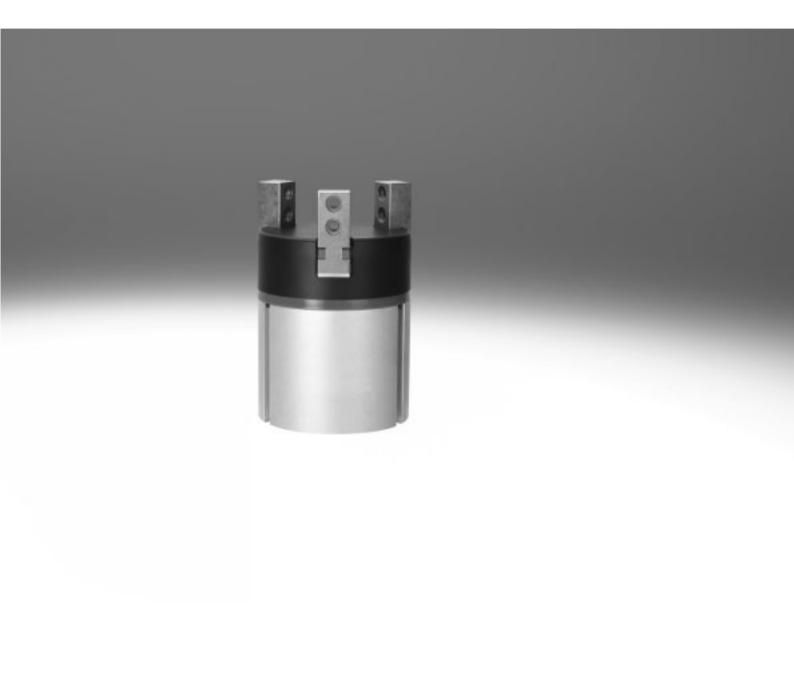
## **FESTO**





Key features

### At a glance

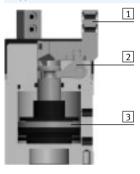
General information

- Resilient and precise T-slot guide of the gripper jaws
- High gripping forces with compact dimensions
- Gripper jaw centring options
- Max. repetition accuracy
- Gripping force retention Internal fixed flow control
- Wide range of options for mounting on drive units
- Sensor technology:
  - Adaptable position sensor for the small gripper sizes
  - Integratable proximity sensors for the medium and large gripper sizes

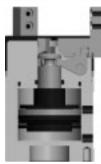
Flexible range of applications

- Can be used as a double-acting and single-acting gripper
- Compression spring for supplementary or retaining gripping forces
- Suitable for external and internal gripping

### The technology in detail Gripper closed







- 1 Gripper jaw
- 2 Reversing lever
- 3 Piston with magnet



Note

Gripper selection

sizing software

→ www.festo.com

### Position sensing/force control

With position transmitter SMAT-8M



Analogue positional feedback possible

Analogue output 0 ... 10 V

#### With proportional pressure regulator VPPM



Infinite adjustment of the gripping force possible

- Setpoint input
  - 0 ... 10 V
  - 4 ... 20 mA

### With proximity sensor SMT-8G



Multiple positions can be sensed:

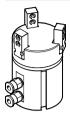
- Open
- Closed
- Workpiece gripped

## Three-point grippers DHDS Key features

**FESTO** 

### Supply ports

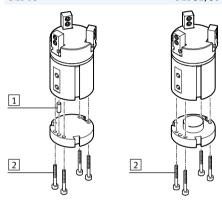
At the side



### **Mounting options**

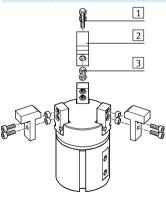
Size 16

Size 32, 50



- 1 Centring pin
- 2 Mounting screws

### Mounting options for external gripper fingers

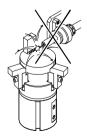


- 1 Mounting screws
- 2 Gripper fingers
- 3 Centring sleeves

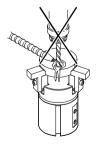


Note

These grippers are not designed for the following or similar sample applications:



• Welding spatter



- Machining
- Aggressive media



• Grinding dust

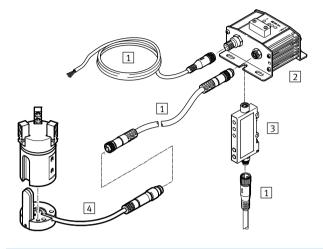
## Three-point grippers DHDS Peripherals overview

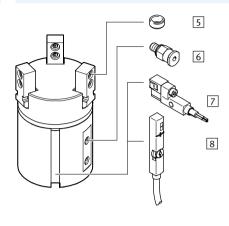


### Peripherals overview

DHDS-16

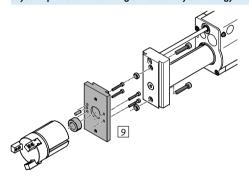


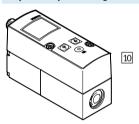




### System product for handling and assembly technology



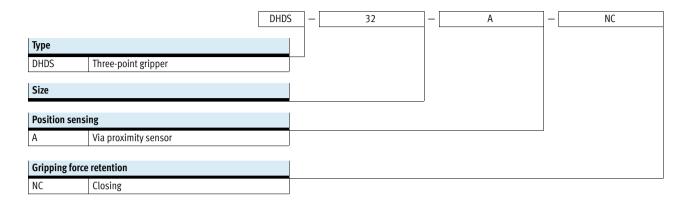




Acces	sories			
	Туре	Size	Description	→ Page/Internet
1	Connecting cable	16 50	For connecting evaluation unit and signal converter	17
	NEBU			
2	Evaluation unit	16	For evaluating signals for position sensor SMH-S1	17
	SMH-AE1			
3	Signal converter	16	For evaluating signals for position sensor SMH-S1	17
	SVE4			
4	Position sensor	16	Adaptable and integratable sensor technology, for sensing the piston	17
	SMH-S1		position	
5	Centring sleeve	16 50	For centring the gripper fingers on the gripper jaws	17
	ZBH		The scope of delivery of the gripper includes 6 centring sleeves	
6	Push-in fitting	16 50	For connecting compressed air tubing with standard O.D.	quick star
	QS			
7	Proximity sensor	32, 50	For sensing the piston position	18
	SMT-8G		<ul> <li>Proximity sensor does not project past the housing at the bottom</li> </ul>	
8	Position transmitter	32, 50	Continuously senses the position of the piston. Has an analogue output	18
	SMAT-8M		with an output signal in proportion to the piston position.	
9	Adapter kit	16 50	Connecting plate between drive and gripper	14
	DHAA, HMSV, HAPG, HAPS, HMVA			
10	Proportional pressure regulator	16 50	For infinite adjustment of the gripping force	vppm
	VPPM			

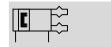
## Three-point grippers DHDS Type codes





**FESTO** 

Function Double-acting DHDS-...-A



16 ... 50 mm





Function – Variants Single-acting or with gripping force retention ... ... closing DHDS-...-NC





General technical data							
Size		16	32	50			
Design		Lever	Lever				
		Forced motion sequence					
Mode of operation		Double-acting					
Gripper function		Three-point					
Gripping force retention		NC	NC	NC			
Number of gripper jaws		3	3				
Max. load per external gripper finger <sup>1)</sup>	[g]	50	150	250			
Stroke per gripper jaw	[mm]	2.5	3.9	6			
Pneumatic connection		M3	M5	G1/8			
Repetition accuracy <sup>2)</sup>	[mm]	≤ 0.04					
Max. interchangeability	[mm]	≤ ±0.2					
Max. operating frequency	[Hz]	≤ 4					
Rotational symmetry	[mm]	<∅0.2					
Position sensing		Via position sensor	Via proximity sens	sor, position transmitter			
Type of mounting		Via female thread and dowel	pin				
Mounting position		Any					

