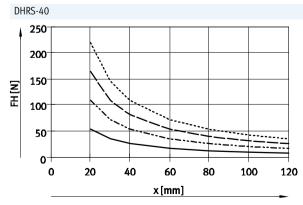
External gripping (closing)









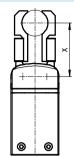


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Gripping force F_H per gripper jaw as a function of operating pressure and lever arm \boldsymbol{x}

The gripping forces as a function of operating pressure and lever arm can be determined from the following graphs.

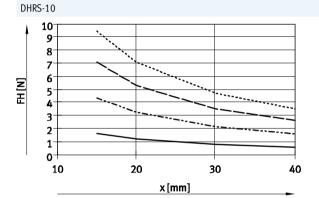
The gripping torque is not constant within the opening angle \rightarrow 12.

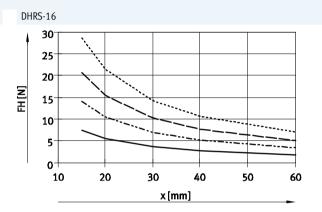


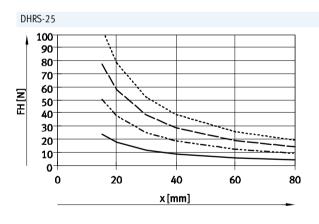


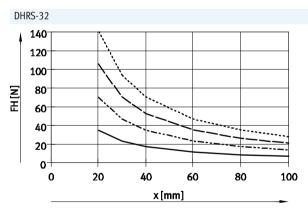


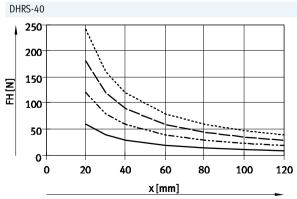
Internal gripping (opening)











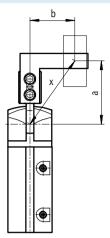
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Gripping force F_H per gripper jaw at 6 bar as a function of lever arm \boldsymbol{x} and eccentricity \boldsymbol{a} and \boldsymbol{b}

The following formula must be used to calculate the lever arm x with eccentric gripping:

$$x = \sqrt{a^2 + b^2}$$

The gripping force F_H can be read from the graphs (\rightarrow 10/11) using the calculated value x.



Calculation example

Given:

Distance a = 25 mm

Distance b = 20 mm

To be calculated: The gripping force at 6 bar,

with a DHRS-16,

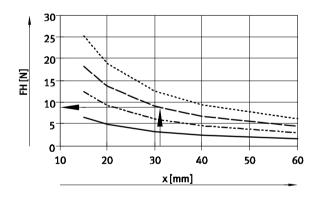
used as an external gripper

Procedure:

Calculating the lever arm x

$$x = \sqrt{25^2 + 20^2}$$

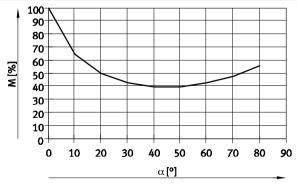
The graph (→ 10) gives a value of F_H = 8 N for the gripping force.



Torque curve M as a function of opening angle $\boldsymbol{\alpha}$

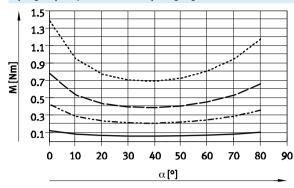
The drive principle of the gripper jaws means that the torque is not constant within the opening angle. The percentage of torque available in each case can be seen in the graph.

An opening angle of 0° means a parallel gripper jaw position.



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Spring torque M_{F} as a function of opening angle α



DHRS-16 ---- DHRS-25 DHRS-32 ----- DHRS-40

Determination of the actual gripping torques M_{Grtotal} for DHRS-...-NC as a function of application

The radial gripper with integrated spring type DHRS-...-NC (closing gripping force retention) can be used as:

- single-acting grippers
- grippers with supplementary gripping force and
- grippers with gripping force retention depending on requirements.

