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Key features

Design

General

The SMAT-8M is a position transmitter for the contactless sensing of the piston position of drives that can be detected magnetically. It supplies a displacement-proportional analogue

output signal in the position measuring range.

It is connected directly to the analogue PLC inputs without any accessories. With its extremely compact design, the SMAT-8M is the ideal solution for grippers, short-stroke cylinders and all applications in which installation space is restricted.



Note

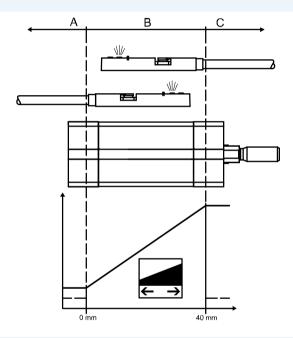
It can be used with Festo cylinders with T-slot (profile slot 8) as well as round cylinders and tie-rod cylinders with mounting kits. A selection aid with suitable drives can be found on the following pages.

Position measuring range

The SMAT-8M supplies a displacement-proportional analogue output signal of 0 ... 10 V in the position measuring range of up to 40 mm (depending on the drive used). In other words, the output voltage increases when the piston moves in the direction of the piston rod. When the piston retracts, the output voltage drops.

The installation direction of the SMAT-8M is irrelevant in this case. To achieve the best possible function on the drive in question, the position measuring range must be initialised on the drive during installation.

As a visual aid, the green LED lights up within the position measuring range (B) and the red LED lights up outside of the measuring range (A)/(C) in normal operation.

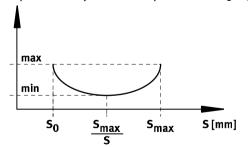


Repetition accuracy

The repetition accuracy is ± 0.025 mm on grippers and ± 0.1 mm on standard drives.

With standard drives, the repetition accuracy in the centre of the measuring range is lower than at the edge. It is ±0.06 mm at a distance of ±5 mm from the centre, for example. For critical applications, it is recommended that the SMAT-8M be mounted so as to have the relevant measuring points close to 5.5 V.

Repetition accuracy as a function of position measuring range S



Position transmitters SMAT-8M, for T-slot Selection aid



Drive/gripper	Usability	Position me	Position measuring		
	on drive	range approx.			
		With ini-	Without		
		tialisation	initialisa-		
			tion ²⁾		
		[mm]	[mm]		
Standards-based cylinders					
Standard cylinder DSBC-32	+	26	26		
Standard cylinder DSBC-40	+	26	26		
Standard cylinder DSBC-50	+	30	27		
Standard cylinder DSBC-63	+	33	33		
Standard cylinder DSBC-80	+	37	37		
Standard cylinder DSBC-100	+	33	31		
Standard cylinder DSBC-125	+	35	34		
Standard cylinder DSBG-32	+	19	17		
Standard cylinder DSBG-40	+	24	23		
Standard cylinder DSBG-50	+	27	26		
Standard cylinder DSBG-63	+	27	27		
Standard cylinder DSBG-80	+	30	33		
Standard cylinder DSBG-100	+	29	27		
Standard cylinder DSBG-125	+	27	24		
Standard cylinder DSNU/ESNU-8	+	19	17		
Standard cylinder DSNU/ESNU-10	+	22	19		
Standard cylinder DSNU/ESNU-12	+	21	19		
Standard cylinder DSNU/ESNU-16	+	21	19		
Standard cylinder DSNU/ESNU-20	+	20	18		
Standard cylinder DSNU/ESNU-25	+	28	22		
Round cylinder DSNU/ESNU-32	+	25	23		
Round cylinder DSNU/ESNU-40	+	29	30		
Round cylinder DSNU/ESNU-50	+	31	29		
Round cylinder DSNU/ESNU-63	+	36	33		
Standard cylinder DNCB-32	+	25	23		
Standard cylinder DNCB-40	+	28	19		
Standard cylinder DNCB-50	+	30	26		
Standard cylinder DNCB-63	+	32	27		
Standard cylinder DNCB-80	+	35	32		
Standard cylinder DNCB-100	+	29	26		
Standard cylinder DNC-32	+	29	32		
Standard cylinder DNC-40	o ¹⁾	-	_		
Standard cylinder DNC-50	o ¹⁾	-	_		
Standard cylinder DNC-63	+	34	28		
Standard cylinder DNC-80	+	35	29		
Standard cylinder DNC-100	+	37	33		
Standard cylinder DNC-125	+	38	32		
Standard cylinder DNG-32	+	28	19		
Standard cylinder DNG-40	+	34	30		
-					
-	-				
-					
Standard cylinder DNG-50 Standard cylinder DNG-63 Standard cylinder DNG-80 Standard cylinder DNG-100	0 ¹⁾ + + + +	- 32 32 32	- 25 25 27		

