

Motor controllers CMMS-AS, for servo motors



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Key features

| Comparison of motor controllers    |       |                        |                            |  |
|------------------------------------|-------|------------------------|----------------------------|--|
| Motor controller<br>For motor type |       | CMMS-AS<br>Servo motor | CMMP-AS<br>Servo motor     | CMMS-ST<br>Stepper motor                   |
| Torque at standstill               | [Nm]  | 4.7                    | 25                         | 9.3  |
| Peak torque                        | [Nm]  | 9.2                    | 48                         | 9.3  |
| Speed                              | [rpm] | 6,000                  | 6,000                      | 2,000                                      |
| Position sets                      |       | 63                     | 255                        | 63   |
| Measuring system                   |       | Incremental/absolute   | Incremental/absolute       | Incremental                                |
| Extended I/O interface             |       | 4 working modes        | Flexibly configurable      | 4 working modes                            |
| Notification of remaining distance |       | 1 for n                | Separate for all positions | 1 for n                                    |
| Torque reduction                   |       | No                     | Separate for all positions | No   |
| Set linking                        |       | Linear                 | With branching             | Linear                                     |
| STO/SS1                            |       | To EN 61800-5-2        | To EN 61800-5-2            | To EN 61800-5-2<br>with external circuitry |

## Performance characteristics

| Compactness  | Motion control   |
|--|--|
| <ul style="list-style-type: none"> <li>• Small dimensions</li> <li>• Full integration of all components for controller and power section, including RS232 and CANopen interface</li> <li>• Integrated brake chopper</li> <li>• Integrated EMC filters</li> </ul> | <ul style="list-style-type: none"> <li>• Automatic actuation for a holding brake integrated in the motor</li> <li>• Adheres to the current CE and EN standards without additional external measures (motor cable length of up to 15 m)</li> </ul>  |
|  | <ul style="list-style-type: none"> <li>• Digital absolute shaft encoder in single-turn and multi-turn versions</li> <li>• Can be operated as a torque, speed or position controller</li> <li>• Integrated positioning controller</li> <li>• Time-optimised (trapezoidal) or jerk-free (S-shaped) positioning</li> <li>• Absolute and relative movements</li> </ul> |
|  | <ul style="list-style-type: none"> <li>• Point-to-point positioning with and without approximate positioning</li> <li>• Position synchronisation</li> <li>• Electronic gear unit</li> <li>• 63 position sets</li> <li>• 8 travel profiles</li> <li>• Wide range of homing methods</li> </ul>   |

## Fieldbus interfaces

Integrated:



Optional:




## Input/output

- Freely programmable I/Os
- High-resolution 12-bit analogue input
- Jog/teach mode
- Simple linking to a higher-level controller via I/O or fieldbus
- Synchronous operation
- Master/slave mode

## Integrated sequence control

- Automatic sequence of position sets without a higher-level controller
- Linear and cyclic position sequences
- Adjustable delay times

## Integrated safety functions

- The positioning controllers included in the CMMS-AS range support "Safe Torque off (STO)" and "Safe Stop 1 (SS1)" functions with protection against unexpected startup in accordance with EN 61800-5-2
- Protection against unexpected start-up
- Two-channel disconnection of the output stage
- Less external circuitry
- Shorter response times in the event of an error
- Faster restart, intermediate circuit remains charged

## Interpolating multi-axis movement

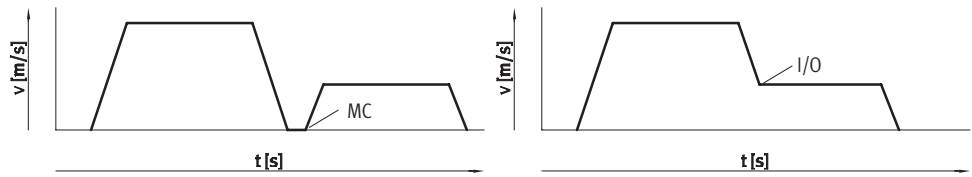
- With a suitable controller, the CMMS-AS can perform path movements with interpolation via CANopen. The controller specifies setpoint position values in a fixed time pattern to this end. In between, the servo positioning controller independently interpolates the data values between two data points.