In order to calculate the available gripping torque M_{Grtotal} (per gripper jaw), the data from the graphs for the gripping force $F_H \rightarrow 10/11$, the

$$M_{Gr} = F_H * x * M [\%]$$

torque curve (> 12) and the spring torque M_F (→ 13) must be combined accordingly.

M_{Gr} Gripping torque F_H Gripping force Lever arm Torque curve

Application

Single-acting

- Gripping with spring force: $M_{Grtotal} = M_F$
- Gripping with pressure force: $M_{Grtotal} = M_{Gr} - M_{F}$

Supplementary gripping force

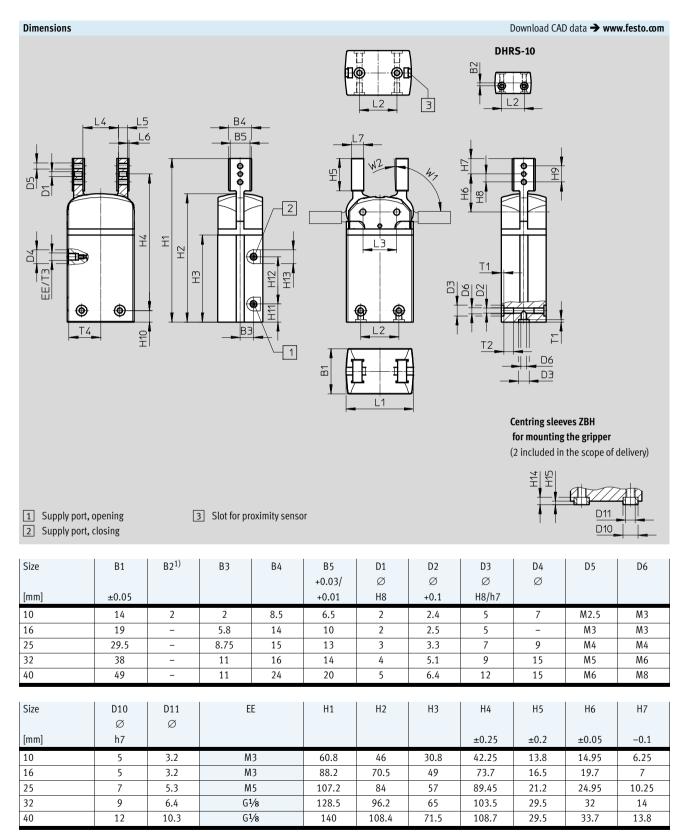
• Gripping with pressure and spring

 $M_{Grtotal} = M_{Gr} + M_{F}$

Gripping force retention

• Gripping with spring force: $M_{Grtotal} = M_F$

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¹⁾ Tolerance for centring hole ± 0.02 mm; tolerance for thread ± 0.1 mm



Size	Н8	Н9	H10 ²⁾	H11	H12	H13	H14	H15	L1	L2 ¹⁾	L3
[mm]							-0.2	-0.3	±0.05		±0.02
10	4	8	12.3	8.8	16	7	2.4	1.2	24	15	12.4
16	4	8	7.5	12.25	23	7	2.4	1.2	33.4	16	17
25	5.25	10.5	7.5	11.8	31	9	3	1.4	44	25	22.2
32	7	14	11	20	25	15	4	1.9	51	29	25.8
40	8	16	17.5	9	46	15	5	2.4	59	33	30

Size	L4	L5	L6	L7	T1	T2	T3	T4	W1	W2
[mm]		±0.05			+0.1	+1	+0.5		±2°	+3°
10	12	4	0.5	5	1.2	through	3.5	11.6	90	2
16	21	4	1	6	1.2	5.8	4.5	16	90	2
25	23.2	6	1	8	1.6	6.4	4.5	21	90	2
32	24.8	8	1	10	2.1	12.9	6.5	24	90	2
40	29.6	10	1	12	2.6	13.4	6	28.4	90	2

