## **Cushioning components**



- Adjustable or self-adjusting
- With linear or progressive characteristic
- Stop elements: combination of cushioning and end-position sensing
- Specified types in accordance with ATEX directive for potentially explosive atmospheres
   → www.festo.com/en/ex

## Cushioning components Product range overview

Function	Туре	Version	Brief description	Area of application
Shock	Elastome	er absorber		
Function Shock absorber	DYEF-Y1		Mechanical shock absorber with flexible rubber buffer	Mini slide DGSL
			• Cushioning stroke cannot be adjusted	
	on         Type         Version         Brief description           Per         Eastomer absorber              • Mechanical shock absorber with flexible rubber buffer • Cushioning stroke cannot be adjusted • No fixed stop • Continuous mounting thread with internal hes DYEF-Y1F • Mechanical shock absorber with flexible rubber buffer • Cushioning stroke can be adjusted • With fixed stop • Continuous mounting thread with internal hes • Continuous mounting thread with internal hes • Adjustable DYSR • Self-adjusting • Self-adjustind			
		Version         Brief description           omer absorber         • Mechanical shock absorber with flexible rubber buffer           • Cushioning stroke cannot be adjusted         • No fixed stop           • Ontinuous mounting thread with internal hex         • Mechanical shock absorber with flexible rubber buffer           • Cushioning stroke can be adjusted         • Mechanical shock absorber with flexible rubber buffer           • Cushioning stroke can be adjusted         • With fixed stop           • Continuous mounting thread with internal hex         • Continuous mounting thread with internal hex           stable         • Hydraulic shock absorber with path-controlled flow control function           • Rapidly increasing cushioning force curve         • Short cushioning stroke           • Suitable for rotary drives         • Maintenance-free           • Medraulic shock absorber with path-controlled flow control function         • Rapidly increasing cushioning force curve           • Suitable for rotary drives         • Maintenance-free         • Medraulic shock absorber with path-controlled flow control function           • Rapidly increasing cushioning force curve         • Solitable for rotary drives         • Maintenance-free           • Metal end position at the housing         • Ontinuous mounting thread with internal hex         • Hydraulic shock absorber with path-controlled flow control function           • Slowly increasing cushioning force curve         • Lon		
	DYEF-Y1F		Mechanical shock absorber with flexible rubber buffer	Mini slide DGSL
			• Cushioning stroke can be adjusted	<ul> <li>Swivel module DSM-B</li> </ul>
		S	With fixed stop	<ul> <li>Semi-rotary drive DROD-B</li> </ul>
			Continuous mounting thread with internal hex	
	Adjustab	le		
	DYSR		<ul> <li>Hydraulic shock absorber with spring return</li> </ul>	-
			Adjustable cushioning hardness	
	DYSR Self-adju	0 at		
	Self-adiu	isting		
	VSR.C		Hydraulic shock absorber with path-controlled flow control function	Linear drive DGPL
	ISINC		Ranidly increasing cushioning force curve	Linear drive DGC
		US DE	Short cushioning stroke	Linear unit SLE
			Short cushoning shoke     Suitable for retary drives	
			Suitable for foldry drives     Maintenance free	
			Continuous mounting thread	
	DVSC		Hydraulic shock absorber with path-controlled flow control function	Swivel module DSM-B
	DISC	- Studie	Papidly increasing cushioning force curve	Swivel Induite DSM-D
		()	Kapiti y increasing cusiforning force curve	• Swiver/timear unit DSE-D
			Suitable for rotary drives	
			Maintenance free	
			Maintenancence	
			Continuous mounting thread with internal hey	
	VCDW/	-	Continuous mounting timead with meenal nex	Linear drive DGC
	1 JIW	- AND	Slowly increasing cushioning force curve	Linear module HMP
		Contraction of the second seco	Long cushioning stroke	HMDI
			Suitable for low-vibration operation	Handling module HSP
			Short cycle times possible	HSW
			Maintenance-free	11300
			Continuous mounting thread with spanner flat	
	DYSW		Hydraulic shock absorber with nath-controlled flow control function	Mini slide DGSI
	DISW		Slowly increasing cushioning force curve	Handling module HSW
		O.S. AN	Long cushioning strake	inalianity include 15W
			Suitable for low-vibration operation	
			Short cycle times possible	
			Maintenance-free	
			Metal end position at the housing	
			Continuous mounting thread with internal hex	

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## Cushioning components Product range overview

#### Size Stroke Energy absorption Free of copper, PTFE and **Position sensing** → Page/Internet per stroke silicone [J] [mm] Elastomer absorber 0.015 ... 0.55 M4, M5, M6, M8, M10, 0.9, 1.0, 1.2, 1.3, 1.5 7 M12, M14, M16 M4, M5, M6, M8, M10, 1.7, 2.8, 3.1, 3.4, 3.7, 0.005 ... 1.2 10 M12, M14, M16, M22 4.2, 5, 4.8, 7 Adjustable 8, 12, 16, 20, 25, 32 8, 12, 20, 25, 40, 60 4 ... 384 14 \_ \_ Self-adjusting 4, 5, 7, 8, 10, 12, 16, 20, 4, 5, 8, 10, 12, 20, 25, 0.6 ... 380 18 25,32 40,60 Size 4 ... 20 5, 7, 8, 12, 16 22 5, 8, 12, 18 1 ... 25 5, 7, 8, 10, 12, 16, 20 8, 10, 14, 17, 20, 26, 34 1.3 ... 70 26 0.8 ... 12 4, 5, 7, 8, 10, 12 6, 8, 10, 14, 17, 20 30

## Cushioning components Product range overview

Function	Туре	Version	Brief description	Area of application
Stop	Self-adjusti	ng		
element	YSRWJ	CANADA DE	<ul> <li>Cushioning with self-adjusting, progressive hydraulic shock absorber (YSRW)</li> <li>Slowly increasing cushioning force curve</li> <li>Adjustable cushioning stroke</li> <li>End-position sensing with proximity sensors SME/SMT-8</li> <li>Precision end-position adjustment</li> <li>Stop elements YSRWJ can be used for a wide variety of applications in handling and</li> </ul>	• Linear module HMPL
			assembly technology	
Hydraulic	Adjustable			
cushioning cylinder	DYHR	8-200	<ul> <li>Hydraulic cushioning cylinder for constant, slow braking speeds across the entire stroke</li> <li>Braking speed can be precisely adjusted</li> <li>A built-in compression spring returns the piston rod to the initial position</li> <li>Suitable for slow feed speeds in the range up to 0.1 m/s</li> </ul>	-

## Cushioning components Product range overview

Size	Stroke	Energy absorption per stroke	Position sensing	Free of copper, PTFE and silicone	→ Page/Internet						
	[mm]	U1									
Self-adjusting	Self-adjusting										
5, 7, 8	8, 10, 14	1 3			34						
			•	-							
Adjustable											
16, 20, 25, 32	20, 25, 40, 50, 60, 80,	32 768			38						
	120										
			-	-							

## Shock absorbers DYEF- ... -Y1, without fixed stop



## Shock absorbers DYEF- ... -Y1, without fixed stop Technical data

- **O** - Size M4 ... M16 -Stroke length 0.9 ... 1.5 mm



General technical data											
Size			M4	M5	M6	M8	M10	M12	M14	M16	
Stroke		[mm]	0.9	1.5	1.5	1.3	1	1.2	1.2	1.3	
Mode of operation			Elastomer cushioning without metal fixed stop								
Cushioning			Not adjustat	ole							
Cushioning length [mm]		0.9	1.5	1.5	1.3	1	1.2	1.2	1.3		
Type of mounting			Via lock nut								
Max. impact velocity		[m/s]	0.8								
Mounting position			Any								
Product weight		[g]	2.1	3.6	6	14	23	45.5	82.5	106	
	S	[g]	1.1	2	3	8.6	12	15	31	40	
Ambient temperature		[°C]	0 +60							-	
Corrosion resistance class Cl	RC <sup>1)</sup>		2	2							

Corrosion resistance class 2 according to Festo standard 940 070
 Components subject to moderate corrosion stress. Externally visible parts with primarily decorative surface requirements which are in direct contact with a normal industrial environment or media such as coolants or lubricating agents.