- Valid for unthrottled operation
- 2) End-position drift under constant conditions of use with 100 consecutive strokes, concentric to the central shaft

Operating and environmental condit	tions	
Min. operating pressure		
DHDSA	[bar]	2
DHDSA-NC	[bar]	4
Max. operating pressure	[bar]	8
Operating medium		Compressed air in accordance with ISO 8573-1:2010 [7:4:4]
Note on operating/pilot medium		Operation with lubricated medium possible (in which case lubricated operation will always be required)
Ambient temperature <sup>1)</sup>	[°C]	+5 +60
Corrosion resistance class CRC <sup>2)</sup>		1

- Note operating range of proximity sensors

Corrosion resistance class CRC 1 to Festo standard FN 940070

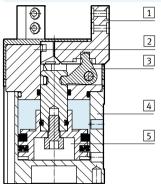
Low corrosion stress. For dry indoor applications or transport and storage protection. Also applies to parts behind covers, in the non-visible interior area, and parts which are covered in the application (e.g. drive trunnions).

Weight [g]			
Size	16	32	50
DHDSA	96	276	920
DHDSA-NC	99	281	932



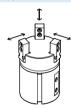
### Materials

### Sectional view



Three-point gripper						
1 (	Gripper jaw	High-alloy stainless steel				
2 (	Cover cap	Polyamide				
3 R	Reversing lever	Hardened sintered steel				
4 H	Housing	Hard anodised wrought aluminium alloy				
5 F	Piston	Polyacetal				
- 1	Note on materials	Free of copper and PTFE				
		RoHS-compliant				

### Gripping force [N] at 6 bar



Size		16	32	50
Gripping force per gripper jaw				
DHDSA	Opening	40	135	280
	Closing	29	115	250
Total gripping force				
DHDSA	Opening	120	405	840
	Closing	87	345	750

### Characteristic load values at the gripper jaws



The indicated permissible forces and torques apply to a single gripper jaw. They include the lever arm, additional applied loads due to the workpiece or external gripper fingers and acceleration forces occurring during movement.

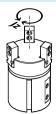
The zero coordinate line (gripper finger point of rotation) must be taken into consideration for the calculation of torques.

Size		16	32	50
Max. permissible force F <sub>z</sub>	[N]	50	150	250
Max. permissible torque M <sub>x</sub>	[Nm]	2	9	24
Max. permissible torque M <sub>y</sub>	[Nm]	2	9	24
Max. permissible torque $M_z$	[Nm]	2	9	24



Technical data

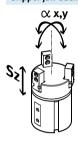
### Mass moment of inertia [kgcm<sup>2</sup>]



Mass moment of inertia of the threepoint gripper in relation to the central axis, without external gripper fingers, without load.

Size	16	32	50
DHDS	0.14	0.79	6.10
DHDSNC	0.14	0.82	6.18

### Gripper jaw backlash



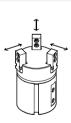
The plain-bearing guide used in the grippers means that there is backlash between the gripper jaws and the housing. The values entered in the table for the backlash were calculated in accordance with the traditional accumulative tolerance method.

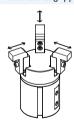
Size		16	32	50
Max. gripper jaw backlash Sz	[mm]	≤ 0.02		
Max. gripper jaw angular backlash ax,	[°]	≤ 0.5	≤ 0.2	
ay				

### Opening and closing times [ms] at 6 bar

Without external gripper fingers

With external gripper fingers





The indicated opening and closing times [ms] were measured at room temperature at an operating pressure of 6 bar with horizontally mounted grippers without additional gripper

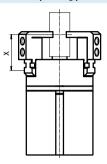
fingers. The grippers must be throttled for greater loads [g]. Opening and closing times must then be adjusted accordingly.