Ordering da	ıta	
Size	Double-acting	Single-acting or with gripping force retention
	without compression spring	Closing
[mm]	Part No. Type	Part No. Type
10	1310159 DHRS-10-A	-
16	1310160 DHRS-16-A	1310161 DHRS-16-A-NC
25	1310162 DHRS-25-A	1310163 DHRS-25-A-NC
32	1310164 DHRS-32-A	1310165 DHRS-32-A-NC
40	1310166 DHRS-40-A	1310167 DHRS-40-A-NC

¹⁾ Tolerance for centring hole ± 0.02 mm, tolerance for thread ± 0.1 mm 2) Tolerance for centring hole -0.05 mm, tolerance for thread ± 0.1 mm

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Adapter kit HMSV, HAPG, HAPS, HMVA, DHAA Material: Wrought aluminium alloy Free of copper and PTFE RoHS-compliant



Combination	Drive	Gripper			Adapter	kit	
	Size	Size	Mounting option		CRC ¹⁾	Part No.	Туре
							,,
DGSL/DHRS	DGSL	DHRS			HMSV		
K	8, 10	10				548784	HMSV-54
	12, 16	16			2	548785	HMSV-55
	20, 25	25, 32	•	•		548786	HMSV-56
T (DUDC	CIT	DUDG			LUADO		
SLT/DHRS	SLT	DHRS			HAPS	470//0	HADC 2
	10	10				178448	HAPS-2
	MY /	16	_	-	2	178449	HAPS-3
	20 25	25 32				178450 178451	HAPS-4 HAPS-5
	23	32				170431	110.33
DPZ/DHRS	DPZ	DHRS			HAPG		
//	10, 16	16		-		163250	HAPG-1
	16	25		-	2	163251	HAPG-2
	20	25		-		163252	HAPG-3
	25, 32	32		-		163253	HAPG-4
IMD/DLIDC	HMP	DHRS			HMSV		
· · · · · · · · · · · · · · · · · · ·	Direct mountin						
	16, 20	16	•	•		177666	HMSV-20
	16, 20, 25	25		•		177761	HMSV-21
	16, 20, 25, 32			•	2	177762	HMSV-22
	25	40		•		177763	HMSV-23
MPJOHRS	32	40		•		177764	HMSV-24
	Dovetail moun	ting	I.				
	16, 20	16		•		177767	HMSV-27
	16, 20, 25	25		•		177768	HMSV-28
	16, 20, 25, 32			•	2	177769	HMSV-29
	25	40		•		177770	HMSV-30
	32	40	•			178211	HMSV-31

Corrosion resistance class CRC 2 to Festo standard FN 940070 Moderate corrosion stress, Indoor applications in which condensation may occur. External visible parts with primarily decorative requirements for the surface and which are in direct contact with the ambient atmosphere typical for industrial applications.

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Adapter kit HMSV, HAPG, HAPS, HMVA, DHAA Material: Wrought aluminium alloy Free of copper and PTFE RoHS-compliant



