Standard cylinders DNCI, with measuring transducer DADE

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Measuring transducer DADE

Standard cylinders DNCI, with measuring transducer DADE

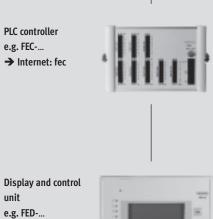
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Components for positioning and measuring using the standard cylinder DNCI



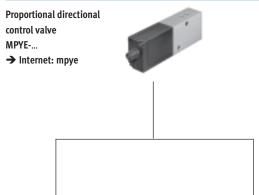








Positioning with end-position controller SPC11 or axis controller SPC200



→ Internet: soft stop Closed loop end-position controller

Soft Stop



Axis controller SPC200



→ Internet: fed

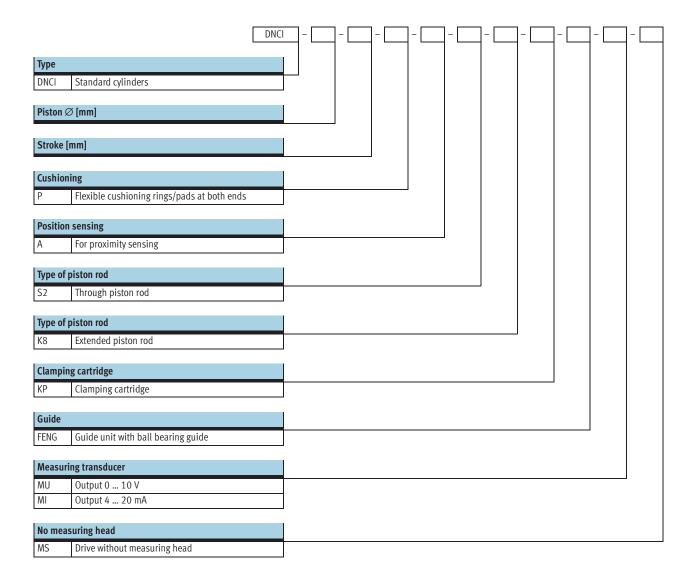
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Standard cylinders DNCI, with measuring transducer DADE



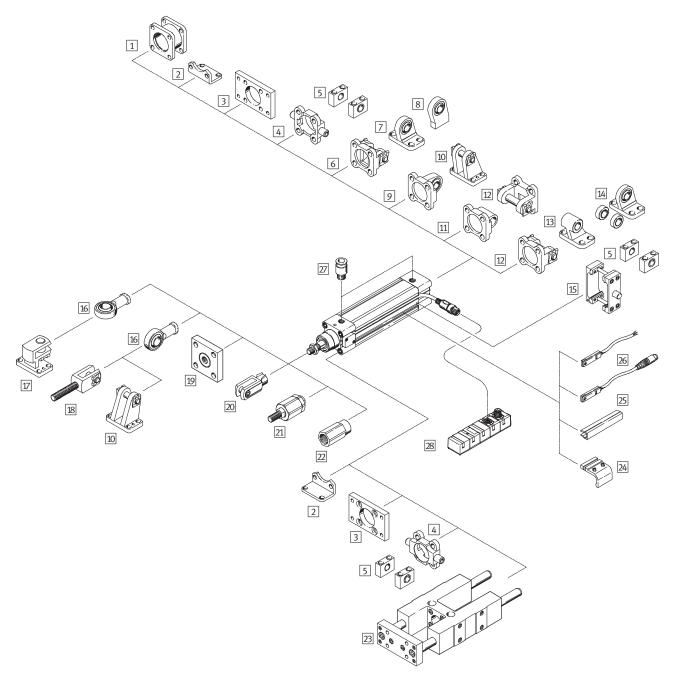
3

Type code



Standard cylinders DNCI, with measuring transducer DADE Peripherals overview





Acce	ccessories								
	Туре	Brief description	→ Page/Internet						
1	Adapter kit ¹⁾ DPNC	For connecting two cylinders with identical piston \varnothing to form a multi-position cylinder	dpnc						
2	Foot mounting HNC	For mounting the drive on the bearing and end cap	hnc						
3	Flange mounting FNC	For mounting the drive on the bearing and end cap	fnc						
4	Trunnion mounting ZNCF/CRZNG	For swivelling movements of the drive on the bearing or end caps	pivot pin						
5	Trunnion support LNZG/CRLNZG	-	lnzg						