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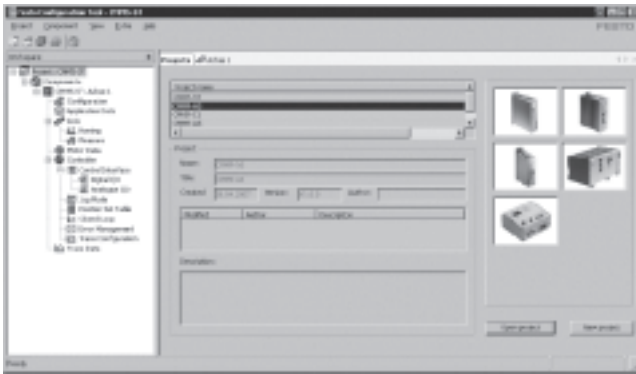
## Travel program

- Linking of any number of position sets into a travel program
- Further switching conditions for the travel program possible via digital inputs, for example  
 MC – motion complete  
 I/O – digital inputs



## FCT software – Festo Configuration Tool

Software platform for electric drives from Festo



- All drives in a system can be managed and archived in a common project
- Project and data management for all supported device types
- Simple to use thanks to graphically-supported parameter entry
- Universal mode of operation for all drives
- Working offline at your desk or online at the machine

## FHPP – Festo Handling and Positioning Profile

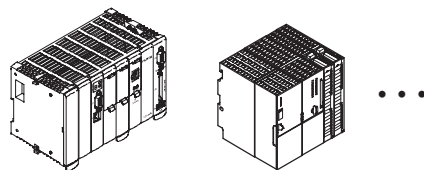
Optimised data profile

Festo has developed an optimised data profile, the “Festo Handling and Positioning Profile (FHPP)”, that is tailored to handling and positioning applications.

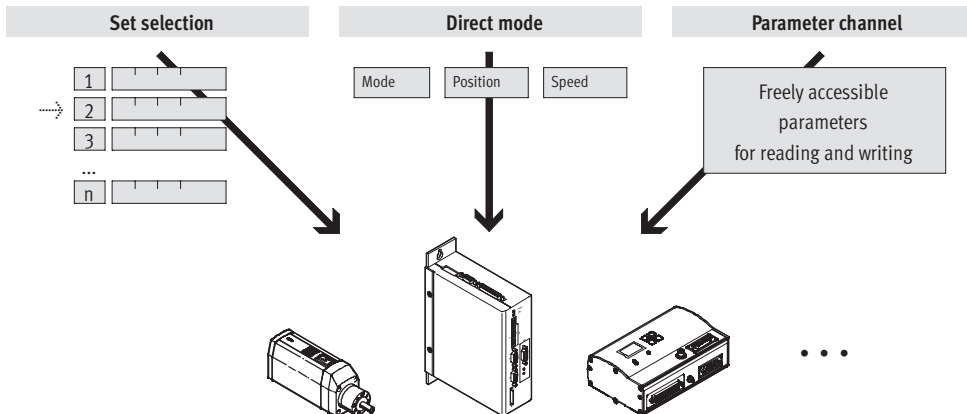
The FHPP data profile permits the actuation of Festo motor controllers, using a fieldbus interface, via standardised control and status bytes.

The following are defined, among others:

- Operating modes
- I/O data structure
- Parameter objects
- Sequence control

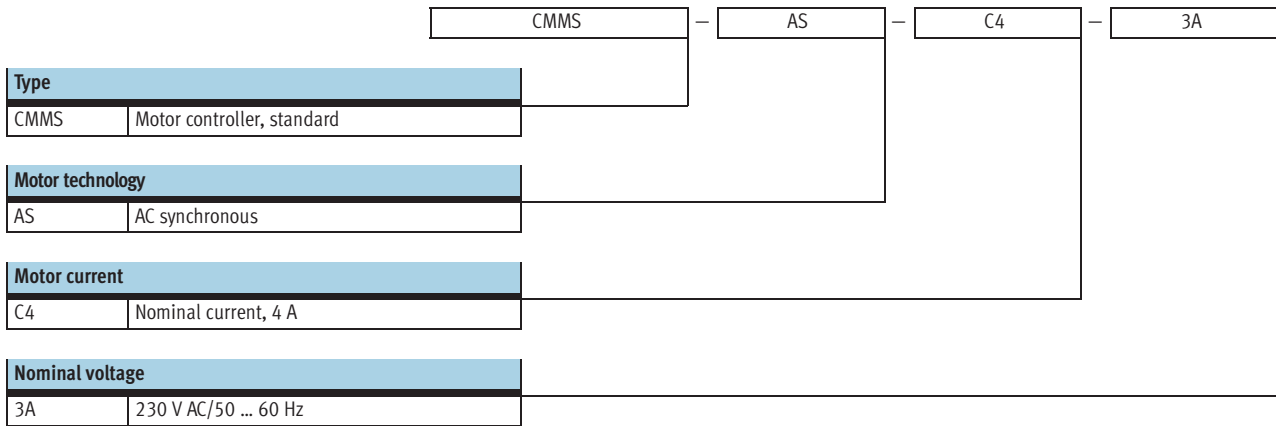


Fieldbus communication



## Motor controllers CMMS-AS, for servo motors

Type codes



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Technical data

Fieldbus interfaces



| General technical data                                   |       |   |
|--|-------|---|
| Type of mounting   |       | Screwed to a mounting plate                                     |
| Display  |       | 7-segment display   |
| Parameterisation interface                               |       | RS232 (9,600 ... 115,000 bits/s)                                |
| Encoder interface input                                  |       | Setpoint position value as encoder signal                       |
|  |       | EnDat V2.2  |
| Encoder interface output                                 |       | Actual value feedback via encoder signals in speed control mode |
|  |       | Setpoint specification for downstream slave drive               |
|  |       | Resolution 4,096 ppr  |
| Braking resistor, integrated                             | [Ω]   | 230   |
| Braking resistor, external                               | [Ω]   | 100   |
| Impedance of setpoint input                              | [kΩ]  | 20  |
| Pulse power of braking resistor                          | [kVA] | 0.7   |
| Operating range of analogue outputs                      | [V]   | 0 ... 10  |
| Number of analogue outputs                               |       | 1   |
| Characteristics of analogue outputs                      |       | Short circuit-proof   |
| Operating range of analogue inputs                       | [V]   | ±10   |
| Number of analogue inputs                                |       | 1   |
| Characteristics of analogue inputs                       |       | Differential inputs   |
|  |       | Configurable for speed  |
|  |       | Configurable for torque   |
| Resolution of analogue outputs                           | [Bit] | 8   |
| Mains filter   |       | Integrated  |
| Max. length of motor cable without external mains filter | [m]   | 15  |
| Product weight   | [g]   | 2,500   |

| Technical data – Fieldbus interface      |            |                                   |               |                          |          |
|--|------------|-----------------------------------|---------------|--------------------------|----------|
| Interfaces                               | I/O        | CANopen                           | Profibus DP   | DeviceNet                |          |
| Operating range of logic inputs          | [V]        | 12 ... 30                         | –             | –                        |          |
| Number of digital logic inputs           |            | 14                                | –             | –                        |          |
| Characteristics of logic inputs          |            | Freely configurable               | –             | –                        |          |
| Number of digital logic outputs          |            | 5                                 |               |                          |          |
| Characteristics of digital logic outputs |            | Freely configurable in some cases |               |                          |          |
| Process coupling                         |            | For 63 position sets              |               |                          |          |
| Communication profile                    |            | –                                 | DS301, FHPP   | DP-V0 / FHPP             | FHPP     |
|  |            | –                                 | DS301, DSP402 | Step7 functional modules |          |
| Max. fieldbus transmission rate          | [Mbit/s]   | –                                 | 1             | 12                       | 0.5      |
| Interface                                | Integrated | ■                                 | ■             | –                        | –        |
|  | Optional   | –                                 | –             | ■<br>→ 9                 | ■<br>→ 9 |

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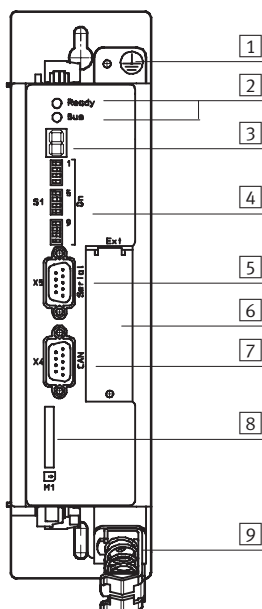
Technical data