Drive/gripper	Usability	Docition mo	Position measuring		
blive/glippel	on drive	_			
	on unve	range approx. With ini- Without			
		tialisation	initialisa-		
		tiatisation	tion ²⁾		
		f1			
		[mm]	[mm]		
Standards-based cylinders		_			
Compact cylinder AND/AEN-12	+	22	22		
Compact cylinder ADN/AEN-16	+	26	26		
Compact cylinder ADN/AEN-20	+	30	28		
Compact cylinder ADN/AEN-25	+	27	24		
Compact cylinder ADN/AEN-32	+	31	31		
Compact cylinder ADN/AEN-40	+	28	20		
Compact cylinder ADN/AEN-50	+	25	21		
Compact cylinder ADN/AEN-63	+	31	29		
Compact cylinder ADN/AEN-80	o ¹⁾	-	-		
Compact cylinder ADN/AEN-100	+	28	24		
Compact cylinder ADN/AEN-125	+	37	33		
			-1		
Cylinders with piston rod					
Short-stroke cylinder ADVC/AEVC-32	+	Stroke	Stroke		
		< position	< position		
		measuring	measuring		
		range	range		
		SMAT-8M	SMAT-8M		
Short-stroke cylinder ADVC/AEVC-40	+		24		
Short-stroke cylinder ADVC/AEVC-50	+		Stroke		
Cl. I. I. I. ADVC/ADVC	_		< position		
Short-stroke cylinder ADVC/AEVC-63	+		measuring		
Short-stroke cylinder ADVC/AEVC-80	+		range		
Short Stroke cylinder / IDVe// IEVe 00			SMAT-8M		
Short-stroke cylinder ADVC/AEVC-100	+		24		
Compact cylinder ADVU/AEVU-12	+	23	20		
Compact cylinder ADVU/AEVU-16	+	20	17		
Compact cylinder ADVU/AEVU-20	+	29	28		
Compact cylinder ADVU/AEVU-25	+	25	21		
Compact cylinder ADVU/AEVU-32	+	27	23		
Compact cylinder ADVU/AEVU-40	+	24	21		
Compact cylinder ADVU/AEVU-50	+	22	18		
Compact cylinder ADVU/AEVU-63	+	32	27		
Compact cylinder ADVU/AEVU-80	+	35	28		
Compact cylinder ADVU/AEVU-100	+	33	26		
Compact cylinder ADVU/AEVU-125	+	35	31		
Flat cylinder DZF-12	+	29	26		
Flat cylinder DZF-18	+	26	24		
Flat cylinder DZF-25	+	28	23		
Flat cylinder DZF-32	+	26	17		
Flat cylinder DZF-40	o ¹⁾	-	-		
,		1			
Flat cylinder DZF-50	o ¹⁾	-	-		

On request

Different from technical data. Usability on request.

Position measuring range without initialisation (as supplied from the factory)

