## Position transmitters SMAT-8E, for T-slot

Product overview



- Position measuring range 50 mm
- Analogue output 0 ... 10 V and 0 ... 20 mA
- Integrated out-of-range detection
- Repeat accuracy ± 0,064 mm
- Direct mounting in T-slot

Detailed product information

→ www.festo.com/catalogue/smat

Product overview							
Design	Type of mounting	Measuring prin- ciple	Operating voltage range	Analogue output	Switch output	Switching el- ement function	→ Page
Position transmitter SMAT-8E							
For T-slot	Insertable in slot lengthwise	Magnetic	15 30 V DC	0 10 V 0 20 mA	_	_	43

## Position transmitters SMAT-8E, for T-slot

Key features

#### **FESTO**

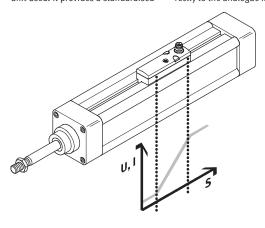
#### Design

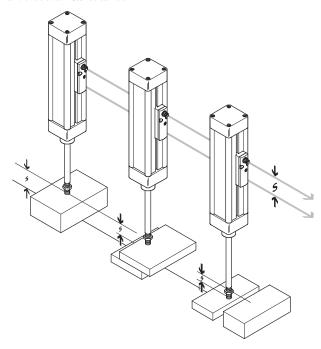
The SMAT-8E is a sturdy magnetic measuring system with a 50 mm working range, regardless of the drive unit used. It provides a standardised

analogue current and voltage signal via an M8x1 plug connection. The transmitter can thus be connected directly to the analogue input of a pro-

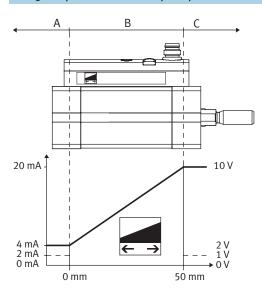
grammable logic controller. The piston position of the pneumatic cylinder is detected by contactless sensing and the travel distance can be

measured between any set switching points with typical repeatabilityof 0.1 mm.





#### Analogue output as a function of the piston position



Analogue output [V] [mA]		Description	Area
0	0	No valid signal, e.g. no operating voltage	-
1	2	Piston outside of measuring range after operat-	A <b>,</b> C
		ing voltage is switched on	
2	4	Piston has left the measuring range in the nega-	Α
		tive direction	
10	20	Piston has left the measuring range in the posi-	С
		tive direction	
2 10	4 20	Piston within the measuring range at the rel-	В
		evant position	



Sensors that detect magnetic fields, such as the position transmitter SMAT, must not be secured onto the

drive using mountings made from ferritic materials, as this can lead to malfunction.

# **Position transmitters SMAT-8E, for T-slot** Selection aid

Drive	Piston $\varnothing$	Suitability
Standards-based cylinders		
Standard cylinders DSNU, ESNU		0
Standard cylinders DSN, ESN		0
Standard cylinders DNCB		++
Standard cylinders DNC		++
Standard cylinders DNG		-
Standard cylinders CDNR with se	nsor strip	-
Standard cylinders DNU		
Standard cylinders ADN		++
		•
Cylinders with piston rod		
Compact cylinders ADVU, AEVU		++
Short-stroke cylinders ADVC, AEVC	Ø 6 25	-
	Ø 32 100	++
Flat cylinders EZH-10/40-40-A-B		+
Flat cylinders DZF	Ø 12, 25, 32, 40, 63	+
	Ø 18, 50	++
Flat cylinders DZH	Ø 16 25	+
	Ø 32 63	-
Round cylinders DSNU, ESNU		0
Round cylinders DSW, ESW		0
Round cylinders DSEU, ESEU		0
Multimount cylinders DMM, EMM		+
Round cylinders CRDG		0
Round cylinders CRDSW		0
Standard cylinders CRHD		0
Standard cylinders CRDSNU		0
Standard cylinders CRDNG		-
Standard cylinders CRDNGS		-
Rodless cylinders		
Linear drives DGC		-
Linear drives DGP, DGPL		-
Linear drives SLG		_
Linear drives DGO	~	_
Linear drives SLM	Ø 12, 40	++
	Ø 16 32	0
Semi-rotary drives		
Swivel modules DSM	Ø 6 10	<u> </u>
Semi-rotary drives DRQ		_
Semi-rotary drives DRQD	Ø 6, 8, 12, 40, 50	_
rotary arrived bridge	Ø 16 32	++
	~ 10 72	
Function-oriented drives		
Stopper cylinders STA, STAF		-
Linear/swivel clamps CLR		0
Swivel/linear units DSL		-