Size		16	32	50
Without external gripper fingers				
DHDSA	Opening	26	44	62
	Closing	42	51	55
DHDSA-NC	Opening	31	55	73
	Closing	34	47	50
With external gripper fingers per gripper	finger (as a fur	nction of the load)		
DHDS	100 g	100	-	-
	200 g	-	100	_
	300 g	-	200	100
	400 g	-	-	200
	500 g	-	-	300



### Gripping force F<sub>H</sub> per gripper jaw as a function of operating pressure and lever arm x

The gripping forces as a function of operating pressure and lever arm can be determined from the following graphs.

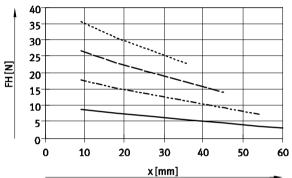




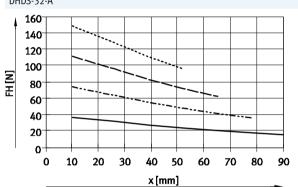


### External gripping (closing)

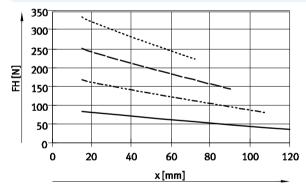




### DHDS-32-A



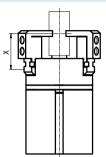
### DHDS-50-A





### Gripping force F<sub>H</sub> per gripper jaw as a function of operating pressure and lever arm x

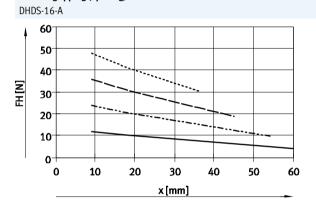
The gripping forces as a function of operating pressure and lever arm can be determined from the following graphs.

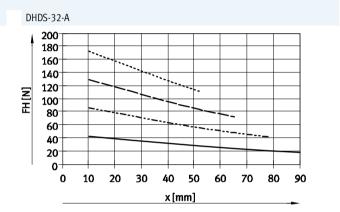


2 bar 4 bar 6 bar ----- 8 bar

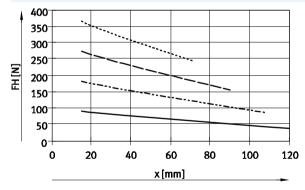


### Internal gripping (opening)





### DHDS-50-A



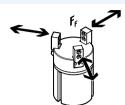
Technical data

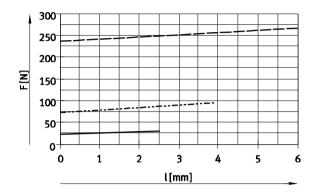


### Spring force F<sub>F</sub> as a function of size and gripper jaw stroke l

Gripping force retention for DHDS-...-NC

The spring forces F<sub>F</sub> as a function of gripper jaw stroke can be determined from the following graph.





DHDS-16-A-NC DHDS-32-A-NC DHDS-50-A-NC

#### Spring force F<sub>F</sub> as a function of size, gripper jaw stroke l and lever arm x per gripper finger

The lever arm x must be taken into consideration when determining the actual spring force F<sub>Ftotal</sub>. The formulae for calculating the spring force are provided in the table below.

Gripping force retention	Size	F <sub>Ftotal</sub> per gripper finger
NC	16	-0.1* x+0.33* F <sub>F</sub>
	32	-0.2* x+0.33* F <sub>F</sub>
	50	-0.3* x+0.33* F <sub>F</sub>

### Determination of the actual gripping forces F<sub>Gr</sub> for DHDS-...-NC as a function of application per gripper finger

The three-point grippers with integrated spring type DHDS-...-NC (closing gripping force retention) can be used as:

- single-acting grippers

- grippers with supplementary gripping force and

- grippers with gripping force retention depending on requirements. In order to calculate the available gripping forces F<sub>Gr</sub> (per gripper finger), the gripping force (F<sub>H</sub>) and spring force (F<sub>Ftotal</sub>) must be combined accordingly.

