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Key features

At a glance

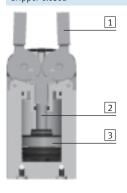
General information

- Lateral gripper jaw support for high torque loads
- Self-centring
- Gripper jaw centring options
- Max. repetition accuracy
- Gripping force retention
- Internal fixed flow control
- Wide range of options for mounting on drive units
- Sensor technology:
 - Adaptable position sensor for the small gripper sizes
 - Integratable proximity sensors for the medium and large gripper sizes

Flexible range of applications

- Can be used as a double-acting and single-acting gripper
- Compression spring for supplementary or retaining gripping forces
- Suitable for external and internal gripping

The technology in detail Gripper closed



Gripper open



- 1 Gripper jaw
- 2 Slotted guide plate
- 3 Piston with magnet

Note

Gripper selection sizing software

→ www.festo.com

Position sensing/force controlWith position transmitter SMAT-8M



Infinite position sensing possible

• Analogue output 0 ... 10 V



With proportional pressure regulator $\ensuremath{\mathsf{VPPM}}$

Infinite adjustment of the gripping force possible

- Setpoint input
- 0 ... 10 V
- 4 ... 20 mA

With proximity sensor SMT-8G



Multiple positions can be sensed:

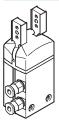
- Open
- Closed
- Workpiece gripped



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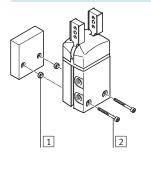
Supply ports

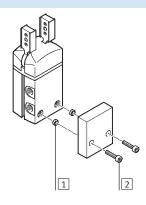
At the side



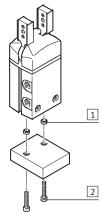
Mounting options

At the side



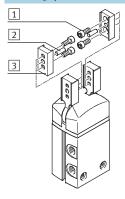






- 1 Centring sleeves
- 2 Mounting screws

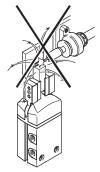
Mounting options for external gripper fingers



- 1 Mounting screws
- Centring pins
- 3 Gripper fingers

Note

These grippers are not designed for the following or similar sample applications:



• Welding spatter



- Machining
- Aggressive media

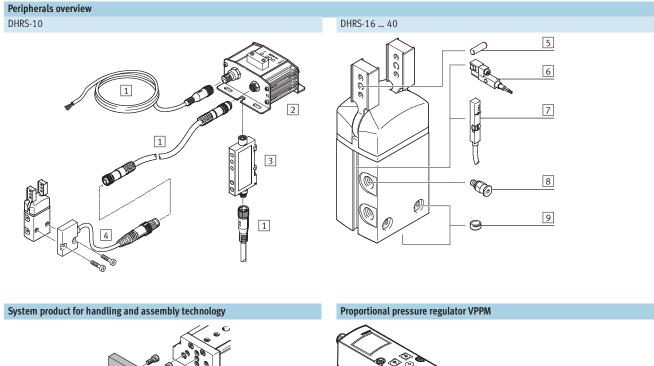


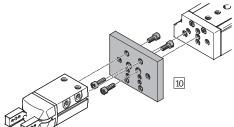
• Grinding dust

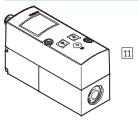


Radial grippers DHRS Peripherals overview

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Radial grippers DHRS Peripherals overview

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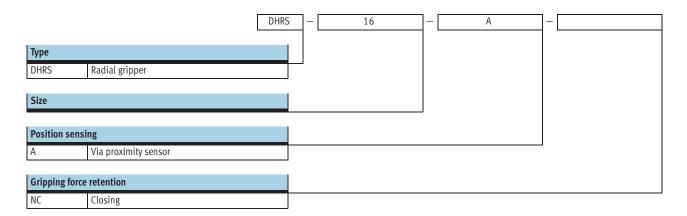
5

Acces	sories		
	Туре	Brief description	→ Page/Internet
1	Connecting cable	For connecting evaluation unit and signal converter	21
	NEBU		
2	Evaluation unit	For evaluating signals for position sensor SMH-S1	21
	SMH-AE1	• For size 10	
3	Signal converter	For evaluating signals for position sensor SMH-S1	21
	SVE4	• For size 10	
4	Position sensor	Adaptable and integratable sensor technology, for sensing the piston position	21
	SMH-S1	• For size 10	
5	Centring pin	For centring the gripper fingers on the gripper jaws	-
6	Proximity sensor	For sensing the piston position	22
	SMT-8G	 Proximity sensor does not project past the housing at the bottom 	
		• For size 16 40	
7	Position transmitter	Continuously senses the position of the piston. Has an analogue output with an output	22
	SMAT-8M	signal in proportion to the piston position	
		• For size 16 40	
8	Push-in fitting	For connecting compressed air tubing with standard O.D.	quick star
	QS		
9	Centring sleeve	For centring the gripper during mounting	21
	ZBH	The scope of delivery of the gripper includes 2 centring sleeves	
10	Adapter kit	Connecting plate between drive and gripper	16
	HMSV, HAPG, HAPS, HMVA		
11	Proportional pressure regulator	For infinite adjustment of the gripping force	vppm
	VPPM		



Radial grippers DHRS Type codes

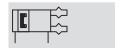
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Function Double-acting DHRS-...-A

