



Key features

Design

General

The SMAT-8M is a position transmitter for the contactless sensing of the piston position of drives that can be detected magnetically. It supplies a displacement-proportional analogue output signal in the position measuring range. It is connected directly to the analogue PLC inputs without any accessories. With its extremely compact design,

the SMAT-8M is the ideal solution for grippers, short-stroke cylinders and all applications in which installation space is restricted.

Note

It can be used with Festo cylinders with T-slot (profile slot 8) as well as round cylinders and tie-rod cylinders with mounting kits. A selection aid with suitable drives can be found on the following pages.

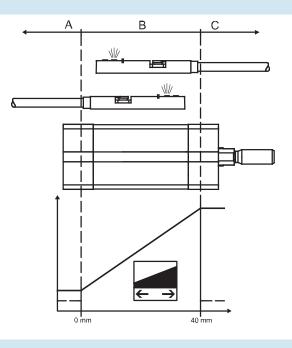
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Position measuring range

The SMAT-8M supplies a displacement-proportional analogue output signal of 0 ... 10 V in the position measuring range of up to 40 mm (depending on the drive used). In other words, the output voltage increases when the piston moves in the direction of the piston rod. When the piston retracts, the output voltage drops.

The installation direction of the SMAT-8M is irrelevant in this case. To achieve the best possible function on the drive in question, the position measuring range must be initialised on the drive during installation.

As a visual aid, the green LED lights up within the position measuring range (B) and the red LED lights up outside of the measuring range (A)/(C) in normal operation.

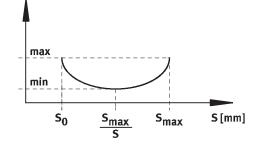


Repetition accuracy

The repetition accuracy is ±0.025 mm on grippers and ±0.1 mm on standard drives.

With standard drives, the repetition accuracy in the centre of the measuring range is lower than at the edge. It is ±0.06 mm at a distance of ±5 mm from the centre, for example. For critical applications, it is recommended that the SMAT-8M be mounted so as to have the relevant measuring points close to 5.5 V.

Repetition accuracy as a function of position measuring range S



Position transmitters SMAT-8M, for T-slot Selection aid

Drive/gripper	Usability	Position me	asuring	D
	on drive	range appro	ox.	
		With	Without	
		initialisati	initialisati	
		on	on ²⁾	
		[mm]	[mm]	
Standards-based cylinders				C
Standard cylinder DSNU/ESNU-8	+	19	17	S
Standard cylinder DSNU/ESNU-10	+	22	19	
Standard cylinder DSNU/ESNU-12	+	21	19	
Standard cylinder DSNU/ESNU-16	+	21	19	
Standard cylinder DSNU/ESNU-20	+	20	18	
Standard cylinder DSNU/ESNU-25	+	28	22	S
Round cylinder DSNU/ESNU-32	+	25	23	S
Round cylinder DSNU/ESNU-40	+	29	30	
Round cylinder DSNU/ESNU-50	+	31	29	S
Round cylinder DSNU/ESNU-63	+	36	33	6
Standard cylinder DNCB-32	+	25	23	S
Standard cylinder DNCB-40	+	28	19	S
Standard cylinder DNCB-50	+	30	26	C
Standard cylinder DNCB-63	+	32	27	C
Standard cylinder DNCB-80	+	35	32	C
Standard cylinder DNCB-100	+	29	26	C
Standard cylinder DNC-32	+	29	32	C
Standard cylinder DNC-40	0 ¹⁾	-	-	C
Standard cylinder DNC-50	01)	-	-	C
Standard cylinder DNC-63	+	34	28	C
Standard cylinder DNC-80	+	35	29	C
Standard cylinder DNC-100	+	37	33	C
Standard cylinder DNC-125	+	38	32	C
Standard cylinder DNG-32	+	28	19	Fl
Standard cylinder DNG-40	+	34	30	Fl
Standard cylinder DNG-50	01)	-	-	Fl
Standard cylinder DNG-63	+	32	25	Fl
Standard cylinder DNG-80	+	32	25	Fl
Standard cylinder DNG-100	+	32	27	Fl
Compact cylinder AND/AEN-12	+	22	22	Fl
Compact cylinder ADN/AEN-16	+	26	26	
Compact cylinder ADN/AEN-20	+	30	28	R
Compact cylinder ADN/AEN-25	+	27	24	Li
Compact cylinder ADN/AEN-32	+	31	31	Li
Compact cylinder ADN/AEN-40	+	28	20	Li
Compact cylinder ADN/AEN-50	+	25	21	Li
Compact cylinder ADN/AEN-63	+	31	29	
Compact cylinder ADN/AEN-80	01)	-	-	Fi
Compact cylinder ADN/AEN-100	+	28	24	Li
Compact cylinder ADN/AEN-125	+	37	33	Li

