

Mini slides DGSL-N, NPT

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Mini slides DGSL-N, NPT

Key features

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General information

- Double-acting drives
- Wide range of options for mounting on:
 - Drives, grippers
- System product for handling and assembly technology
- Highly flexible thanks to wide range of assembly and connection options on:
 - Drive body, slide, yoke plate

The technology in detail



[1] Cushioning



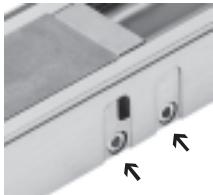
- Choice of four cushioning types:
 - Elastic cushioning without metal end position (P)
 - Elastic cushioning without metal end position, short design (E)
 - Elastic cushioning with metal end position (P1)
 - Hydraulic shock absorbers (Y3)

[2] Cover



- The cover stops foreign parts or dirt getting into the guide
- The cover comes in different lengths and can be trimmed as required by the customer

[3] Coarse stroke adjustment



- The end stop for the advanced end position can be adjusted mechanically, for example to shorten the stroke

[4] Clamping unit



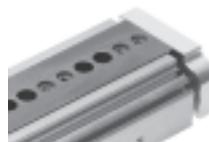
- Mechanical clamping, for fixing the slide in any position; frictional locking (C)

[4] End-position locking



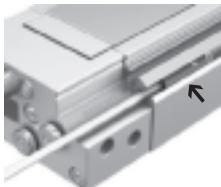
- Mechanical locking when the end position is reached, for fixing the slide in the unpressurised, retracted state; positive locking (E3)

[5] Innovative guide unit



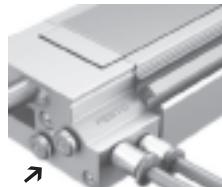
- Wide roller track, which provides extremely high rigidity
- High load capacity
- High precision
- Housing and steel slide form a guide: there are no accumulative tolerances

[6] Position sensing



- Proximity sensors can be integrated, so there are no projecting parts
- Two slots for mounting
- Clearly visible from the side and from above

[7] Supply ports



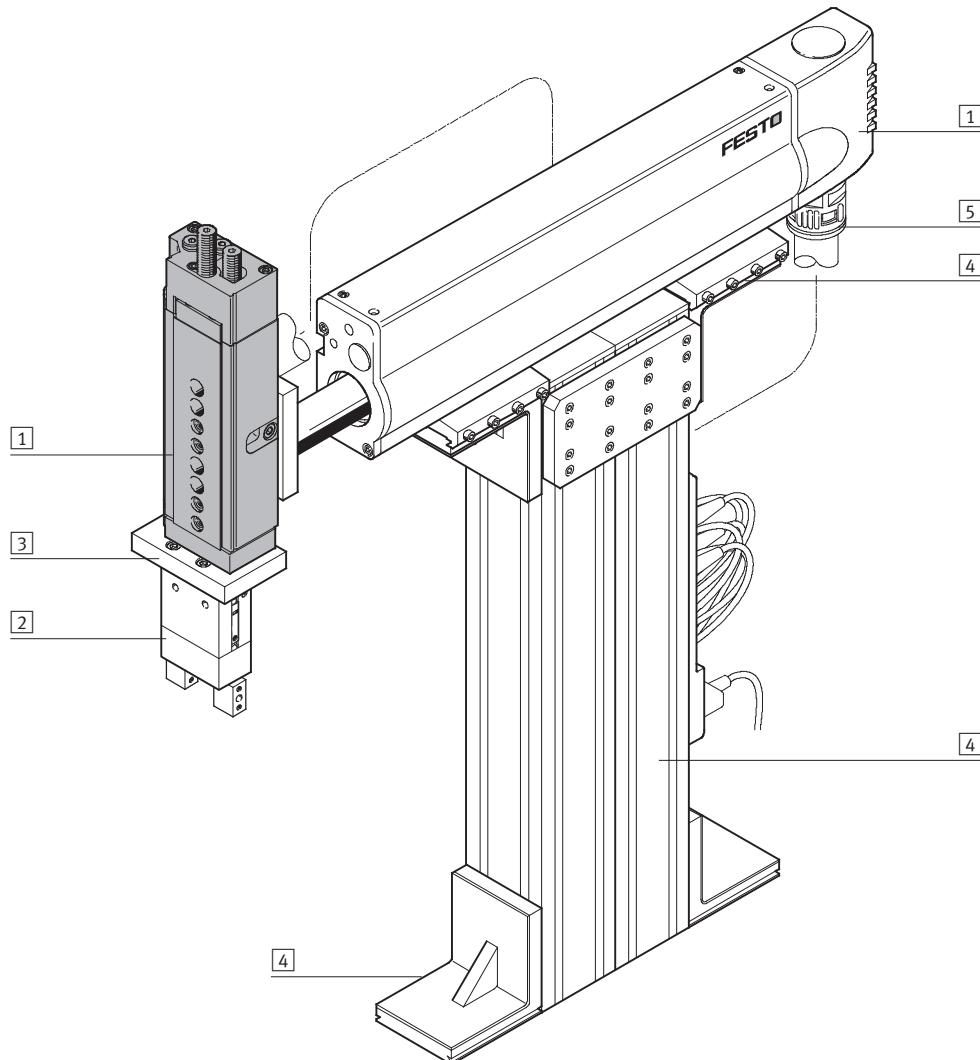
- Choice of two sides:
 - On front face
 - At the side

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System example

System product for handling and assembly technology



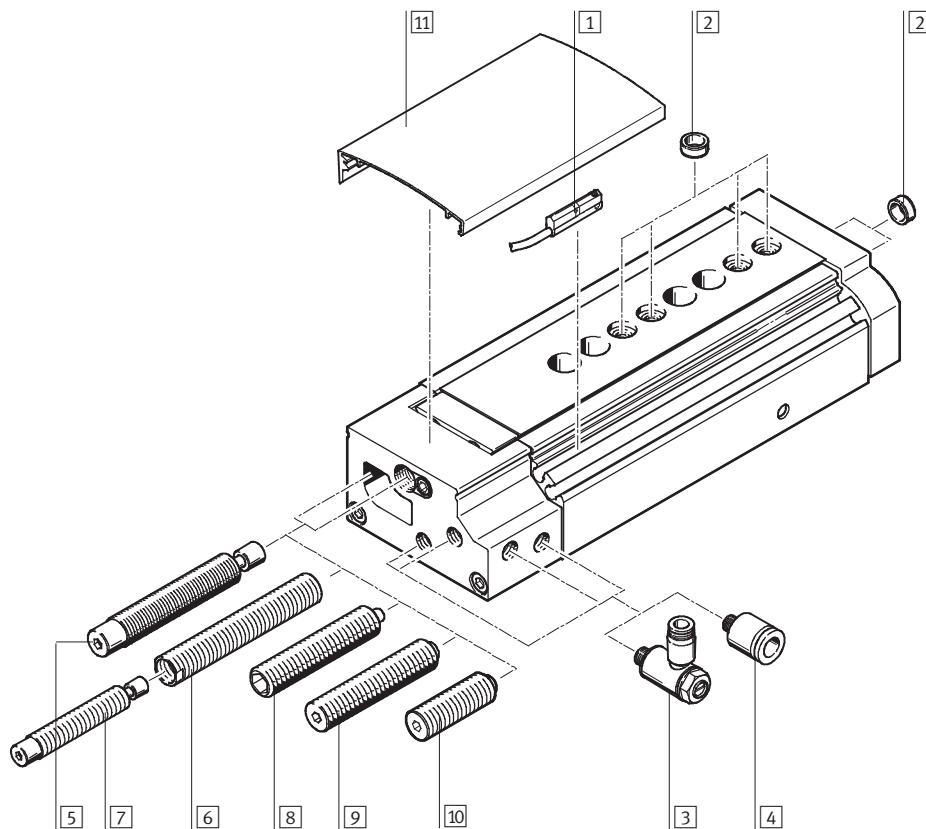
System components and accessories

	Brief description	➔ Page/Internet
[1] Drives	Wide range of combinations possible within handling and assembly technology	drive
[2] Grippers	Wide range of variations possible within handling and assembly technology	gripper
[3] Adapters	For drive/drive and drive/gripper connections	adapter kit
[4] Basic components	Profiles and profile connections as well as profile/drive connections	basic component
[5] Installation components	For a clear, safe layout of electrical cables and tubing	installation component
- Axes	Wide range of combinations possible within handling and assembly technology	axis
- Motors	Servo and stepper motors, with or without gearing	motor

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Peripherals overview

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- - Note
End stops must not be removed.

Accessories	Brief description	➔ Page/Internet
[1] Proximity sensor SME/SMT-10	For position sensing. Can be integrated in sensor slot, so there are no projecting parts	42
[2] Centring sleeve ZBH	For centring loads and attachments (centring sleeves are included in the scope of delivery of the mini slide)	41
[3] One-way flow control valve GRLA	For regulating speed	42
[4] Push-in fitting QB	For connecting compressed air tubing with standard O.D.	42
[5] Cushioning with shock absorber Y3	For large loads and high speed. Ensures precise, metal-to-metal contact after the cushioning	41
[6] Reducing sleeve DAYH	For installing a smaller shock absorber. For applications where the cushioning energy lies between the cushioning Y3 and P1	41
[7] Shock absorber DYSW	➔ 12 (shock absorber selection)	41
[8] Cushioning with stop P1	Precision metal stop for small loads at low speed	41
[9] Cushioning P	<ul style="list-style-type: none"> Flexible stop for medium loads at medium speed (standard design) 	41
[10] Cushioning E	<ul style="list-style-type: none"> Flexible stop for medium loads at medium speed (short design) 	41
[11] Cover DADS	<ul style="list-style-type: none"> For protection, to stop foreign parts or dirt getting into the guide The cover can be trimmed as required by the customer 	40

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Type codes

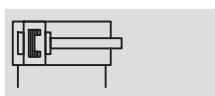
DGSL	-	N	-	10	-	100	-		E3	-	Y3	A												
Type																								
Double-acting																								
DGSL	Mini slide																							
System of units																								
N	Imperial																							
Size																								
Stroke [mm]																								
Clamping unit																								
C	Attached																							
End-position locking																								
E3	With piston rod in retracted position																							
Cushioning																								
P	Elastic cushioning without metal end position, both ends																							
P1	Elastic cushioning with metal end position, both ends																							
Y3	Progressive shock absorber, both ends																							
E	Elastic cushioning without metal end position, both ends, short design																							
Position sensing																								
A	Via proximity sensor																							

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Technical data

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Function



Wearing parts kits

➔ 40

- Ø - Size

10 ... 25

- | - Stroke length

10 ... 200 mm



General technical data

Size	10	12	16	20	25
Pneumatic connection	M5, suitable for 10-32 UNF			1/8 NPT	
Design	Scotch yoke system				
Guide	Ball bearing cage guide				
Type of mounting	Via through-hole				
	Via female thread				
Cushioning	P	Flexible cushioning without metal end position, both ends			
	E	Flexible cushioning without metal end position, both ends, short design			
	P1	Flexible cushioning with metal end position, both ends, adjustable			
	Y3	With progressive shock absorber, both ends			
Position sensing		Via proximity sensor			
Mounting position		Any			
Max. advancing speed	[m/s]	0.8			
Max. retracting speed	[m/s]	0.8			
Repetition accuracy	P1/Y3 [mm]	±0.01			
	P [mm]	0.3			

Operating and environmental conditions

Size	10	12	16	20	25
Operating medium	Dried compressed air, lubricated or unlubricated				
Min. operating pressure	[bar]	1.5	1		
Max. operating pressure	[bar]	8			
Ambient temperature ¹⁾	[°C]	0 ... +60			

1) Note operating range of proximity sensors.

Piston Ø, forces and impact energy

Size	10	12	16	20	25
Piston Ø [mm]	12	16	20	25	32
Theoretical force at 6 bar, advancing	[N]	68	121	188	295
Theoretical force at 6 bar, retracting	[N]	51	104	158	247
Impact energy in the end positions	P, E [Nm]	0.12	0.25	0.35	0.45
	P1 [Nm]	0.04	0.06	0.12	0.2
	Y3 [Nm]	1.3	2.5	4	8
	1) [Nm]	0.8	1.3	2.5	4
					8

1) With reducing sleeve and next smallest shock absorber.

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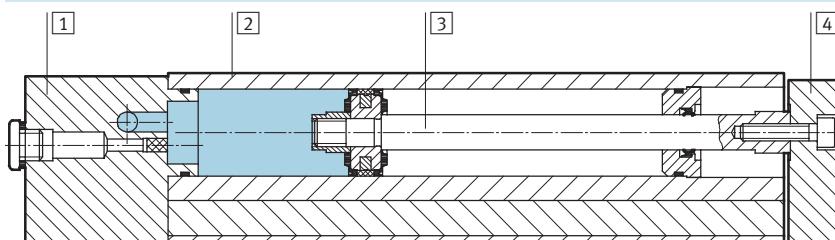
Technical data

Weight [g]		Stroke	10	12	16	20	25
Product weight without cushioning component							
	10	396	604	896	1,535	2,520	
	20	434	660	954	1,649	2,670	
	30	470	711	1,008	1,746	2,824	
	40	507	762	1,072	1,857	2,983	
	50	548	813	1,143	1,991	3,137	
	80	727	1,112	1,365	2,295	4,019	
	100	813	1,229	1,712	2,921	4,519	
	150	—	1,499	2,034	3,620	5,344	
	200	—	—	—	4,248	6,139	
Moving load without cushioning component							
	10	163	256	403	660	998	
	20	180	279	432	710	1,052	
	30	194	299	459	750	1,115	
	40	208	320	486	801	1,181	
	50	226	340	519	858	1,244	
	80	299	456	618	998	1,567	
	100	334	507	776	1,254	1,761	
	150	—	614	910	1,566	2,102	
	200	—	—	—	1,807	2,432	
Cushioning component							
	P	14	23	45.6	82.4	106	
	E	9	12	15	31	40	
	P1	12	19.7	39.6	77.3	104	
	Y3	11	21	42	67	91	
	1)	18	33	52	91	131	

1) With reducing sleeve and next smallest shock absorber.