Standard cylinders DNCI, with measuring transducer DADE Peripherals overview



Acce	ssories		
	Туре	Brief description	→ Page/Internet
6	Swivel flange ¹⁾	For swivelling movements of the drive on the end cap	snc
	SNC		
7	Clevis foot mounting ¹⁾	With spherical bearing	lsng
	LSNG		
8	Clevis foot mounting ¹⁾	Weld-on, with spherical bearing	lsnsg
	LSNSG		
9	Swivel flange ¹⁾	For swivelling movements of the drive on the end cap, with spherical bearing	sncs
	SNCS		
10	Clevis foot mounting ¹⁾	-	lbg
F1	LBG		
11	Swivel flange ¹⁾	For swivelling movements of the drive on the end cap	sncl
42	SNCL Swivel flange ¹⁾	For any colling managements of the drive on the and as a	anah
12	SNCB	For swivelling movements of the drive on the end cap	sncb
13	Clevis foot mounting ¹⁾		lng
וטו	LNG/CRLNG		1115
14	Clevis foot mounting ¹⁾	With spherical bearing	lsn
	LSN	man spirotour southing	
15	Trunnion mounting kit	For swivelling movements of the drive	zmcm
	ZNCM		
16	Rod eye	With spherical bearing	sgs
	SGS/CRSGS		
17	Right-angle clevis foot	-	lqg
	LQG		
18	Rod clevis	With male thread	sga
	SGA		
19	Coupling piece	For compensating radial deviations	ksg
	KSG		
	Coupling piece	For cylinders with a non-rotating piston rod to compensate for radial deviations	ksz
	KSZ		
20	Rod clevis	Permits a swivelling movement of the cylinder in one plane	sg
24	SG/CRSG	For comparating radial and angular desirations	el.
21	Self-aligning rod coupler FK	For compensating radial and angular deviations	fk
22	Adapter	For a vacuum suction cup	ad
22	AD	Tot a vacuum saction cup	uu
23	Guide unit	For protecting standard cylinders from torsion at high torque loads	feng
	FENG	, p	
24	Mounting kit	For mounting proximity sensors SME/SMT-8 in combination with guide unit FENG	smb-8
	SMB-8-FENG		
25	Slot cover	To protect the sensor cable and keep dirt out of the sensor slots	abp
	ABP-5-S		
26	Proximity sensor	Can be integrated in the cylinder profile barrel	proximity sensor
	SME/SMT-8		
27	Push-in fitting	For connecting compressed air tubing with standard external diameters	quick star
	QS		
28	Measuring transducer	Converts sensor signals of the standard cylinder DNCI into one voltage signal of 0 10 V	16
	MU, MI	and/or current signal of 4 20 mA	

Not with variants S2
 Guide unit FENG-KF must be attached to the piston rod such that backlash is eliminated

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Function







32 ... 63 mm



Stroke length 10 ... 2,000 mm



General technical data							
Piston ∅		32	40	50	63		
Constructional design		Piston					
		Piston rod					
		Profile barrel					
Mode of operation		Double-acting					
Cushioning		Flexible cushioning rings	s/pads at both ends				
Position sensing		Integrated displacement encoder					
		For proximity sensing ¹⁾					
Measuring principle (displacement encoder)		Digital					
Type of mounting		Foot mounting	Foot mounting				
Stroke	[mm]	10 2,000					
Torsion protection/Guide ³⁾		Guide rod with yoke, wit	n ball bearing guide				
Stroke	[mm]	100 500					
Piston rod extension	[mm]	1 500					
Pneumatic connection		G1/8	G1/4	G1/4	G3/8		
Electrical connection		Cable with 8-pin plug, round type M12					
Cable length	[m]	1.5					

- Not included in the scope of delivery, can be ordered as an option
 Guide unit FENG-KF must be ordered as an option and will be supplied attached, the max. stroke is reduced

Forces [N] and impact energy [Nm]											
Piston ∅		32	40	50	63						
Theoretical force at 6 bar		483	754	1,178	1,870						
advancing	S2	415	633	990	1,682						
Theoretical force at 6 bar		415	633	990	1,682						
retracting S2		415	633	990	1,682						
Impact energy at end positions		0.1	0.2	0.2	0.5						

Permissible impact velocity:

$$v_{\text{perm.}} = \sqrt{\frac{2 \times E_{\text{perm.}}}{m_{\text{dead}} + m_{\text{load}}}}$$

Permissible impact velocity v_{perm}. Max. impact energy E_{perm}. $\mathsf{m}_{\mathsf{dead}}$ Moving load (drive)

Note

These specifications represent the

maximum values which can be re-Moving work load ached. Note the maximum permitted $m_{load} \ = \frac{2 \ x \ E_{perm.}}{v^2} \ - \ m_{dead}$ Maximum permissible load: impact energy.