	11	Destation	!			
Drive/gripper	Usability	Position measuring				
	on drive	range approx.				
		With	Without			
		initialisati	initialisati			
		on	on ²⁾			
		[mm]	[mm]			
Cylinders with piston rod						
Short-stroke cylinder ADVC/AEVC-32	+	Stroke	Stroke			
		< position	< position			
		measuring	measuring			
		range	range			
		SMAT-8M	SMAT-8M			
Short-stroke cylinder ADVC/AEVC-40	+		24			
Short-stroke cylinder ADVC/AEVC-50	+		Stroke			
Short-stroke cylinder ADVC/AEVC-63	+	_	< position			
Short-Stroke Cylinder ADVC/AEVC-05	-		measuring			
Short-stroke cylinder ADVC/AEVC-80	+	-	range			
			SMAT-8M			
Short-stroke cylinder ADVC/AEVC-100	+		24			
Compact cylinder ADVU/AEVU-12	+	23	20			
Compact cylinder ADVU/AEVU-16	+	20	17			
Compact cylinder ADVU/AEVU-20	+	29	28			
Compact cylinder ADVU/AEVU-25	+	25	21			
Compact cylinder ADVU/AEVU-32	+	27	23			
Compact cylinder ADVU/AEVU-40	+	24	21			
Compact cylinder ADVU/AEVU-50	+	22	18			
Compact cylinder ADVU/AEVU-63	+	32	27			
Compact cylinder ADVU/AEVU-80	+	35	28			
Compact cylinder ADVU/AEVU-100	+	33	26			
Compact cylinder ADVU/AEVU-125	+	35	31			
Flat cylinder DZF-12	+	29	26			
Flat cylinder DZF-18	+	26	24			
Flat cylinder DZF-25	+	28	23			
Flat cylinder DZF-32	+	26	17			
Flat cylinder DZF-40	0 ¹⁾		-			
Flat cylinder DZF-50	0 ¹⁾ 0 ¹⁾	-	-			
Flat cylinder DZF-63	01)	-	-			
Podloss sulindors						
Rodless cylinders Linear drive DGC-18	+	30	26			
Linear drive DGC-18	• • • • • • • • • • • • • • • • • • • •	-	-			
Linear drive DGC-32	0 ¹⁾	-	_			
Linear drive DGC-32	0 ¹ /	-	_			
	0-7	-	-			
Function-oriented drives						
Linear/swivel clamp CLR-12	+	22	22			
Linear/swivel clamp CLR-16	+	26	26			
Linear/swivel clamp CLR-20	+	30	28			
Linear/swivel clamp CLR-25	+	27	20			
Linear/swivel clamp CLR-32	+	31	31			
Linear/swivel clamp CLR-40	+	28	20			
Linear/swivel clamp CLR-50	+	25	20			
Linear/swivel clamp CLR-63	+	31	29			
Encarjoniver eramp cere of		<i></i>	/			

+ Unrestricted use

- On request
 Different from technical data. Usability on request.
 Position measuring range without initialisation (as supplied from the factory)