Materials

Sectional view



Mini slide

[1] End cap	Anodised aluminium
[2] Housing	Anodised aluminium
[3] Piston rod	High-alloy steel
[4] Yoke plate	Anodised aluminium
— Guide	Tempered steel
— Seals	Thermoplastic rubber, hydrogenated nitrile rubber, nitrile rubber
Note on materials	Free of copper and PTFE

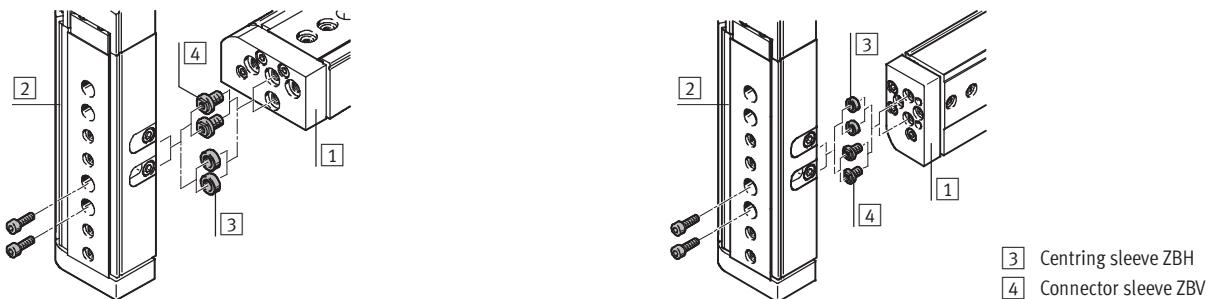
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Technical data

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Possible combinations without adapter plate

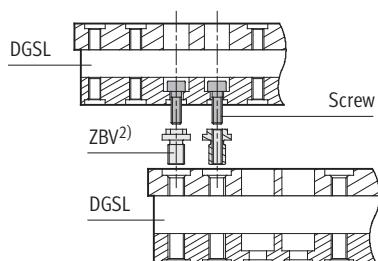
Pick & place



Piggy-back assembly



Mounting example with connector sleeve ZBV



	[1] Basic drive	Size	10	12	16	20	25
[2] Assembly drive	10	2x M4x14 2x ZBH-7 ¹⁾	ZBV-M5-7 ²⁾	ZBV-M5-7 ²⁾	-	-	
	12	-	2x M5x14 2x ZBH-7 ¹⁾	2x M5x16 2x ZBH-7 ¹⁾	ZBV-M6-9 ²⁾	ZBV-M6-9 ²⁾	
	16	-	-	2x M5x18 2x ZBH-7 ¹⁾	ZBV-M6-9 ²⁾	ZBV-M6-9 ²⁾	
	20	-	-	-	2x M6x20 2x ZBH-9 ¹⁾	2x M6x20 2x ZBH-9 ¹⁾	
	25	-	-	-	-	2x M6x30 2x ZBH-9 ¹⁾	

1) Centring sleeves ZBH are included in the scope of delivery of the mini slide DGSL

2) Connector sleeves ZBV → 41

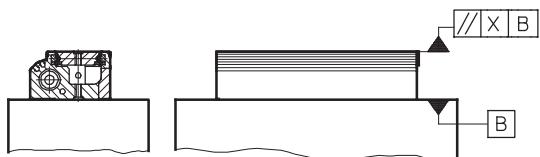
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Technical data

Parallelism [mm]

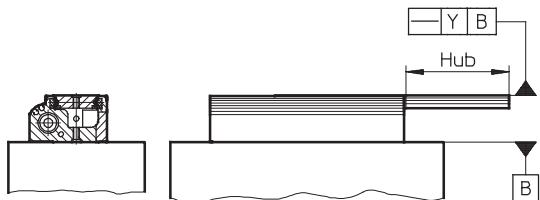
The term parallelism refers to the accuracy of alignment between the mounting surface and the slide surface.



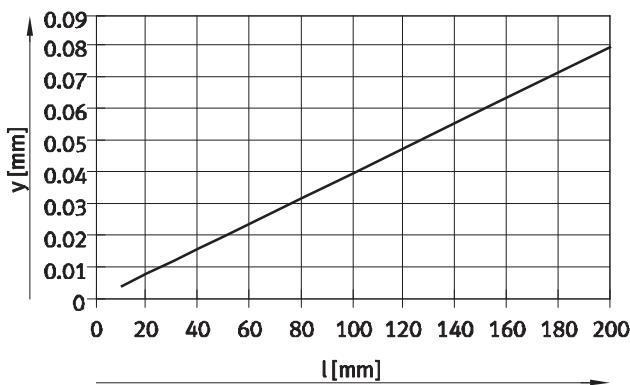
Size	Stroke [mm]	10	12	16	20	25
Parallelism X	10	0.02	0.02	0.02	0.02	0.02
	20	0.02	0.025	0.025	0.025	0.025
	30	0.025	0.025	0.025	0.03	0.03
	40	0.025	0.03	0.03	0.035	0.035
	50	0.03	0.035	0.035	0.04	0.04
	80	0.035	0.04	0.04	0.045	0.045
	100	0.045	0.05	0.05	0.055	0.055
	150	—	0.075	0.075	0.08	0.08
	200	—	—	—	0.08	0.08

Linearity [mm]

The term linearity refers to the accuracy of alignment between the mounting surface and the slide surface as a function of the stroke.



Linear travel accuracy y as a function of stroke length l



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Technical data

Adjustable end-position range

Coarse adjustment of the advanced end position

The mini slide DGSL allows the front fixed stop to be adjusted by removing the cover.

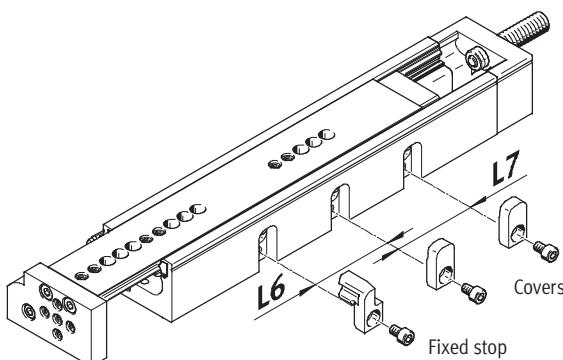
This permits stroke reduction down to the next but one smaller standard stroke through a combination of coarse and precision adjustments.

Advantages:

- Can be flexibly adapted to the application
- Integrated, which means fewer conversion overheads
- Large setting range



Note
Removal of the fixed stops can result in the destruction of the mini slide DGSL.



Size	10		12		16		20		25	
	L6	L7								
10	-	-	-	-	-	-	-	-	-	-
20	-	-	-	-	-	-	-	-	-	-
30	-	-	-	-	-	-	-	-	-	-
40	-	-	-	-	-	-	-	-	-	-
50	-	-	-	-	-	-	-	-	-	-
80	24	-	29	-	35	-	-	-	55	-
100	24	24	29	-	35	-	44	-	55	-
150	-	-	29	29	35	-	44	-	55	-
200	-	-	-	-	-	-	44	44	55	-

Example:

DGSL-N-12-150-...

Max. stroke = 150 mm

By adjusting the fixed stop by the dimension L6:

Stroke = 150 - 29 = 121 mm

By adjusting the fixed stop by the dimension L6 and L7:

Stroke = 150 - 29 - 29 = 92 mm

The stroke can additionally be reduced by means of precision adjustment:

Stroke = 150 - 29 - 29 - 29

= 63 mm

Precision adjustment
of the advanced and retracted end
position → 11

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Technical data

Adjustable end-position range

Precision adjustment of the advanced and retracted end position

Precision adjustment of the required stroke reduction is possible using the cushioning components (on the slide and in the end cap).

Advantages:

- Precision adjustment is precisely fixed by the clamping component
- No readjustment required, position is fully retained under load

- Quick and easy adjustment, only one tool required

Step 1:

Loosen the clamping component.

Step 2:

Position the slide by hand in the desired end position.

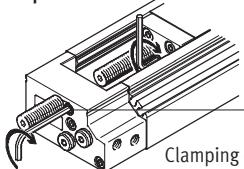
Step 3:

Turn the stop element using an Allen key until the end position is reached.

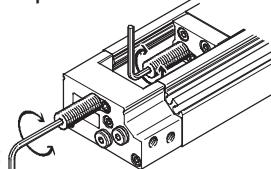
Step 4:

Tighten the clamping component.

Step 1



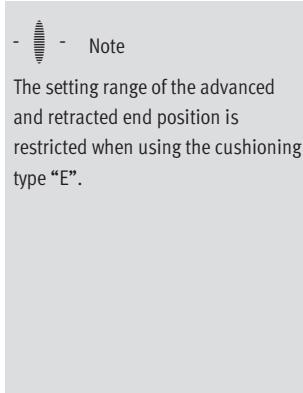
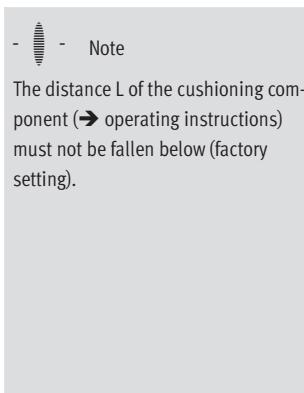
Step 2 ... 4



Adjustable end-position range [mm] per end position/stroke reduction

Size	10	12	16	20	25
Advanced end position					
With cushioning	P	-27.5	-29	-37.5	-50.5
	E	-13	-9	-3.5	-6.5
	P1	-27.5	-29	-37.5	-50.5
	Y3	-24	-29	-36.5	-44
	1)	-24	-29	-36.5	-44
Retracted end position					
With cushioning	P	-20	-25.5	-39.5	-49.5
	E	-5.5	-5.5	-5.5	-5.5
	P1	-20	-25.5	-39.5	-49.5
	Y3	-15	-25.5	-38.5	-42
	1)	-15	-25.5	-38.5	-42

1) With reducing sleeve and next smallest shock absorber.



Mini slides DGSL-N, NPT

Technical data

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Shock absorber selection

Effective load m as a function of impact velocity v

The mini slide DGSL allows the shock absorber to be replaced and, in this way, the cushioning behaviour to be influenced (depending on the effective load).

This is done by removing the existing shock absorbers on the DGSL and replacing them with a smaller shock absorber as appropriate to the application (→ description below).

Graphs

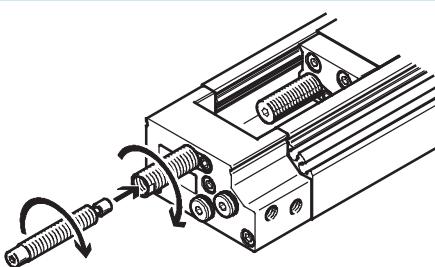
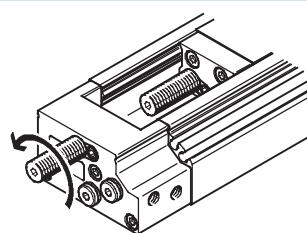
for selecting a suitable shock absorber as a function of the mounting position of the mini slide → from 13.

Ordering data

Shock absorbers DYSW, DYEF and reducing sleeve DAYH → 41.

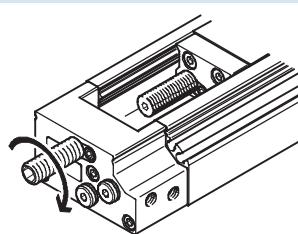
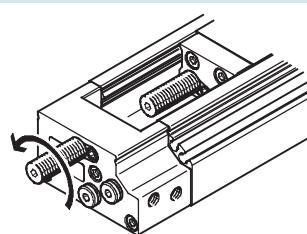
With smaller loads:

The next smallest shock absorber DYSW can be installed with the help of the reducing sleeve DAYH.



With very small loads:

The shock absorber DYEF can be installed in this case.



Selection example:

Existing drive:

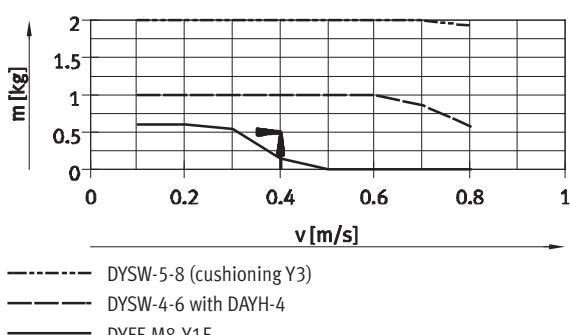
Mini slide: DGSL-N-10-...-Y3-A

Given:

Effective load: 500 g

Impact velocity: 0.4 m/s

Mounting position: Horizontal



Result:

The first cushioning curve, which is located above the point of intersection, is the most suitable for this case. Due to the low effective load of less than one kilogram, the cushioning characteristics are greatly improved by

replacing the shock absorber DYSW-5-8 integrated in the mini slide with the reducing sleeve DAYH-4 and the next smallest shock absorber DYSW-4-6.

Fundamentally, the following applies: shock absorbers must be loaded. Since the shock absorber DYSW-4-6 is more fully utilised in this case, both the service life of the shock absorber

and the cushioning characteristics are improved.