### Application forces per gripper finger

Single-acting

• Gripping with spring force:  $\mathsf{F}_\mathsf{Gr} = \mathsf{F}_\mathsf{Ftotal}$ 

• Gripping with pressure force:  $\mathsf{F}_\mathsf{Gr} = \mathsf{F}_\mathsf{H} - \mathsf{F}_\mathsf{Ftotal}$ 

Supplementary gripping force

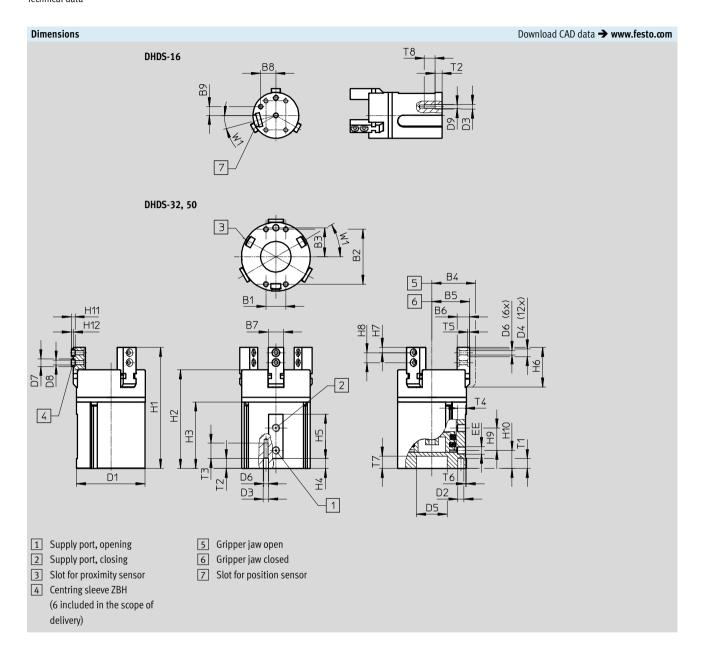
• Gripping with pressure and spring force:

 $F_{Gr} = F_H + F_{Ftotal}$ 

Gripping force retention

• Gripping with spring force:  $F_{Gr} = F_{Ftotal}$ 







Size	B1	B2	В3	B4		B5	В6		B7	В8	В9
[mm]			±0.02	±0.5	5 ±	0.5	-0.02/-0.05		-0.02	-0.1	-0.1
16	13	19	11.5	20	1	7.5	7		6	9.96	5.75
32	13	36	19	28.5	5 2	4.6	8		10	-	_
50	25	54	30	43	3	37	12		14	-	-
Size	D1	D2	D3	D4		)5	D6		D7	D8	D9
	Ø	Ø	Ø	Ø	!	Ø			Ø	Ø	
[mm]		Н8	Н8	H8	+0.05	5/+0.02			h7		
16	30	3	3.2	5		-	M3		5	3.2	M2.5
32	45	4	3.5	5	2	20	M3		5	3.2	-
50	70	5	6	7	3	30	M5		7	5.3	-
Size	EE	H1	H2	Н3	H4	H5	Н	6	H7	H8 <sup>1)</sup>	H9
[mm]											
16	M3	60	47.9	32.6	4.5	24	21	.5	3	6	12
32	M5	78	63.2	42.2	5.2	29	2	6	3.5	6.5	14.7
50	G1/8	107.5	86.5	56	6.7	40	3	7	5	10	22
Size	H10	T1	T2	T3	T4	T5	Т	6	T7	T8	W1
[mm]		min.	min.	+1	-0.5	+0.1	1 ±0	.2		±1	
16	11	4.5	4.5	8	4	1.2		1	_	7	15°
32	10.5	6.5	6.5	10	4	1.1	0.	.5	8	-	30°
50	16	7	7	18	6	1.6			9	-	30°