Energy [J]								
Size	M4	M5	M6	M8	M10	M12	M14	M16
Max. energy absorption per stroke	0.015	0.05	0.08	0.12	0.25	0.35	0.45	0.55

Mass range [kg]										
Size	M4	M5	M6	M8	M10	M12	M14	M16		
Mass range up to	0.15	0.35	0.7	1	2	3	5	7		

## Shock absorbers DYEF- ... -Y1, without fixed stop

#### **FESTO**

Technical data



 Shock absorber

 1
 Buffer
 Nitrile rubber

 2
 Housing
 High-alloy steel

 Seals
 Nitrile rubber

 Note on materials
 Free of copper, PTFE and silicone

 RoHS-compliant
 RoHS-compliant





DYEF-(S-)M4-Y1
 DYEF-(S-)M5-Y1



#### DYEF-(S)-M12/M14/M16-Y1



 DYEF-(S-)M12-Y1
 DYEF-(S-)M14-Y1
 DYEF-(S-)M16-Y1

# Shock absorbers DYEF- ... -Y1, without fixed stop Technical data



DYEF-S-M-... – Short version



Size	B1	D1	L	1	L2	=©1	=©2	Max. tightening torque =G1
			DYEF-M	DYEF-S-M				
					+0.3			[Nm]
M4	2.2	M4x0.5	22	12	0.9	7	1.3	0.5
M5	2.7	M5x0.5	26	14.5	1.8	8	1.5	0.8
M6	2.5	M6x0.5	30	15	1.8	8	2	1
M8	3	M8x1	38	23.5	2	10	2.5	2
M10	3.5	M10x1	41	21	1.8	13	3	3
M12	4	M12x1	54	20	2	15	4	5
M14	5	M14x1	72	28	2	17	4	8
M16	5	M16x1	75	31.5	2	19	5	20

Ordering data		
Size	Part No.	Туре
DYEF-M – Lo	ong version	
M4	1179810	DYEF-M4-Y1
M5	1179818	DYEF-M5-Y1
M6	1179831	DYEF-M6-Y1
M8	1179834	DYEF-M8-Y1
M10	1179837	DYEF-M10-Y1
M12	1179840	DYEF-M12-Y1
M14	1179863	DYEF-M14-Y1
M16	1179879	DYEF-M16-Y1
DYEF-S-M	Short version	
M4	1152500	DYEF-S-M4-Y1
M5	1152507	DYEF-S-M5-Y1
M6	1152524	DYEF-S-M6-Y1
M8	1152536	DYEF-S-M8-Y1
M10	1152959	DYEF-S-M10-Y1
M12	1153004	DYEF-S-M12-Y1
M14	1153017	DYEF-S-M14-Y1
M16	1153023	DYEF-S-M16-Y1

# Shock absorbers DYEF- ... -Y1F, with fixed stop

		DYEF	 M8	]-[	Y1	F
Туре						
DYEF	Shock absorber					
Size						
				1		
Design chara	cteristic					
Y1	Internal hex					
Stop						
F	With fixed stop					

## Shock absorbers DYEF- ... -Y1F, with fixed stop Technical data

- **O** - Size M4 ... M22 - 1 Stroke length 1.7 ... 7 mm



General technical data												
Size		M4	M5	M6	M8	M10	M12	M14	M16	M22		
Stroke	[mm]	1.7	2.8	3.1	3.4	3.7	4.2	5	4.8	7		
Mode of operation Elastomer cushioning with metal fixed stop												
Cushioning		Adjustable	Adjustable									
Cushioning length	[mm]	1.7	2.8	3.1	3.4	3.7	4.2	5	4.8	7		
Type of mounting		Via lock nut										
Max. impact velocity	[m/s]	0.8										
Mounting position		Any										
Product weight	[g]	1.6	2.9	5.1	11.9	19.7	39.6	77.3	104	200		
Ambient temperature	[°C]	0 +60										
Corrosion resistance class CRC <sup>1)</sup>		2										

1) Corrosion resistance class 2 according to Festo standard 940 070 Components subject to moderate corrosion stress. Externally visible parts with primarily decorative surface requirements which are in direct contact with a normal industrial environment or media such as coolants or lubricating agents.

Force [N]										
Size	M4	M5	M6	M8	M10	M12	M14	M16	M22	
Min. insertion force <sup>1)</sup>	15	30	40	60	70	100	150	180	500	

1) This is the minimum force that must be applied so that the shock absorber is pushed precisely into the retracted end position. This value is reduced correspondingly in the event of an extended external end position or a reduction in the cushioning stroke.

Energy [J]									
Size	M4	M5	M6	M8	M10	M12	M14	M16	M22
Max. energy absorption per stroke	0.005	0.02	0.03	0.04	0.06	0.12	0.2	0.25	1.2
Mass range [kg]									
Size	M4	M5	M6	M8	M10	M12	M14	M16	M22
Mass range up to	0.15	0.25	0.4	0.6	1.2	1.8	3	5	15

## Shock absorbers DYEF- ... -Y1F, with fixed stop

Technical data

# Materials Sectional view 1 2 3



Shock	Shock absorber					
1	Buffer	Nitrile rubber				
2	Adjustable sleeve	Stainless steel				
3	Setting piece	Stainless steel				
-	Seals	Nitrile rubber				
	Note on materials	Free of copper, PTFE and silicone				
		RoHS-compliant				



- ----- DYEF-M12 ---- DYEF-M14
- ----- DYEF-M16

———— DYEF-M22

# Shock absorbers DYEF- ... -Y1F, with fixed stop Technical data



Size	B1	D1	L1	L2	=©1	=©2	=©3	Max. tightening torque =©1
				+0.3				[Nm]
M4	2.2	M4x0.5	22	1.7	7	1.3	2.5	0.5
M5	2.7	M5x0.5	26	2.8	8	1.5	3	0.8
M6	2.5	M6x0.5	30	3.1	8	2	4	1
M8	3	M8x1	38	3.4	10	2.5	5	2
M10	3.5	M10x1	41	3.7	13	3	6	3
M12	4	M12x1	54	4.2	15	4	8	5
M14	5	M14x1	72	5	17	4	8	8
M16	5	M16x1	75	4.8	19	5	10	20
M22	5	M22x1.5	78	7	27	5	10	35

Ordering data		
Size	Part No.	Туре
M4	548370	DYEF-M4-Y1F <sup>1)</sup>
M5	548371	DYEF-M5-Y1F
M6	548372	DYEF-M6-Y1F
M8	548373	DYEF-M8-Y1F
M10	548374	DYEF-M10-Y1F
M12	548375	DYEF-M12-Y1F
M14	548376	DYEF-M14-Y1F
M16	548377	DYEF-M16-Y1F
M22	1113706	DYEF-M22-Y1F

1) The scope of delivery for this size includes an Allen key.

Peripherals overview and type codes

### FESTO



Access	ories		
	Туре	Brief description	→ Page/Internet
1	Shock absorber	Hydraulic shock absorber with adjustable cushioning characteristics	15
	DYSR		
2	Mounting flange	Mounting option for shock absorber	42
	YSRF		
3	Buffer	For protecting the piston rod	44
	YSRP		

#### Type codes



·O· New

## Shock absorbers DYSR

Technical data



 Size 8 ... 32
 Stroke length 8 ... 60 mm



General technical data							
Size		8	12	16	20	25	32
Stroke	[mm]	8	12	20	25	40	60
Mode of operation		Hydraulic shoc	k absorber with sprin	g return			
		Single acting, p	oushing				
Cushioning		Adjustable, force-dependent, hard characteristic curve					
Cushioning length	[mm]	8	12	20	25	40	60
Type of mounting		Via lock nut					
Impact velocity	[m/s]	0.1 3					
Mounting position		Any	Any				
Product weight	[g]	60	105/120 <sup>1)</sup>	200/250 <sup>1)</sup>	355/425 <sup>1)</sup>	715	1,355
Ambient temperature	[°C]	-10 +80	-10 +80				
Corrosion resistance class CRC <sup>2)</sup> 1							

1) Applies to shock absorbers with special thread T

2) Corrosion resistance class 1 according to Festo standard 940 070

Components subject to low corrosion stress. Transport and storage protection. Parts that do not have primarily decorative surface requirements, e.g. in internal areas that are not visible or behind covers

Reset time [s]						
Size	8	12	16	20	25	32
Reset time <sup>1)</sup>	≤ 0.2		≤ 0.3		≤ 0.4	≤ 0.6

1) The specified technical data refers to ambient temperature. At -10 °C, the reset time can be up to 1 s for sizes 12, 16 and up to 3 s for sizes 8, 20, 25, 32

Force [N]						
Size	8	12	16	20	25	32
Min. insertion force <sup>1)</sup>	18	38	66	110	155	175
Max. stop force <sup>2)</sup> in the end positions	400	900	1,600	2,500	4,000	6,400
Min. resetting force <sup>3)</sup>	1.8	4.5	5.4	9	12.5	18

1) This is the minimum force that must be applied so that the shock absorber is pushed precisely into the retracted end position. This value is reduced correspondingly with an extended external end position

2) If the maximum stop force is exceeded, a fixed stop (e.g. YSRA) must be fitted 0.5 mm before the end of stroke

3) This is the maximum force that can act on the piston rod, allowing for full extension of the shock absorber (e.g. protruding bolt)

Energy [J]						
Size	8	12	16	20	25	32
Max. energy absorption per stroke	4	10.8	32	62.5	160	384
Max. energy absorption per hour	24,000	60,000	100,000	135,000	220,000	330,000
Max. residual energy	0.01	0.05	0.16	0.32	0.8	2

Technical data

#### Materials Sectional view 2. W. 11.111 20 25 32 Size 12 16 8 High-alloy steel, hardened Piston rod 2 Housing Nickel-plated brass Galvanised steel Buffer Polyacetal Seals Nitrile rubber Note on materials RoHS-compliant

## Selection graph for shock absorbers with infinitely adjustable cushioning DYSR Impact velocity v as a function of mass m



Three force curves are shown for each shock absorber. Interim values must be calculated by averaging.

The arrows relate to the examples starting on page 48.