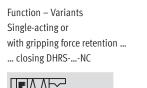


-N-Size

10 ... 40 mm

-T-Opening angle 180°

www.festo.com/en/ Spare_parts_service





General technical data								
Size		10	16	25	32	40		
Design		Forced motion seque	Forced motion sequence					
Mode of operation		Double-acting						
Gripper function		Radial						
Guide		Plain-bearing guide						
Gripping force retention		-	NC	NC	NC	NC		
Number of gripper jaws		2						
Opening angle per gripper jaw	[°]	90	90					
Pneumatic connection		M3	M3	M5	G1/8	G1/8		
Repetition accuracy ¹⁾	[mm]	≤ 0.1						
Max. interchangeability	[mm]	≤ ±0.2						
Max. operating frequency	[Hz]	4		3		2		
Rotational symmetry	[mm]	<∅0.2						
Position sensing		Via position sensor	Via proximity sensor,	, position transmitter				
Type of mounting	Via through-hole and centring sleeve							
		Via female thread an	d centring sleeve					
Mounting position		Any						

 $^{1) \}quad \text{End-position drift under constant conditions of use with } 100 \text{ consecutive strokes in the direction of movement of the gripper jaws}$

Operating and environmental conditions										
Size		10	16	25	32	40				
Min. operating pressure										
DHRSA	[bar]	2								
DHRSA-NC	[bar]	-	4							
Max. operating pressure	[bar]	8								
Operating medium		Compressed air i	Compressed air in accordance with ISO 8573-1:2010 [7:4:4]							
Note on operating/pilot medium		Operation with lu	ubricated mediun	n possible (in which cas	e lubricated operation	will always be required)				
Ambient temperature ¹⁾	[°C]	+5 +60	+5 +60							
Corrosion resistance class CRC ²⁾		1								

Note operating range of proximity sensors
 Corrosion resistance class 1 according to Festo standard 940 070
 Components subject to low corrosion stress. Transport and storage protection. Parts that do not have primarily decorative surface requirements, e.g. in internal areas that are not visible or behind covers.

Weight [g]										
Size	10	16	25	32	40					
DHRSA	44	114	270	480	829					
DHRSA-NC	-	118	277	490	844					

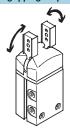
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Materials Sectional view 1 2 3 4

Radi	al gripper	
1	Gripper jaw	High-alloy stainless steel
2	Cover cap	Polyamide
3	Slotted guide plate	Tempered steel
4	Piston	Polyacetal
5	Housing	Hard anodised wrought aluminium alloy
-	Seals	Nitrile rubber
-	Note on materials	Free of copper and PTFE
		RoHS-compliant

Total gripping torque [Ncm] at 6 bar

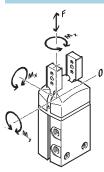
5



The gripping torque is not constant within the opening angle \rightarrow 12.

Size		10	16	25	32	40
DHRSA	RSA Opening		62	233	423	725
	Closing	15	55	215	390	660

Static characteristic load values at the gripper jaws



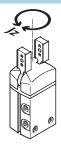
The indicated permissible forces and torques apply to a single gripper jaw. They include the lever arm, additional applied loads due to the workpiece or external gripper fingers and acceleration forces occurring during

movement.

The zero coordinate line (gripper jaw guide) must be taken into consideration for the calculation of torques.

Size	10	16	25	32	40	
Max. permissible force F _z	[N]	30	40	75	120	200
Max. permissible torque M _X	[Nm]	0.8	1.3	3.2	6.2	14
Max. permissible torque M _y	[Nm]	0.8	1.3	3.2	6.2	14
Max. permissible torque M _z	[Nm]	0.8	1.3	3.2	6.2	14

Mass moment of inertia [kgm²x10-4]



Mass moment of inertia of the radial gripper in relation to the central axis, without external gripper fingers, without load.

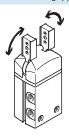
Size	10	16	25	32	40
DHRSA	0.03	0.14	0.69	1.66	4.18
DHRSA-NC	-	0.15	0.71	1.69	4.24



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Opening and closing times [ms] at 6 bar

Without external gripper fingers

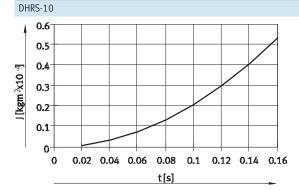


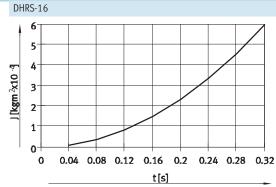
The indicated opening and closing times [ms] were measured at room $temperature \ at \ an \ operating \ pressure$ of 6 bar with horizontally mounted grippers without additional gripper

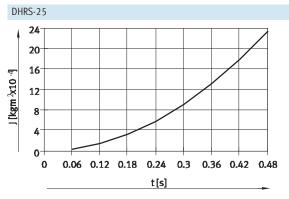
fingers (average values). The grippers must be throttled for greater applied loads. Opening and closing times must then be adjusted accordingly.