Position transmitters SMAT-8M, for T-slot Selection aid

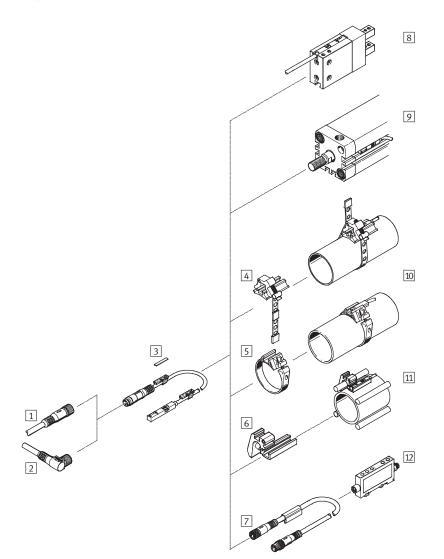
Drive/gripper	Usability on drive	Position me	-
	on arive	range appro	
		With	Without
		initialisati	initialisati on ²⁾
		on	•
		[mm]	[mm]
Drives with linear guides		•	
Guided drive DFM-12	+	21	22
Guided drive DFM-16	+	15	16
Guided drive DFM-20	+	24	22
Guided drive DFM-25	+	26	25
Guided drive DFM-32	+	25	22
Guided drive DFM-40	0 ¹⁾	-	-
Guided drive DFM-50	+	21	18
Guided drive DFM-63	+	31	27
Guided drive DFM-80	+	30	30
Guided drive DFM-100	+	25	24
Guided drive DFM-12-B	+	16	22
Guided drive DFM-16-B	+	20	21
Guided drive DFM-20-B	+	26	27
Guided drive DFM-25-B	+	24	22
Guided drive DFM-32-B	+	29	28
Guided drive DFM-40-B	+	30	29
Guided drive DFM-50-B	+	31	31
Guided drive DFM-63-B	+	33	32
Linear unit SLE-10	+	22	22
Linear unit SLE-16	+	21	21
Linear unit SLE-20	+	20	20
Linear unit SLE-25	+	28	28
Linear unit SLE-32	+	25	25
Linear unit SLE-40	+	29	29
Linear unit SLE-50	+	31	31

Drive/gripper	Usability on drive	Position means range appro	x.		
		With initialisati on	Without initialisati on ²⁾		
Llandling units		[mm]	[mm]		
Handling units	· ·	Ctrake	itian		
Three-point gripper DHDS-32	+	Stroke < pos			
Three-point gripper DHDS-50	+	measuring ra	ange		
Parallel gripper DHPS-10	+	SMAT-8M			
Parallel gripper DHPS-16	+	_			
Parallel gripper DHPS-20	+				
Parallel gripper DHPS-25	+				
Parallel gripper DHPS-35	+				
Parallel gripper HGPL-63	0 ¹⁾				
Parallel gripper HGPT-40-B	+				
Parallel gripper HGPT-50-B	+				
Parallel gripper HGPT-63-B	+	16	15		
Parallel gripper HGPT-80-B	+	16	12		
Angle gripper DHWS-16	+	Stroke < pos	ition		
Angle gripper DHWS-25	+	measuring ra	ange		
Angle gripper DHWS-32	+	SMAT-8M			
Angle gripper DHWS-40	+	+			
Radial gripper DHRS-16	+	1			
Radial gripper DHRS-25	+	1			
Radial gripper DHRS-32	+	1			
Radial gripper DHRS-40	+	1			
Radial gripper HGRT-40-A-G2	+	-			
Radial gripper HGRT-50-A-G2	0 ¹⁾	1			

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Horrestricted use
On request
Different from technical data. Usability on request.
Position measuring range without initialisation (as supplied from the factory)

Position transmitters SMAT-8M, for T-slot Peripherals overview



Acce	ssories	→ Page/Internet
1	Connecting cable NEBU-M8G4	10
2	Connecting cable NEBU-M8W4	10
3	Inscription label ASLR	10
4	Mounting kit SMBR-8-8/100-S6, heat-resistant	10
5	Mounting kit SMBR	10
6	Mounting SMBZ-8	10
7	Connecting cable NEBU-M8G4	10
8	Three-point gripper DHDS	dhds
	Three-point gripper HGDD	hgdd
	Parallel gripper DHPS	dhps
	Parallel gripper HGPD	hgpd
	Parallel gripper HGPT	hgpt
	Angle gripper DHWS	dhws
	Radial gripper DHRS	dhrs
	Radial gripper HGRT	hgrt