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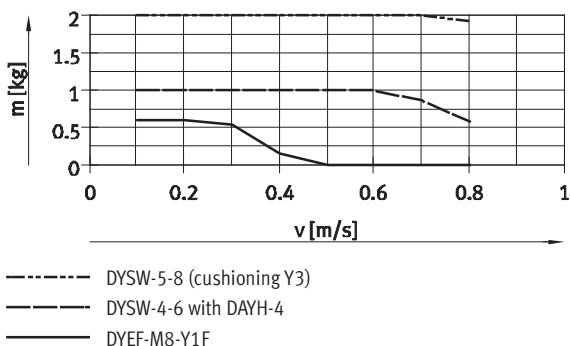
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Technical data

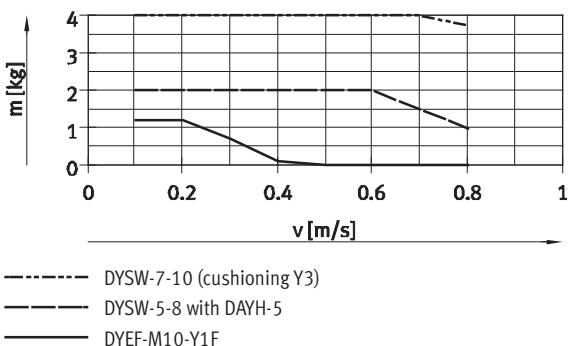
Shock absorber selection

Effective load m as a function of impact velocity v – horizontal mounting position

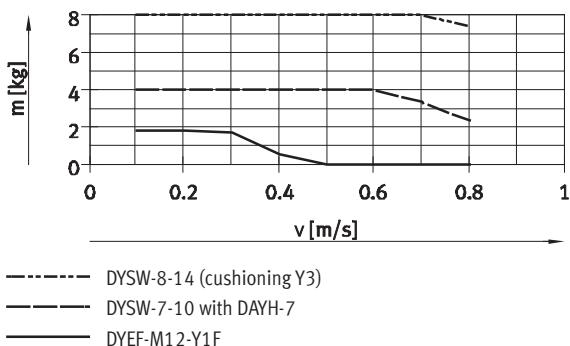
DGSL-N-10



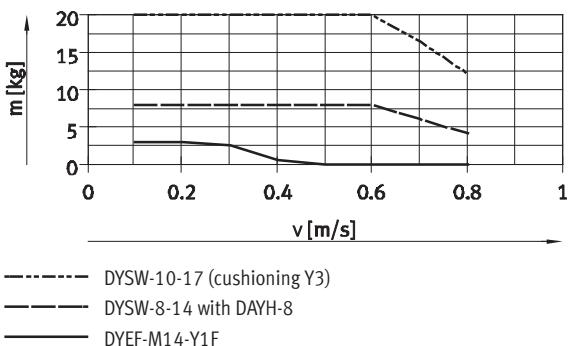
DGSL-N-12



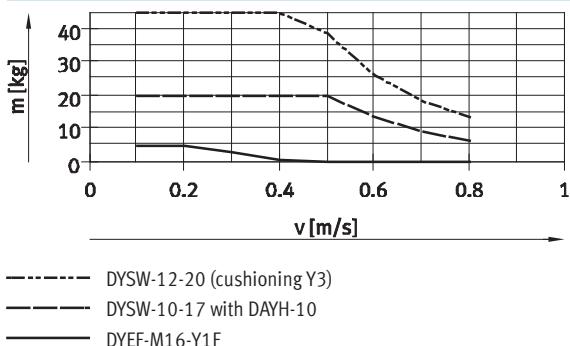
DGSL-N-16



DGSL-N-20



DGSL-N-25



Mini slides DGSL-N, NPT

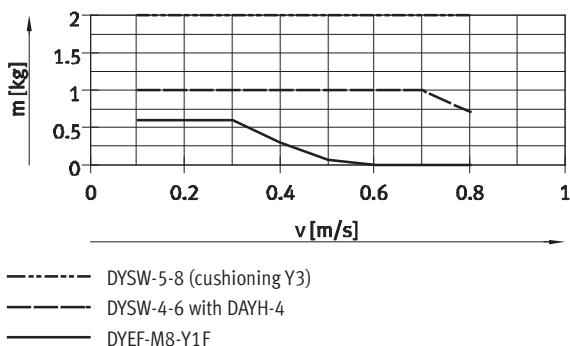
Technical data

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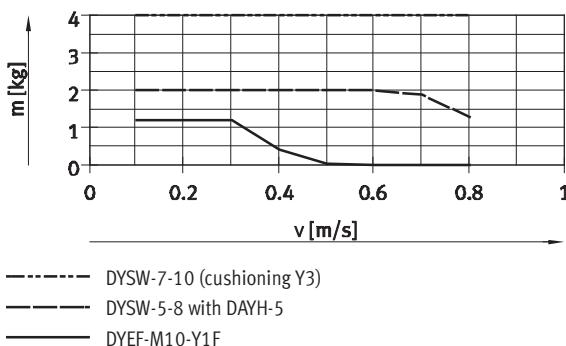
Shock absorber selection

Effective load m as a function of impact velocity v – vertical mounting position, effective load moving upwards

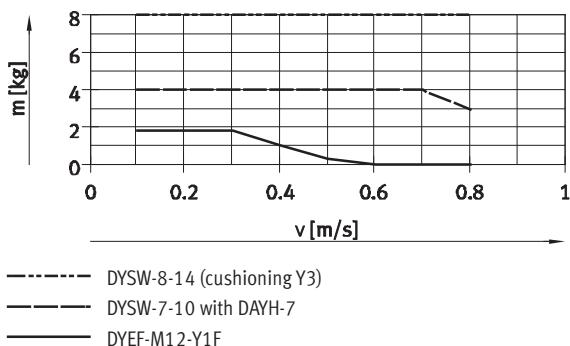
DGSL-N-10



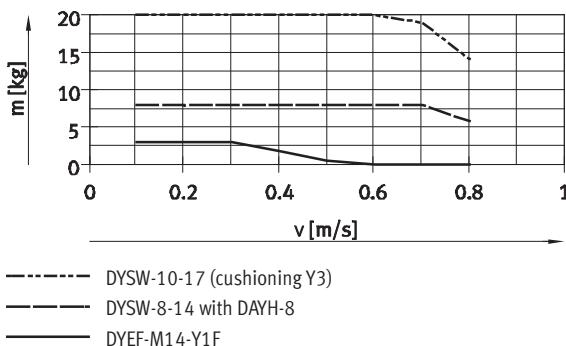
DGSL-N-12



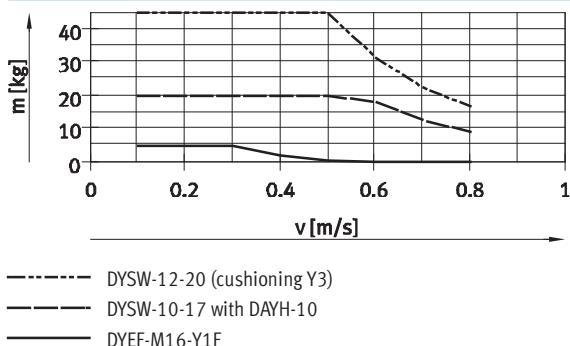
DGSL-N-16



DGSL-N-20



DGSL-N-25



Mini slides DGSL-N, NPT

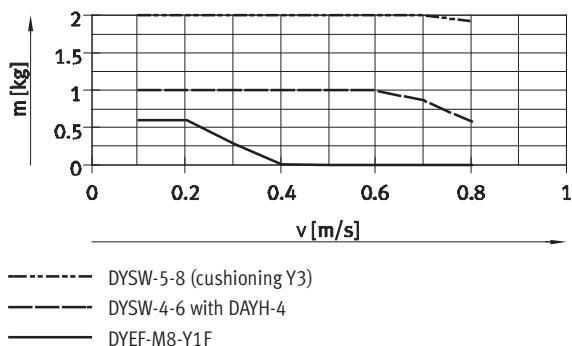
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Technical data

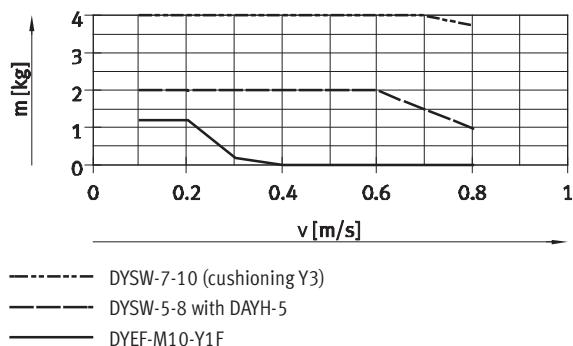
Shock absorber selection

Effective load m as a function of impact velocity v – vertical mounting position, effective load moving downwards

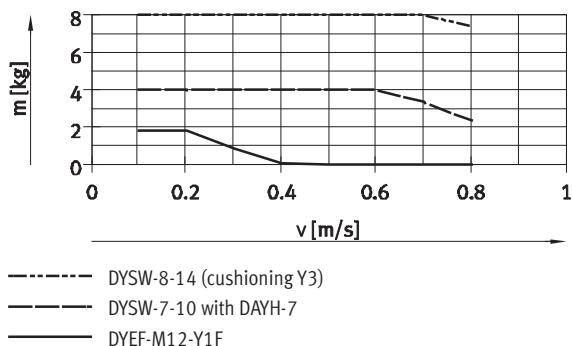
DGSL-N-10



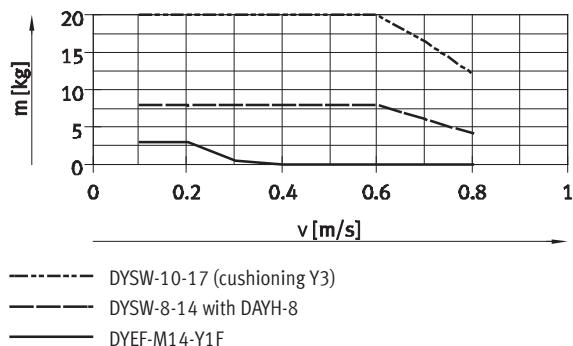
DGSL-N-12



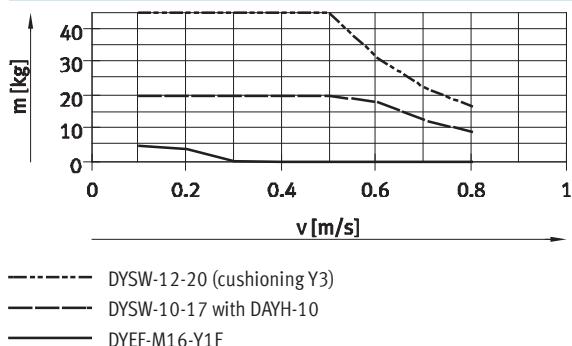
DGSL-N-16



DGSL-N-20



DGSL-N-25



Mini slides DGSL-N, NPT

Technical data

FESTO

Shock absorber selection

Travel time t as a function of effective load m and cushioning P/E – horizontal mounting position



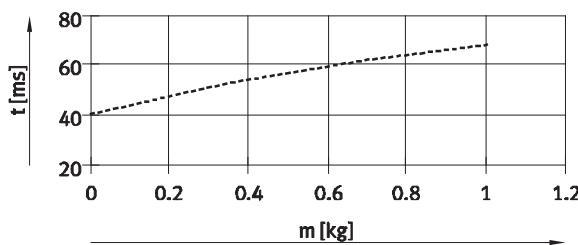
The values in the graphs are determined by calculation.
The travel time as a function of effective load must not be reduced below

the values shown, because the kinetic impact or residual energy in the end positions can result in damage to the drive.

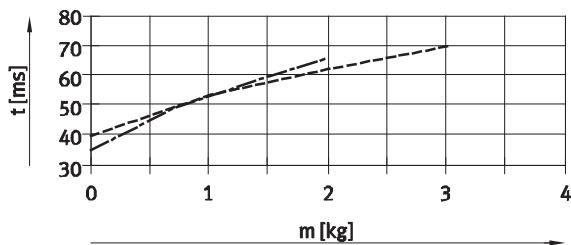
Vertical mounting position
→ 19

Advancing

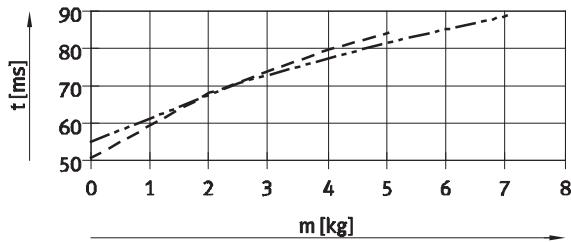
Stroke 10 mm, size 10



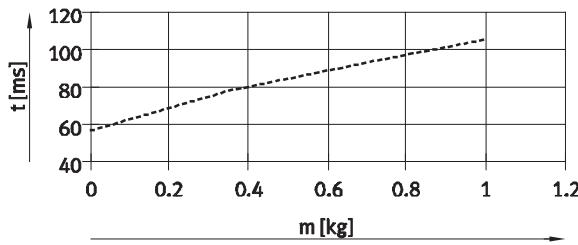
Stroke 10 mm, size 12 ... 16



Stroke 10 mm, size 20 ... 25

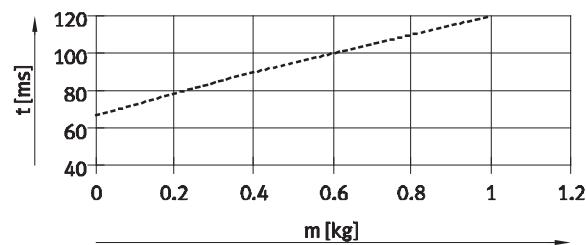


Stroke 30 mm, size 10

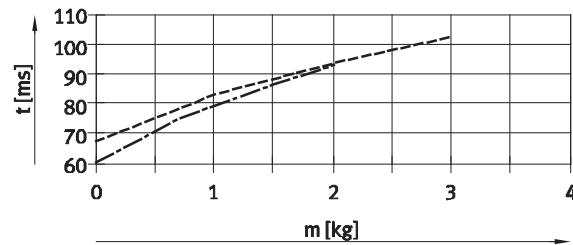


Retracting

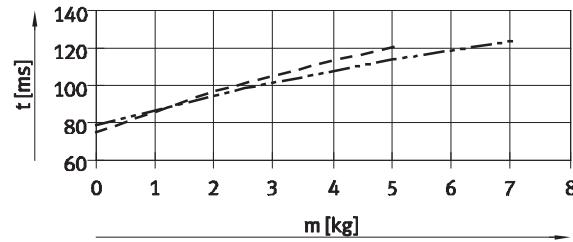
Stroke 10 mm, size 10



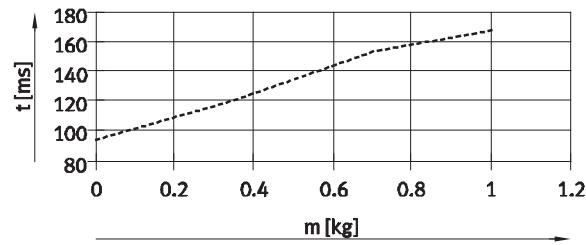
Stroke 10 mm, size 12 ... 16



Stroke 10 mm, size 20 ... 25



Stroke 30 mm, size 10



Legend:
 - - - DGSL-N-10
 - - - DGSL-N-12
 - - - DGSL-N-16
 - - - DGSL-N-20
 - - - DGSL-N-25

Mini slides DGSL-N, NPT

FESTO

Technical data

Shock absorber selection

Travel time t as a function of effective load m and cushioning P/E – horizontal mounting position



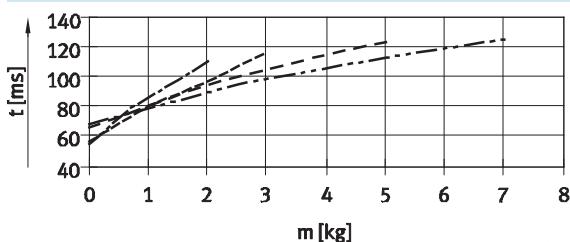
The values in the graphs are determined by calculation.
The travel time as a function of effective load must not be reduced below

the values shown, because the kinetic impact or residual energy in the end positions can result in damage to the drive.