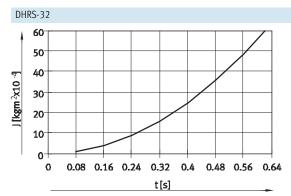
Size	10	16	25	32	40			
Without external gripper fingers								
DHRSA	Opening	35	61	102	111	113		
	Closing	91	63	105	119	142		
DHRSA-NC	Opening	-	75	150	131	151		
	Closing	-	43	96	88	110		

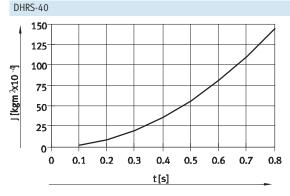
Opening and closing times t to be set at 6 bar as a function of mass moment of inertia of the gripper fingers











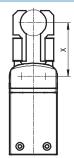


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Gripping force $\boldsymbol{F}_{\boldsymbol{H}}$ per gripper jaw as a function of operating pressure and lever arm \boldsymbol{x}

The gripping forces as a function of operating pressure and lever arm can be determined from the following graphs.

The gripping torque is not constant within the opening angle \rightarrow 12.

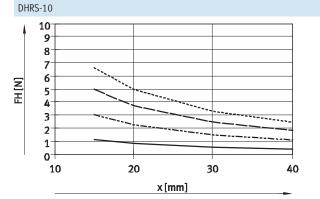


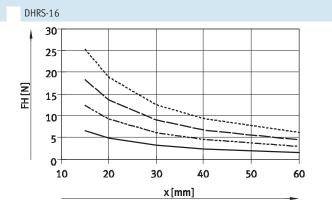
2 bar 4 bar 6 bar ----- 8 bar Note

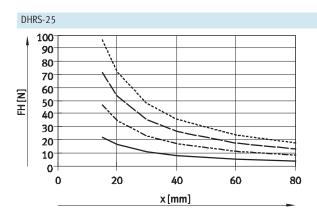
Gripper selection sizing software

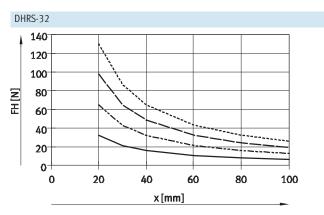
→ www.festo.com











DHRS-40 250 200 150 H. 100 50 20 60 80 100 0 120 x[mm]

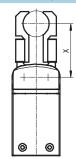


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Gripping force $\boldsymbol{F}_{\boldsymbol{H}}$ per gripper jaw as a function of operating pressure and lever arm \boldsymbol{x}

The gripping forces as a function of operating pressure and lever arm can be determined from the following graphs.

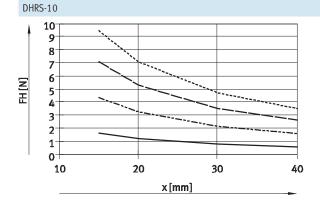
The gripping torque is not constant within the opening angle \rightarrow 12.

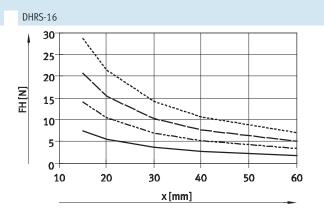


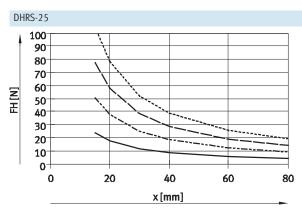
2 bar --- 4 bar 6 bar ----- 8 bar

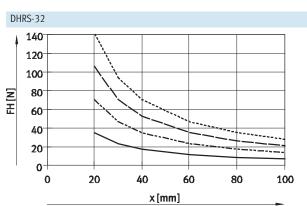
Note Gripper selection sizing software → www.festo.com

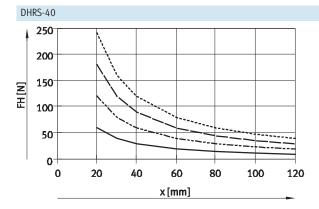
Internal gripping (opening)













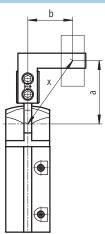
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Gripping force $F_{\mbox{\scriptsize H}}$ per gripper jaw at 6 bar as a function of lever arm x and eccentricity a and b

The following formula must be used to calculate the lever arm x with eccentric gripping:

$$x = \sqrt{a^2 + b^2}$$

The gripping force F_H can be read from the graphs (\rightarrow 10/11) using the calculated value x.



Calculation example

Given:

Distance a = 25 mm

Distance b = 20 mm

To be calculated:

The gripping force at 6 bar,

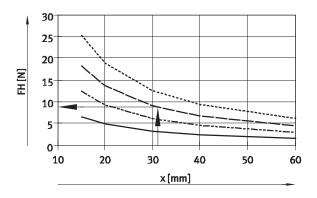
with a DHRS-16,

used as an external gripper

Procedure: Calculating the lever arm \boldsymbol{x}

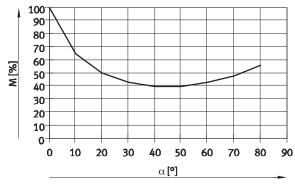
$$x = \sqrt{25^2 + 20^2}$$

The graph $(\rightarrow 10)$ gives a value of F_H = 8 N for the gripping force.



Torque curve M as a function of opening angle $\boldsymbol{\alpha}$

The drive principle of the gripper jaws means that the torque is not constant within the opening angle. The percentage of torque available in each case can be seen in the graph. An opening angle of 0° means a parallel gripper jaw position.