Operating and environmental conditions								
Operating pressure	[bar]	0.6 12						
Operating medium ²⁾		Compressed air, filtered and unlubricated, filter unit 5 µm						
Ambient temperature ³⁾	[°C]	-20 +80						
Vibration resistance		To DIN/IEC 68 Parts 2 – 6, severity level 2						
Continuous shock resistance		To DIN/IEC 68 Parts 2 – 82, severity level 2						
CE symbol (declaration of conformance)		In accordance with EU EMC Directive						
Protection class (displacement encoder)		IP65 to IEC 60 529						
Corrosion resistance class CRC ⁴⁾		1						

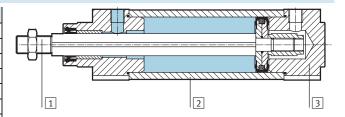
- The proportional directional control valve MPYE used requires the characteristic values
 Note operating range of proximity sensors
 Corrosion resistance class 1 according to Festo standard 940 070 Components requiring low corrosion resistance. Transport and storage protection. Parts that do not have primarily decorative surface requirements, e.g. in internal areas that are not visible or behind covers.

Piston Ø		32	40	50	63
		52	70	30	0,5
Basic drive DNCI					
	Product weight with 0 mm stroke	521	853	1,319	1,914
	Additional weight per 10 mm stroke	30	44	62	71
	Moving load with 0 mm stroke	95	175	316	383
	Additional weight per 10 mm stroke	8	14	23	23
<u> </u>					
Drive with through	piston rod DNCIS2				
	Product weight with 0 mm stroke	586	981	1,553	2,165
	Additional weight per 10 mm stroke	39	60	87	96
	Maring land with 0 mm strake	1.55	1//	207	264
,	Moving load with 0 mm stroke	155	164	297	364
	Additional weight per 10 mm stroke	17	30	48	48
Additional weight	with extended piston rod K8				
	Additional weight per 10 mm stroke	8	14	23	23
Additional weight	with clamping cartridge KP	-			
	Product weight	234	394	700	1,147
Additional waith	with avide weit FFNC				
Additional weight	with guide unit FENG	T	Ta a a a	1	T
	Product weight with 0 mm stroke	1,530	2,370	4,030	5,410
	Additional weight per 10 mm stroke	18	32	50	62

Materials

Sectional view

Stan	Standard cylinders									
1	Piston rod	High-alloy steel								
2	Cylinder barrel	Anodised aluminium								
3	Bearing/end caps	Die-cast aluminium								
-	Dynamic seals	Polyurethane TPE-U								
-	Static seals	Nitrile rubber								
-	Lubricant	Klüberplex BE31-102								
Disp	lacement encoder									
-	Sensor housing	Polyacetate								
-	Cable sheath	Polyurethane								
-	Plug housing	Polybuteneterephthalate								
-	Wall mounting plate	Polyacetate								
-	Screws for mounting plate	Steel								





Electrical data, displacement encoder		
Linearity error ¹⁾	[mm]	±(0.07±0.02xL)
Max. speed of travel	[m/s]	1.5
Ambient temperature	[°C]	-20 +80
Max. temperature coefficient	[ppm/°K]	30
Protection class		IP65
CE symbol (declaration of conformance)		In accordance with EU EMC Directive
Max. permitted magnetic disruption field at	[kA/m]	10
100 mm interval from the sensor ²⁾		
Electrical connection		Cable with 8-pin plug, round type M12
Cable length	[m]	1.5

¹⁾ Maximum deviation of the output signal from "best fit" line (characteristic curve with nominal gradient). L = Length of measuring system in meters
2) See also mounting conditions

Standard cylinders DNCI, with measuring transducer DADE

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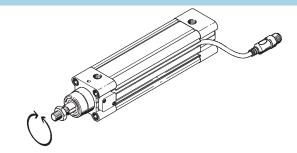
Technical data

Torques and lateral forces

The piston rod must not absorb any torque. We therefore recommend that an external guide FENG-KF be used with the drive DNCI. The guide unit is delivered installed.