| Electrical data                       |        |            |
|---------------------------------------|--------|------------|
| Output connection data                |        |            |
| Output voltage range                  | [V AC] | 0 ... 210  |
| Nominal output current                | [A]    | 4          |
| Peak current                          | [A]    | 10         |
| Max. peak current duration            | [s]    | 2          |
| Max. intermediate circuit voltage     | [V DC] | 380        |
| Mains frequency                       | [Hz]   | 50 ... 60  |
| Load supply                           |        |            |
| Nominal voltage phases                |        | 1          |
| Input voltage range                   | [V AC] | 95 ... 255 |
| Max. nominal input current            | [A]    | 5          |
| Rated output                          | [VA]   | 600        |
| Peak output                           | [VA]   | 1,200      |
| Logic supply                          |        |            |
| Nominal voltage                       | [V DC] | 24 ±20%    |
| Nominal current                       | [A]    | 4 ... 5    |
| Max. current of digital logic outputs | [mA]   | 100        |

| Operating and environmental conditions  |   |
|---|---|
| Digital logic outputs                   | Not electrically isolated   |
| Logic inputs                            | Electrically isolated   |
| Protection class                        | IP20  |
| Protective function                     | I <sup>2</sup> t monitoring   |
|   | Intermediate circuit over-/undervoltage   |
|   | Short circuit in output stage   |
|   | Standstill monitoring   |
|   | Temperature monitoring  |
| Ambient temperature                     | [°C] 0 ... +50  |
| Storage temperature                     | [°C] -25 ... +70  |
| Relative air humidity                   | [%] 0 ... 90 (non-condensing)   |
| CE mark (see declaration of conformity) | To EU Low Voltage Directive   |
| STO/SS1                                 | To EN 61800-5-2   |
| Safety function                         | "Protection against unexpected start-up" to DIN EN ISO 13849-1, category 3, performance level d, SIL 2 to Table 4 |

## View of motor controller

From the front



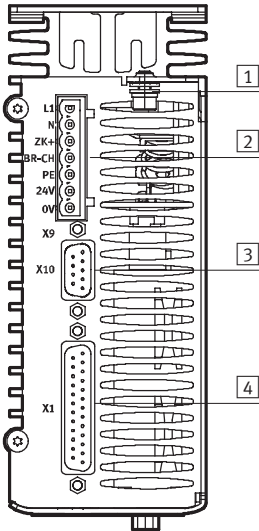
- 1 Earthing
- 2 Ready/bus LED
- 3 Status display
- 4 Fieldbus settings and boot loader
- 5 Interface: RS232/RS485
- 6 Technology module (optional)
- 7 Interface: CAN bus
- 8 SD memory card
- 9 Screened connection

# Motor controllers CMMS-AS, for servo motors

Technical data

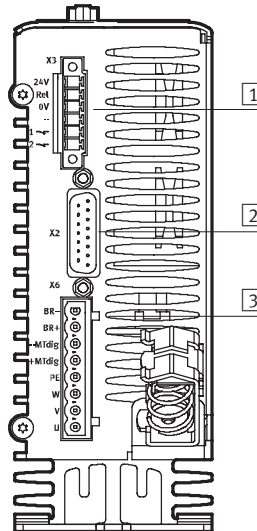
## View of motor controller

From above



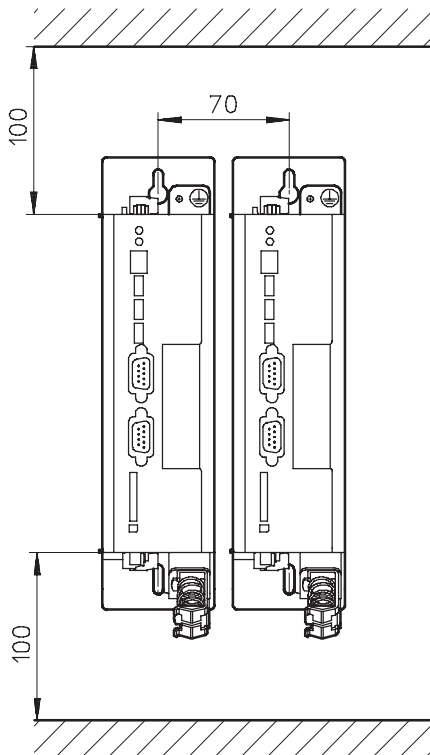
- 1 Earthing screw
- 2 Power supply
- 3 Increment generator output
- 4 I/O interface