<sup>1)</sup> Tolerance for centring hole  $\pm 0.02~\text{mm}$  Tolerance for thread  $\pm 0.1~\text{mm}$ 

Ordering data	a	
Size	Double-acting	Single-acting or with gripping force retention
	without compression spring	Closing
[mm]	Part No. Type	Part No. Type
16	1259491 DHDS-16-A	1259492 DHDS-16-A-NC
32	1259493 DHDS-32-A	1259494 DHDS-32-A-NC
50	1259495 DHDS-50-A	1259496 DHDS-50-A-NC



Adapter kit DHAA, HAPG, HMSV, HMVA Material:

Wrought aluminium alloy Free of copper and PTFE RoHS-compliant



The kit includes the individual mounting interface as well as the necessary mounting material.

Permissible drive/gripper cor	nbinations with adapter ki	it		D	ownload CAD data → www.festo.com		
Combination	Drive Gripper		Adapter k	Adapter kit			
	Size	Size	CRC <sup>1)</sup>	Part No.	Туре		
HMP/DHDS	HMP	DHDS	HMSV				
<i>K</i> .	Direct mounting						
	16, 20, 25	32		177765	HMSV-25		
	25, 32	50	2	177766	HMSV-26		
	Dovetail mounting	L					
	16, 20, 25	32	_	178212	HMSV-32		
	25, 32	50	2	178213	HMSV-33		
				1			
DGP, DGE, DGEA/DHDS	DG	DHDS	HMVA. HA	APG, HMSV			
(0.	Direct mounting		7				
	18 <sup>2)</sup> , 25	16		196788	HMVA-DLA18/25		
				193921	HAPG-36-S3		
	40	16	2	196790	HMVA-DLA40		
				193921	HAPG-36-S3		
	Dovetail mounting			1			
	40	32		196790	HMVA-DLA40		
				178212	HMSV-32		
	40	50	2	196790	HMVA-DLA40		
				178213	HMSV-33		
DRQD/DHDS	DRQD	DHDS	HAPG				
<u> </u>	8, 12	16		187569	HAPG-35		
	16	16		187567	HAPG-SD2-13		
	20	32		184481	HAPG-SD2-5		
	25	50	2	184484	HAPG-SD2-8		
A PARTY OF THE PAR	32	50		184487	HAPG-SD2-11		
	40, 50	50		526026	HAPG-SD2-20		
				II.			
DRRD/DHDS	DRRD	DHDS	DHAA				
	12	16		2823512	DHAA-G-Q11-12-B4-16		
	16	16		2136626	DHAA-G-Q11-16-B4-16		
	16	32		2151381	DHAA-G-Q11-16-B4-32		
	20	32		2136339	DHAA-G-Q11-20-B4-32		
	25	32	2	1471583	DHAA-G-Q11-25-B4-32		
Se Color	25	50		1731165	DHAA-G-Q11-25-B4-50		
	32	50		1907040	DHAA-G-Q11-32-B4-50		
	35	50		2135899	DHAA-G-Q11-35-B4-50		

<sup>1)</sup> Corrosion resistance class CRC 2 to Festo standard FN 940070 Moderate corrosion stress. Indoor applications in which condensation may occur. External visible parts with primarily decorative requirements for the surface and which are in direct contact with the ambient atmosphere typical for industrial applications.

2) Only for DGEA-...



Adapter kit HAPG

Material:

Wrought aluminium alloy Free of copper and PTFE RoHS-compliant



The kit includes the individual mounting interface as well as the necessary mounting material.