Drive	Piston $\varnothing$	Suitability
Drives with linear guide		
Mini slides SLS, SLF, SLT		-
Twin cylinders SPZ	Ø 10, 25	0
	Ø 16	++
	Ø 32	-
Slide units SLZ		-
Guided cylinders DFP	Ø 10 16	-
	Ø 25 80	0
Mini guided drives DFC		-
Guided drives DFM	Ø 12, 25, 50	++
	Ø 16, 20, 32, 40, 63, 80	+
	Ø 100	-
Guided drives DFM-B	Ø 12, 16, 25, 32	-
	Ø 20	+
	Ø 40, 50	++
	Ø 63	-
Linear units SLE		-
Twin cylinders DPZC		-
Twin cylinders DPZ		-
Handling units		
Linear modules HMP		-
Linear modules HMPL		-
Handling modules HSP		-
Feed separators HPV		-
Three-point grippers HGD		-
Parallel grippers HGP		-
Parallel grippers HGPP		-
Parallel grippers HGPT		-
Angle grippers HGW		-
Radial grippers HGR		-
Cushioning components		,
Hydraulic stop elements YSRWJ		-
Electrical positioning systems		
Toothed belt axes DGE-ZR		-
Spindle axes DGE-SP		-
System components		
System components Heavy-duty guides HD		
Heavy-duty guides HD		_
Valve actuators		
		Τ .
Copac linear actuators DLP-A		_

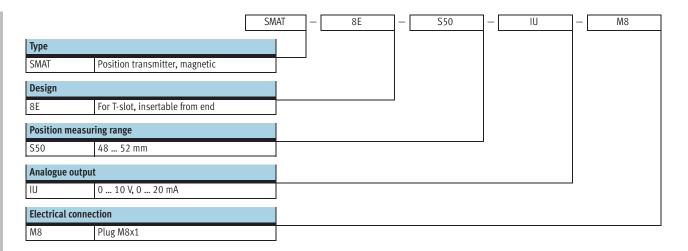
 <sup>++</sup> Unrestricted use
 - Sensor function guaranteed without restriction; installation direction and clamping are drive-specific

Upon request

## Position transmitters SMAT-8E, for T-slot

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Type codes, technical data

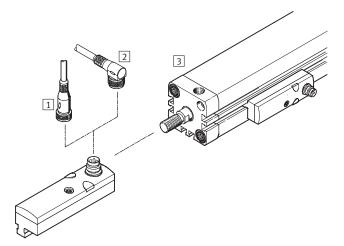


Technical data			
Design			
Design		For T-slot	
Type of mounting		Clamped, insertable in slot lengthwise	
Status display		Red LED = outside measuring range	
Electrical data			
Analogue output	[V]	0 10	
	[mA]	0 20	
Typical scanning interval	[ms]	2.85	
Displacement resolution	[mm]	0.064	
Electrical connection		Plug, M8x1, 4-pin	
Operating voltage range	[V DC]	15 30	
Protection against short circuit		Yes	
Protection against overloading		Yes	
Protection against polarity reversal		For all electrical connections	
Measuring principle		Magnetic	
Position measuring range	[mm]	48 52	
Repetition accuracy, analogue value	[mm]	±0.064	
Typical linearity error	[mm]	0.25	
Max. speed of travel [m/s]		3	
Protection class		IP65, IP67	
Operating and environmental conditions			
		-20 +50 <sup>1)</sup>	
Ambient temperature [°C]		In accordance with EU EMC directive	
CE mark (see declaration of conformity)  Certification		c UL us - Listed (OL)	
Certification		C-Tick	
		CHCK	
Materials			
Housing		Reinforced polyamide	
		Polycarbonate	

 $1) \quad \hbox{ Extended ambient temperature range on request} \\$ 

Ordering data				
	Analogue output	Electrical connection	Part No.	Туре
• 9	0 10 V 0 20 mA	Plug, M8x1, 4-pin	540 191	SMAT-8E-S50-IU-M8

# Position transmitters SMAT-8E, for T-slot Peripherals overview



Acces	ssories	→ Page
1	Connecting cable NEBU-M8G4	45
2	Connecting cable NEBU-M8W4	45
3	Fitted to drive with T-slot	43

Ordering data	– Connec	Technical data → 261			
	Number of wires	Cable length [m]	Part No.	Туре	
Straight plug socket					
	4	2.5	541 342	NEBU-M8G4-K-2.5-LE4	
		5	541 343	NEBU-M8G4-K-5-LE4	
Angled plug socket					
	4	2.5	541 344	NEBU-M8W4-K-2.5-LE4	
<b>66</b>		5	541 345	NEBU-M8W4-K-5-LE4	