Vertical mounting position
→ 19

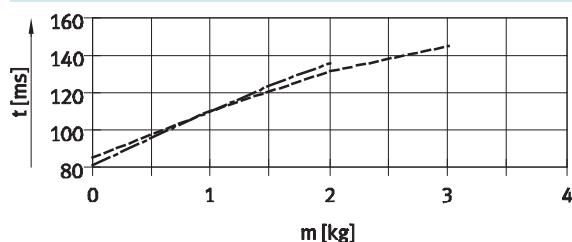
Advancing

Stroke 30 mm, size 12 ... 25

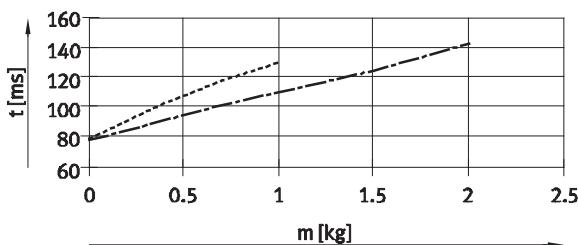


Retracting

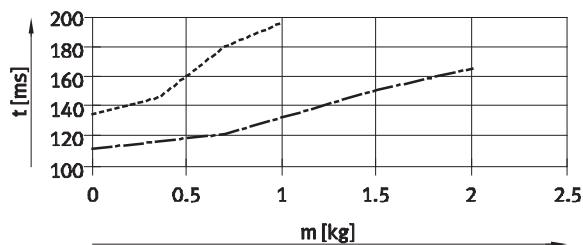
Stroke 30 mm, size 12 ... 16



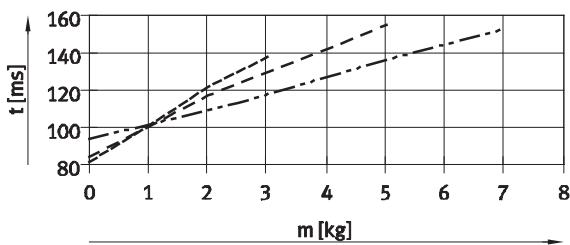
Stroke 50 mm, size 10 ... 12



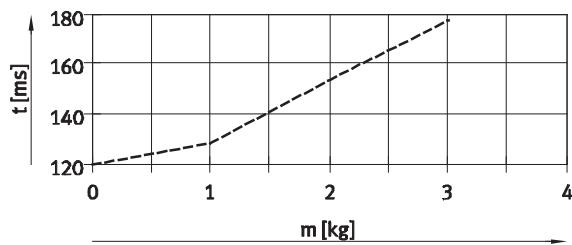
Stroke 50 mm, size 10 ... 12



Stroke 50 mm, size 16 ... 25

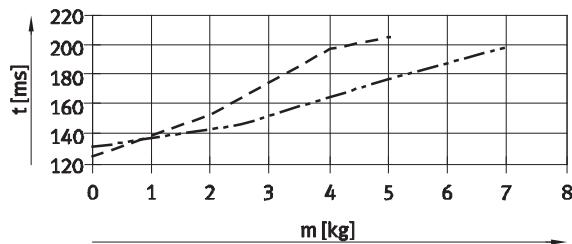


Stroke 50 mm, size 16 ... 25



Legend:
 - - - DGSL-N-10
 - - - DGSL-N-12
 - - - DGSL-N-16
 - - - DGSL-N-20
 - - - DGSL-N-25

Stroke 50 mm, size 20 ... 25



Mini slides DGSL-N, NPT

Technical data

FESTO

Shock absorber selection

Travel time t as a function of effective load m and cushioning P/E – horizontal mounting position



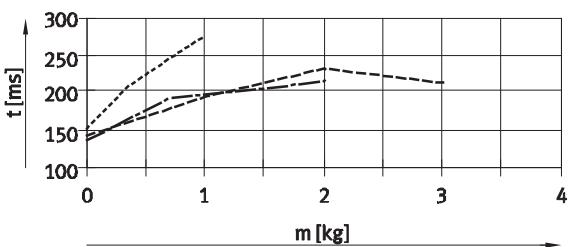
The values in the graphs are determined by calculation.
The travel time as a function of effective load must not be reduced below

the values shown, because the kinetic impact or residual energy in the end positions can result in damage to the drive.

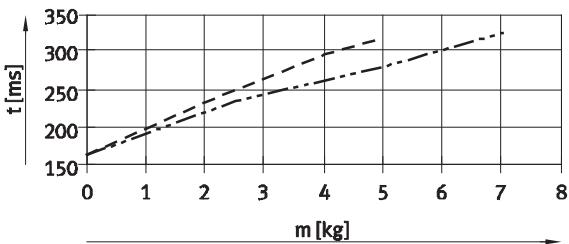
Vertical mounting position
→ 19

Advancing

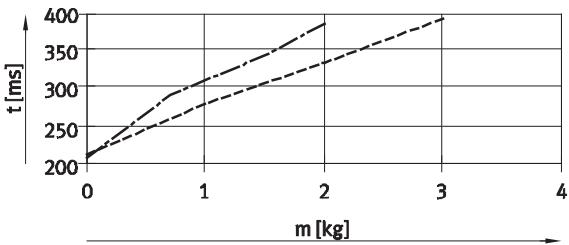
Stroke 100 mm, size 10 ... 16



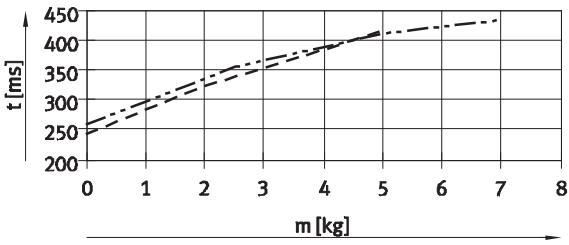
Stroke 100 mm, size 20 ... 25



Stroke 150 mm, size 12 ... 16



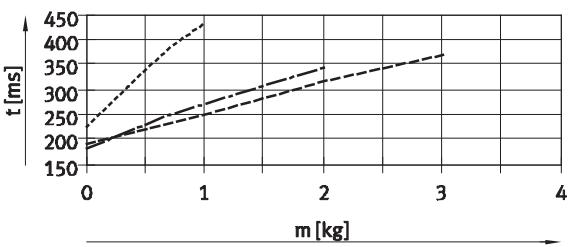
Stroke 150 mm, size 20 ... 25



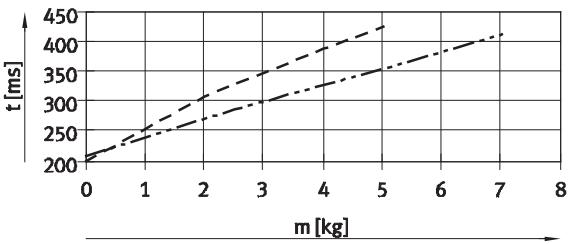
Legend:
 - - - DGSL-N-10
 - - - DGSL-N-12
 - - - DGSL-N-16
 - - - DGSL-N-20

Retracting

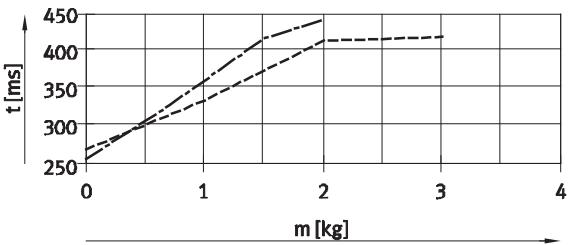
Stroke 100 mm, size 10 ... 16



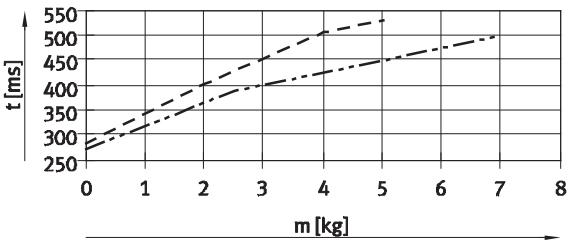
Stroke 100 mm, size 20 ... 25



Stroke 150 mm, size 12 ... 16



Stroke 150 mm, size 20 ... 25



Mini slides DGSL-N, NPT

FESTO

Technical data

Shock absorber selection

Travel time t as a function of effective load m and cushioning P/E – horizontal mounting position



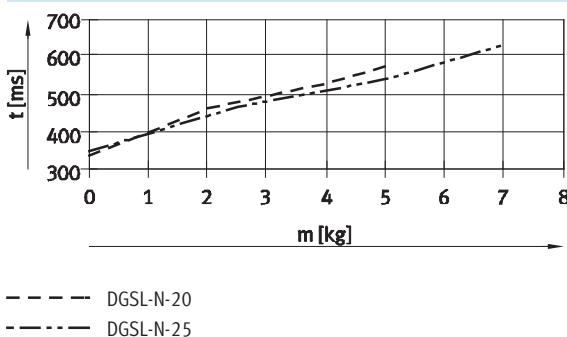
The values in the graphs are determined by calculation.
The travel time as a function of effective load must not be reduced below

the values shown, because the kinetic impact or residual energy in the end positions can result in damage to the drive.

Vertical mounting position
→ 19

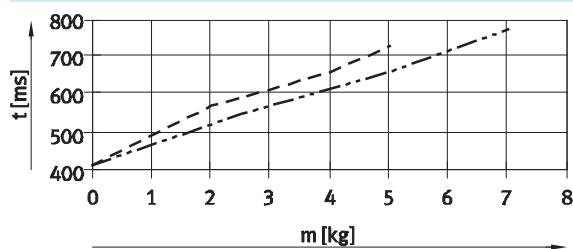
Advancing

Stroke 200 mm, size 20 ... 25



Retracting

Stroke 200 mm, size 20 ... 25



Vertical mounting position

The travel times for a vertical mounting position are calculated by multiplying the data ascertained for horizontal mounting position by a correction factor ka (advancing) and kr (retracting), see adjacent table.

Given:

Stroke = 200 mm

Size = 20

Effective load = 3 kg

Ascertained travel time th (horizontal),
see graph:

– Advancing = 500 ms

– Retracting = 600 ms

Calculated travel time tv (vertical):

– Advancing: $tv = th \times ka$

$$tv = 500 \text{ ms} \times 0.9 = 450 \text{ ms}$$

– Retracting: $tv = th \times kr$

$$tv = 600 \text{ ms} \times 1.1 = 660 \text{ ms}$$

Stroke [mm]	Size	Advancing (ka) ¹⁾	Retracting (kr)
10	10	0.95	1.1
	12, 16, 20, 25	0.95	1.2
30	10	0.95	1.1
	12, 16, 20, 25	0.95	1.2
50	10, 12	0.9	1.1
	16, 20, 25	1.1	1.2
100	10, 12, 16, 20, 25	1	1.1
150	12, 16, 20, 25	1	1.1
200	20, 25	0.9	1.1

1) Downward.

Mini slides DGSL-N, NPT

Technical data

FESTO

Shock absorber selection

Travel time t as a function of effective load m and cushioning P1 – horizontal mounting position



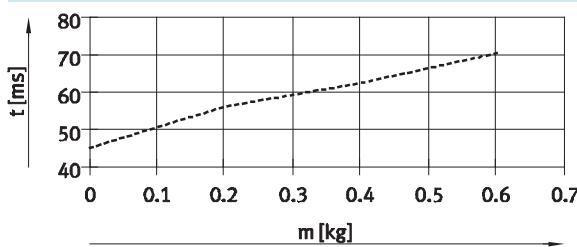
The values in the graphs are determined by calculation.
The travel time as a function of effective load must not be reduced below

the values shown, because the kinetic impact or residual energy in the end positions can result in damage to the drive.