The permissible static and dynamic characteristic load values with and without attached guide as well as with regard to the technical data of the variants (S2, S8, S9)

→ Internet: dnc



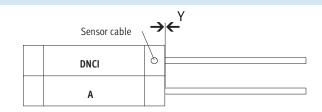
Mounting conditions

When mounting a drive A with magnet (for position sensing), in addition to a standard cylinder DNCI, the following conditions must be observed:

- X Minimum distance between the drives
- Y Offset between the drives on the bearing cap

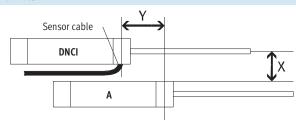
Parallel assembly

If the offset Y = 0 mm, the drives can be assembled directly next to one another.



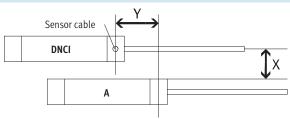
Offset assembly, cable outlet between the drives

If the offset Y > 0 mm and the cable outlet is between the drives, the distance from X > 70 mm must be observed.



Offset assembly, cable outlet upwards or downwards

If the offset Y > 0 mm and the cable outlet is up or down, the distance from X > 60 mm must be observed.

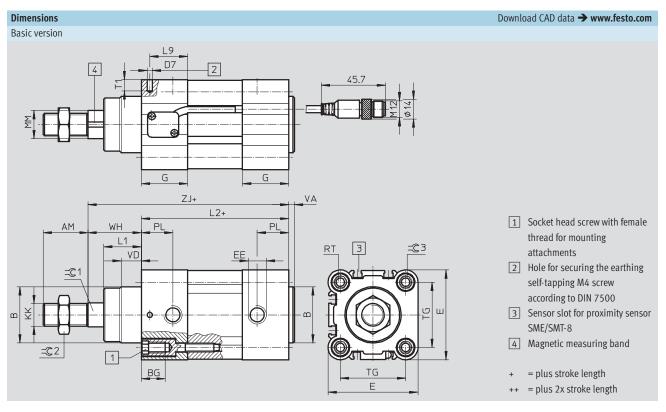


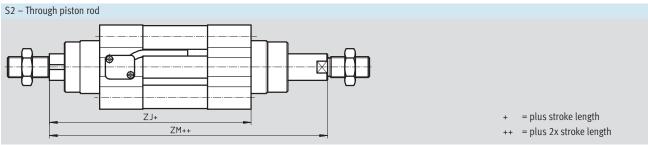
Pin assignment of plug, view of plug

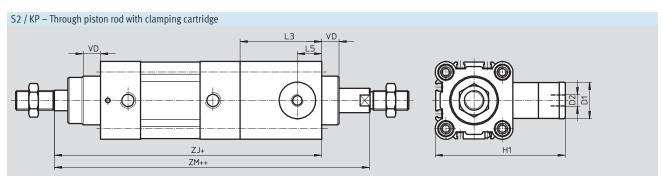
L	Pin	Function	Colour
ľ	1	5 V	black
ſ	2	GND	brown
	3	sin+	red
ſ	4	sin-	orange
	5	COS-	green
	6	COS+	yellow
	7	Screening	Screening
	8	-	-