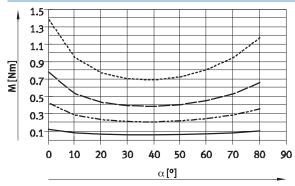




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Technical data

Spring torque M_{F} as a function of opening angle α



DHRS-16
DHRS-25
DHRS-32
DHRS-40

Determination of the actual gripping torques $\mathbf{M}_{Grtotal}$ for DHRS-...-NC as a function of application

The radial gripper with integrated spring type DHRS-...-NC (closing gripping force retention) can be used as:

- single-acting grippers
- grippers with supplementary gripping force and
- grippers with gripping force retention depending on requirements.

In order to calculate the available gripping torque $M_{Grtotal}$ (per gripper jaw), the data from the graphs for the gripping force $F_H (\rightarrow 10/11)$, the

torque M_F (\Rightarrow 13) must be combined accordingly.

torque curve (> 12) and the spring

$$M_{Gr} = F_H * x * M [\%]$$

 $\begin{array}{ll} M_{Gr} \ \ Gripping \ torque \\ F_{H} \ \ Gripping \ force \end{array}$

x Lever arm M Torque curve

Application

Single-acting

- Gripping with spring force: $M_{Grtotal} = M_{F}$
- Gripping with pressure force: M_{Grtotal} = M_{Gr} - M_F

Supplementary gripping force

• Gripping with pressure and spring force:

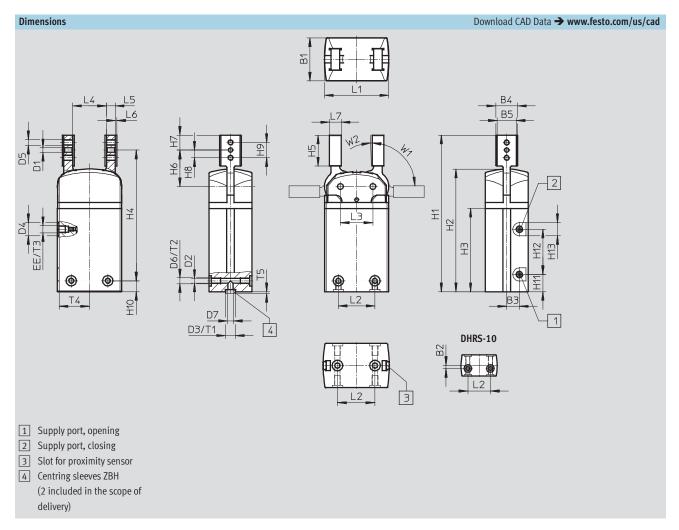
 $M_{Grtotal} = M_{Gr} + M_{F}$

Gripping force retention

• Gripping with spring force: M_{Grtotal} = M_F







Size	B1	B2 ¹⁾	В3	B4	B5 +0.03/	D1 Ø	D2 Ø	D3 Ø	D4 Ø	D5
[mm]	±0.05				+0.01	H8	+0.1	H8/h7	,_	
10	14	2	2	8.5	6.5	2	2.4	5	7	M2.5
16	19	-	5.8	14	10	2	2.5	5	-	M3
25	29.5	-	8.75	15	13	3	3.3	7	9	M4
32	38	-	11	16	14	4	5.1	9	15	M5
40	49	-	11	24	20	5	6.4	12	15	M6

Size	D6	D7 Ø	EE	H1	H2	Н3	H4	H5	Н6
[mm]							±0.25	±0.2	±0.05
10	M3	3.2	M3	60.8	46	30.8	42.25	13.8	14.95
16	M3	3.2	M3	88.2	70.5	49	73.70	16.5	19.7
25	M4	5.3	M5	107.2	84	57	89.45	21.2	24.95
32	M6	6.4	G1/8	128.5	96.2	65	103.5	29.5	32
40	M8	10.3	G1//8	140	108.4	71.5	108.7	29.5	33.7

¹⁾ Tolerance for centring hole ± 0.02 mm; tolerance for thread ± 0.1 mm



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Size	H7	Н8	Н9	H10 ²⁾	H11	H12	H13	L1	L2 ¹⁾	L3
[mm]	-0.1							±0.05		±0.02
10	6.25	4	8	12.3	8.8	16	7	24	15	12.4
16	7	4	8	7.5	12.25	23	7	33.4	16	17
25	10.25	5.25	10.5	7.5	11.8	31	9	44	25	22.2
32	14	7	14	11	20	25	15	51	29	25.8
40	13.8	8	16	17.5	9	46	15	59	33	30

Size	L4	L5	L6	L7	T1	T2	T3	T4	T5	W1	W2
[mm]		±0.05			+0.1	+1	+0.5		-0.3	±2°	+3°
10	12	4	0.5	5	1.2	through	3.5	11.6	1.2	90	2
16	21	4	1	6	1.2	5.8	4.5	16	1.2	90	2
25	23.2	6	1	8	1.6	6.4	4.5	21	1.4	90	2
32	24.8	8	1	10	2.1	12.9	6.5	24	1.9	90	2
40	29.6	10	1	12	2.6	13.4	6	28.4	2.4	90	2