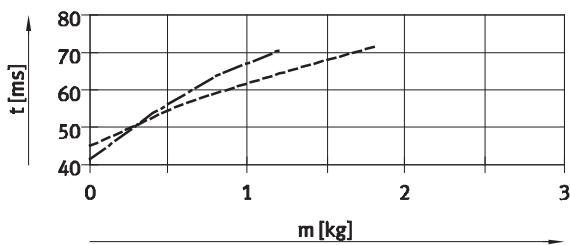
Vertical mounting position
→ 23

Advancing

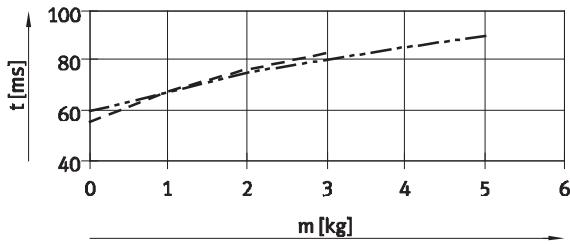
Stroke 10 mm, size 10



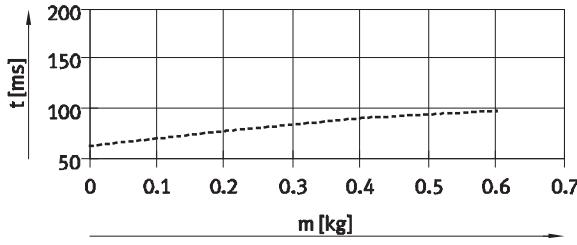
Stroke 10 mm, size 12 ... 16



Stroke 10 mm, size 20 ... 25



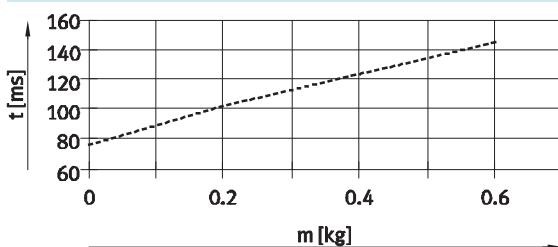
Stroke 30 mm, size 10



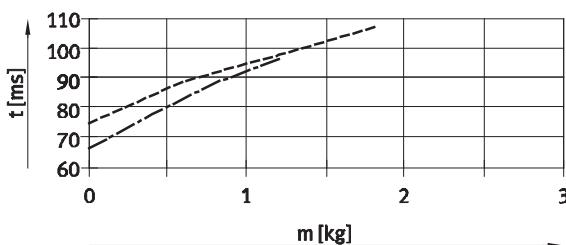
Legend:
 - - - DGSL-N-10 - - - DGSL-N-20
 - - - DGSL-N-12 - - - DGSL-N-25
 - - - DGSL-N-16

Retracting

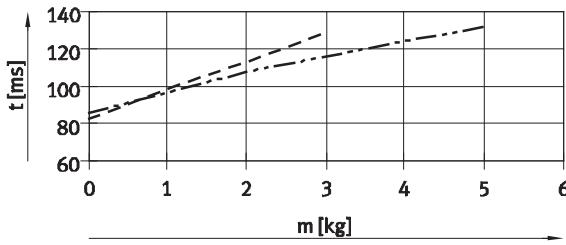
Stroke 10 mm, size 10



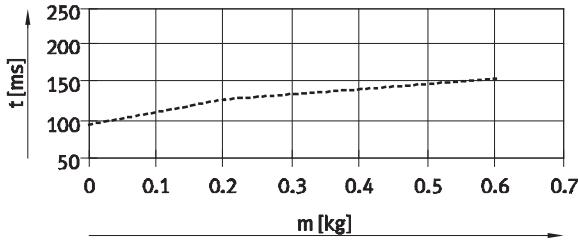
Stroke 10 mm, size 12 ... 16



Stroke 10 mm, size 20 ... 25



Stroke 30 mm, size 10



Mini slides DGSL-N, NPT

FESTO

Technical data

Shock absorber selection

Travel time t as a function of effective load m and cushioning P1 – horizontal mounting position



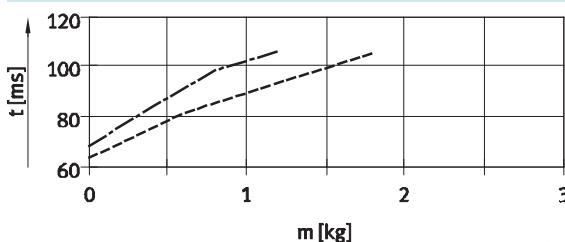
The values in the graphs are determined by calculation.
The travel time as a function of effective load must not be reduced below

the values shown, because the kinetic impact or residual energy in the end positions can result in damage to the drive.

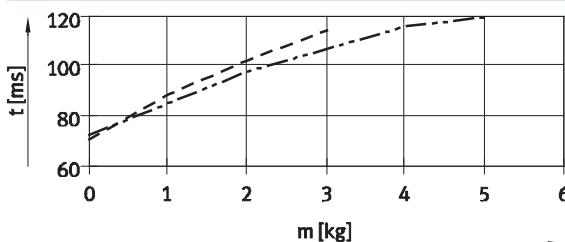
Vertical mounting position
→ 23

Advancing

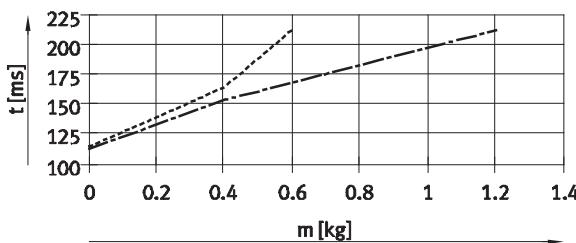
Stroke 30 mm, size 12 ... 16



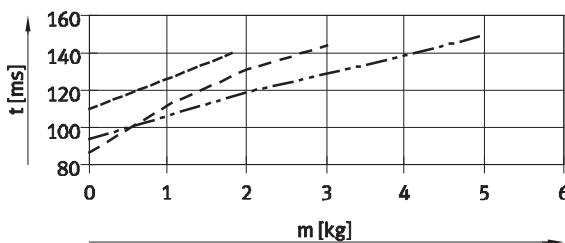
Stroke 30 mm, size 20 ... 25



Stroke 50 mm, size 10 ... 12



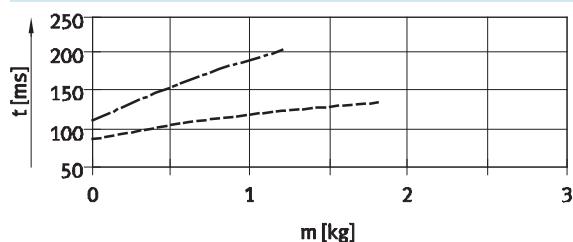
Stroke 50 mm, size 16 ... 25



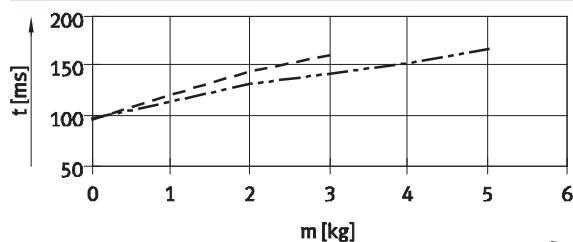
Legend:
 - - - DGSL-N-10
 - - - DGSL-N-12
 - - - DGSL-N-16
 - - - DGSL-N-20
 - - - DGSL-N-25

Retracting

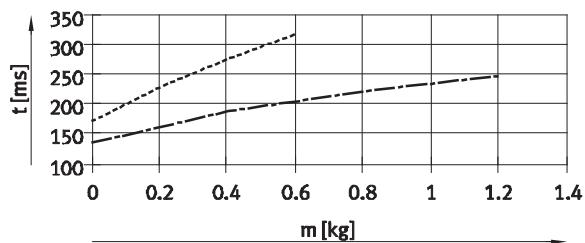
Stroke 30 mm, size 12 ... 16



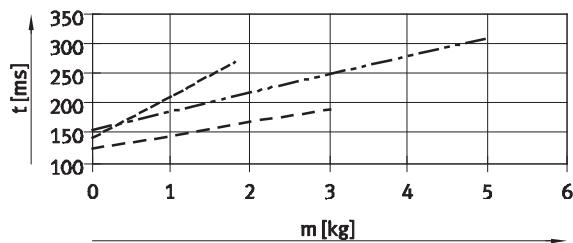
Stroke 30 mm, size 20 ... 25



Stroke 50 mm, size 10 ... 12



Stroke 50 mm, size 16 ... 25



Mini slides DGSL-N, NPT

Technical data

FESTO

Shock absorber selection

Travel time t as a function of effective load m and cushioning P1 – horizontal mounting position



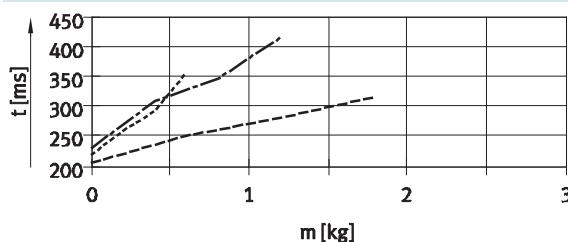
The values in the graphs are determined by calculation.
The travel time as a function of effective load must not be reduced below

the values shown, because the kinetic impact or residual energy in the end positions can result in damage to the drive.

Vertical mounting position
→ 23

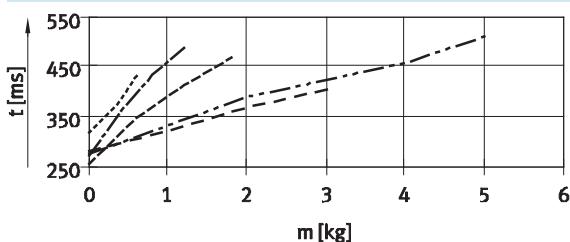
Advancing

Stroke 100 mm, size 10 ... 16

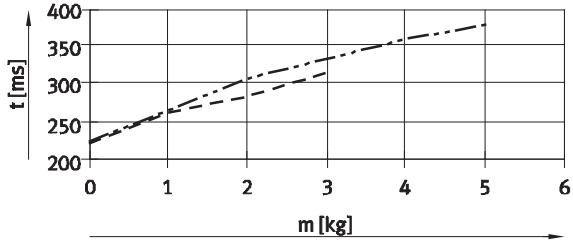


Retracting

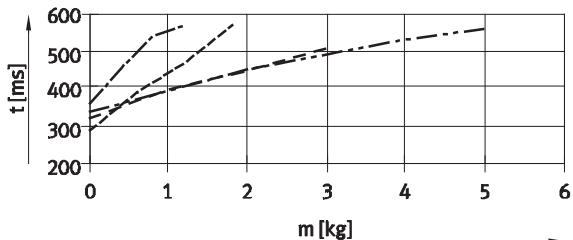
Stroke 100 mm, size 10 ... 25



Stroke 100 mm, size 20 ... 25

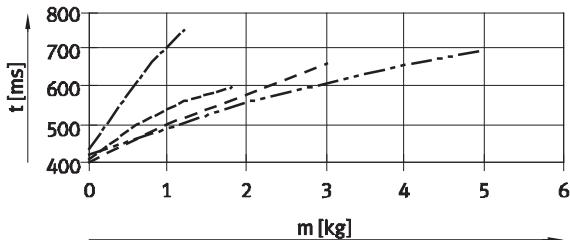


Stroke 150 mm, size 12 ... 25



----- DGSL-N-10
— DGSL-N-12
- - - DGSL-N-16
- - - DGSL-N-20
- - - DGSL-N-25

Stroke 150 mm, size 12 ... 25



Mini slides DGSL-N, NPT

FESTO

Technical data

Shock absorber selection

Travel time t as a function of effective load m and cushioning P1 – horizontal mounting position



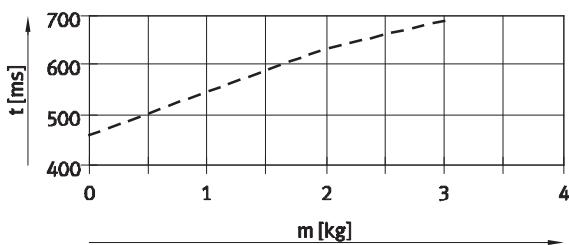
The values in the graphs are determined by calculation.
The travel time as a function of effective load must not be reduced below

the values shown, because the kinetic impact or residual energy in the end positions can result in damage to the drive.

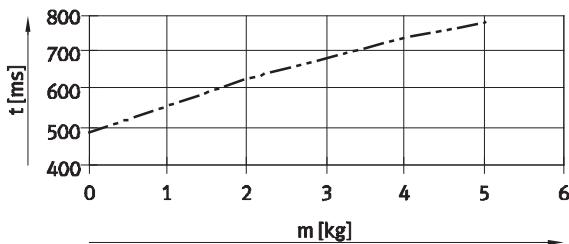
Vertical mounting position
→ 23

Advancing

Stroke 200 mm, size 20



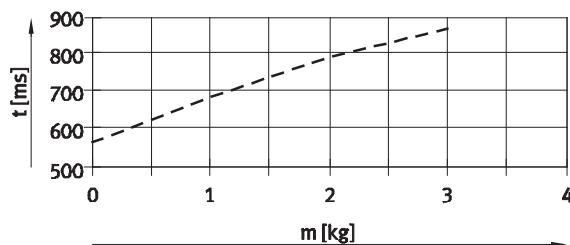
Stroke 200 mm, size 25



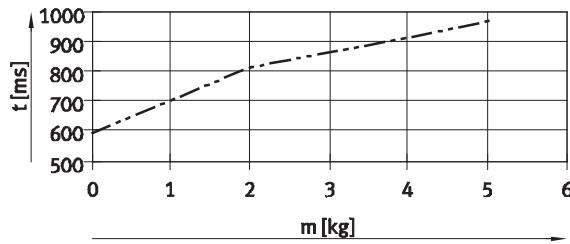
— DGSL-N-20
— DGSL-N-25

Retracting

Stroke 200 mm, size 20



Stroke 200 mm, size 25



Vertical mounting position

The travel times for a vertical mounting position are calculated by multiplying the data ascertained for horizontal mounting position by a correction factor ka (advancing) and kr (retracting), see adjacent table.

Given:

Stroke = 200 mm
Size = 20
Effective load = 2 kg
Ascertained travel time th (horizontal), see graph:
– Advancing = 640 ms
– Retracting = 780 ms
Calculated travel time tv (vertical):
– Advancing: $tv = th \times ka$
 $tv = 640 \text{ ms} \times 0.9 = 576 \text{ ms}$
– Retracting: $tv = th \times kr$
 $tv = 780 \text{ ms} \times 1.1 = 858 \text{ ms}$

Stroke [mm]	Size	Advancing (ka) ¹⁾	Retracting (kr)
10	10	1	1.1
	12, 16, 20, 25	1.1	1.2
30	10	1	1.1
	12, 16, 20, 25	1.1	1.2
50	10, 12	1	1.1
	16, 20, 25	0.9	1.1
100	10, 12, 16, 20, 25	0.95	1.1
150	12, 16, 20, 25	0.95	1.1
200	20, 25	0.9	1.1

1) Downward.