Position transmitters SMAT-8M, for T-slot Selection aid





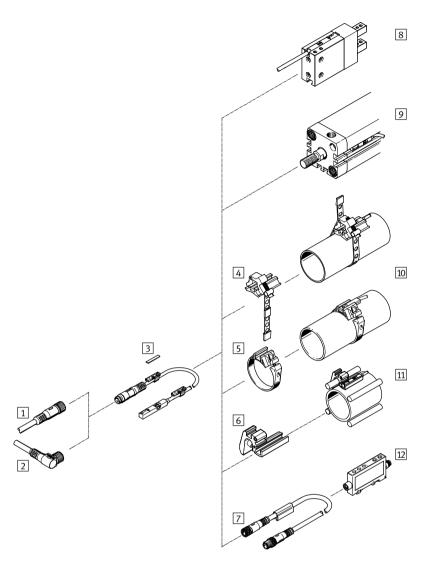
Drive/gripper	Usability on drive	Position measuring range approx.		
		With ini- tialisation	Without initialisa- tion ²⁾	
		[mm]	[mm]	
Rodless cylinders				
Linear drive DGC-18	+	30	26	
Linear drive DGC-25	o ¹⁾	-	-	
Linear drive DGC-32	o ¹⁾	-	-	
Linear drive DGC-40	o ¹⁾	-	-	
Function-oriented drives				
Linear/swivel clamp CLR-12	+	22	22	
Linear/swivel clamp CLR-16	+	26	26	
Linear/swivel clamp CLR-20	+	30	28	
Linear/swivel clamp CLR-25	+	27	24	
Linear/swivel clamp CLR-32	+	31	31	
Linear/swivel clamp CLR-40	+	28	20	
Linear/swivel clamp CLR-50	+	25	21	
Linear/swivel clamp CLR-63	+	31	29	
		7-	/	
Drives with linear guides				
Guided drive DFM-12	+	21	22	
Guided drive DFM-16	+	15	16	
Guided drive DFM-20	+	24	22	
Guided drive DFM-25	+	26	25	
Guided drive DFM-32	+	25	22	
Guided drive DFM-40	o ¹⁾	-	-	
Guided drive DFM-50	+	21	18	
Guided drive DFM-63	+	31	27	
Guided drive DFM-80	+	30	30	
Guided drive DFM-100	+	25	24	
Guided drive DFM-12-B	+	16	22	
Guided drive DFM-16-B	+	20	21	
Guided drive DFM-20-B	+	26	27	
Guided drive DFM-25-B	+	24	22	
Guided drive DFM-32-B	+	29	28	
Guided drive DFM-40-B	+	30	29	
Guided drive DFM-50-B	+	31	31	
Guided drive DFM-63-B	+	33	32	
Linear unit SLE-10	+	22	22	
Linear unit SLE-16	+	21	21	
Linear unit SLE-20	+	20	20	
Linear unit SLE-25	+	28	28	
Linear unit SLE-32	+	25	25	
Linear unit SLE-40	+	29	29	
Linear unit SLE-50	+	31	31	

Drive/gripper	Usability	Position me	•
	on drive	range appro	
		With ini-	Without
		tialisation	initialisa-
			tion ²⁾
		[mm]	[mm]
Handling units			
Three-point gripper DHDS-32	+	Stroke < pos	ition
Three-point gripper DHDS-50	+	measuring range	
Parallel gripper DHPS-10	+	SMAT-8M	
Parallel gripper DHPS-16	+		
Parallel gripper DHPS-20	+		
Parallel gripper DHPS-25	+		
Parallel gripper DHPS-35	+		
Parallel gripper HGPL-63	o ¹⁾		
Parallel gripper HGPT-40-B	+		
Parallel gripper HGPT-50-B	+		
Parallel gripper HGPT-63-B	+	16	15
Parallel gripper HGPT-80-B	+	16	12
Angle gripper DHWS-16	+	Stroke < position	
Angle gripper DHWS-25	+	measuring range SMAT-8M	
Angle gripper DHWS-32	+		
Angle gripper DHWS-40	+		
Radial gripper DHRS-16	+		
Radial gripper DHRS-25	+		
Radial gripper DHRS-32	+		
Radial gripper DHRS-40	+		
Radial gripper HGRT-40-A-G2	+		
Radial gripper HGRT-50-A-G2	o ¹⁾		
Semi-rotary drives with rack and pinion			
Semi-rotary drive DRRD-16	+	151	164
Semi-rotary drive DRRD-20	+	120	120
Semi-rotary drive DRRD-25	+	183	183
Semi-rotary drive DRRD-32	+	159	159
Semi-rotary drive DRRD-35	+	185	182
Semi-rotary drive DRRD-40	+	116	116
Semi-rotary drive DRRD-50	+	82	82
Semi-rotary drive DRRD-63	+	64	64