1	DYSR-8-8
2	DYSR-12-12
3	DYSR-16-20

4 DYSR-20-255 DYSR-25-406 DYSR-32-60

Shock absorber	Force A =	Force A =	Force A =
DYSR-8-8	0 N	100 N	200 N
DYSR-12-12	0 N	200 N	500 N
DYSR-16-20	0 N	500 N	800 N
DYSR-20-25	0 N	800 N	1,200 N
DYSR-25-40	0 N	1,200 N	2,000 N
DYSR-32-60	0 N	2,000 N	3,000 N



 DYSR-8-8-Y5
 DYSR-12-12-Y5
 DYSR-16-20-Y5
 DYSR-20-25-Y5
 DYSR-25-40-Y5
 DYSR-32-60-Y5

·O· New

## Shock absorbers DYSR

Technical data





#### 1 Cushioning adjustment Buffer (included in the scope

of delivery)

ng adjustment + = Cushioning becomes harder ed in the scope - = Cushioning becomes softer



Download CAD Data **→ www.festo.com/us/cad** 

1 Cushioning adjustment Buffer YSRP (not included in the scope of delivery) + = Cushioning becomes harder

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= Cushioning becomes softer



Туре	B1	D1	D2	D3	D4	D5	L1	L2
			Ø	Ø	Ø	Ø		
				±0.2	+0.15	+0.15/-0.1		±0.1
DYSR-8-8-Y5	4	M12x1	4	8	-	12	77±0.1	30
DYSR-12-12-Y5	E	M15x1	6			15	07.01	26
DYSR-12-12-Y5-T		M16x1	0			16	97±0.1	50
DYSR-16-20-Y5	4	M20x1.25	o	-	-	20	115.01	52
DYSR-16-20-Y5-T	0	M22x1.5	0		20	22	115±0.1	
DYSR-20-25-Y5	o	M24x1.25	10	-	-	24	129.01	60
DYSR-20-25-Y5-T	0	M26x1.5	10		24	26	1 J0±0.1	00
DYSR-25-40-Y5	10	M30x1.5	12	-	28.8	30	178±0.1	80
DYSR-32-60-Y5	12	M37x1.5	15	-	34.8	37	230±0.15	108

Туре	L3	L4	L5	L6	=©1	=©2	Max. tightening torque ≕©1	
		±0.2		±0.2			[Nm]	
DYSR-8-8-Y5	16.2+0.6/-0.45	8	8+0.5/-0.35	-	15	4	5	
DYSR-12-12-Y5	18 4.0 25/ 0.2	_	64.0451.04	-	10	5	30	
DYSR-12-12-Y5-T	10.4+0.55/-0.2	_	0.4+0.45/-0.4		19	J	20	
DYSR-16-20-Y5	28 5 0 44 0 2		9 E 0 454 0 4	-	24	F	25	
DYSR-16-20-Y5-T	20.3+0.4/-0.3	_	0.0+0.45/-0.4	28	27	J		
DYSR-20-25-Y5	35 6.041 0.2	_	10 6.045/ 04	-	30	5	60	
DYSR-20-25-Y5-T	JJ.0+0.4/-0.5	_	10.0+0.45/-0.4	28	32	J	00	
DYSR-25-40-Y5	52.8+0.4/-0.3	-	12.8+0.45/-0.4	28	36	6	80	
DYSR-32-60-Y5	76+0.5/-0.4	-	16+0.5/-0.4	28	46	6	100	

Ordering data		
Size	Part No.	Туре
8	1138641	DYSR-8-8-Y5
12	1138642	DYSR-12-12-Y5
	1138643	DYSR-12-12-Y5-T
16	1138644	DYSR-16-20-Y5
	1138645	DYSR-16-20-Y5-T
20	1138646	DYSR-20-25-Y5
	1138647	DYSR-20-25-Y5-T
25	1138648	DYSR-25-40-Y5
32	1138649	DYSR-32-60-Y5

→ Internet: www.festo.com/catalog/...

Peripherals overview and type codes

## FESTO



Access	ories		
	Туре	Brief description	→ Page/Internet
1	Shock absorber YSR-C	Hydraulic shock absorber with rapidly increasing cushioning force curve	19
2	Reducing sleeve DAYH	To improve the cushioning performance in the case of underload, the built-in shock absorber can be replaced by the next smallest shock absorber with the help of the reducing sleeve	45
3	Mounting flange YSRF	Mounting option for shock absorber	42
4	Mounting flange YSRF-S	Mounting option for shock absorber with attached stop sleeve and position sensing	43
5	Stop limiters YSRA	Stroke limiter for shock absorber	44
-	Inductive proximity sensor SIEN	For mounting flange YSRF-S	45

### Type codes



Technical data



**0** -Size 4 ... 32 mm

> Stroke length 4 ... 60 mm



General technical data											
Size		4	5	7	8	10	12	16	20	25	32
Stroke	[mm]	4	5	5	8	10	12	20	25	40	60
Mode of operation Hydraulic shock absorbers with return spring											
		Single acti	ngle acting, pushing								
Cushioning		Self-adjust	Self-adjustable								
Cushioning length	[mm]	4	5	5	8	10	12	20	25	40	60
Type of mounting		With lockn	ut								
Impact velocity	[m/s]	0.05 2		0.05 3							
Mounting position		Any									
Product weight	[g]	5	8	16	32	51	74	185	318	600	1220
Ambient temperature	[°C]	-10 +80	)								
Corrosion resistance class	CRC <sup>1)</sup>	2									

1) Corrosion resistance class 2 to Festo standard 940 070 Components subject to moderate corrosion stress. Externally visible parts with primarily decorative surface requirements which are in direct contact with a normal industrial environment or media such as coolants or lubricating agents

Reset time [s]										
Size	4	5	7	8	10	12	16	20	25	32
Reset time <sup>1)</sup>	≤ 0.2						≤ 0.3		≤ 0.4	≤ 0.5

1) The specified technical data refers to ambient temperature. At higher temperatures in the 80 °C range, the max. mass and the cushioning work must be reduced by 50% approx. At -10 °C, the reset time may be up to 1 second

Forces [N]										
Size	4	5	7	8	10	12	16	20	25	32
Min. insertion force <sup>1)</sup>	6.5	7.5	10	18	25	35	60	100	140	160
Max. stop force <sup>2)</sup> in end positions	100	200	300	500	700	1,000	2,000	3,000	4,000	6,000
Min. resetting force <sup>3)</sup>	0.7	0.9	1.2	2.5	3.5	5	6	10	14	20

1) This is the minimum force that must be applied so that the shock absorber is pushed exactly into the retracted end position. This value is reduced correspondingly in the event of an extended external end-position

If the max. stop force is exceeded, a fixed stop (e.g. YSRA) 0.5 mm must be fitted before the end of stroke
 This is the maximum force which may act upon the piston rod, allowing for full extension of the shock absorber (e.g. protruding stem)

Energies [J]										
Size	4	5	7	8	10	12	16	20	25	32
Max. energy absorption per stroke	0.6	1	2	3	6	10	30	60	160	380
Max. energy absorption per hour	5,600	8,000	12,000	18,000	26,000	36,000	64,000	92,000	150,000	220,000
Max. residual energy	0.006	0.01		0.02	0.03	0.05	0.16	0.32	0.8	2

Mass range [kg]										
Size	4	5	7	8	10	12	16	20	25	32
Permissible mass range up to	1.2	1.5	5	15	25	45	90	120	200	400

Technical data



1	Housing	Brass, nickel-plated		
2	Piston rod	High-alloy steel		
3	Buffer	Polyamide		Steel with
				polyurethane
-	Seals	Nitrile rubber, polyurethane		
-	Note on materials	Free of copper, PTFE and silicone		-
		Conforms to RoHS		

#### Selection graph for self-adjusting shock absorbers YSR-C Impact velocity dependent on mass m



Three force curves are shown for each shock absorber. Interim values must be calculated by averaging. The arrows relate to the examples starting on page  $\rightarrow$  49.



1	YSR-4-4-C	5	YSR-12-12-C
2	YSR-5-5-C	6	YSR-16-20-C
2	YSR-7-5-C	7	YSR-20-25-C
3	YSR-8-8-C	8	YSR-25-40-C
4	YSR-10-10-C	10	YSR-32-60-C

Shock absorber	Force A =	Force A =	Force A =
YSR-4-4-C	0 N	-	50 N
YSR-5-5-C	0 N	50 N	100 N
YSR-7-5-C	0 N	100 N	200 N
YSR-8-8-C	0 N	100 N	200 N
YSR-10-10-C	0 N	150 N	300 N
YSR-12-12-C	0 N	200 N	500 N
YSR-16-20-C	0 N	500 N	800 N
YSR-20-25-C	0 N	800 N	1,200 N
YSR-25-40-C	0 N	1,200 N	2,500 N
YSR-32-60-C	0 N	2,000 N	4,000 N

Technical data

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#### Note

To increase the service life: Avoid the ingress of dirt or fluids into the piston chamber via the piston rod by, for example, using a cover.