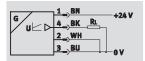
Acce	ssories	➔ Page/Internet
9	Standard cylinder DNCB	dncb
	Standard cylinder DNC	dnc
	Compact cylinder ADN	adn
	Short-stroke cylinder ADVC/AEVC	advc
	Compact cylinder ADVU/AEVU	advu
	Flat cylinder DZF	dzf
	Linear drive DGC	dgc
	Linear/swivel clamp CLR	clr
	Guided drive DFM	dfm
10	Standard cylinder/round cylinder DSNU	dsnu
	Linear unit SLE	sle
11	Standard cylinder DSBG	dsbg
12	Signal converter SVE4	sve4

Position transmitters SMAT-8M, for T-slot Type codes

	SMAT	 8	М]- [U] - [E	-[0,3]-[M8D
Туре											
SMAT Position transmitter, magnetic											
Design											
8 For T-slot			J								
Sensor design											
M Insertable in slot, centre clamping				1							
Switching input/output											
U 0 10 V						-					
Cable characteristics											
E Suitable for energy chains/robot applications								1			
Cable length											
0,3 0.3 m										J	
Electrical connection											
M8D M8 plug, 4-pin, rotatable thread											

Technical data

Function Normal operation





General technical data

General technical data				
For T-slot				
c UL us - Listed (OL)				
C-tick				
To EU EMC Directive ¹⁾				
RoHS-compliant				
Cable, halogen-free				
Cable, oil resistant				

For information about the applicability of the component see the manufacturer's EC declaration of conformity at: www.festo.com
 Support
 Support
 User documentation.
 If the component is subject to restrictions on usage in residential, office or commercial environments or small businesses, further measures to reduce the emitted interference may be necessary.

±0.025 on grippers³⁾

Input signal/measuring element

Measuring principle	Magnetic
Position measuring range [mm]	$\leq 40^{2}$

2) Depending on drive/gripper used.

Signal processing		
Max. speed of travel	[m/s]	3
Output, general		
Displacement resolution	[mm]	≤ 0.05 ²⁾
Repetition accuracy	[mm]	±0.1 on cylinders ³⁾

Depending on drive/gripper used.
 Use of a non-rotating piston rod or a mechanical structure to protect against rotation is recommended.

Analogue output		
Typical linearity error	[mm]	±1 on cylinders ²⁾
		±0.2 on grippers ²⁾

2) Depending on drive/gripper used.

Electrical outputs				
Analogue output	[V]	010		
Protection against short circuit		Yes		
Protection against overloading		Yes		
Output signal		Analogue		

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Technical data

Electronics		
Operating voltage range	[V DC]	15 30
Typical scanning interval	[ms]	2.8
Protection against polarity reversal		For all electrical connections

Electromechanics			
Electrical connection		Cable with plug, M8x1, knurled ring, 4-pin	
Ambient temperature with flexible	[°C]	-5 +70	
cable installation			
Cable length	[m]	0.3	
Cable characteristics		Energy chain + robots	
Cable test conditions		Energy chain: 50,000 cycles, bending radius 30 mm	
		Torsional strength: >300,000 cycles, ±270°/0.1 m	
		Resistance to bending: to Festo standard; test conditions on request	
Information on materials for cable sheath		TPE-U(PU)	

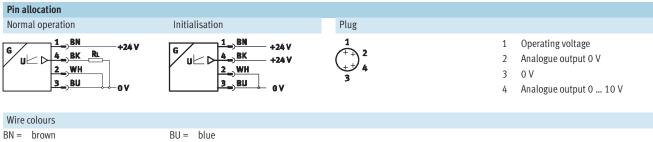
Mechanical components				
Type of mounting		Secured with screw, insertable in the slot from above		
Product weight	[g]	10		
Information on housing materials		Reinforced PA6		