	1		1		Download CAD data → www.festo.
Combination	Drive	Gripper	Adapter		
	Size	Size	CRC <sup>1)</sup>	Part No.	Туре
ISP/DHDS	HSP	DHDS	HAPG		
	16	16		192705	HAPG-36-S1
	.		2	540882	HAPG-71-B
	25	16	2	192705	HAPG-36-S1
				540883	HAPG-72-B
ISW/DHDS	HSW	DHDS	HAPG		
<b>*</b>	16	16	2	192705	HAPG-36-S1
			2	540882	HAPG-71-B
	DSM	DHDS	HAPG		
	8, 10	16		187569	HAPG-35
DSM/DHDS			HAPG 2	187569 163272	HAPG-35 HAPG-23
DSM/DHDS	8, 10 25	16 32	2		
OSM/DHDS	8, 10 25	16 32 DHDS		163272	HAPG-23
OSM/DHDS	8, 10 25 ERMB 20	16 32 DHDS 32	2 HAPG	163272	HAPG-23 HAPG-SD2-5
	8, 10 25	16 32 DHDS	2	163272	HAPG-23

<sup>1)</sup> Corrosion resistance class CRC 2 to Festo standard FN 940070 Moderate corrosion stress. Indoor applications in which condensation may occur. External visible parts with primarily decorative requirements for the surface and which are in direct contact with the ambient atmosphere typical for industrial applications.



Adapter kit Material:

HAPG Wrought aluminium alloy

Free of copper and PTFE RoHS-compliant



The kit includes the individual mounting interface as well as the necessary mounting material.

Permissible drive/gripper combi	nations with adapter kit	Download CAD data → www.festo.com			
Combination	Drive	Gripper	Adapter kit		
	Size	Size	CRC <sup>1)</sup>	Part No.	Туре
EHMB/DHDS	EHMB	DHDS	HAPG		
	20	50	2	184487	HAPG-SD2-11
	25, 32	50	2	526026	HAPG-SD2-20

Corrosion resistance class CRC 2 to Festo standard FN 940070 Moderate corrosion stress. Indoor applications in which condensation may occur. External visible parts with primarily decorative requirements for the surface and which are in direct contact with the ambient atmosphere typical for industrial applications.





Ordering data						
	For size	Comment	Weight	Part No.	Туре	PU <sup>1)</sup>
	[mm]		[g]			
Centring sleev	e ZBH				Technical data → Intern	et: zbh
Centring sleev	e ZBH 16, 32	For centring the gripper fingers on the gripper jaws	1	189652	Technical data → Interne	et: zbh 10

1) Packaging unit

Ordering data				
Туре	For size	Weight	Part No.	Туре
		[g]		
Position sensor SMH-S1				Technical data → Internet: smh-s1
	16	30	175713	SMH-S1-HGD16

### Signal converter/evaluation unit for position sensor SMH-S1

Signal converter SVE4

Evaluation unit SMH-AE1

- Converts analogue signals into switching points
- Switching function freely programmable with teach-in
- Threshold value, hysteresis or window comparator
- Converts analogue signals into switching points
- With 3 potentiometers for setting 3 switching points

nta						
For size	Input connection	Output connection	Switching	Weight	Part No.	Туре
			output	[g]		
erter SVE4						Technical data → Internet: sve4
16	Socket M8x1,	Plug M8x1,	2x PNP	19	544216	SVE4-HS-R-HM8-2P-M8
	4-pin	4-pin	2x NPN		544219	SVE4-HS-R-HM8-2N-M8
unit SMH-AE1						Technical data → Internet: smh-ae
16	Socket M8x1,	Plug M12x1,	3x PNP	170	175708	SMH-AE1-PS3-M12
	4-pin	5-pin	3x NPN		175709	SMH-AE1-NS3-M12
e	For size erter SVE4 16 unit SMH-AE1	For size Input connection  erter SVE4  16 Socket M8x1, 4-pin  unit SMH-AE1  16 Socket M8x1,	For size Input connection Output connection  erter SVE4  16 Socket M8x1, Plug M8x1, 4-pin  unit SMH-AE1  16 Socket M8x1, Plug M12x1,	For size Input connection Output connection Switching output  erter SVE4  16 Socket M8x1, Plug M8x1, 2x PNP 4-pin 2x NPN  unit SMH-AE1  16 Socket M8x1, Plug M12x1, 3x PNP	For size Input connection Output connection Switching output [g]  enter SVE4  16 Socket M8x1, Plug M8x1, 2x PNP 4-pin 2x NPN  Init SMH-AE1  16 Socket M8x1, Plug M12x1, 3x PNP 170	For size