From underneath



- 1 Safe stop
- 2 Increment generator input
- 3 Motor connection

## Installation clearance for motor controller

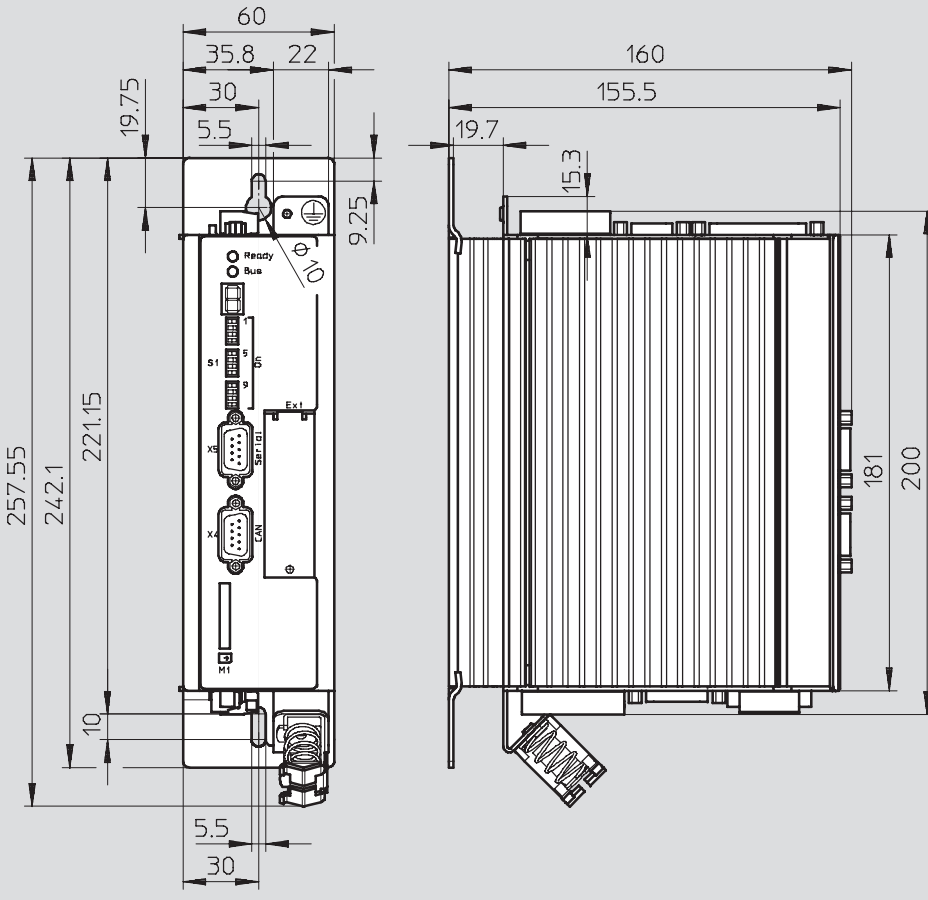


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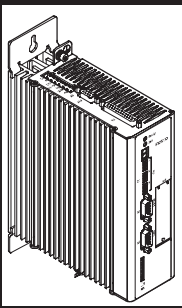
Technical data

**Dimensions**

Download CAD data → [www.festo.com](http://www.festo.com)



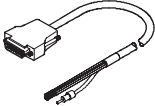
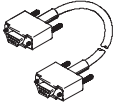
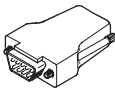
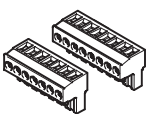
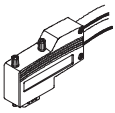

**Ordering data**

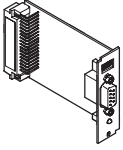
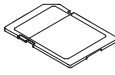
|   | Brief description   | Part No.       | Type                 |
|---|---|----------------|----------------------|
|  | The plug assortment NEKM (→ 9) and the operator package (→ 10) are included in the scope of delivery. | <b>552 741</b> | <b>CMMS-AS-C4-3A</b> |



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Accessories

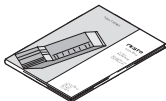
| Ordering data – Cables and plugs  |   |                  |          |                         |
|---|---|------------------|----------|-------------------------|
|   | Brief description   | Cable length [m] | Part No. | Type                    |
|    | Control cable, for I/O interface to any controller  | 2.5              | 552 254  | NEBC-S1G25-K-2.5N-LE26  |
|    | Programming cable   | 1.5              | 160 786  | PS1-ZK11-NULLMODEM-1,5M |
|    | Encoder plug  | –                | 564 264  | NECC-A-S-S1G9-C2M       |
|    | Plug assortment, comprising plug for power supply and plug for motor connection. The plug assortment is included in the scope of delivery | –                | 560 504  | NEKM-C-4                |
|   | Plug for Profibus interface   | –                | 533 780  | FBS-SUB-9-WS-PB-K       |
|  | Plug for DeviceNet interface  | –                | 525 635  | FBSD-KL-2X5POL          |