Unrestricted use
 On request
 Different from technical data. Usability on request.
 Position measuring range without initialisation (as supplied from the factory)

Position transmitters SMAT-8M, for T-slot Peripherals overview

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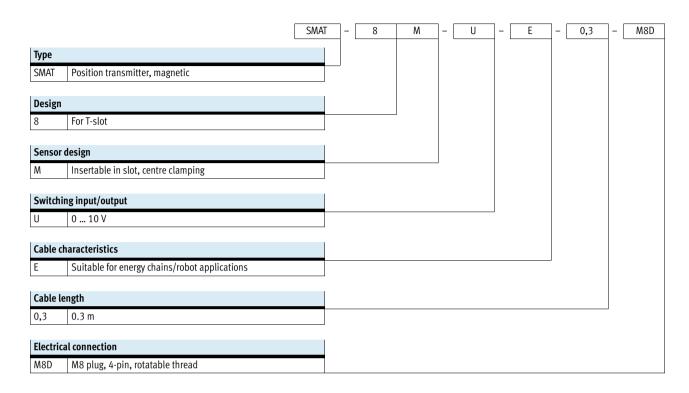


Acce	ssories	→ Page/Internet	
1	Connecting cable NEBU-M8G4	10	
2	Connecting cable NEBU-M8W4	10	
3	Inscription label ASLR	10	
4	Mounting kit SMBR-8-8/100-S6, heat-resistant	10	
5	Mounting kit SMBR	10	
6	Mounting SMBZ-8 10		
7	Connecting cable NEBU-M8G4	10	
8	Three-point gripper DHDS dhds		
	Three-point gripper HGDD	hgdd	
	Parallel gripper DHPS dhps		
	Parallel gripper HGPD	hgpd	
	Parallel gripper HGPT	hgpt	
	Angle gripper DHWS dhws		
	Radial gripper DHRS	dhrs	
	Radial gripper HGRT	hgrt	

Acce	ssories	→ Page/Internet
9	Standard cylinder DNCB	dncb
	Standard cylinder DNC	dnc
	Compact cylinder ADN	adn
	Short-stroke cylinder ADVC/AEVC	advc
	Compact cylinder ADVU/AEVU	advu
	Flat cylinder DZF dzf	
	Linear drive DGC dgc	
	Linear/swivel clamp CLR	clr
	Guided drive DFM	dfm
10	Standard cylinder/round cylinder DSNU	dsnu
	Linear unit SLE	sle
11	Standard cylinder DSBG	dsbg
12	Signal converter SVE4	sve4



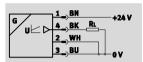
Type codes



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Technical data

Function Normal operation





General technical data		
Design	For T-slot	
Certification	c UL us - Listed (OL)	
	C-tick	
CE marking (see declaration of conformity)	To EU EMC Directive ¹⁾	
Special features	Oil resistant	
Note on materials	RoHS-compliant	
	Halogen-free	

Input signal/measuring elemen	ıt	
Measuring principle		Magnetic
Position measuring range	[mm]	$\leq 40^{2}$

2) Depending on drive/gripper used.

Signal processing		
Max. speed of travel	[m/s]	3

Output, general		
Displacement resolution	[mm]	≤ 0.05 ²⁾
Repetition accuracy	[mm]	±0.1 on cylinders ³⁾
		±0.025 on grippers ³⁾
	[°]	±0.5 on semi-rotary drive DRRD

- Depending on drive/gripper used.
 Use of a non-rotating piston rod or a mechanical structure to protect against rotation is recommended.

Analogue output		
Typical linearity error	[mm]	±1 on cylinders ²⁾
		±0.2 on grippers ²⁾

2) Depending on drive/gripper used.