Display/operation	
Status display	LED red, green

Immissions/emissions			
Ambient temperature	[°C]	-25 +75	
Protection class		IP65, IP68	
Corrosion resistance class	CRC ⁴⁾	2	

4)

Corrosion resistance class 2 as per Festo standard 940 070 Components subject to moderate corrosion stress. Externally visible parts with primarily decorative surface requirements which are in direct contact with a normal industrial environment or media such as coolants or lubricating agents.

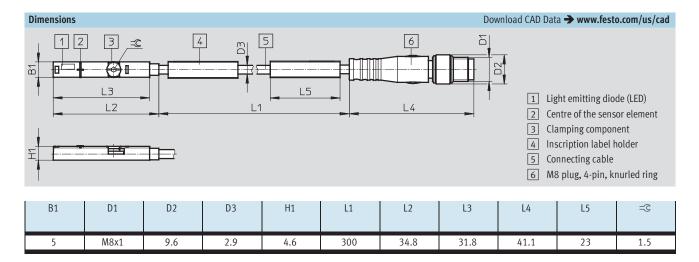


BK = black

WH = white

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Technical data



Ordering data					
Size	Analogue output [V]		Cable length [m]	Part No.	Туре
STIRE STREET		M8 plug, 4-pin, rotatable thread	0.3	553744	SMAT-8M-U-E-0,3-M8D

Position transmitters SMAT-8M, for T-slot Accessories

Ordering da	ata – Mounting attachments	
	For piston diameter	Part No. Type
Mounting k	it SMBR-8-8/100-S6, heat-resistant	
	8 100	538937 SMBR-8-8/100-S6
Mounting k	it SMBR	
	8	175091 SMBR-8-8
	10	175092 SMBR-8-10
\bigcirc	12	175093 SMBR-8-12
	16	175094 SMBR-8-16
	20	175095 SMBR-8-20
	25	175096 SMBR-8-25
	32	175097 SMBR-8-32
	40	175098 SMBR-8-40
	50	175099 SMBR-8-50
	63	175100 SMBR-8-63
Mounting S	MBZ	
Bach	32 100	537806 SMBZ-8-32/100
	125 320	537808 SMBZ-8-125/320

Ordering data – Connecting cable NEBU-M8					Technical data 🗲 Internet: nebu
	Electrical connection, left	Electrical connection, right	Cable length	Part No.	Туре
			[m]		
	Straight socket, M8x1, 4-pin	Cable, open end, 4-wire	2.5	541342	NEBU-M8G4-K-2.5-LE4
STR.			5	541343	NEBU-M8G4-K-5-LE4
STREE OF	Straight socket, M8x1, 4-pin	Straight socket, M8x1, 4-pin	2.5	554035	NEBU-M8G4-K-2.5-M8G4
	Angled socket, M8x1, 4-pin	Cable, open end, 4-wire	2.5	541344	NEBU-M8W4-K-2.5-LE4
ST.C.			5	541345	NEBU-M8W4-K-5-LE4

Ordering data – Inscription label ASLR						
	Size	Part No.	Туре	PU ¹⁾		
	23x4 mm	541598	ASLR-L-423	34		

1) Packaging unit in quantity per frame

Product Range and Company Overview

A Complete Suite of Automation Services

Our experienced engineers provide complete support at every stage of your development process, including: conceptualization, analysis, engineering, design, assembly, documentation, validation, and production.



Custom Automation Components Complete custom engineered solutions



Custom Control Cabinets Comprehensive engineering support and on-site services



Complete Systems Shipment, stocking and storage services

The Broadest Range of Automation Components

With a comprehensive line of more than 30,000 automation components, Festo is capable of solving the most complex automation requirements.



Electromechanical Electromechanical actuators, motors, controllers & drives



Pneumatics Pneumatic linear and rotary actuators, valves, and air supply



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