Combination	Drive	Gripper			Adapter	kit		
	Size	Size	Mounting option		CRC ¹⁾	Part No.	Туре	
DGP, DGE, DGEA/DHRS	DG	DHRS			HMVA, H	APG, HMSV		
£2	Direct mount	ing						
	18 ²⁾ , 25 ³⁾	10				196788	HMVA-DLA18/25	
			-	-		192706	HAPG-37-S1	
	403)	10				196790	HMVA-DLA40	
Carlo			-	•		192706	HAPG-37-S1	
	18 ²⁾ , 25 ³⁾	16				196788	HMVA-DLA18/25	
			-	•	2	192705	HAPG-36-S1	
	403)	16			2	196790	HMVA-DLA40	
			-	•		192705	HAPG-36-S1	
	18 ²⁾ , 25 ³⁾	25	_	_		196788	HMVA-DLA18/25	
			•	•		193922	HAPG-37-S4	
	403)	25	_	_		196790	HMVA-DLA40	
			•	•		193922	HAPG-37-S4	
	Dovetail mou	Dovetail mounting						
	18 ²⁾ , 25	16	_	_		196788	HMVA-DLA18/25	
			•	•		177767	HMSV-27	
	40	16	_	_		196790	HMVA-DLA40	
			•	•		177767	HMSV-27	
	18 ²⁾ , 25	25	_	_		196788	HMVA-DLA18/25	
			•	•		177768	HMSV-28	
	40	25	_	_	2	196790	HMVA-DLA40	
			•	•		177768	HMSV-28	
	40	32	_	_		196790	HMVA-DLA40	
			•			177769	HMSV-29	
	40	40	_			196790	HMVA-DLA40	
			•			177770	HMSV-30	

¹⁾ Corrosion resistance class CRC 2 to Festo standard FN 940070 Moderate corrosion stress. Indoor applications in which condensation may occur. External visible parts with primarily decorative requirements for the surface and which are in direct contact with the ambient atmospheric sphere typical for industrial applications.
2) Only for DGEA-...
3) Only for DGE.../DGP...

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Adapter kit HMSV, HAPG, HAPS, HMVA, DHAA Material: Wrought aluminium alloy Free of copper and PTFE RoHS-compliant



- Note

Permissible drive/gripper co					1		ownload CAD data → www.festo.co
Combination	Drive	Gripper			Adapter		_
	Size	Size	Mounting option		CRC ¹⁾	Part No.	Туре
			·				
DRQD/DHRS	DRQDFW	DHRS			HAPG		
	6, 8, 12	10				187568	HAPG-34
	16 ²⁾	10				187566	HAPG-SD2-12
	16 ²⁾	16	•			184477	HAPG-SD2-1
and the second s	16 ²⁾	25				184478	HAPG-SD2-2
	20 ²⁾	25	•			184479	HAPG-SD2-3
	20 ²⁾	32	•		2	184480	HAPG-SD2-4
	25 ³⁾	25	•			184482	HAPG-SD2-6
	25 ³⁾	32	•			184483	HAPG-SD2-7
	32 ³⁾	32				184485	HAPG-SD2-9
	32 ³⁾	40				184486	HAPG-SD2-10
	40, 50	40				526027	HAPG-SD2-21
	DRQDZW	DHRS			HAPG	<u>'</u>	
	16	16				163267	HAPG-18
	16	25				163268	HAPG-19
	20	25			2	163269	HAPG-20
	20	32	•	•		163270	HAPG-21
	25	32				163271	HAPG-22
DRRD/DHRS	DRRD	DHRS			DHAA		
באווטןטאאכ	8	10			DITAA	2816591	DHAA-G-Q11-8-B2/B3-10
	10	10	-			2816068	DHAA-G-Q11-0-B2/B3-10
	12	10	-			2814790	DHAA-G-Q11-10-B2/B3-10
	12	16	-			2811183	DHAA-G-Q11-12-B2/B3-16
	16	16	-			1979085	DHAA-G-Q11-12-B2/B3-16
	16	25	-			1978889	DHAA-G-Q11-16-B2/B3-25
	20	25	-				
		_	_			1978443	DHAA-G-Q11-20-B2/B3-25
	20 25	32 25		-		1979912 1801802	DHAA-G-Q11-20-B2/B3-32 DHAA-G-Q11-25-B2/B3-25
			-				
	25	32	_			1802969	DHAA-G-Q11-25-B2/B3-32
	32	32	-			1979992	DHAA-G-Q11-32-B2/B3-32
	32 35, 40	40		-		1980014 1980059	DHAA-G-Q11-32-B2/B3-40 DHAA-G-Q11-35/40-B2/B3-40

Corrosion resistance class CRC 2 to Festo standard FN 940070 Moderate corrosion stress. Indoor applications in which condensation may occur. External visible parts with primarily decorative requirements for the surface and which are in direct contact with the ambient atmosphere typical for industrial applications.