Electrical outputs		
Analogue output	[V]	0 10
Protection against short circuit		Yes
Protection against overloading		Yes
Output signal		Analogue



Technical data

Electronics				
Operating voltage range	[V DC]	15 30		
Typical scanning interval	[ms]	2.8		
Protection against polarity reversal		For all electrical connections		

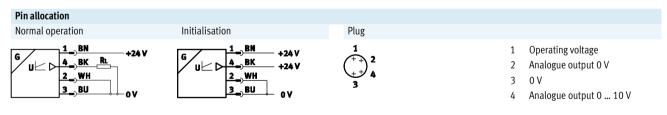
Electromechanics				
Electrical connection		Cable with plug, M8x1, knurled ring, 4-pin		
Ambient temperature with flexible	[°C]	-5 +70		
cable installation				
Cable length	[m]	0.3		
Cable characteristics		Energy chain + robots		
Cable test conditions		Energy chain: 50,000 cycles, bending radius 30 mm		
		Torsional strength: >300,000 cycles, ±270°/0.1 m		
		Resistance to bending: to Festo standard; test conditions on request		
Information on materials for cable sheath		TPE-U(PUR)		

Mechanical components				
Type of mounting		Secured with screw, insertable in the slot from above		
Product weight	[g]	10		
Information on housing materials		Reinforced PA6		

Display/operation	
Status display	LED red, green

Immissions/emissions				
Ambient temperature	[°C]	-25 +75		
Protection class		IP65, IP68		
Corrosion resistance class	CRC ⁴⁾	2		

⁴⁾ Corrosion resistance class 2 as per Festo standard 940 070 Components subject to moderate corrosion stress. Externally visible parts with primarily decorative surface requirements which are in direct contact with a normal industrial environment or media such as coolants or lubricating agents.

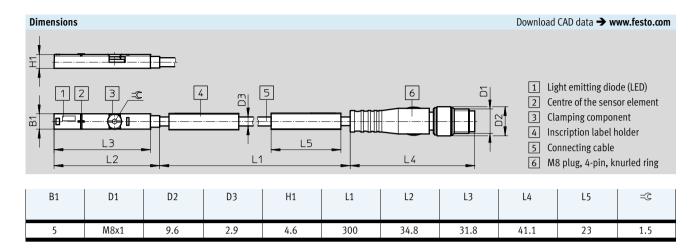


Wire colours

BN = brown BU = blue BK = black WH = white



Technical data



Ordering data					
Size	Analogue output [V]	Electrical connection	Cable length [m]	Part No.	Туре
ST.		M8 plug, 4-pin, rotatable thread	0.3	553744	SMAT-8M-U-E-0,3-M8D

Position transmitters SMAT-8M, for T-slot Accessories



Ordering dat	a – Mounting attachments		
	For piston diameter	Part No.	Туре
Mounting kit	SMBR-8-8/100-S6, heat-resistant		
	8 100	538937	SMBR-8-8/100-S6
Mounting kit	SMBR	·	
	8	175091	SMBR-8-8
	10	175092	SMBR-8-10
	12	175093	SMBR-8-12
	16	175094	SMBR-8-16
	20	175095	SMBR-8-20
	25	175096	SMBR-8-25
	32	175097	SMBR-8-32
	40	175098	SMBR-8-40
	50	175099	SMBR-8-50
	63	175100	SMBR-8-63
Mounting SN	BZ		
(Sam)	32 100	537806	SMBZ-8-32/100
	125 320	537808	SMBZ-8-125/320

Ordering data	- Connecting cable NEBU-M8				Technical data → Internet: nebu
	Electrical connection, left	Electrical connection, right	Cable length [m]	Part No.	Туре
	Straight socket, M8x1, 4-pin	Cable, open end, 4-wire	2.5	541342	NEBU-M8G4-K-2.5-LE4
6081			5	541343	NEBU-M8G4-K-5-LE4
	Straight socket, M8x1, 4-pin	Straight socket, M8x1, 4-pin	2.5	554035	NEBU-M8G4-K-2.5-M8G4
	Angled socket, M8x1, 4-pin	Cable, open end, 4-wire	2.5	541344	NEBU-M8W4-K-2.5-LE4
			5	541345	NEBU-M8W4-K-5-LE4

Ordering data – Inscription label ASLR							
	Size	Part No.	Туре	PU ¹⁾			
	23x4 mm	541598	ASLR-L-423	34			

¹⁾ Packaging unit in quantity per frame