Size	B1	D1	D2	D3	D4	L1
			Ø	Ø	Ø	
[mm]						±0.1
4	2,5	M6x0,5	2	3,8 ±0,1	5,3 ±0,05	28,5
5	3	M8x1	2.5	5 ±0.1	6.7 ±0.05	29
7	3.5	M10x1	3	6 ±0.1	8.6 ±0.05	34
8	4	M12x1	4	8 ±0.2	10.4 ±0.1	46
10	5	M14x1	5	10 ±0.2	12.4 ±0.1	55
12	5	M16x1	6	12 ±0.2	14.5 ±0.1	64
16	6	M22x1.5	8	16 ±0.2	19,6 ±0.1	86
20	8	M26x1.5	10	20 ±0.2	23,8 ±0.1	104
25	10	M30x1.5	12	25 ±0.2	27,8 ±0.1	152
32	12	M37x1.5	15	32 ±0.2	34,8 ±0.1	205

Size [mm]	L2 ±0.3	L3	L4	L5	<i>=</i> ©1	<i>≕</i> ©2	Max. tightening torque ∹© 1 [Nm]
4	18,5	8,3 +0,6/-0,3	4 ±0,1	4,3 +0,35/-0,25	8	2	1
5	19	10.8 +0.6/-0.3	5.5 ±0.1	5.8 +0.55/-0.25	10		2
7	23	12.3 +0.7/-0.35	7 ±0.2	7.3 +0.55/-0.25	13		3
8	33	16.3 +0.7/-0.35	8 ±0.2	8.3 +0.55/-0.25	15		5
10	42	20.5 +0.7/-0.35	10 ±0.2	10.5 +0.55/-0.25	17		8
12	51	24.5 +0.7/-0.35	12 ±0.2	12.5 +0.55/-0.25	19	-	20
16	69	36.5 +0.7/-0.35	16 ±0.2	16.5 +0.55/-0.25	27		35
20	87	45.5 +0.7/-0.35	20 ±0.2	20.5 +0.55/-0.25	32		60
25	125	61.5 +1.25/-0.75	20.5 ±0.4	21.5 +0.95/-0.55	36		80
32	179	87 +1.25/-0.75	26 ±0.4	27 +0.95/-0.55	46		100

Ordering of	lata	
Size	Part No.	Туре
[mm]		
4	540060	YSR-4-4-C <sup>1)</sup>
5	158981	YSR-5-5-C <sup>1)</sup>
7	160272	YSR-7-5-C <sup>1)</sup>
8	34571	YSR-8-8-C <sup>1)</sup>
10	191199	YSR-10-10-C <sup>1)</sup>
12	34572	YSR-12-12-C <sup>1)</sup>
16	34573	YSR-16-20-C <sup>1)</sup>
20	34574	YSR-20-25-C <sup>1)</sup>
25	160273	YSR-25-40-C
32	160274	YSR-32-60-C

1) Free of copper, PTFE and silicone

Peripherals overview and type codes



Access	icessories							
	Туре	Brief description	→ Page/Internet					
1	Shock absorber DYSC	Hydraulic shock absorber with rapidly increasing cushioning force curve	23					
2	Reducing sleeve DAYH	To improve the cushioning performance in the case of underload, the built-in shock absorber can be replaced by the next smallest shock absorber with the help of the reducing sleeve	45					

### Type codes



Technical data



0-Size 5 ... 16 Stroke length

5 ... 18 mm



## General technical data

o chicrat te chinicat auta							
Size		5	7	8	12	16	
Stroke	[mm]	5	5	8	12	18	
Mode of operation		Hydraulic shock absorb	er with spring return				
		Single acting, pushing					
Cushioning		Self-adjusting, hard cha	Self-adjusting, hard characteristic curve				
Cushioning length	[mm]	5	5	8	12	18	
Type of mounting		With lock nut					
Impact velocity	[m/s]	0.05 2	0.05 3				
Mounting position		Any					
Product weight	[g]	9	17	36	81	210	
Ambient temperature	[°C] -10 +80						
Corrosion resistance class CR	C <sup>1)</sup>	2					

1) Corrosion resistance class 2 to Festo standard 940 070 Components subject to moderate corrosion stress. Externally visible parts with primarily decorative surface requirements which are in direct contact with a normal industrial environment or media such as coolants or lubricating agents

Reset time [s]								
Size	5	7	8	12	16			
Reset time <sup>1)</sup>	≤ 0.2				≤ 0.3			

1) The specified technical data refers to ambient temperature. At higher temperatures in the 80 °C range, the max. mass and the cushioning work must be reduced by 50% approx. At -10 °C, the reset time may be up to 1 second

Forces [N]									
Size	5	7	8	12	16				
Min. insertion force <sup>1)</sup>	7.5	10	18	35	60				
Max. stop force <sup>2)</sup> in end positions	200	300	500	1,000	2,000				
Min. resetting force <sup>3)</sup>	0.9	1.2	2.5	5	6				

1) This is the minimum force that must be applied so that the shock absorber is pushed exactly into the retracted end position. This value is reduced correspondingly in the event of an extended external end position

If the max. stop force is exceeded, a fixed stop (e.g. YSRA) 0.5 mm must be fitted before the end of stroke
 This is the maximum force which may act upon the piston rod, allowing for full extension of the shock absorber (e.g. protruding stem)

Energies [J]								
Size	5	7	8	12	16			
Max. energy absorption per stroke	1	2	3	10	25			
Max. energy absorption per hour	8,000	12,000	18,000	36,000	50,000			
Max. residual energy	0.01		0.02	0.05	0.16			

Mass range [kg]								
Size	5	7	8	12	16			
Mass range up to	1.5	5	15	45	70			

Technical data



Selection graph for self-adjusting shock absorbers DYSC



Three force curves are shown for each shock absorber. Interim values must be calculated by averaging.

1 DYSC-5-5-Y1F 2 DYSC-7-5-Y1F



3 DYSC-8-8-Y1F 4 DYSC-12-12-Y1F

5 DYSC-16-18-Y1F

Shock absorber	Force A =	Force A =	Force A =
DYSC-5-5-Y1F	0 N	50 N	100 N
DYSC-7-5-Y1F	0 N	100 N	200 N
DYSC-8-8-Y1F	0 N	100 N	200 N
DYSC-12-12-Y1F	0 N	200 N	500 N
DYSC-16-18-Y1F	0 N	500 N	800 N

L3

Technical data

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To increase the service life: Avoid the ingress of dirt or fluids into the piston chamber via the piston rod by, for example, using

Size	B1	D1	D2 Ø	D3 Ø	D4 Ø	L1	L2
[mm]						±0.1	+0.3/-0.2
5	3	M8x1	2.5	4.7 ±0.05	6.7 ±0.05	38.6	28.4
7	3.5	M10x1	3	6 ±0.1	8.6 ±0.05	45.15	34.15
8	4	M12x1	4	7 ±0.1	10.4 ±0.1	59.05	46.05
12	5	M16x1	6	11 ±0.1	14.5 ±0.1	82.5	69.5
16	6	M22x1.5	8	15 ±0.1	19,6 ±0.1	110	93

Size	L3 <sup>1)</sup>	L4	<i>=</i> ©1	=©2	Max. tightening torque ≓©1
[mm]					[Nm]
5	5.5	5 +0.32/-0.28	10	2.5	2
7	7	5 +0.37/-0.28	13	3	3
8	8	8 +0.42/-0.33	15	4	5
12	12	12 +0.50/-0.35	19	5	20
16	17	18 +0.50/-0.35	27	5	35

1) Buffer length

Ordering data		
Size	Part No.	Туре
[mm]		
5	548011	DYSC-5-5-Y1F
7	548012	DYSC-7-5-Y1F
8	548013	DYSC-8-8-Y1F
12	548014	DYSC-12-12-Y1F
16	553593	DYSC-16-18-Y1F

## Shock absorbers YSRW Peripherals overview and type codes

### FESTO



Access	ories		
	Туре	Brief description	→ Page/Internet
1	Shock absorber YSRW	Hydraulic shock absorber with progressive cushioning characteristic	27
2	Mounting flange YSRF	Mounting option for shock absorber	42
3	Mounting flange YSRF-S	Mounting option for shock absorber with attached stop sleeve and position sensing	43
4	Stop limiters YSRA	Stroke limiter for shock absorber	44
-	Inductive proximity sensor SIEN	For mounting flange YSRF-S	45

### Type codes

		YSRW	-	10	] – ]	20
Туре						
YSRW	Shock absorber		4			
Size						
Stroke [mm]						

Technical data





8 ... 34 mm



#### General technical data Size 5 7 8 10 12 16 20 Stroke [mm] 8 10 14 17 20 26 34 Mode of operation Hydraulic shock absorbers with return spring Single acting, pushing Self-adjustable Cushioning Cushioning length [mm] 8 10 14 17 20 26 34 Type of mounting With locknut [m/s] Impact velocity 0.1 ... 2 0.1 ... 3 Mounting position Any Product weight 190 330 [g] 8 18 34 54 78 Ambient temperature [°C] -10 ... +80 Corrosion resistance class CRC<sup>1)</sup>

1) Corrosion resistance class 2 to Festo standard 940 070

Components subject to moderate corrosion stress. Externally visible parts with primarily decorative surface requirements which are in direct contact with a normal industrial environment or media such as coolants or lubricating agents

Reset time [s]							
Size	5	7	8	10	12	16	20
Reset time <sup>1)</sup>	≤ 0.2				≤ 0.3		