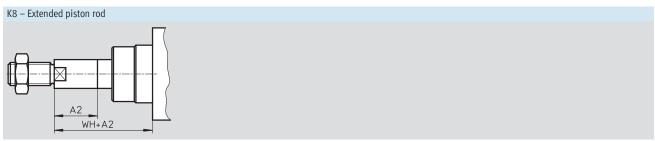








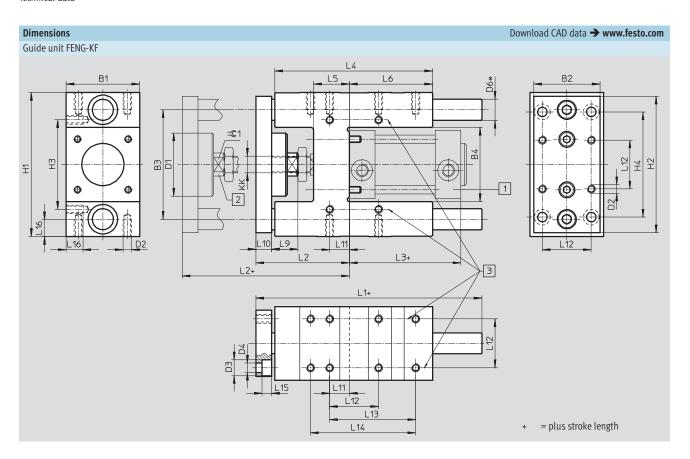






Ø [mm]	AM	A2 max.	B ∅ d11	BG	D1 Ø f9	D2	D7 ∅	E	EE	G	H1
32	22	500	30	16	20	M5	3.7	45	G1/8	28	67
40	24	500	35	16	24	G1/8	3.7	54	G1/4	33	88
50	32	500	40	17	30	G1/8	3.7	64	G1/4	33	107
63	32	500	45	17	38	G1/8	3.7	75	G3/8	40.5	123
Ø [mm]	KK	L1	L2	L3	L5	L9	MM Ø f8	PL	RT	T1	TG
32	M10x1.25	18	94	45	14	22.5	12	15.6	M6	8	32.5
40	M12x1.25	21.3	105	53	16	27	16	14	M6	8	38
50	M16x1.5	26.8	106	67	20	27	20	14	M8	8	46.5
63	M16x1.5	27	121	76	24	33	20	17	M8	8	56.5
Ø	PI	VD	WH	Z	J	ZI	W	=©1	= ©2	=0	3
[mm]					KP		KP				
32	4	10	26	120	165	148	193	10	16	6	,)
40	4	10.8	30	135	188	167	220	13	18	6	Ó
50	4	14.3	37	143	210	183	250	17	24	8	
63	4	14.5	37	158	234	199	275	17	24	8	3







For Ø	B1	B2	В3	B4	D1	D2	D3	D4	D6	H1
					Ø		Ø	Ø	Ø	
[mm]	-0.3		±0.2	±0.3					h6	
32	50	45	74	50.5	44	M6	11	6.6	12	97 _{-0.4}
40	58	54	87	58.5	44	M6	11	6.6	16	115-0.4
50	70	63	104	70.5	60	M8	15	9	20	137 _{-0.5}
63	85	80	119	85.5	60	M8	15	9	20	152 _{-0.5}

For Ø	H2	Н3	H4	KK	L1	L2	L3	L4	L5	L6
[mm]		±0.2	±0.2							
32	90	61	78	M10x1.25	155	67+5	94	125	24	76
40	110	69	84	M12x1.25	170	75 ₊₅	105	140	28	81
50	130	85	100	M16x1	188	89+10	106	150	34	79
63	145	100	105	M16x1	220	89+10	121	182	34	111

For Ø	L9	L10	L11	L12	L13	L14	L15	L16	=©1
[mm]				±0.2	±0.2	±0.2			
32	20	12	4.3	32.5	70.3	78	6.5	12	15
40	22	12	11	38	84	-	6.5	14	15
50	25	15	18.8	46.5	81.8	100	9	16	19
63	25	15	15.3	56.5	105	-	9	16	19

Standard cylinders DNCI, with measuring transducer DADE Ordering data – Modular products



	ry data								
Module No.	Function	Pist	on Ø	Stroke	Cushioning		Position sensing		
	J								
535 411	DNCI	32		10 2,000	Р	A	P		
535 412		40							
535 413		50							
535 414		63							
Order									
example									
535 411	DNCI	- 32		- 100	– P	- 1	4	-	
Ordering table		1	1	1	1		la i	l l	
Piston Ø		32	40	50	63	Condi-	Code	Enter	
						tions		code	
Module No.		535 411	535 412	535 413	535 414				
Function		Standard cylind	er with integrated dis	placement encoder, non	rotating piston rod		DNCI	DNCI	
Piston Ø	[mm]	32	40	50	63				
Stroke	[mm]	10 2,000			1				
Cushioning		Flexible cushion	ning rings/pads at bot		-P	-P			
Position ser	Position sensing For proximity sensing -A -A							-A	

Transfer order	code							
	DNCI	7 –	_	_	P	-	Α] -

Standard cylinders DNCI, with measuring transducer DADE Ordering data – Modular products



O Options					
Type of piston rod	Piston rod extended at front	Clamping unit	Guide	Measuring transducer	Measuring head
S2	K8	КР	FENG	MU MI	MS
	-	-	_	-	-