| Ordering data – Plug-in cards   |   |          |                |  |
|---|---|----------|----------------|--|
|   | Brief description                                   | Part No. | Type           |  |
|  | Interface, for Profibus interface                   | 547 450  | CAMC-PB        |  |
|   | Interface, for DeviceNet interface                  | 547 451  | CAMC-DN        |  |
|  | Memory card, for data backup and firmware downloads | 562 211  | CAMC-M-S-F2-V1 |  |

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Accessories

| Ordering data – Software and documentation  |   |                |                     |
|---|---|----------------|---------------------|
|   | Brief description   | Part No.       | Type                |
|  | Operator package contains:<br>– CD-ROM<br>– with manual for CMMS-AS,<br>in de, en, es, fr, it, sv<br>– with FCT (Festo Configuration Tool) configuration software,<br>in de, en<br>– Brief description<br>This package is included in the scope of delivery | <b>559 868</b> | <b>GSIB-CMMS-AS</b> |

| Ordering data – Documentation <sup>1)</sup>                                       |          |                         |                       |  |                         |
|---|----------|-------------------------|-----------------------|--|-------------------------|
|   | Language | Part No.                | Type                  | Part No.   | Type                    |
|   |          | for motor controller    |                       | Festo Handling and Positioning Profile (FHPP) for the motor controller family CMM... |                         |
|  | DE       | 564 227                 | P.BE-CMMS-AS-3A-HW-DE | 555 695  | P.BE-CMM-FHPP-SW-DE     |
|   | EN       | 564 228                 | P.BE-CMMS-AS-3A-HW-EN | 555 696  | P.BE-CMM-FHPP-SW-EN     |
|   | ES       | 564 229                 | P.BE-CMMS-AS-3A-HW-ES | 555 697  | P.BE-CMM-FHPP-SW-ES     |
|   | FR       | 564 230                 | P.BE-CMMS-AS-3A-HW-FR | 555 698  | P.BE-CMM-FHPP-SW-FR     |
|   | IT       | 564 231                 | P.BE-CMMS-AS-3A-HW-IT | 555 699  | P.BE-CMM-FHPP-SW-IT     |
|   | SV       | 564 232                 | P.BE-CMMS-AS-3A-HW-SV | 555 700  | P.BE-CMM-FHPP-SW-SV     |
|   |          | for CANopen interface   |                       | for Profibus interface   |                         |
|   | DE       | 554 351                 | P.BE-CMMS-CO-SW-DE    | 554 345  | P.BE-CMMS-FHPP-PB-SW-DE |
|   | EN       | 554 352                 | P.BE-CMMS-CO-SW-EN    | 554 346  | P.BE-CMMS-FHPP-PB-SW-EN |
|   | ES       | 554 353                 | P.BE-CMMS-CO-SW-ES    | 554 347  | P.BE-CMMS-FHPP-PB-SW-ES |
|   | FR       | 554 354                 | P.BE-CMMS-CO-SW-FR    | 554 348  | P.BE-CMMS-FHPP-PB-SW-FR |
|   | IT       | 554 355                 | P.BE-CMMS-CO-SW-IT    | 554 349  | P.BE-CMMS-FHPP-PB-SW-IT |
|   | SV       | 554 356                 | P.BE-CMMS-CO-SW-SV    | 554 350  | P.BE-CMMS-FHPP-PB-SW-SV |
|   |          | for DeviceNet interface |                       |  |                         |
| DE  | 554 357  | P.BE-CMMS-FHPP-DN-SW-DE |                       |  |                         |
| EN  | 554 358  | P.BE-CMMS-FHPP-DN-SW-EN |                       |  |                         |
| ES  | 554 359  | P.BE-CMMS-FHPP-DN-SW-ES |                       |  |                         |
| FR  | 554 360  | P.BE-CMMS-FHPP-DN-SW-FR |                       |  |                         |
| IT  | 554 361  | P.BE-CMMS-FHPP-DN-SW-IT |                       |  |                         |
| SV  | 554 362  | P.BE-CMMS-FHPP-DN-SW-SV |                       |  |                         |

1) Manual in paper form is not included in the scope of delivery