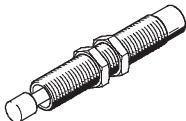
Mini slides DGSL-N, NPT

Technical data

FESTO

Shock absorber selection

Travel time t as a function of effective load m and cushioning Y3 – horizontal mounting position



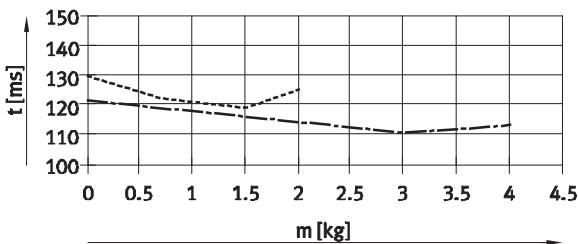
The values in the graphs are determined by calculation.
The travel time as a function of effective load must not be reduced below

the values shown, because the kinetic impact or residual energy in the end positions can result in damage to the drive.

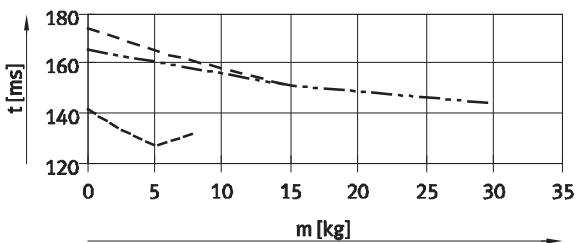
Vertical mounting position
→ 25

Advancing

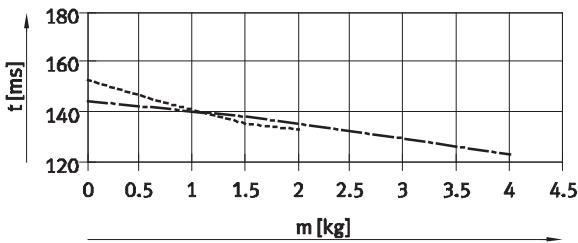
Stroke 30 mm, size 10 ... 12



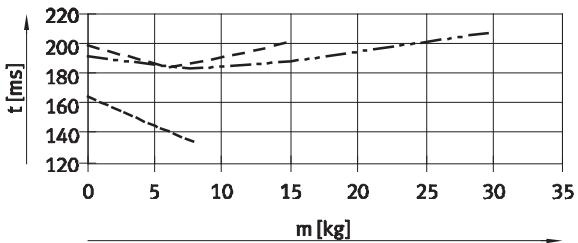
Stroke 30 mm, size 16 ... 25



Stroke 50 mm, size 10 ... 12



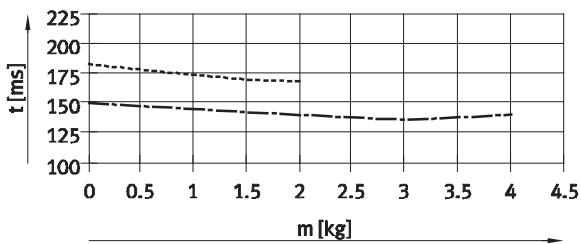
Stroke 50 mm, size 16 ... 25



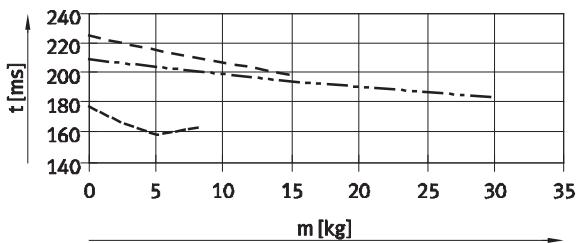
Legend:
 - - - DGSL-N-10
 - - - DGSL-N-12
 - - - DGSL-N-16
 - - - DGSL-N-20

Retracting

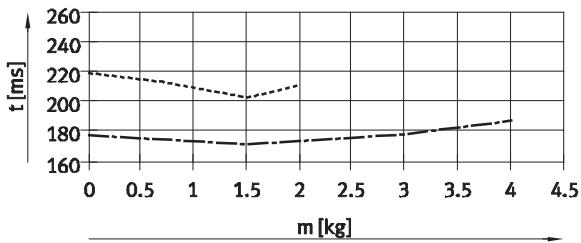
Stroke 30 mm, size 10 ... 12



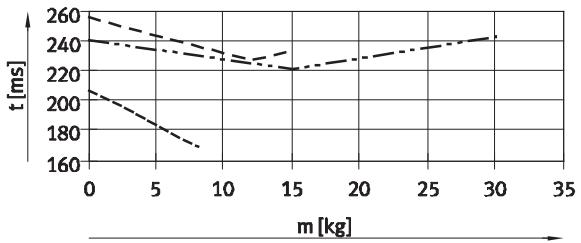
Stroke 30 mm, size 16 ... 25



Stroke 50 mm, size 10 ... 12



Stroke 50 mm, size 16 ... 25



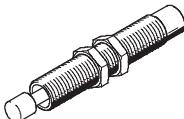
Mini slides DGSL-N, NPT

FESTO

Technical data

Shock absorber selection

Travel time t as a function of effective load m and cushioning Y3 – horizontal mounting position



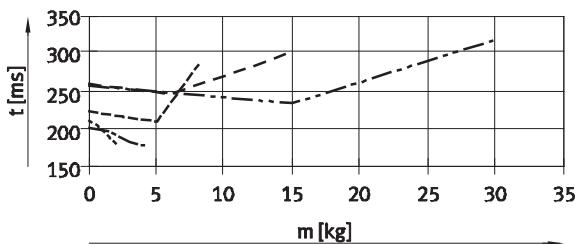
The values in the graphs are determined by calculation.
The travel time as a function of effective load must not be reduced below

the values shown, because the kinetic impact or residual energy in the end positions can result in damage to the drive.

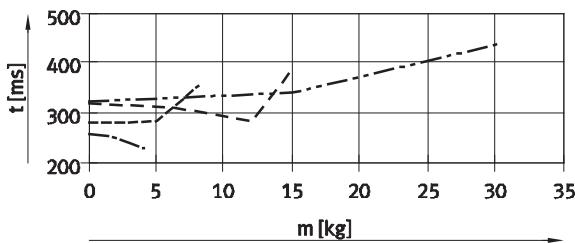
Vertical mounting position
→ 25

Advancing

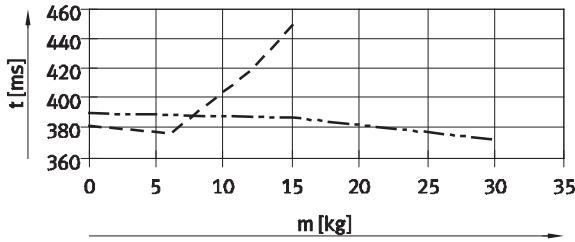
Stroke 100 mm, size 10 ... 25



Stroke 150 mm, size 12 ... 25



Stroke 200 mm, size 20 ... 25



— DGSL-N-10
— DGSL-N-12
— DGSL-N-16
— DGSL-N-20
— DGSL-N-25

Vertical mounting position

The travel times for a vertical mounting position are calculated by multiplying the data ascertained for horizontal mounting position by a correction factor ka (advancing) and kr (retracting), see adjacent table.

Given:

Stroke = 200 mm
Size = 20
Effective load = 10 kg
Ascertained travel time th (horizontal), see graph:
– Advancing = 405 ms
– Retracting = 490 ms
Calculated travel time tv (vertical):
– Advancing: $tv = th \times ka$
 $tv = 405 \text{ ms} \times 0.9 = 365 \text{ ms}$
– Retracting: $tv = th \times kr$
 $tv = 490 \text{ ms} \times 1.5 = 735 \text{ ms}$

Stroke [mm]	Size	Advancing (ka) ¹⁾	Retracting (kr)
30	10, 12	0.95	1.2
	16, 20, 25	0.9	1.5
50	10, 12	0.9	1.5
	16, 20, 25	0.9	1.5
100	10, 12, 16, 20, 25	0.8	1.5
150	12, 16, 20, 25	0.9	1.5
200	20, 25	0.9	1.5

1) Downward.

Mini slides DGSL-N, NPT

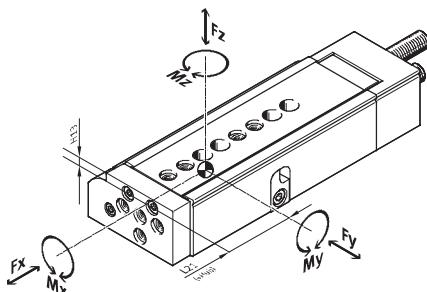
Technical data

FESTO

Dynamic characteristic load values

Torques are indicated with reference to the centre of the guide.

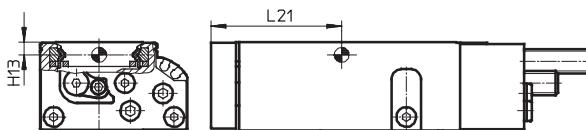
These values must not be exceeded during dynamic operation. Special attention must be paid to the cushioning phase.



If the drive is simultaneously subjected to several of the indicated forces and torques, the following equation must be satisfied in addition to the indicated maximum loads:

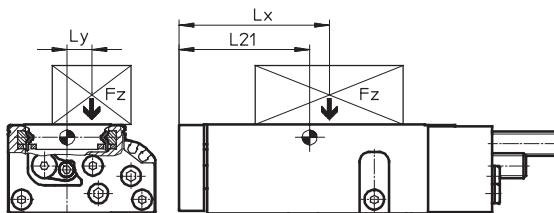
$$\frac{|F_y|}{F_{y\max.}} + \frac{|F_z|}{F_{z\max.}} + \frac{|M_x|}{M_{x\max.}} + \frac{|M_y|}{M_{y\max.}} + \frac{|M_z|}{M_{z\max.}} \leq 1$$

Position of the guide centre



Calculation example

Given:



Mini slide = DGSL-N-10
Stroke length = 80 mm
Lever arm L_x = 50 mm
Lever arm L_y = 30 mm
Load F_z = 0.8 kg
Acceleration a = 0 m/s^2

To be calculated:

F_y, F_z, M_x, M_y, M_z
and
verification of operation
with combined load

Solution:

$$L21 = 83 \text{ mm from table}$$

$$F_y = 0 \text{ N}$$

$$F_z = m \times g \\ = 0.8 \text{ kg} \times 9.81 \text{ m/s}^2 = 7.848 \text{ N}$$

$$M_x = m \times g \times L_y \\ = 0.8 \text{ kg} \times 9.81 \text{ m/s}^2 \times 30 \text{ mm} = 0.236 \text{ Nm}$$

$$M_y = m \times g \times [(L21+\text{stroke}) \cdot L_x] \\ = 0.8 \text{ kg} \times 9.81 \text{ m/s}^2 \times [(83 \text{ mm} + 80 \text{ mm}) - 50 \text{ mm}] = 0.886 \text{ Nm}$$

$$M_z = 0 \text{ Nm}$$

Combined load:

$$\frac{|F_y|}{F_{y\max.}} + \frac{|F_z|}{F_{z\max.}} + \frac{|M_x|}{M_{x\max.}} + \frac{|M_y|}{M_{y\max.}} + \frac{|M_z|}{M_{z\max.}} \\ = 0 + \frac{7.848 \text{ N}}{1200 \text{ N}} + \frac{0.236 \text{ Nm}}{18 \text{ Nm}} + \frac{0.886 \text{ Nm}}{12 \text{ Nm}} + 0 = 0.094 \leq 1$$

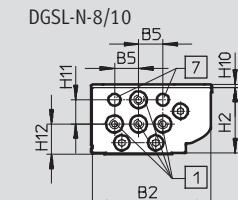
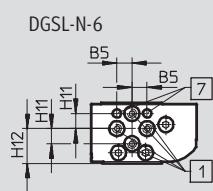
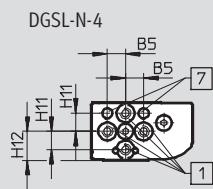
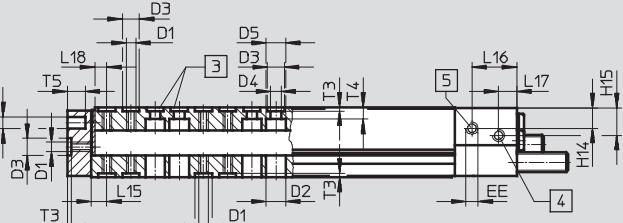
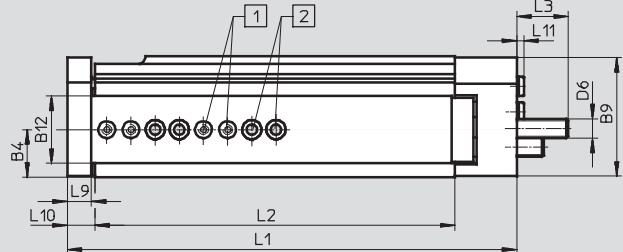
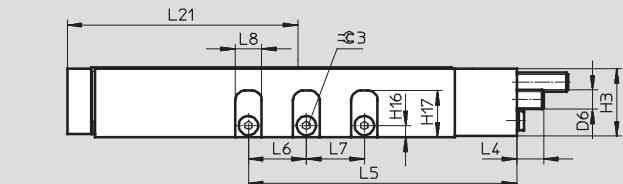
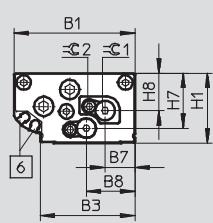
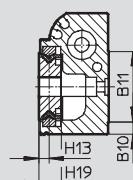
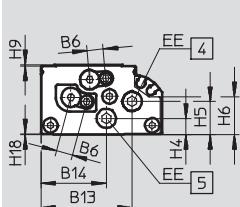
Mini slides DGSL-N, NPT