² Possible in combination with DRQD-...-E422 (flanged shaft with energy through-feed).
3 Possible in combination with DRQD-...-E444 (flanged shaft with energy through-feed).

FESTO

Adapter kit HMSV, HAPG, HAPS, HMVA, DHAA Material: Wrought aluminium alloy Free of copper and PTFE RoHS-compliant



Permissible drive/gripper com	1	i			1		ownload CAD data → www.festo.co
Combination	Drive	Gripper			Adapter I		
	Size	Size	Mounting option		CRC1)	Part No.	Туре
HSP/DHRS	HSP	DHRS			HAPG	'	
	12	10				192709	HAPG-60-S1
			-	-		540881	HAPG-70-B
	16	10		_		192706	HAPG-37-S1
المراج ال			-	_		540882	HAPG-71-B
	16	16		_	2	192705	HAPG-36-S1
			-	_	2	540882	HAPG-71-B
	25	16		_		192705	HAPG-36-S1
						540883	HAPG-72-B
	25	25		_		193922	HAPG-37-S4
			_	_		540883	HAPG-72-B
		·					
HSW/DHRS	HSW	DHRS			HAPG		
	12, 16	10	-	_		192706	HAPG-37-S1
			_		2	540882	HAPG-71-B
	12, 16	16	-	_	_	192705	HAPG-36-S1
DSM/DHRS	DSMFW	DHRS			HAPG		
~	6, 8, 10	10			2	187568	HAPG-34
• / •	-,-,-	-					
	DSM	DHRS		•			וואו פ-54
	DSM 12	DHRS 16	■	-	HAPG	163266	HAPG-17
	12 16	16 16	•		HAPG	163266 163267	HAPG-17
	12 16 16	16 16 25	-	•		163266 163267 163268	HAPG-17 HAPG-18
	12 16 16 25	16 16 25 25		•	HAPG	163266 163267 163268 163269	HAPG-17 HAPG-18 HAPG-19
	12 16 16 25 25	16 16 25		•	HAPG	163266 163267 163268	HAPG-17 HAPG-18 HAPG-19 HAPG-20
	12 16 16 25	16 16 25 25 32		- - - -	HAPG	163266 163267 163268 163269 163270	HAPG-17 HAPG-18 HAPG-19 HAPG-20 HAPG-21
	12 16 16 25 25	16 16 25 25 32		- - - -	HAPG	163266 163267 163268 163269 163270	HAPG-17 HAPG-18 HAPG-19 HAPG-20 HAPG-21
DSL/DHRS	12 16 16 25 25 32	16 16 25 25 25 32 32		- - - -	HAPG 2	163266 163267 163268 163269 163270	HAPG-17 HAPG-18 HAPG-19 HAPG-20 HAPG-21
DSL/DHRS	12 16 16 25 25 32	16 16 25 25 25 32 32 32		• • • •	HAPG 2	163266 163267 163268 163269 163270 163271	HAPG-17 HAPG-18 HAPG-19 HAPG-20 HAPG-21 HAPG-22
DSL/DHRS	12 16 16 25 25 32 DSL	16 16 25 25 32 32 32 DHRS		• • • • •	HAPG 2	163266 163267 163268 163269 163270 163271	HAPG-17 HAPG-18 HAPG-19 HAPG-20 HAPG-21 HAPG-22
DSL/DHRS	12 16 16 25 25 32 DSL 16 20	16 16 25 25 32 32 32 DHRS 16 16		•	HAPG 2	163266 163267 163268 163269 163270 163271	HAPG-17 HAPG-18 HAPG-19 HAPG-20 HAPG-21 HAPG-22
DSL/DHRS	12 16 16 25 25 32 DSL 16 20 20	16 16 25 25 32 32 32 16 16 16 25			HAPG 2	163266 163267 163268 163269 163270 163271 163266 163267 163268	HAPG-17 HAPG-18 HAPG-19 HAPG-20 HAPG-21 HAPG-22 HAPG-17 HAPG-18 HAPG-19