1) The specified technical data refers to ambient temperature. At higher temperatures in the 80 °C range, the max. mass and the cushioning work must be reduced by 50% approx. At -10 °C, the reset time may be up to 1 second

Forces [N]							
Size	5	7	8	10	12	16	20
Min. insertion force <sup>1)</sup>	7.5	10	18	25	35	60	100
Max. stop force <sup>2)</sup> in end positions	200	300	500	700	1,000	2,000	3,000
Min. resetting force <sup>3)</sup>	0.9	1.2	2.5	3.5	5	6	10

1) This is the minimum force that must be applied so that the shock absorber is pushed exactly into the retracted end position. This value is reduced correspondingly in the event of an extended external end-position

2)

If the max. stop force is exceeded, a fixed stop (e.g. YSRA) 0.5 mm must be fitted before the end of stroke This is the maximum force which may act upon the piston rod, allowing for full extension of the shock absorber (e.g. protruding stem) 3)

Energies [J]							
Size	5	7	8	10	12	16	20
Max. energy absorption per stroke	1.3	2.5	4	8	12	35	70
Max. energy absorption per hour	10,000	15,000	21,000	30,000	41,000	68,000	100,000
Max. residual energy	0.01		0.02	0.03	0.05	0.16	0.32

Mass range [kg]							
Size	5	7	8	10	12	16	20
Permissible mass range up to	2	5	10	20	30	50	80

Technical data



Selection graph for self-adjusting shock absorbers with progressive characteristics YSRW Impact velocity dependent on mass m





Three force curves are shown for each shock absorber. Interim values must be calculated by averaging.

1 YSRW-5-8 2 YSRW-7-10 3 YSRW-8-14

4 YSRW-10-17

5	Y	SR	W-	1	2-	2	C

6 YSRW-16-26

7 YSRW-20-34

Shock absorber	Force A =	Force A =	Force A =
YSRW-5-8	0 N	50 N	100 N
YSRW-7-10	0 N	75 N	150 N
YSRW-8-14	0 N	100 N	200 N
YSRW-10-17	0 N	150 N	300 N
YSRW-12-20	0 N	200 N	400 N
YSRW-16-26	0 N	500 N	800 N
YSRW-20-34	0 N	800 N	1,200 N

Technical data



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#### Note

To increase the service life: Avoid the ingress of dirt or fluids into the piston chamber via the piston rod by, for example, using a cover.

Size	B1	D1	D2	D3	D4 Ø	L1	L2	L3
[mm]			~	~	~	±0.1	±0.3	
5	3	M8x1	2.5	5 ±0.1	6.7 ±0.05	33.5	22.5	13.8 +0.6/-0.25
7	3.5	M10x1	3	6 ±0.1	8.6 ±0.05	41	30	17.3 +0.7/-0.25
8	4	M12x1	4	8 ±0.2	10.4 ±0.1	53	40	22.3 +0.7/-0.25
10	5	M14x1	5	10 ±0.2	12.4 ±0.1	62	49	27.5 +0.7/-0.25
12	5	M16x1	6	12 ±0.2	14.5 ±0.1	72.5	59.5	32.5 +0.7/-0.25
16	6	M22x1.5	8	16 ±0.2	20 ±0.1	91	70	42.5 +0.7/-0.35
20	8	M26x1.5	10	20 ±0.2	24 ±0.1	112	91	54.5 +0.7/-0.35

Size	L4	L5	L6	L7	=©1	=©2	Max. tightening torque ∹©1
[mm]			+0.5				[Nm]
5	5.5 ±0.1	5.8 +0.35/-0.25	5	3.5 ±0.25	10	7	2
7	7 ±0.2	7.3 +0.35/-0.25	6	4.3 ±0.25	13	9	3
8	8 ±0.2	8.3 +0.4/-0.25	8	5.3 +0.3/-0.25	15	11	5
10	10 ±0.2	10.5 +0.4/-0.25	10	6.5 +0.3/-0.25	17	13	8
12	12 ±0.2	12.5 +0.4/-0.25	12	7.5 +0.3/-0.25	19	15	20
16	16 ±0.2	16.5 +0.4/-0.25	12	9.5 +0.3/-0.25	27	20	35
20	20 ±0.2	20.5 +0.4/-0.25	12	11.5 +0.3/-0.25	32	24	60

Ordering d	lata	
Size	Part No.	Туре
[mm]		
5	191192	YSRW-5-8
7	191193	YSRW-7-10
8	191194	YSRW-8-14
10	191195	YSRW-10-17
12	191196	YSRW-12-20
16	191197	YSRW-16-26
20	191198	YSRW-20-34

Peripherals overview and type codes

### FESTO



Access	Accessories							
	Туре	Brief description	→ Page/Internet					
1	Shock absorber DYSW	Hydraulic shock absorber with rapidly increasing cushioning force curve	31					
2	Reducing sleeve DAYH	To improve the cushioning performance in the case of underload, the built-in shock absorber can be replaced by the next smallest shock absorber with the help of the reducing sleeve	45					

### Type codes



Technical data







**FESTO** 

General technical data								
Size		4	5	7	8	10	12	
Stroke	[mm]	6	8	10	14	17	20	
Mode of operation		Hydraulic shock ab	sorber with spring re	turn				
		Single acting, push	ing					
Cushioning		Self-adjusting, soft	Self-adjusting, soft characteristic curve					
Cushioning length	[mm]	6	8	10	14	17	20	
Type of mounting		With lock nut			·	•		
Impact velocity	[m/s]	0.1 2		0.1 3				
Assembly position		Any						
Product weight	[g]	6	11	21	42	67	91	
Ambient temperature	[°C]	C] –10 +80						

Reset time [s]							
Size	4	5	7	8	10	12	
Reset time <sup>1)</sup>	≤ 0.2					≤ 0.3	

1) The specified technical data refers to ambient temperature. At higher temperatures in the 80 °C range, the max. mass and the cushioning work must be reduced by 50% approx. At -10 °C, the reset time may be up to 1 second

Forces [N]							
Size	4	5	7	8	10	12	
Min. insertion force <sup>1)</sup>	6.5	7.5	10	18	25	35	
Max. stop force <sup>2)</sup> in end positions	100	200	300	500	700	1,000	
(housing)							
Min. resetting force <sup>3)</sup>	0.7	0.9	1.2	2.5	3.5	5	

1) This is the minimum force that must be applied so that the shock absorber is pushed exactly into the retracted end position. This value is reduced correspondingly in the event of an extended external end position

If the max. stop force is exceeded, a fixed stop (e.g. YSRA) 0.5 mm must be fitted before the end of stroke
 This is the maximum force which may act upon the piston rod, allowing for full extension of the shock absorber (e.g. protruding stem)

Energies [J]							
Size	4	5	7	8	10	12	
Max. energy absorption per stroke	0.8	1.3	2.5	4	8	12	
Max. energy absorption per hour	7,000	10,000	15,000	21,000	30,000	41,000	
Max. residual energy	0.006	0.01	0.01	0.02	0.03	0.05	

Mass range [kg]							
Size	4	5	7	8	10	12	
Mass range up to	1.2	2	5	10	20	30	

Technical data



#### Selection graph for self-adjusting shock absorbers with progressive characteristics DYSW Impact velocity dependent on mass m

3 5 З.0 2.5 2,0 v [m/s] 1,5 1.0 0,5 0 0,4 0,6 2 ġ. 4 5 6 8 10 20 30 50 1**.**2 m [kg]



Three force curves are shown for each shock absorber. Interim values must be calculated by averaging.

 1
 DYSW-4-6-Y1F

 2
 DYSW-5-8-Y1F

 3
 DYSW-7-10-Y1F



4	DYSW-8-14-Y1F

5 DYSW-10-17-Y1F

6 DYSW-12-20-Y1F

Shock absorber	Force A =	Force A =	Force A =
DYSW-4-6-Y1F	0 N	-	50 N
DYSW-5-8-Y1F	0 N	50 N	100 N
DYSW-7-10-Y1F	0 N	75 N	150 N
DYSW-8-14-Y1F	0 N	100 N	200 N
DYSW-10-17-Y1F	0 N	150 N	300 N
DYSW-12-20-Y1F	0 N	200 N	400 N

Shock absorber in end position

Technical data



To increase the service life: Avoid the ingress of dirt or fluids into the piston chamber via the piston rod by, for example, using

Size	B1	D1	D2 Ø	D3 Ø	D4 Ø	L1
[mm]						+0.1
4	2.5	M6x0.5	2	3.5±0.05	5.35±0.05	35.5
5	3	M8x1	2.5	4.7±0.05	6.7±0.05	43.1
7	3.5	M10x1	3	6±0.1	8.6±0.05	52.05
8	4	M12x1	4	7±0.1	10.4±0.1	66.05
10	5	M14x1	5	9±0.1	12.4±0.1	77.55
12	5	M16x1	6	11±0.1	14.4±0.1	90.75

Size [mm]	L2 +0.3 -0.2	L3	L4	<i>≍</i> ©1	=©2	Max. tightening torque ∹©1 [Nm]
4	25.5	6+0.30/-0.24	4±0.05	8	2	1
5	33.1	8+0.32/-0.28	5.5±0.1	10	2.5	2
7	41.05	10+0.37/-0.28	7±0.2	13	3	3
8	53.05	14+0.37/-0.28	8±0.2	15	4	5
10	64.55	17+0.37/-0.28	10±0.2	17	4	8
12	77.75	20+0.45/-0.30	12±0.2	19	5	20