Ordering data		
Size	Double-acting	Single-acting or with gripping force retention
	without compression spring	Closing
[mm]	Part No. Type	Part No. Type
10	1310159 DHRS-10-A	-
16	1310160 DHRS-16-A	1310161 DHRS-16-A-NC
25	1310162 DHRS-25-A	1310163 DHRS-25-A-NC
32	1310164 DHRS-32-A	1310165 DHRS-32-A-NC
40	1310166 DHRS-40-A	1310167 DHRS-40-A-NC

¹⁾ Tolerance for centring hole ± 0.02 mm, tolerance for thread ± 0.1 mm 2) Tolerance for centring hole -0.05 mm, tolerance for thread ± 0.1 mm

Radial grippers DHRS Accessories

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Adapter kit HMSV, HAPG, HAPS, HMVA, DHAA Material: Wrought aluminium alloy Free of copper and PTFE RoHS-compliant

Note

The kit includes the individual mounting interface as well as the necessary mounting material.

Permissible drive/grippe Combination	Drive	Gripper			Adapter		d CAD Data → www.festo.com/us/ca
Combination	Size	Size	Mounting option	 I	CRC ¹⁾	Part No.	Туре
	0.20	0.20	- Soprior		-		7,70
OGSL/DHRS	DGSL	DHRS			HMSV	'	
K	8, 10	10				548784	HMSV-54
	12, 16	16	•		2	548785	HMSV-55
	20, 25	25,32				548786	HMSV-56
		•					
LT/DHRS	SLT	DHRS			HAPS		
LITUTING	ور الم	10	•	_	TIALS	178448	HAPS-2
10.5	16	16		_		178449	HAPS-3
	20	25	_	_	2	178450	HAPS-4
	25	32		_		178451	HAPS-5
PZ/DHRS	DPZ	DHRS			HAPG		
	> 10,16	16		_	1	163250	HAPG-1
	16	25		_		163251	HAPG-2
	20	25	•	_	2	163252	HAPG-3
A SECTION A	25, 32	32		_		163253	HAPG-4
	·	I	l			l	
MP/DHRS	НМР	DHRS			HMSV		
		ting			I		
	16, 20	16	•	•		177666	HMSV-20
	16, 20, 25	25	•			177761	HMSV-21
WP/DHRS	16, 20, 25,	32 32		•	2	177762	HMSV-22
	25	40				177763	HMSV-23
	32	40				177764	HMSV-24
	Dovetail mo	unting					
	16, 20	16	•	•		177767	HMSV-27
	16, 20, 25	25	•			177768	HMSV-28
	16, 20, 25,	32 32			2	177769	HMSV-29
	25	40				177770	HMSV-30
	32	40			\dashv	178211	HMSV-31

¹⁾ Corrosion resistance class 2 according to Festo standard 940 070 Components subject to moderate corrosion stress. Externally visible parts with primarily decorative surface requirements which are in direct contact with a normal industrial environment or media such as coolants or lubricating agents.



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Accessories

Adapter kit HMSV, HAPG, HAPS, HMVA, DHAA Material: Wrought aluminium alloy Free of copper and PTFE RoHS-compliant

Note

The kit includes the individual mounting interface as well as the necessary mounting material.

Permissible drive/gripper con	mbinations with	adapter kit					d CAD Data → www.festo.com/us/cad
Combination	Drive	Gripper			Adapter k	it	
	Size	Size	Mounting option	ı	CRC ¹⁾	Part No.	Туре
DGP, DGE, DGEA/DHRS	DG	DHRS			HMVA, HA	APG, HMSV	
√2.	Direct moun	ting					
	18 ²⁾ , 25 ³⁾	10	_			196788	HMVA-DLA18/25
			_	_		192706	HAPG-37-S1
	403)	10	•			196790	HMVA-DLA40
				_		192706	HAPG-37-S1
	18 ²⁾ , 25 ³⁾	16	•	_		196788	HMVA-DLA18/25
			•	•		192705	HAPG-36-S1
	403)	16	_	_	2	196790	HMVA-DLA40
			•	•		192705	HAPG-36-S1
	18 ²⁾ , 25 ³⁾	25	_	_		196788	HMVA-DLA18/25
			•	•		193922	HAPG-37-S4
	403)	25				196790	HMVA-DLA40
			•	•		193922	HAPG-37-S4
	Dovetail mou	unting	,		<u> </u>	<u> </u>	
	18 ²⁾ , 25	16		_		196788	HMVA-DLA18/25
			•	•		177767	HMSV-27
	40	16	_			196790	HMVA-DLA40
			•	•		177767	HMSV-27
	18 ²⁾ , 25	25				196788	HMVA-DLA18/25
			•			177768	HMSV-28
	40	25			2	196790	HMVA-DLA40
			•	•		177768	HMSV-28
	40	32			-	196790	HMVA-DLA40
			•	•		177769	HMSV-29
	40	40			-	196790	HMVA-DLA40
		10	•			177770	HMSV-30

¹⁾ Corrosion resistance class 2 according to Festo standard 940 070 Components subject to moderate corrosion stress. Externally visible parts with primarily decorative surface requirements which are in direct contact with a normal industrial environment or media such as coolants or lubricating agents.

²⁾ Only for DGE.../DGP...
3) Only for DGE.../DGP...



Radial grippers DHRS Accessories

FESTO

Adapter kit HMSV, HAPG, HAPS, HMVA, DHAA Material: Wrought aluminium alloy Free of copper and PTFE RoHS-compliant

Note

The kit includes the individual mounting interface as well as the necessary mounting material.