Technical data

FESTO

Dimensions

Size 10



[1] Mounting thread (centring sleeves included in the scope of delivery)

[2] Through-holes for mounting the drive

[4] Supply port, advancing

[3] Centring holes (centring sleeves included in the scope of delivery)

[5] Supply port, retracting

[6] Slots for proximity sensor SME/SMT-10

[7] Centring hole

General dimensions

Size	B1	B2	B3	B4	B5	B6	B7	B8	B9	B10	B11	B12	B13	B14	D1
10	50	49	39.2	19.65	10	6.8	12.35	20.1	49	5	29.2	28	37.7	27	M4

Size	D2	D3	D4	D5	D6	D7	EE ¹⁾	H1	H2	H3	H4	H5	H6	H7	H8
10	8	7 ^{H7}	4.3	8	M8x1	5 ^{H7}	M5	29	27.1	28	6.8	13.8	15.8	22.8	15.5

Size	H9	H10	H11	H12	H13	H14	H15	H16	H17	H18	H19	T3	T4	T5	=C 2 ¹⁾	=C 3
10	0.6	1.4	10	12.5	4.2	8.75	11.75	4.8	19.25	0.4	9	1.6	5	7.5	2.5	3

1) Suitable for 10-32 UNF

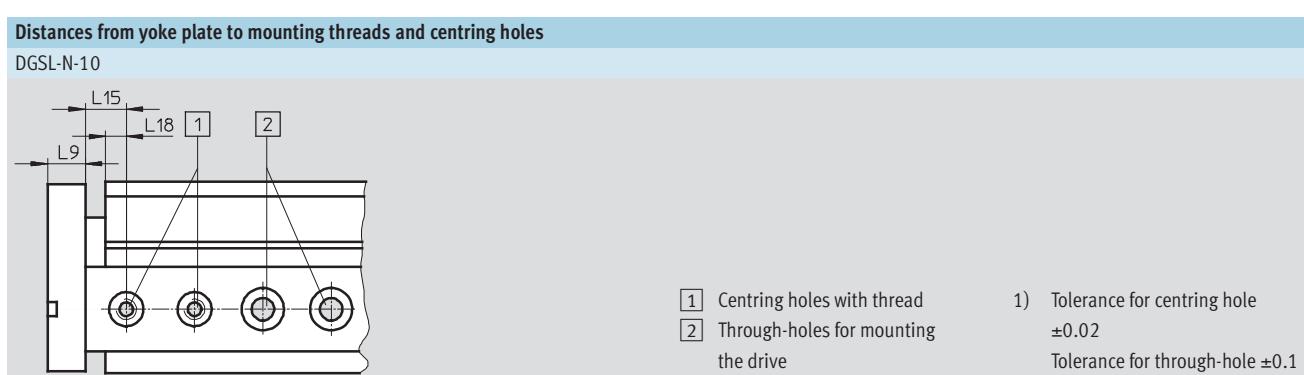
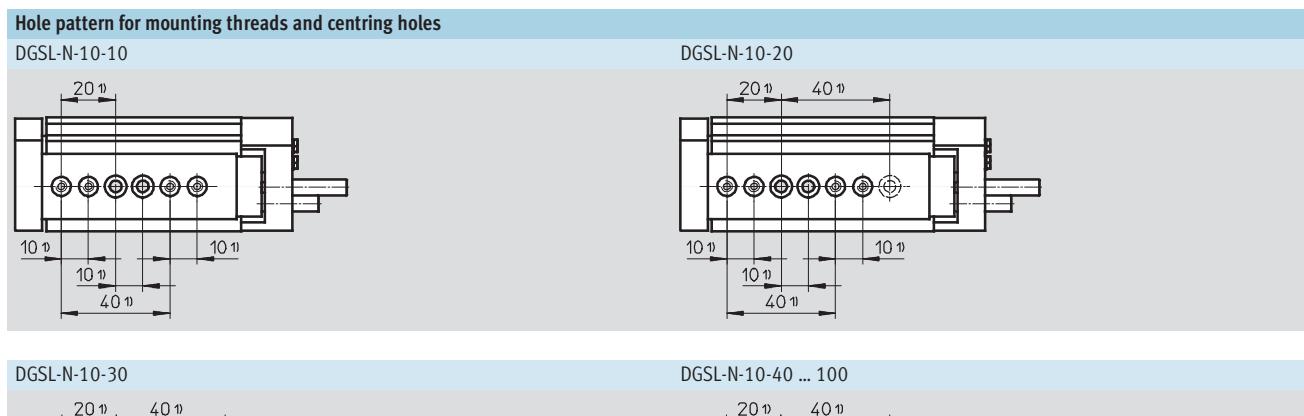
Mini slides DGSL-N, NPT

FESTO

Technical data

Size	Stroke	L1	L2	L5	L6	L7	L8	L9	L10	L11	L15 ±0.05	L16	L17	L18 ±0.05	L21
10	10	103.1	66	41.3	–	–	11	10	11.6	2.5	6.4	18.5	7.5	5	43
	20	112.8	75.7	51											46
	30	122.8	85.7	61											51
	40	132.8	95.7	71											56
	50	142.8	105.7	81											61
	80	186.2	149.1	111		24									83
	100	206.2	169.1	131		24		24							96

Size	Cushioning	L3 max.	L4 max.	=C 1	
				For adjusting the cushioning stroke	For adjusting the end position
10	P	22.8	12.5	–	2.5
	E	8.8	0	–	2.5
	P1	20.5	10.2	2.5	5
	Y3	25.5	14.9	–	2.5



Mini slides DGSL-N, NPT

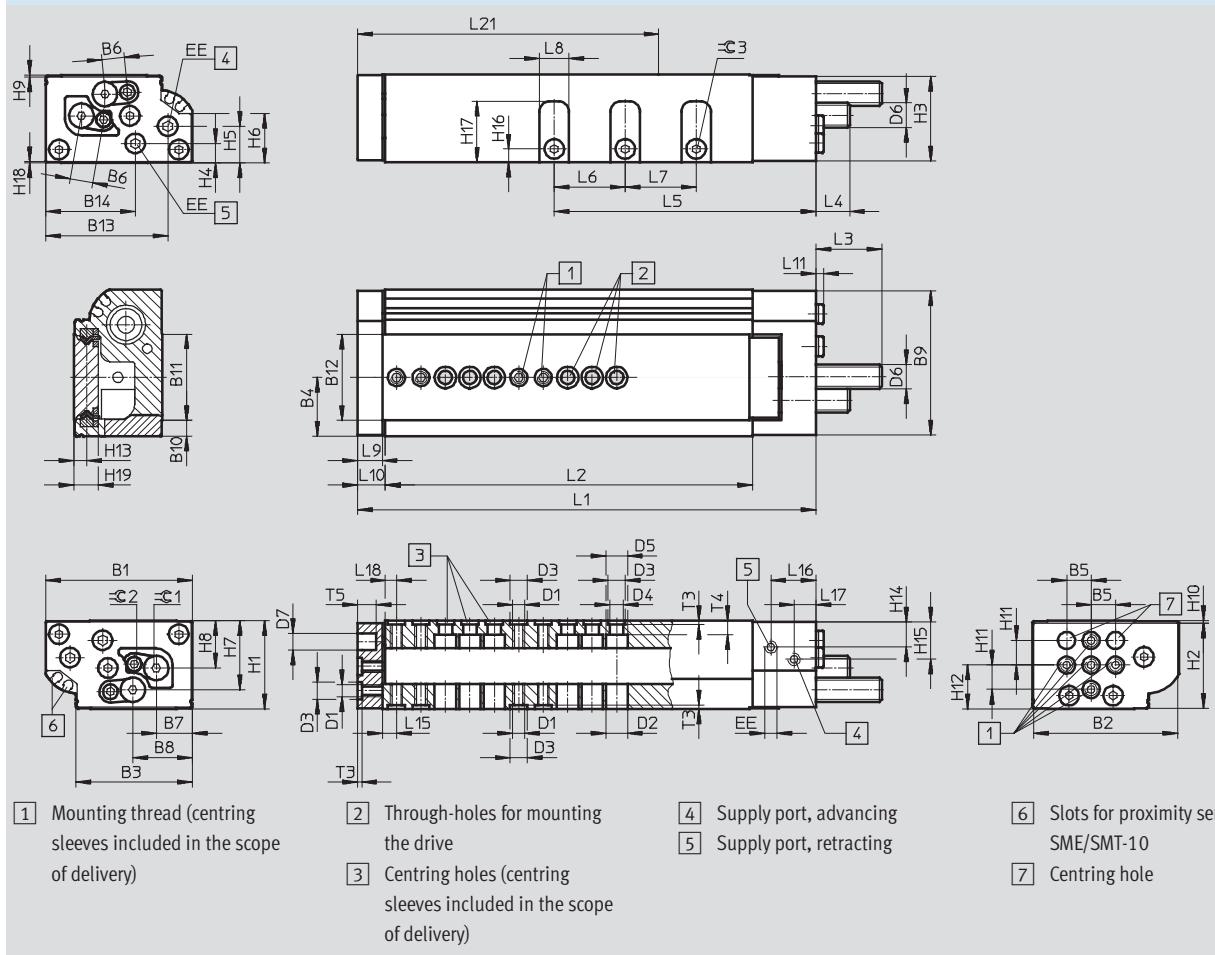
FESTO

Technical data

Dimensions

Size 12/16

Download CAD data → www.festo.com



General dimensions

Size	B1	B2	B3	B4	B5	B6	B7	B8	B9	B10	B11	B12	B13	B14	D1	
12	60	59	47.6	24	10	9.2	14.7	24.3	59	6.4	35.35	35.2	50	36.7	M5	
16	66	65	53.5	26.7	10	11.1	16.7	27.5	65	7.75	37.9	38	50.4	36.7	M5	
Size	D2	D3	D4	D5	D6	D7	EE ¹⁾	H1	H2	H3	H4	H5	H6	H7	H8	
12	8.8	7 ^{H7}	5.5	8.8	M10x1	8 ^{H7}	M5	36	34.8	34.7	8	15.1	20.35	28.2	19.3	
16	8.8	7 ^{H7}	5.5	9.2	M12x1	8 ^{H7}	M5	40	38	39	8.5	16.7	20.6	31.7	20.8	
Size	H9	H10	H11	H12	H13	H14	H15	H16	H17	H18	H19	T3 +0.1	T4	T5	=C 2	=C 3
12	0.8	0.95	10	17.9	5.2	10.75	15.75	5.5	24.9	0.5	10	1.6	5.6	7.5	3	3
16	0.5	1.5	10	20	6.4	10.5	16.7	7	26.6	0.5	12.4	1.6	6.1	9	4	4

1) Suitable for 10-32 UNF

Mini slides DGSL-N, NPT

FESTO

Technical data

Stroke-dependent dimensions

Size	Stroke	L1	L2	L5	L6	L7	L8	L9	L10	L11	L15 ±0.05	L16	L17	L18 ±0.05	L21
12	10	106.2	68.6	42.4	29	–	–	12	10	11.6	2.5	5.8	18.5	9	4.5
	20	116.2	78.6	52.4											44
	30	126.2	88.6	62.4											49
	40	136.2	98.6	72.4											54
	50	146.2	108.6	82.4											59
	80	197.6	160	112.4											64
	100	217.6	180	132.4			29								88
	150	267.6	230	182.4											98
16	10	124.1	82.5	45	35	–	–	14	12	13.6	2.5	6.8	21	10	5.5
	20	134.6	93	54.6											54
	30	144.6	103	64.6											59
	40	154.6	113	74.6											64
	50	164.6	123	84.6											69
	80	194.6	153	114.6											74
	100	243.6	202	134.6											89
	150	293.6	252	184.6											113
															138

Cushioning-dependent dimensions

Size	Cushioning	L3 max.	L4 max.	=C 1	
				For adjusting the cushioning stroke	For adjusting the end position
12	P	28.1	14.9	–	3
	E	8.8	0	–	3
	P1	26	12.8	3	6
	Y3	36.9	23.7	–	3
16	P	42.3	26.1	–	4
	E	8.8	0	–	4
	P1	40	23.8	4	8
	Y3	51.9	35.7	–	4