Ordering data							
Size	Part No.	Туре					
[mm]							
4	548070	DYSW-4-6-Y1F					
5	548071	DYSW-5-8-Y1F					
7	548072	DYSW-7-10-Y1F					
8	548073	DYSW-8-14-Y1F					
10	548074	DYSW-10-17-Y1F					
12	548075	DYSW-12-20-Y1F					

## Stop elements YSRWJ Peripherals overview and type codes

### Peripherals overview



Access	Accessories							
	Туре	Brief description	➔ Page/Internet					
1	Stop element	Hydraulic shock absorber with progressive cushioning characteristic.	35					
	YSRWJ	The cushioning length is adjustable						
2	Proximity switches	Sensing option for end positions	45					
	SME-/SMT-8							

### Type codes

		YSRWJ	]-	7	]-[	10	-	A	
Туре									
YSRWJ	Shock absorber								
Size									
Stroke [mm]									
Position sensi	ng						-		
A	Position sensing								

## Stop elements YSRWJ Technical data







General technical data									
Size		5	7	8					
Stroke	[mm]	8	10	14					
Mode of operation		A piston rod in front of the shock a	bsorber transmits the force to the	shock absorber. This serves as the end stop and					
		actuates the proximity sensor via a	magnet mounted on it						
		Single acting, pushing							
Cushioning		Self-adjustable							
Cushioning length [mm]		8	10	14					
Type of mounting		With locknut							
Position sensing		Via proximity sensor							
Impact velocity	[m/s]	0.05 2 0.05 3							
Repetition accuracy	[mm]	0.02							
Mounting position		Any							
Product weight	[g]	45 75 110							
Ambient temperature	[°C]	0+60							
Corrosion resistance class (	CRC <sup>1)</sup>	2							

1) Corrosion resistance class 2 to Festo standard 940 070

Components subject to moderate corrosion stress. Externally visible parts with primarily decorative surface requirements which are in direct contact with a normal industrial environment or media such as coolants or lubricating agents

Reset time [s]										
Size	5	7	8							
Reset time <sup>1)</sup>	≤ 0.2									

1) The specified technical data refers to ambient temperature. At higher temperatures in the 80 °C range, the max. mass and the cushioning work must be reduced by 50% approx. At -10 °C, the reset time may be up to 1 second

Forces [N]			
Size	5	7	8
Min. insertion force <sup>1)</sup>	5	18	80
Max. stop force <sup>2)</sup> in end positions	200	300	500
Min. resetting force <sup>3)</sup>	1.5	2	3.5

1) This is the minimum force that must be applied so that the shock absorber is pushed exactly into the retracted end position

1 -

2) Impact force may not exceed the maximum specified value3) This is maximum force that can be exerted on the piston rod so that the shock absorber advances fully

Energies [J]										
Size	5	7	8							
Max. energy absorption per stroke	1	2	3							
Max. energy absorption per hour 10,000		15,000	21,000							
Max. residual energy	0.01	0.02								

Mass range [kg]										
Size	5	7	8							
Permissible mass range up to	2	5	10							

## Stop elements YSRWJ Technical data



Stop element					
1	Stop bolt	Steel, stainless and reinforced			
2	Distance sleeve	Galvanised steel			
3	Threaded barrel	Brass, nickel-plated			
-	Note on materials	Free of copper, PTFE and silicone			
		Conforms to RoHS			

#### Selection graphs for limit stops with shock absorber YSRWJ

Impact velocity dependent on mass m



#### YSRWJ-8-14-A



Without additional force 1

- 2 With additional force A = 100 N
- 3 With additional force A = 150 N

## Stop elements YSRWJ Technical data



- 1 Soft cushioning characteristics cushioning stroke is adjustable
- 2 End-position sensing via proximity sensor SME-/SMT-8 that can be integrated
- 3 Precision end-position adjustment
- 4 Precision end position thanks to internal, metallic inserts



Size	B1	B2	D1	D2	D3	D4	D5	H1	L1
[mm]		+0.4			+0.1		+0.1	+0.3	+0.3/-0.1
5	3	8.1	M8x1	4	12	6.7 ±0.05	2	16.5	97.4
7	3.5	8.5	M10x1	6	14	8.6 ±0.05	2.4	18.3	144.8
8	4	8.5	M12x1	8	16	10.4 ±0.1	2.4	20.75	133.3
Size	L2	L3	L4	L5	L6	L7	=©1	=©2	Max. tightening
									torque ≓©1
[mm]	+0.4		+0.45/-0.1	+0.5	+0.1/-0.55	+0.3			[Nm]
5	32.5	8 +0.7/-0.55	21.6	5	4.4	0.5	10	7	2
7	40	10 +0.8/-0.55	21.1	6	4	0.5	13	9	3
8	40	14 +0.8/-0.55	33.6	8	4.4	0.5	15	11	5

Ordering d	ata	
Size	Part No.	Туре
[mm]		
5	192968	YSRWJ-5-8-A
7	192967	YSRWJ-7-10-A
8	192966	YSRWJ-8-14-A

## Hydraulic cushioning cylinders DYHR Peripherals overview and type codes

## FESTO



Access	ccessories										
	Туре	➔ Page/Internet									
1	Hydraulic cushioning cylinder DYHR	Hydraulic cushioning cylinder with spring return for slow feed speeds	39								
2	Mounting flange YSRF	Mounting option for hydraulic cushioning cylinder	42								
3	Buffer YSRP	For protecting the piston rod	44								

### Type codes

		DYHR	]-	16	 - 20	-	¥5
Туре							
DYHR	Hydraulic cushioning cylinder						
Size							
Stroke [mm]							
Design charac	teristic						
Y5	Internal hex for setting the flow control val	lve					

**FESTO** 

## Hydraulic cushioning cylinders DYHR Technical data

Function







General technical data											
Size		16		20		25		32			
Stroke	[mm]	20	40	25	50	40	80	60	120		
Mode of operation		Hydraulic cus	hioning cylind	er with spring	return						
		Single-acting	, pushing								
Braking speed		Adjustable	Adjustable								
Type of mounting		Via lock nut									
Max. impact velocity	[m/s]	0.3									
Mounting position		Any									
Feed speed	[mm/s]	0.2 100									
Product weight	[g]	190	255	360	440	720	900	1,380	1,810		
Ambient temperature	[°C]	0 +80									
Corrosion resistance class CRC <sup>1)</sup>		1									

1) Corrosion resistance class 1 according to Festo standard 940 070

Components subject to low corrosion stress. Transport and storage protection. Parts that do not have primarily decorative surface requirements, e.g. in internal areas that are not visible or behind covers

Reset times [s]				
Size	16	20	25	32
Short stroke <sup>1)</sup>	≤ 0.4	≤ 0.5	≤ 0.8	≤ 1.2
Long stroke <sup>1)</sup>	≤ 0.8	≤1	≤ 1.6	≤ 2.4

1) Increased reset times must be expected at low temperatures (0 °C). Up to 5 s with sizes 12 and 16 and up to 12 s with sizes 25 and 32.

Forces [N]				
Size	16	20	25	32
Min. feed force <sup>1)</sup>	160	250	400	640
Max. feed force <sup>2)</sup>	1,600	2,500	4,000	6,400
Resetting force <sup>3)</sup>	5.4	9	12.5	18

1) Min. required force for constant braking speed with repetition accuracy

2) Corresponds to max. force in the end position

3) With piston rod advanced

Energies [J]									
Size	16	16		20		25		32	
Stroke [mm]	20	40	25	50	40	80	60	120	
Max. energy absorption per stroke	32	64	62.5	125	160	320	384	768	
Max. energy absorption per hour	100,000	150,000	135,000	200,000	220,000	330,000	330,000	495,000	
Max. residual energy in the end position	0.16		0.32		0.8		2		

## Hydraulic cushioning cylinders DYHR Technical data



Flow control valve open

----- Flow control valve closed

## Hydraulic cushioning cylinders DYHR Technical data



Size	Stroke	B1	D1	D2 Ø	D3 Ø	D4 Ø	L1
	[mm]				+0.15/-0.1	+0.15	
16	20	6	M20v1 25	Q	20	_	115±0.1
	40	0	M20X1.23	0	20	_	150±0.1
20	25	8	M2/y1 25	10	2/	_	138±0.1
	50	0	M24X1.2J	10	24		181±0.1
25	40	10	M30v1 5	10	30	28.8	178±0.1
	80	10	MJUX1.J	12	00	20.0	242±0.15
32	60	12	M37v1 5	15	37	3/1 8	230±0.15
	120	12	111.7/11.7	1)	57	24.0	325±0.2

Size	Stroke	L2	L3	L4	L5	<i>=</i> ©1	=©2
	[mm]	±0.1			±0.2		
16	20	52	28.5+0.4/-0.3	8 5 0 (5/ 0 (		24	F
	40		48.5+0.4/-0.3	0.0+0.45/-0.4	_	24	5
20	25	60	35.6+0.4/-0.3	10 6.045/ 04	_	30	5
	50	00	60.6+0.4/-0.3	10.0+0.45/-0.4	_	50	5
25	40	80	52.8+0.4/-0.3	129 0454 04	20	26	6
	80	80	92.8+0.4/-0.3	12.0+0.45/-0.4	20	50	0
32	60	108	76+0.5/-0.4	16.05/04	28	46	6
	120	100	136+0.5/-0.4	10+0.5/-0.4	20	40	0