Permissible drive/gripper Combination	Drive	Gripper			Adapter I		I CAD Data → www.festo.com/us/ca
combination	Size	Size	Mounting option		CRC ¹⁾	Part No.	Туре
DRQD/DHRS	DRQDFW	DHRS			HAPG		
	6, 8, 12	10	•			187568	HAPG-34
	16 ²⁾	10	•			187566	HAPG-SD2-12
	16 ²⁾	16	•			184477	HAPG-SD2-1
	16 ²⁾	25	•			184478	HAPG-SD2-2
	20 ²⁾	25	•			184479	HAPG-SD2-3
•	20 ²⁾	32	•		2	184480	HAPG-SD2-4
	25 ³⁾	25	•			184482	HAPG-SD2-6
	25 ³⁾	32	•			184483	HAPG-SD2-7
	32 ³⁾	32				184485	HAPG-SD2-9
	32 ³⁾	40	•			184486	HAPG-SD2-10
	40, 50	40	•			526027	HAPG-SD2-21
	DRQDZW	DHRS			HAPG	_	
	16	16	•			163267	HAPG-18
	16	25	•			163268	HAPG-19
	20	25			2	163269	HAPG-20
	20	32	•			163270	HAPG-21
	25	32				163271	HAPG-22
RRD/DHRS	DRRD	DHRS			DHAA		
כאחט/טחאס	16	16		_	рпаа	1979085	DHAA-G-Q11-16-B2/B3-16
	16	25	-		_	1978889	DHAA-G-Q11-16-B2/B3-25
	20	25	-		_	1978443	DHAA-G-Q11-10-B2/B3-25
	20	32	-		-	1979912	DHAA-G-Q11-20-B2/B3-32
	25	25	-			1801802	DHAA-G-Q11-25-B2/B3-25
	25	32				1802969	DHAA-G-Q11-25-B2/B3-32
	32	32	-		\dashv	1979992	
	32	40			\dashv		DHAA-G-Q11-32-B2/B3-32
	35, 40	40	-			1980014 1980059	DHAA-G-Q11-32-B2/B3-40 DHAA-G-Q11-35/40-B2/B3-40

¹⁾ Corrosion resistance class 2 according to Festo standard 940 070 Components subject to moderate corrosion stress. Externally visible parts with primarily decorative surface requirements which are in direct contact with a normal industrial environment or media such as coolants or

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²⁾ Possible in combination with DRQD-...-E422 (flanged shaft with energy through-feed).

³⁾ Possible in combination with DRQD-...-E444 (flanged shaft with energy through-feed).

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Accessories

Adapter kit HMSV, HAPG, HAPS, HMVA, DHAA Material: Wrought aluminium alloy Free of copper and PTFE ROHS-compliant

Note

The kit includes the individual mounting interface as well as the necessary mounting material.