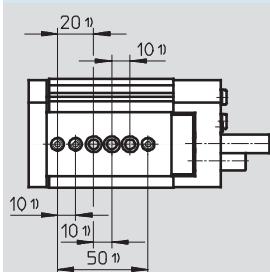
Mini slides DGSL-N, NPT

Technical data

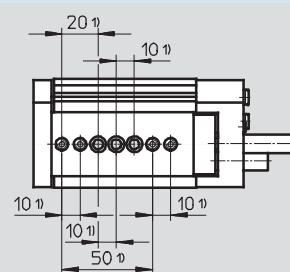
FESTO

Hole pattern for mounting threads and centring holes

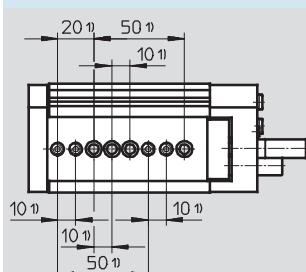
DGSL-N-12-10



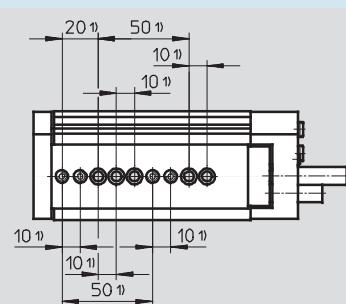
DGSL-N-12-20



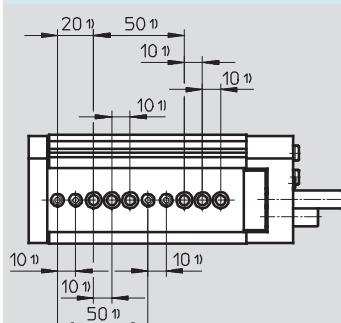
DGSL-N-12-30



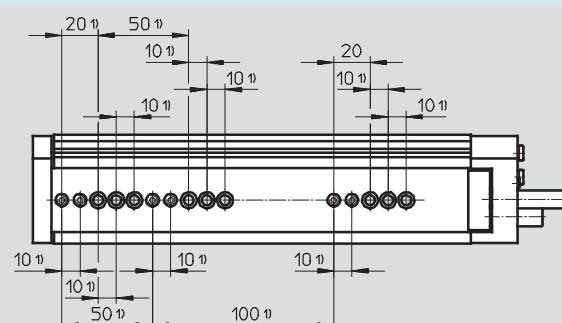
DGSL-N-12-40



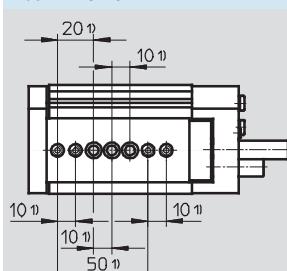
DGSL-N-12-50 ... 100



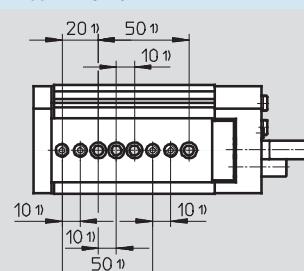
DGSL-N-12-150



DGSL-N-16-10



DGSL-N-16-20



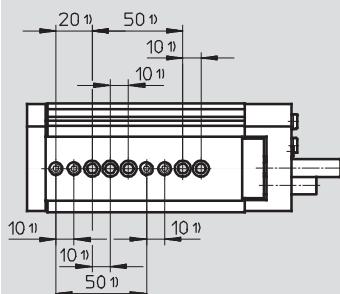
Mini slides DGSL-N, NPT

FESTO

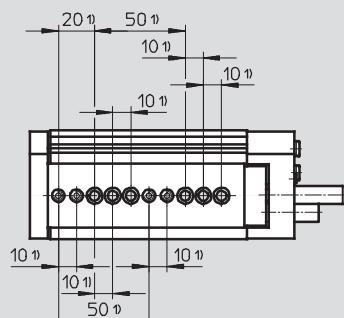
Technical data

Hole pattern for mounting threads and centring holes

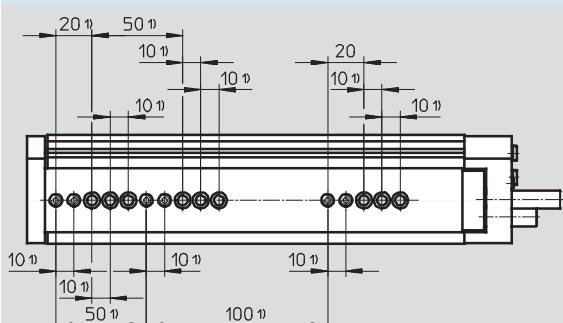
DGSL-N-16-30



DGSL-N-16-40 ... 100

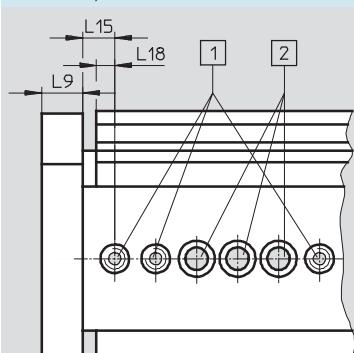


DGSL-N-16-150



Distances from yoke plate to mounting threads and centring holes

DGSL-N-12/16



[1] Centring holes with thread

[2] Through-holes for mounting the drive

1) Tolerance for centring hole ± 0.02

Tolerance for through-hole ± 0.1

Size	L9	L15 ± 0.05	L18
12	10	5.8	4.5
16	12	6.8	5.5

Mini slides DGSL-N, NPT

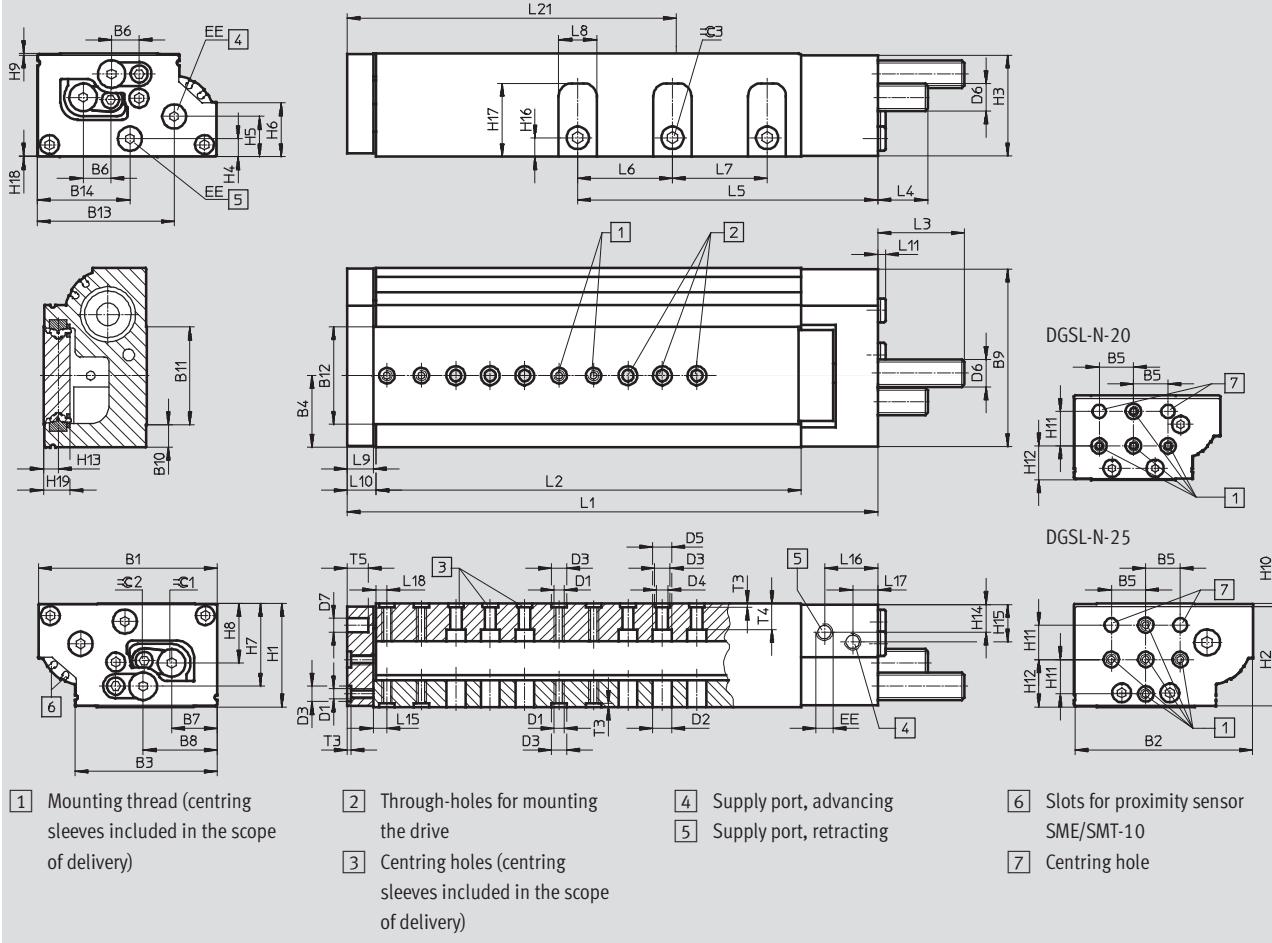
FESTO

Technical data

Dimensions

Size 20/25

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General dimensions

Size	B1	B2	B3	B4	B5	B6	B7	B8	B9	B10	B11	B12	B13	B14	D1
20	85	84	68.85	34.5	20	14	21.4	36.35	83.4	10	48.9	49.2	64.1	48.6	M6
25	104	103	82.6	41.6	20	16.2	26.4	43.1	103	13.25	56.5	56.7	79.4	53.7	M6

Size	D2 ∅	D3 ∅	D4 ∅	D5 ∅	D6	D7 ∅	EE	H1 ±0.08	H2	H3	H4	H5	H6	H7	H8
20	11	9 ^{H7}	6.6	11	M14x1	8 ^{H7}	1/8 NPT	49	46.5	47.7	10.3	20.6	23.2	38.2	26.1
25	11	9 ^{H7}	6.6	11	M16x1	8 ^{H7}	1/8 NPT	60	57.5	58.5	10.5	23.4	31.2	48	34.5

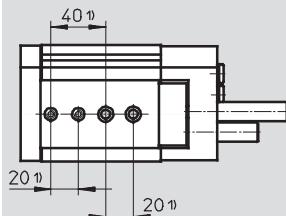
Size	H9	H10	H11	H12	H13	H14	H15	H16	H17	H18	H19	T3 +0.1	T4	T5	=C 2	=C 3
20	0.5	2	20	19.6	7.55	14.7	14.7	10	33.3	0.8	14.5	2.1	8.8	10	4	5
25	1	2	20	27.5	8.55	16.6	22.2	11	42.7	0.5	15.5	2.1	15.1	12	5	6

Mini slides DGSL-N, NPT

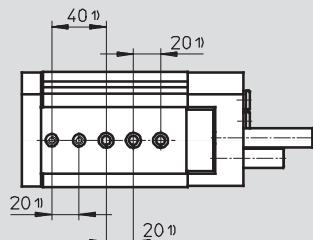
Technical data

Hole pattern for mounting threads and centring holes

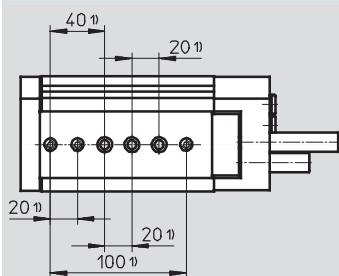
DGSL-N-20-10/20



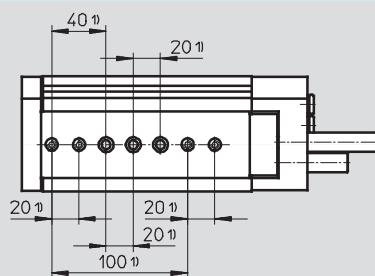
DGSL-N-20-30/40



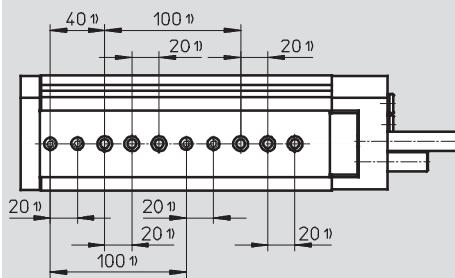
DGSL-N-20-50



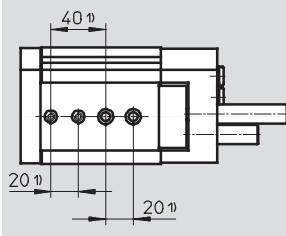
DGSL-N-20-80



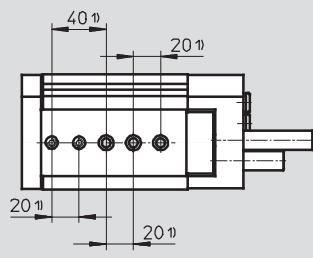
DGSL-N-20-100 ... 200



DGSL-N-25-10



DGSL-N-25-20



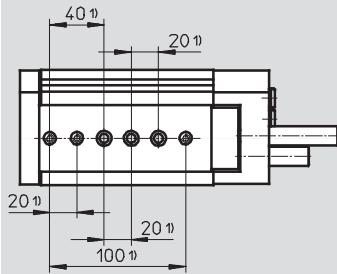
Mini slides DGSL-N, NPT

FESTO

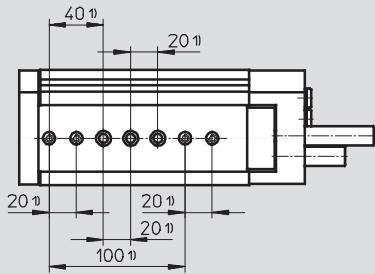
Technical data

Hole pattern for mounting threads and centring holes

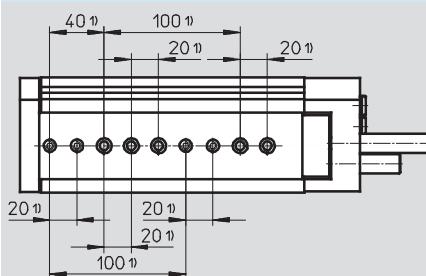
DGSL-N-25-30/40



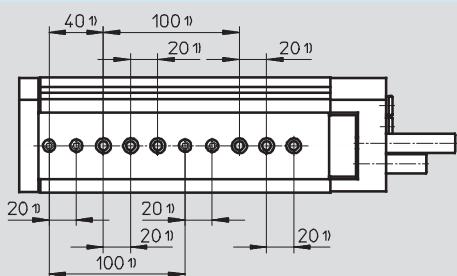
DGSL-N-25-50



DGSL-N-25-80

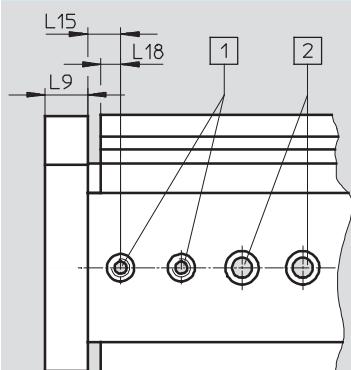


DGSL-N-25-100 ... 200



Distances from yoke plate to mounting threads and centring holes

DGSL-N-20/25



[1] Centring holes with thread

[2] Through-holes for mounting
the drive

1) Tolerance for centring hole
 ± 0.02

Tolerance for through-hole ± 0.1

Size	L9	L15 ± 0.05	L18
20	14	7.8	6.5
25	15	8	6.5