¹⁾ Corrosion resistance class CRC 2 to Festo standard FN 940070
Moderate corrosion stress. Indoor applications in which condensation may occur. External visible parts with primarily decorative requirements for the surface and which are in direct contact with the ambient atmosphere typical for industrial applications.

FESTO

Adapter kit HMSV, HAPG, HAPS, HMVA, DHAA Material: Wrought aluminium alloy Free of copper and PTFE RoHS-compliant



Combination	Drive	Gripper			Adapter	kit	
	Size	Size	Mounting option		CRC ¹⁾	Part No.	Туре
EGSL/DHRS	EGSL	DHRS			HMSV		
K	35	10				548784	HMSV-54
					2	1088262	HMSV-70
	45, 55	16				548785	HMSV-55
	75	25, 32				548786	HMSV-56
ERMB/DHRS	ERMB	DHRS			HAPG		
	20	25	•			184479	HAPG-SD2-3
	25	25	•			184482	HAPG-SD2-6
	20	32			2	184480	HAPG-SD2-4
	25	32				184483	HAPG-SD2-7
	32	32				184485	HAPG-SD2-9
	32	40				184486	HAPG-SD2-10
EHMB/DHRS	EHMB	DHRS			HAPG		
(KIPRI)	20	32	•	•		184485	HAPG-SD2-9
	20	40	•		2	184486	HAPG-SD2-10
	25, 32	40				526027	HAPG-SD2-21

Corrosion resistance class CRC 2 to Festo standard FN 940070 Moderate corrosion stress. Indoor applications in which condensation may occur. External visible parts with primarily decorative requirements for the surface and which are in direct contact with the ambient atmosphere typical for industrial applications.



Ordering data	a							
	For size	Description	Weight	Part No.	Туре	PU ¹⁾		
	[mm]		[g]					
Centring slee	Centring sleeve ZBH Technical data → Internet: zbh							
	10, 16	For centring the gripper during mounting	1	189652	ZBH-5	10		
(1)	25		1	186717	ZBH-7			
	32		1	150927	ZBH-9			
	40		1	189653	ZBH-12			

1) Packaging unit

Ordering data							
Туре	For size	Weight	Part No.	Туре			
		[g]					
Position sensor SMH-S1	Position sensor SMH-S1						
and the second	10	20	175712	SMH-S1-HGR10			

Signal converter/evaluation unit for position sensor SMH-S1

Signal converter SVE4

Evaluation unit SMH-AE1

- Converts analogue signals into switching points
- Switching function freely programmable with teach-in
- Threshold value, hysteresis or window comparator
- Converts analogue signals into switching points
- With 3 potentiometers for setting 3 switching points

Ordering da	ta								
Туре	For size	Input connection	Output connection	Switching	Weight	Part No.	Туре		
				output	[g]				
Signal converter SVE4 Technical data → Internet: sve4									
<u></u>	10	Socket M8x1,	Plug M8x1,	2x PNP	19	544216	SVE4-HS-R-HM8-2P-M8		
		4-pin	4-pin	2x NPN		544219	SVE4-HS-R-HM8-2N-M8		
Evaluation u	nit CMH_AF1						Technical data - Internet: cmh-ae		
Evaluation u	nit SMH-AE1	Contrat MOVA	Diver M4 2.14	2 DND	170	475700	Technical data → Internet: smh-ae		
Evaluation u	nit SMH-AE1	Socket M8x1,	Plug M12x1, 5-pin	3x PNP 3x NPN	170	175708 175709	Technical data → Internet: smh-ae SMH-AE1-PS3-M12 SMH-AE1-NS3-M12		