Ordering data			
Size	Stroke	Part No.	Туре
	[mm]		
16	20	1155690	DYHR-16-20-Y5
	40	1155691	DYHR-16-40-Y5
20	25	1155692	DYHR-20-25-Y5
	50	1155693	DYHR-20-50-Y5
25	40	1155694	DYHR-25-40-Y5
	80	1155695	DYHR-25-80-Y5
32	60	1155696	DYHR-32-60-Y5
	120	1155697	DYHR-32-120-Y5

#### Mounting flange YSRF/YSRF-C

Material: Steel



Possible combinations						
Cushioning components	DYSR		YSR-C	YSRW	YDR	
Mounting flange	Y5	Y5-T				
YSRF						
YSRF-8	-	-	<b>1</b> )	■ <sup>1)</sup>	-	
YSRF-12		-	-	-	-	
YSRF-16		-	-	-		
YSRF-20		-	-	-		
YSRF-25		-		-		
YSRF-32		-		-		
	•	•			•	
YSRF-C						
YSRF-8-C		-			-	
YSRF-12-C	-				-	
YSRF-16-C	-				-	
YSRF-20-C	-				-	

1) For shock absorber size  $\varnothing$  7

Dimension	Dimensions and ordering data												
YSRF													
For size	B1	B2	D1	D2	D3	H1	L1	L2	CRC <sup>1)</sup>	Weight	Part No.	Туре	
[mm]										[g]			
8	16	5.5	10	5.5	10.2	16	25	38	2	50	11681	YSRF-8	
12	25	6.8	11	6.6	15.2	25	36	50	2	175	11682	YSRF-12	
16	30	9	15	9	20.2	30	45	63	2	300	11683	YSRF-16	
20	36	11	18	11	24.2	36	56	78	2	535	11684	YSRF-20	
25	45	13	20	13.5	30.2	45	63	86	2	895	11685	YSRF-25	
32	55	15	24	15.5	37.2	55	80	108	2	1,730	11686	YSRF-32	

1) Corrosion resistance class 2 according to Festo standard 940 070

Components requiring moderate corrosion resistance. Externally visible parts with primarily decorative surface requirements which are in direct contact with a surrounding industrial atmosphere or media such as cooling or lubricating agents

YSRF-C											
For size [mm]	B1	B2	D1	D2	D3	H1	L1	L2	CRC <sup>1)</sup>	Weight [g]	Part No. Type
8	20	5.5	10	5.5	12.2	20	28	41	2	90	34575 YSRF-8-C
12	25	6.8	11	6.6	16.2	25	36	50	2	180	34576 YSRF-12-C
16	32	9	15	9	22.2	32	45	63	2	330	34577 YSRF-16-C
20	40	11	18	11	26.2	40	56	78	2	700	34578 YSRF-20-C

1) Corrosion resistance class 2 according to Festo standard 940 070 Components requiring moderate corrosion resistance. Externally visible parts with primarily decorative surface requirements which are in direct contact with a surrounding industrial atmosphere or media such as cooling or lubricating agents

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### Mounting flange YSRF-S-C

Material: Aluminium, steel Free of copper, PTFE and silicone





Possible combinations		
Cushioning components	YSR-C	YSRW
Mounting flange		
YSRF-S-8-C		
YSRF-S-12-C	•	•
YSRF-S-16-C		
YSRF-S-20-C		

Dimension	Dimensions and ordering data													
For size	B1	D1	D2	H1	H2	H3	H4	L1	L2	L3	T1	Weight	Part No.	Туре
			Ø											
[mm]												[g]		
8	20	M12x1	5.5	35	25	9.5	16	32	45	4	2	12	34579	YSRF-S-8-C
12	25	M16x1	6.6	42	32	12.5	20	36	50	3	4	130	34580	YSRF-S-12-C
16	30	M22x1.5	9	48	38	16.5	22	45	60	8	4	180	34581	YSRF-S-16-C
20	30	M26x1.5	11	52	42	19	23.5	56	80	11.5	4	250	34582	YSRF-S-20-C

#### Note

Inductive sensors for position sensing ightarrow 45

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#### Buffer YSRP

Material: Steel, polyurethane





6 Polyurethane insert

7 Buffer

Dimension	is and ordering da	ta							
For size	D3	D4	L7	L8	=© 2	CRC <sup>1)</sup>	Weight	Part No.	Туре
[mm]							[g]		
8	8	M2	6,7	4	0,9	2	4	539638	YSRP-8
12	12	M4	10	6	2	2	7	11133	YSRP-12
16	16	M5	13.5	8	2.5	2	15	11134	YSRP-16
20	20	M6	17	10	3	2	27	11135	YSRP-20
25	25	M8	20.5	12	4	2	52	11136	YSRP-25
32	32	M8	26	15	4	2	110	11137	YSRP-32

Corrosion resistance class 2 according to Festo standard 940 070
 Components requiring moderate corrosion resistance. Externally visible parts with primarily decorative surface requirements which are in direct contact with a surrounding industrial atmosphere or media such as cooling or lubricating agents

#### Stop limiter YSRA-C

Material: Steel





Dimension	is and ordering data				
For size	D	L	<u>ى</u> =	Weight	Part No. Type
[mm]				[g]	
7	M10x1	14.5	13	12	150932 YSRA-7-C
8	M12x1	18	15	28	150933 YSRA-8-C
12	M16x1	24.5	19	48	150934 YSRA-12-C

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### Reducing sleeve DAYH

Material: Stainless steel



To improve the cushioning performance in the case of underload, the built-in shock absorber can be replaced by the next smallest shock absorber with the help of the reducing sleeve.

Built-in shock absorber	Part No.	Reducing sleeve	Part No.	Next smallest shock absorber
YSRC				
YSR-5-5-C	1165476	DAYH-4	540060	YSR-4-4-C
DYSC				
DYSC-8-8-Y1F	1165484	DAYH-7	548012	DYSC-7-5-Y1F
DYSC-7-5-Y1F	1165480	DAYH-5	548011	DYSC-5-5-Y1F
DYSW				
DYSW-12-20-Y1F	1165491	DAYH-10	548074	DYSW-10-17-Y1F
DYSW-10-17-Y1F	1165488	DAYH-8	548073	DYSW-8-14-Y1F
DYSW-8-14-Y1F	1165484	DAYH-7	548072	DYSW-7-10-Y1F
DYSW-7-10-Y1F	1165480	DAYH-5	548071	DYSW-5-8-Y1F
DYSW-5-8-Y1F	1165476	DAYH-4	548070	DYSW-4-6-Y1F

Ordering data	- Proximity sensors for T-slot, magneto-re	esistive				Technical data 🗲 Internet: smt
	Type of mounting	Switch output	Electrical connection	Cable length [m]	Part No.	Туре
N/O contact						
	Insertable in the slot from above, flush	PNP	Cable, 3-wire	2.5	543867	SMT-8M-PS-24V-K-2,5-0E
13 B	with cylinder profile		Plug M8x1, 3-pin	0.3	543866	SMT-8M-PS-24V-K-0,3-M8D
\$~		NPN	Cable, 3-wire	2.5	543870	SMT-8M-NS-24V-K-2,5-OE
			Plug M8x1, 3-pin	0.3	543871	SMT-8M-NS-24V-K-0,3-M8D
15 A	Insertable in the slot lengthwise, flush	PNP	Cable, 3-wire	2.5	175436	SMT-8-PS-K-LED-24-B
	with the cylinder profile		Plug M8x1, 3-pin	0.3	175484	SMT-8-PS-S-LED-24-B
				•		
N/C contact						
CT. B. M.	Insertable in the slot from above, flush with cylinder profile	PNP	Cable, 3-wire	7.5	543873	SMT-8M-PO-24V-K7,5-OE

Ordering data	Drdering data – Proximity sensors for T-slot, magnetic reed Technical data → Internet: sme					
	Type of mounting	Switch	Electrical connection	Cable length	Part No.	Туре
		output		[m]		
N/O contact						
	Insertable in the slot from above, flush	Contacting	Cable, 3-wire	2.5	543862	SME-8M-DS-24V-K-2,5-OE
AT BEAL	with cylinder profile		Plug M8x1, 3-pin	0.3	543861	SME-8M-DS-24V-K-0,3-M8D
\$~						
15	Insertable in the slot lengthwise, flush	Contacting	Cable, 3-wire	2.5	150855	SME-8-K-LED-24
	with the cylinder profile		Plug M8x1, 3-pin	0.3	150857	SME-8-S-LED-24
N/C contact	N/C contact					
1 Alexandre	Insertable in the slot lengthwise, flush	Contacting	Cable, 3-wire	7.5	160251	SME-8-O-K-LED-24
<b>\$</b>	with the cylinder profile					