Combination	er combinations with a Drive	Gripper			Adapter		d CAD Data → www.festo.com/us/o
COMBINATION	Size	Size	Mounting option		CRC ¹⁾	Part No.	Туре
	3120	3120				T uit iio.	,,,,,
ISP/DHRS	HSP	DHRS			HAPG		
	12	10	-	_		192709	HAPG-60-S1
É	>> L		_			540881	HAPG-70-B
	16	10		_		192706	HAPG-37-S1
أمعرية				_		540882	HAPG-71-B
	16	16		_	2	192705	HAPG-36-S1
					2	540882	HAPG-71-B
	25	16		_		192705	HAPG-36-S1
			_	_		540883	HAPG-72-B
	25	25		_		193922	HAPG-37-S4
			_	-		540883	HAPG-72-B
	•	'				•	
ISW/DHRS	HSW	DHRS			HAPG		
	12, 16	10		_		192706	HAPG-37-S1
					2	540882	HAPG-71-B
	12,16	16				192705	HAPG-36-S1
1.6	12,10	10	_	_		192/03	HAFG-30-31
	12,10	10	•	-		540882	HAPG-71-B
			•	-	Lung		
	DSMFW	DHRS			HAPG	540882	HAPG-71-B
DSM/DHRS	DSMFW 6, 8, 10	DHRS 10	•	-	2		
DSM/DHRS	DSMFW 6, 8, 10 DSM	DHRS 10 DHRS		•		540882	HAPG-71-B
DSM/DHRS	DSMFW 6, 8, 10 DSM 12	DHRS 10 DHRS 16		•	2	540882 187568 163266	HAPG-34 HAPG-17
DSM/DHRS	DSMFW 6, 8, 10 DSM 12 16	DHRS 10 DHRS 16 16		•	2	187568 163266 163267	HAPG-34 HAPG-17 HAPG-18
DSM/DHRS	DSMFW 6, 8, 10 DSM 12 16 16	DHRS 10 DHRS 16 16 25		•	2	187568 163266 163267 163268	HAPG-71-B HAPG-34 HAPG-17 HAPG-18 HAPG-19
	DSMFW 6, 8, 10 DSM 12 16 16 25	DHRS 10 DHRS 16 16 25 25		•	2 HAPG	187568 163266 163267 163268 163269	HAPG-71-B HAPG-34 HAPG-17 HAPG-18 HAPG-19 HAPG-20
DSM/DHRS	DSMFW 6, 8, 10 DSM 12 16 16 25 25	DHRS 10 DHRS 16 16 25 25 32			2 HAPG	187568 163266 163267 163268 163269 163270	HAPG-71-B HAPG-34 HAPG-17 HAPG-18 HAPG-19 HAPG-20 HAPG-21
SM/DHRS	DSMFW 6, 8, 10 DSM 12 16 16 25	DHRS 10 DHRS 16 16 25 25		•	2 HAPG	187568 163266 163267 163268 163269	HAPG-71-B HAPG-34 HAPG-17 HAPG-18 HAPG-19 HAPG-20
SM/DHRS	DSMFW 6, 8, 10 DSM 12 16 16 25 25 32	DHRS 10 DHRS 16 16 25 25 32 32			2 HAPG 2	187568 163266 163267 163268 163269 163270	HAPG-71-B HAPG-34 HAPG-17 HAPG-18 HAPG-19 HAPG-20 HAPG-21
DSM/DHRS DSL/DHRS	DSMFW 6, 8, 10 DSM 12 16 16 25 25 32 DSL	DHRS 10 DHRS 16 16 25 25 32			2 HAPG	187568 163266 163267 163268 163269 163270	HAPG-71-B HAPG-34 HAPG-17 HAPG-18 HAPG-19 HAPG-20 HAPG-21
OSM/DHRS OSL/DHRS	DSMFW 6, 8, 10 DSM 12 16 16 25 25 32 DSL	DHRS 10 DHRS 16 16 25 25 32 32 DHRS		1 1 1 1	2 HAPG 2	187568 163266 163267 163268 163269 163270 163271	HAPG-71-B HAPG-34 HAPG-17 HAPG-18 HAPG-19 HAPG-20 HAPG-21 HAPG-22
OSM/DHRS OSL/DHRS	DSMFW 6, 8, 10 DSM 12 16 16 25 25 32 DSL	DHRS 10 DHRS 16 16 25 25 32 32 DHRS 16			2 HAPG 2 HAPG	187568 163266 163267 163268 163270 163271	HAPG-71-B HAPG-34 HAPG-17 HAPG-18 HAPG-19 HAPG-20 HAPG-21 HAPG-22
OSM/DHRS OSL/DHRS	DSMFW 6, 8, 10 DSM 12 16 16 25 25 32 DSL	DHRS 10 DHRS 16 16 25 25 32 32 DHRS 16 16 16 25			2 HAPG 2	187568 163266 163267 163268 163270 163271 163266 163267 163268	HAPG-71-B HAPG-34 HAPG-17 HAPG-18 HAPG-19 HAPG-20 HAPG-21 HAPG-21 HAPG-17 HAPG-17
DSM/DHRS	DSMFW 6, 8, 10 DSM 12 16 16 25 25 32 DSL	DHRS 10 DHRS 16 16 25 25 32 32 DHRS 16 16			2 HAPG 2 HAPG	187568 163266 163267 163268 163269 163271 163266 163266	HAPG-71-B HAPG-34 HAPG-17 HAPG-18 HAPG-19 HAPG-20 HAPG-21 HAPG-21 HAPG-17 HAPG-17

¹⁾ Corrosion resistance class 2 according to Festo standard 940 070 Components subject to moderate corrosion stress. Externally visible parts with primarily decorative surface requirements which are in direct contact with a normal industrial environment or media such as coolants or lubricating agents.



Radial grippers DHRS Accessories

FESTO

Adapter kit HMSV, HAPG, HAPS, HMVA, DHAA Material: Wrought aluminium alloy Free of copper and PTFE RoHS-compliant

Note

The kit includes the individual mounting interface as well as the necessary mounting material.

Combination	Drive	Gripper			Adapter	kit	
	Size	Size	Mounting option	1	CRC ¹⁾	Part No.	Туре
GSL/DHRS	EGSL	DHRS			HMSV		
Æ. •.	35	10	•			548784	HMSV-54
			_	_	2	1088262	HMSV-70
	45, 55	16	•			548785	HMSV-55
	75	25,32				548786	HMSV-56
		•		•	•		
					_		
GSA/DHRS	EGSA	DHRS	ı		HMSV	1	
ET),	50	16	-			560017	HMSV-61
						548785	HMSV-55
	60	16			2	560019	HMSV-63
						177666	HMSV-20
	60	25,32				560018	HMSV-62
						548786	HMSV-56
RMB/DHRS	ERMB	DHRS			HAPG		
אוואט/טווא:	20	25	-		HAPG	184479	HAPG-SD2-3
	25	25	- :		_	184482	HAPG-SD2-3
			-		_		HAPG-SD2-6
	20 25	32 32		-	2	184480 184483	HAPG-SD2-4
	_						
	32	32	•	-		184485	HAPG-SD2-9
	32	40	•	•		184486	HAPG-SD2-10
HMB/DHRS	EHMB	DHRS			HAPG		
U MONEY OT S	20	32	-			184485	HAPG-SD2-9
	20	40	•		2	184486	HAPG-SD2-10
	25, 32	40	•	•		526027	HAPG-SD2-21
1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1		I.	1	1	_1	_1	

¹⁾ Corrosion resistance class 2 according to Festo standard 940 070 Components subject to moderate corrosion stress. Externally visible parts with primarily decorative surface requirements which are in direct contact with a normal industrial environment or media such as coolants or lubricating agents.