Ordering data	– Connecting cables				Technical data → Internet: nebu
	Electrical connection, left	Electrical connection, right	Cable length [m]	Part No.	Туре
Connection be	tween position sensor and signal converter,	evaluation unit			
	Straight socket, M8x1, 4-pin	Straight plug, M8x1, 4-pin	2.5	554035	NEBU-M8G4-K-2.5-M8G4
Connection be	tween evaluation unit and controller			•	
	Straight socket, M12x1, 5-pin	Cable, open end, 5-wire	2.5	541330	NEBU-M12G5-K-2.5-LE5
			5	541331	NEBU-M12G5-K-5-LE5



Ordering data	– Connecting cables				Technical data → Internet: nebu
	Electrical connection, left	Electrical connection, right	Cable length	Part No.	Туре
			[m]		
Connection be	tween signal converter and controller				
	Straight socket, M8x1, 4-pin	Cable, open end, 4-wire	2.5	541342	NEBU-M8G4-K-2.5-LE4
678			5	541343	NEBU-M8G4-K-5-LE4
'/					
	Angled socket, M8x1, 4-pin	Cable, open end, 4-wire	2.5	541344	NEBU-M8W4-K-2.5-LE4
37			5	541345	NEBU-M8W4-K-5-LE4
					·

Proximity ser	nsor for size 16 40								
Ordering data	Ordering data − Proximity sensors for T-slot, magneto-resistive Technical data → Internet: s								
	Type of mounting	Electrical connection,	Switching	Cable length	Part No.	Туре			
		connection direction	output	[m]					
N/O contact									
A	Insertable in the slot	Cable, 3-wire, lateral	PNP	2.5	547859	SMT-8G-PS-24V-E-2,5Q-0E			
📇	lengthwise	Plug M8x1, 3-pin, lateral		0.3	547860	SMT-8G-PS-24V-E-0,3Q-M8D			
(B)									

Ordering data	a – Connecting cables				Technical data → Internet: nebu
	Electrical connection, left	Electrical connection, right	Cable length [m]	Part No.	Туре
	Straight socket, M8x1, 3-pin	Cable, open end, 3-wire	2.5	541333	NEBU-M8G3-K-2.5-LE3
			5	541334	NEBU-M8G3-K-5-LE3
	Angled socket, M8x1, 3-pin	Cable, open end, 3-wire	2.5	541338	NEBU-M8W3-K-2.5-LE3
			5	541341	NEBU-M8W3-K-5-LE3

Position transmitter

The position transmitter continuously senses the position of the piston.

It has an analogue output with an output signal in proportion to the piston position.

Ordering data − Position transmitters for T-slot Technical data → Internet: position transmitter												
	For size	Position measuring	Analogue output		Type of mounting	Electrical connection	Cable length	Part No.	Туре			
		range	[V]	[mA]			[m]					
	16 40	0 40	0 10	_	Insertable in slot from above	Plug M8x1, 4-pin, in-line	0.3	553744	SMAT-8M-U-E-0,3-M8D			
OF STREET	32, 40	0 50	-	4 20	Insertable in slot from above	Plug M8x1, 4-pin, in-line	0.3	1531265	SDAT-MHS-M50-1L-SA-E-0.3-M8			

Ordering data	ng data – Connecting cables Technical data → Interne										
	Electrical connection, left	Electrical connection, right	Cable length [m]	Part No.	Туре						
	Straight socket, M8x1, 4-pin	Cable, open end, 4-wire	2.5 5	541342 541343	NEBU-M8G4-K-2.5-LE4 NEBU-M8G4-K-5-LE4						
	Angled socket, M8x1, 4-pin	Cable, open end, 4-wire	2.5	541344 541345	NEBU-M8W4-K-2.5-LE4 NEBU-M8W4-K-5-LE4						
		•	·								