# Accessories for cushioning components Technical data

Ordering data – Inductive sensors M8, for mounting flange YSRF-S-C Te					Technical data 🗲 Internet: sien		
	Electrical connectior	ı	Switch	LED	Cable length	Part No.	Туре
	Cable	M8 plug	output		[m]		
NO contact							
and the second se	3 wires	-	PNP	•	2.5	150386	SIEN-M8B-PS-K-L
and the second second	-	3-pin	PNP	•	-	150387	SIEN-M8B-PS-S-L
NC contact							
and the second s	3 wires	-	PNP	•	2.5	150390	SIEN-M8B-PO-K-L
and the second se	-	3-pin	PNP		-	150391	SIEN-M8B-PO-S-L

Ordering data	Ordering data – Connecting cables						
	Electrical connection, left	Electrical connection, right	Cable length	Part No.	Туре		
			[m]				
	Straight socket, M8x1, 3-pin	Cable, open end, 3-wire	2.5	541333	NEBU-M8G3-K-2.5-LE3		
( Caller			5	541334	NEBU-M8G3-K-5-LE3		
	Angled socket, M8x1, 3-pin	Cable, open end, 3-wire	2.5	541338	NEBU-M8W3-K-2.5-LE3		
			5	541341	NEBU-M8W3-K-5-LE3		

## Calculation tool for cushioning components

Technical data

#### This selection aid helps you find the 1. Determine the following values, 2. Select a shock absorber from the Note right shock absorber for every effective at the time of impact: graphs on the following pages. Sizing software application. - Force (A) 3. Check your selection on the basis When you are choosing a shock of its maximum cushioning Shock absorber selection - Equivalent mass mequiv absorber, we recommend that you - Impact velocity (v) →www.festo.com energy (W<sub>max.</sub>) proceed as follows: When you are choosing a shock Permissible energy load per Max. energy absorption per hour absorber for your application, ensure stroke: Max. residual energy that the following values are not W<sub>min</sub>. = 25% Max. stop force in end position exceeded: W<sub>max</sub>. = 100% Recommended energy load per stroke: = 50% ... 100 % Wopt. The (angular) velocity required in the In order to prevent damage to the The fact that the (angular) velocity formulae is the velocity at the time of drive concerned, calculations should appears in the calculation as a the impact on the shock absorber. in the interests of safety be based on squared value means that the This depends on the dynamic the following values: expected error becomes considerably v = 1.25 ... 2 v<sub>m</sub> characteristics of the drive component larger. The calculation can thus be and is thus difficult to determine. $\omega = 1.25 \dots 2 \omega_m$ regarded only as an approximation. The safety factor does, however, Guide values for linear motions: It is better to determine the mean ensure that the selected shock Factor 2 with strokes < 50 mm. velocity ( $v_m = s/t$ or $\omega_m = \phi/t$ ). factor 1.5 with strokes > 50 mm and absorber is not too small. < 100 mm. factor 1.25 with strokes > 100 mm. The following formulae are required A = F + Gfor the calculation: $A = F + m \times g \times \sin \alpha$ $W_{total} = \frac{1}{2} \times m \times v^2 + A \times s < W_{max}$ $W_{h} = W_{total} \times Stroke \div Hours < W_{hmax}$ The following applies additionally for $m_{equiv.} = \frac{J}{R^2}$ $v = \omega \times R$ rotary motions: $A = \frac{M}{R} + m \times g \times \sin \alpha \times \frac{a}{R}$ The following abbreviations are used: A = Additional force = F + G[N]v = Impact velocity [m/s] = Mass moment of inertia I = Cylinder force minus m<sub>equiv.</sub>= Equivalent mass [kg] [kg x m<sup>2</sup>] F = Acceleration due to gravity frictional force [N] = Distance between mass pivot g R G = Force due to weight $9.81 \, [m/s^2]$ point and shock absorber [m] = m x g x sin $\alpha$ = Shock absorber stroke [m] = Angular velocity [rad/s] S ω $\alpha$ = Impact angle [°] = Drive torque [Nm] Μ Special cases: Wtotal= Cushioning work/stroke [J] = Distance between centre of а $\alpha = 0^{\circ}$ : Horizontal motion W<sub>h</sub> = Cushioning work/hour [J] gravity of mass and pivot point G = 0= 90°: Downward motion α G = m x g= 90°: Upward motion: α G = -m x g

## Calculation tool for cushioning components

### FESTO

Technical data

#### Sizing example for linear motion

This example illustrates the procedure for the selection of a shock absorber for the application shown in the adjacent drawing:

= F + m x g x sin  $\alpha$ А = 190 N + 50 x 9.81 x sin  $\alpha$  N = 537 N  $m_{equiv} = m = 50 \text{ kg}$ 

In the process of selecting shock absorbers on the basis of the graphs (see data sheets), the force (A) is governed by the first curve to the right of the point of intersection of the equivalent mass (mequiv) and the impact velocity (v). The curves move to the left as the additional force increases.

Three force curves are given for each shock absorber. Interim values must be calculated by averaging. As the

graphs show (continuous line), possible choices are the shock absorbers DYSR-25-40 and YSR-25-40-C. We must now determine whether the maximum permissible values for cushioning work (W<sub>max.</sub>) and cushioning work per hour (W<sub>hmax.</sub>) are not being exceeded. These maximum permissible values and the stroke length (s) can be found in the tables (below the graphs).

Experiment:				
W <sub>total</sub>	$= \frac{1}{2} \times m \times v^{2} + A \times s$			
	$=(1/2 \times 50 \times 1.5^{2} +$			
	537 x 0.04) Nm = 78 J			

Wh = W<sub>total</sub> x strokes/h = 78 Nm x 1,800 = 140,000 J

For the above application, both shock absorbers are suitable. Further selection criteria are adjustment facilities and size.

m

٧

α = 45° = 190 N

F

= 50 kg

= 1.5 m/s

( $\varnothing$  20 mm with p = 6 bar,

1,800 strokes per hour)

Result		
	DYSR-25-40	YSR-25-40-C
W <sub>total</sub>	78 J	78 J
W <sub>h</sub>	140,000 J	140,000 J
W <sub>max</sub> . <sup>1)</sup>	160 J > W <sub>total</sub>	160 J > W <sub>total</sub>
W <sub>hmax</sub> .	220,000 > W <sub>max.</sub>	150,000 > W <sub>max.</sub>

1) The degree of utilisation is 49% in both cases.

## Calculation tool for cushioning components

Technical data

#### Sizing example for rotary motion

Example for rotary motion:  $m_{equiv} = J/R^2 = 8 \text{ kg}$   $v = \omega x R$ A = M/R = 40 N



In the process of selecting shock absorbers on the basis of graphs (see data sheets), the force (A) is governed by the first curve to the right of the point of intersection of the equivalent mass (m<sub>equiv</sub>) and the impact velocity (v). The curves move to the left as the additional force increases. Three force curves are given for each shock absorber. Interim values must be calculated by averaging. As the graphs show (dotted line), possible choices are the shock absorbers DYSR-16-20 and YSR-16-20-C. We must now determine whether the maximum permissible values for cushioning work (W<sub>max</sub>.) and cushioning work per hour (W<sub>hmax</sub>.) are not being exceeded. These maximum permissible values and the stroke length (s) can be found in the tables (below the graphs).

Note: The impact angle must be noted with rotary applications.

 $\tan\alpha=\frac{s}{R}$ 

s = Cushioning stroke

Experi	ment:		
Wtotal	$= \frac{1}{2} x$	$m \times v^2$	+ A x s

∎total	- /2 < 111 < V + A < 3
	$= (1/2 \times 8 \times 2^2 +$
	40 x 0.02) J = 17 J

$$\begin{split} W_h &= W_{total} \ x \ strokes/h \\ &= 17 \ J \ x \ 900 \\ &= 15,300 \ J \end{split}$$

For the above application, both shock absorbers are suitable. Further selection criteria are adjustment facilities and size.

 $= 2 \text{ kg m}^2$ 

= 4 rad/s

= 0.5 m

= 20 Nm

900 strokes per hour

J

ω

R

Μ

Result		
	DYSR-16-20 <sup>3)</sup>	YSR-16-20-C
W <sub>total</sub>	17 J	17 J
W <sub>h</sub>	15,300 J	15,300 J
W <sub>max.</sub>	$32 \text{ J} > \text{W}_{\text{total}}^{1)}$	$30 \text{ J} > \text{W}_{\text{total}}^{2)}$
W <sub>hmax</sub> .	100,000 > W <sub>max.</sub>	64,000 > W <sub>max.</sub>

The degree of utilisation is 53%.
 The degree of utilisation is 57%.

Use without buffer.

Desult

2010/10 - Subject to change



## Product Range and Company Overview

#### **A Complete Suite of Automation Services**

Our experienced engineers provide complete support at every stage of your development process, including: conceptualization, analysis, engineering, design, assembly, documentation, validation, and production.



**Custom Automation Components** Complete custom engineered solutions



**Custom Control Cabinets** Comprehensive engineering support and on-site services



**Complete Systems** Shipment, stocking and storage services

#### **The Broadest Range of Automation Components**

With a comprehensive line of more than 30,000 automation components, Festo is capable of solving the most complex automation requirements.



Electromechanical Electromechanical actuators, motors, controllers & drives



**Pneumatics** Pneumatic linear and rotary actuators, valves, and air supply



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