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Accessories

Ordering data									
	For size	Description	Weight	Part No.	Туре	PU ¹⁾			
	[mm]		[g]						
Centring sleeve	Centring sleeve ZBH Technical data → Internet: zbh								
	10, 16	For centring the gripper during mounting	1	189652	ZBH-5	10			
(1)	25		1	186717	ZBH-7				
	32		1	150927	ZBH-9				
	40		1	189653	ZBH-12				

1) Packaging unit

Ordering data									
Туре	For size	Weight	Part No.	Туре					
		[g]							
Position sensor SMH-S1	Position sensor SMH-S1								
and the second	10	20	175712	SMH-S1-HGR10					

Signal converter/evaluation unit for position sensor SMH-S1

Signal converter SVE4

Evaluation unit SMH-AE1

- Converts analogue signals into switching points
- Switching function freely programmable with teach-in
- Threshold value, hysteresis or window comparator
- Converts analogue signals into switching points
- With 3 potentiometers for setting 3 switching points

Ordering	data						
Туре	For size	Input connection	Output connection	Switching	Weight	Part No.	Туре
				output	[g]		
Signal cor	nverter SVE4						Technical data → Internet: sve4
O 3.	10	Socket M8x1,	Plug M8x1,	2x PNP	19	544216	SVE4-HS-R-HM8-2P-M8
		4-pin	4-pin	2x NPN		544219	SVE4-HS-R-HM8-2N-M8
Evaluation	n unit SMH-AE1						Technical data → Internet: smh-ae
	10	Socket M8x1,	Plug M12x1,	3x PNP	170	175708	SMH-AE1-PS3-M12
		4-pin	5-pin	3x NPN		175709	SMH-AE1-NS3-M12

Ordering data	– Connecting cables				Technical data → Internet: nebu				
	Electrical connection, left	Electrical connection, right	Cable length [m]	Part No.	Туре				
Connection between position sensor and signal converter/evaluation unit									
	Straight socket, M8x1, 4-pin	Straight plug, M8x1, 4-pin	2.5	554035	NEBU-M8G4-K-2.5-M8G4				
Connection be	tween evaluation unit and controller								
	Straight socket, M12x1, 5-pin	Cable, open end, 5-wire	2.5	541330	NEBU-M12G5-K-2.5-LE5				
6			5	541331	NEBU-M12G5-K-5-LE5				



Radial grippers DHRS Accessories

FESTO

Ordering data	- Connecting cables		Technical data → Internet: nebu						
	Electrical connection, left	Electrical connection, right	Cable length	Part No.	Туре				
			[m]						
Connection be	Connection between signal converter and controller								
	Straight socket, M8x1, 4-pin	Cable, open end, 4-wire	2.5	541342	NEBU-M8G4-K-2.5-LE4				
			5	541343	NEBU-M8G4-K-5-LE4				
	Angled socket, M8x1, 4-pin	Cable, open end, 4-wire	2.5	541344	NEBU-M8W4-K-2.5-LE4				
			5	541345	NEBU-M8W4-K-5-LE4				

Proximity sensor for size 16 40							
Ordering data	a – Proximity sensors for T-		Technical data → Internet: smt				
	Type of mounting	Electrical connection,	Switching	Cable length	Part No.	Туре	
		connection direction	output	[m]			
N/O contact							
A	Insertable in the slot	Cable, 3-wire, lateral	PNP	2.5	547859	SMT-8G-PS-24V-E-2,5Q-0E	
	lengthwise	Plug M8x1, 3-pin, lateral		0.3	547860	SMT-8G-PS-24V-E-0,3Q-M8D	

Proximity sensor for size 16 40							
Ordering data	Technical data → Internet: smat						
	Type of mounting	Electrical connection, connection direction	Analogue output [V]	Cable length [m]	Part No.	Туре	
	Insertable in the slot from above	Plug M8x1, 3-pin, in-line	0 10	0.3	553744	SMAT-8M-U-E-0,3-M8D	

Note

Mode of operation:

The position transmitter continuously senses the position of the piston. It has an analogue output with an output signal in proportion to the piston position.

Ordering data	Technical data → Internet: nebu				
	Electrical connection, left	Electrical connection, right	Cable length	Part No.	Туре
			[m]		
	Straight socket, M8x1, 3-pin	Cable, open end, 3-wire	2.5	541333	NEBU-M8G3-K-2.5-LE3
6			5	541334	NEBU-M8G3-K-5-LE3
	Angled socket, M8x1, 3-pin	Cable, open end, 3-wire	2.5	541338	NEBU-M8W3-K-2.5-LE3
			5	541341	NEBU-M8W3-K-5-LE3

Product Range and Company Overview

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Festo is a leading global manufacturer of pneumatic and electromechanical systems, components and controls for industrial automation, with more than 12,000 employees in 56 national headquarters serving more than 180 countries. For more than 80 years, Festo has continuously elevated the state of manufacturing with innovations and optimized motion control solutions that deliver higher performing, more profitable automated manufacturing and processing equipment. Our dedication to the advancement of automation extends beyond technology to the education and development of current and future automation and robotics designers with simulation tools, teaching programs, and on-site services.

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