### Position transmitters SMAT-8E, for T-slot

Application examples

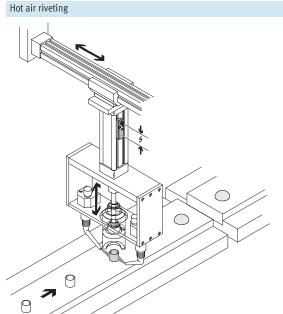
#### **FESTO**

#### **Application examples**

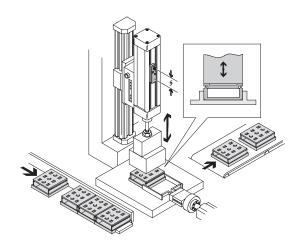
Many typical applications can be found in the areas of object detection and process monitoring:

- Joining procedures
- Clamping
- Position sensing
- Detection of good/reject parts
- Workpiece placement
- Quality inspection
- Wear monitoring
- Thickness measuring

#### Ultrasonic welding

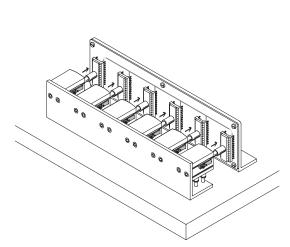


- After the rivet has been heated using hot air, the rivet head is formed by compressing it with the die
- The feed motion of the riveting die is controlled using the position transmitter.



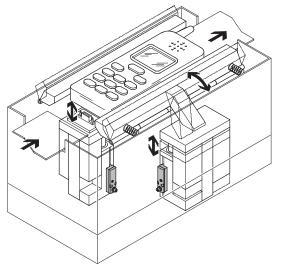
 The joining of sections of material using ultrasonics must be defined.
 The position transmitter is used for contactless and wear-free detection of the feed motion of the sonotrode.

#### Pressing



• Feed or press-in depth is monitored using the position transmitter.

#### Clamping

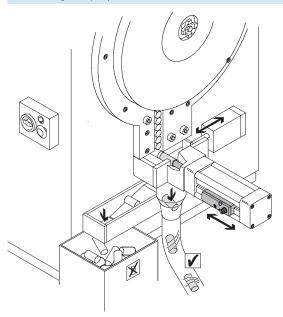


 The position and movement of the clamping jaws is fed back via the position transmitter for process monitoring/quality inspection.

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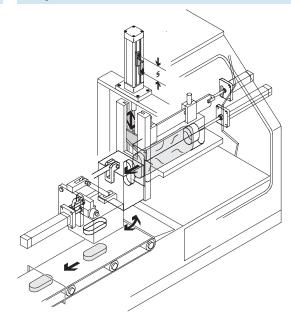
Application examples

#### Detection of good/reject parts



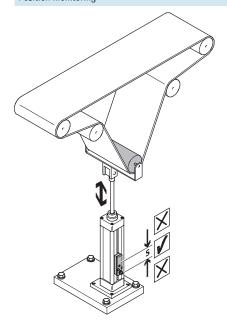
 The length or thickness of components is detected using the position transmitter and sorted into good and reject parts according to the result.

#### Cutting



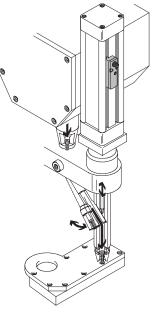
• The cutting depth of the blade is monitored and the blade is retracted when the required depth is reached.

#### Position monitoring



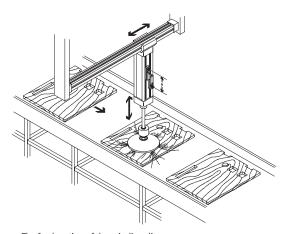
 The desired belt tension is preset using the piston position of the cylinder. The position transmitter is used to monitor an area for the preset piston position. Ageing and stretching of the belt can be detected at an early stage by means of the resulting change in the piston position.

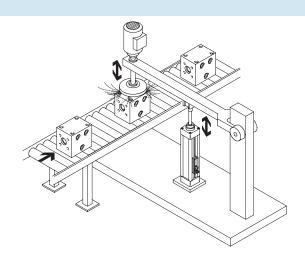
#### Automatic screwdriver application



• The feed motion of the power screwdriver and, consequently, the screw-in depth is detected using the position transmitter and the screwdriver is switched off or reversed depending on the depth. 1.1

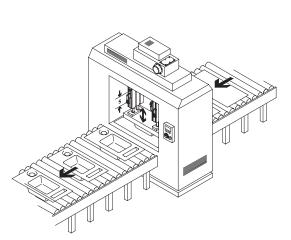
### Grinding





• The feed motion of the grinding disc is monitored using the position transmitter.

#### Punching



• The feed motion of the punching device is monitored using the position transmitter.