Ordering dat	a – Connecting cables				Technical data 🗲 Internet: nebu
	Electrical connection, left	Electrical connection, right	Cable length [m]	Part No.	Туре
Connection b	etween position sensor and signal con	verter/evaluation unit			
	Straight socket, M8x1, 4-pin	Straight plug, M8x1, 4-pin	2.5	554035	NEBU-M8G4-K-2.5-M8G4
Connection b	petween evaluation unit and controller		l l		
	Straight socket, M12x1, 5-pin	Cable, open end, 5-wire	2.5	541330	NEBU-M12G5-K-2.5-LE5
57			5	541331	NEBU-M12G5-K-5-LE5
Connection b	etween signal converter and controller				
	Straight socket, M8x1, 4-pin	Cable, open end, 4-wire	2.5	541342	NEBU-M8G4-K-2.5-LE4
			5	541343	NEBU-M8G4-K-5-LE4
			1	T =	
	Angled socket, M8x1, 4-pin	Cable, open end, 4-wire	2.5	541344	NEBU-M8W4-K-2.5-LE4
			5	541345	NEBU-M8W4-K-5-LE4



Proximity sen:	Proximity sensor for size 32, 50										
Ordering data − Proximity sensors for T-slot, magneto-resistive  Technical data → Internet: sm											
	Type of mounting	Part No.	Туре								
		connection direction	output	[m]							
N/O contact											
A	Insertable in the slot	Cable, 3-wire, lateral	PNP	2.5	547859	SMT-8G-PS-24V-E-2,5Q-0E					
	lengthwise	Plug M8x1, 3-pin, lateral		0.3	547860	SMT-8G-PS-24V-E-0,3Q-M8D					

Ordering dat	a – Connecting cables	Technical data → Internet: nebu			
	Electrical connection, left	Electrical connection, right	Cable length [m]	Part No.	Туре
	Straight socket, M8x1, 3-pin	Cable, open end, 3-wire	2.5	541333	NEBU-M8G3-K-2.5-LE3
<b>3</b>			5	541334	NEBU-M8G3-K-5-LE3
	Angled socket, M8x1, 3-pin	Cable, open end, 3-wire	2.5	541338	NEBU-M8W3-K-2.5-LE3
			5	541341	NEBU-M8W3-K-5-LE3

### Position transmitter

The position transmitter continuously senses the position of the piston.

It has an analogue output with an output signal in proportion to the piston position.

(	Ordering data - Position transmitters for T-slot Technical data → Internet: position trans										
		For size Position Analogue output measuring		Type of mounting	Electrical connection	Cable length	Part No.	Туре			
			range	[V]	[mA]			[m]			
Ć		32, 50	0 40	0 10	-	Insertable in slot from above	Plug M8x1, 4-pin, in-line	0.3	553744	SMAT-8M-U-E-0,3-M8D	

Orderin	ng data	- Connecting cables				Technical data → Internet: nebu
		Electrical connection, left	Electrical connection, right	Cable length	Part No.	Туре
				[m]		
		Straight socket, M8x1, 4-pin	Cable, open end, 4-wire	2.5	541342	NEBU-M8G4-K-2.5-LE4
				5	541343	NEBU-M8G4-K-5-LE4
		Angled socket, M8x1, 4-pin	Cable, open end, 4-wire	2.5	541344	NEBU-M8W4-K-2.5-LE4
Se les				5	541345	NEBU-M8W4-K-5-LE4