Ordering table									
Piston \varnothing		32	40	50	63	Condi-	Code	E	Enter
						tions		C	code
O Type of pist	n rod	Through piston	rod				-S2		
Piston rod	ktended [mr	1] 1 500	. 500						
Clamping (it	Clamping cartri	dge			3	-KP		
Guide		Guide unit with	ball bearing guide	on the sensor head side		4	-FENG		
Measuring	ansducer	Output 0 10	V				-MU		
		Output 4 20	mA				-MI		
Measuring	ead	No measuring h	iead			5	-MS		

2 **K8** In combination with piston rod type S2, the piston rod is only extended at the front 3 **K9** Only with piston rod type S2 4 FENG (the side facing the measuring head) Maximum stroke length 500 mm

Note 5 If repair becomes necessary, the standard cylinder can be ordered without measuring head (→ code: MS). The existing measuring head can then be installed to the new standard cylinder (→ operating instructions for DNCI).

	Transfer order code							
-[-	-	-	-	-	-	

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Measuring transducer DADE-MVC-010 DADE-MVC-420 (Order code MU, MI)

The transducer converts sensor signals of the DNCI standard cylinder into a voltage signal of 0 ... 10 V or a current signal of 4 ... 20 mA. These signals can be evaluated by a PLC with an appropriate signal input.



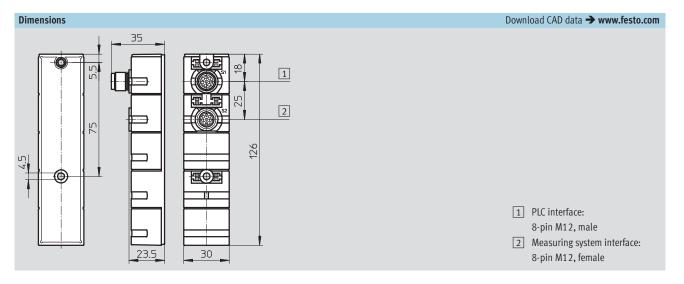
General technical data		
Type of mounting		Via through holes
Mounting position		Any
Repetition accuracy in relation to	≤ 400	±0.1 mm
effective stroke	≤ 750	±0.2 mm
	≤ 1,200	±0.3 mm
	≤ 1,600	±0.4 mm
	≤ 2 , 000	±0.5 mm
Protection against short circuit		Yes
Protection against polarity reversal		Yes
Diagnostic function		Display via LED

General electrical data		
Analogue output	[V]	0 10 (as per EN 61131-2)
	[mA]	0 20 (as per EN 61131-2)
Nominal operating voltage	[V DC]	24 ±25%
Residual ripple	[%]	4 (at 50 Hz)
Current consumption at nominal	[mA]	20 30
operating voltage		
Switching logic at outputs		PNP
Switching logic at inputs		PNP
Debounce time at inputs	[ms]	3
Linearity error FS		0,2%

Operating and environmental condition	S	
Ambient temperature	[°C]	0 55
Protection class		IP65
Relative air humidity		95% non-condensing
CE symbol (see conformity declaration)		As per EU EMC directive
Corrosion resistance class CRC ¹⁾		1
Product weight	[g]	128
Note on material for housing		Polybutylene terephthalate

¹⁾ Corrosion resistance class 1 as per Festo standard 940 070 Components requiring low corrosion resistance Transport and storage protection. Parts that do not have primarily decorative surface requirements, e.g. in internal areas that are not visible or behind covers





Pin allocation

PLC interface



5 + + 2 8
6

Pin	Function	Cable colour
1	24 V	white
2	Measured signal (analogue)	brown
3	Reference output	green
4	0 V measured signal	yellow
5	Reference input	grey
6	Calibration input	pink
7	Ready output	blue
8	0 V power supply and inputs/	red
	outputs	

7
6 1
5 / 0 0 - 8
$\chi^{\circ} \varphi^{\circ} \chi$

Measuring system interface

Pin	Function
1	Ub
2	0 V
3	Signal sine +
4	Signal sine -
5	Signal cosine -
6	Signal cosine +
7	Screening / earth
8	-

Ordering data						
		Description	Part No.	Туре		
Measuring transducer						
	With voltage signal	0 10 V	542 117	DADE-MVC-010		
	With current signal	4 20 mA	542 118	DADE-MVC-420		
·						
Accessories Technical data → Internet: sim						
	Cable with socket	Connecting cable to PLC (length 2 m)	525 616	SIM-M12-8GD-2-PU		
		Connecting cable to PLC (length 5 m)	525 618	SIM-M12-8GD-5-PU		