## Position transmitters SMAT-8E, for T-slot

Product overview



- Position measuring range 50 mm
- Analogue output 0 ... 10 V and 0 ... 20 mA
- Integrated out-of-range detection
- Typical repeat accuracy 0.1 mm
- Direct mounting in T-slot

Detailed product information

→ www.festo.com/catalogue/smat

Product overview							
Design	Type of mounting	Measuring prin- ciple	Operating voltage range	Analogue output	Switch output	Switching el- ement function	→ Page
Position transmitter SMAT-8E							
Position trans	mitter SMAT-8E						
Position trans For T-slot	mitter SMAT-8E Insertable in slot	Magnetic	15 30 V DC	0 10 V	-	-	43

## Position transmitters SMAT-8E, for T-slot

Key features

#### **FESTO**

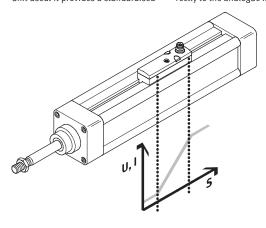
#### Design

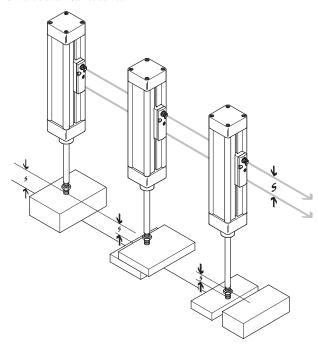
The SMAT-8E is a sturdy magnetic measuring system with a 50 mm working range, regardless of the drive unit used. It provides a standardised

analogue current and voltage signal via an M8x1 plug connection. The transmitter can thus be connected directly to the analogue input of a pro-

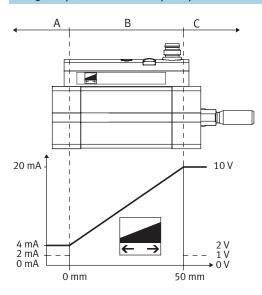
grammable logic controller. The piston position of the pneumatic cylinder is detected by contactless sensing and the travel distance can be

measured between any set switching points with typical repeatabilityof 0.1 mm.





#### Analogue output as a function of the piston position



Analogue output [V] [mA]		Description	Area
0	0	No valid signal, e.g. no operating voltage	-
1	2	Piston outside of measuring range after operat-	A <b>,</b> C
		ing voltage is switched on	
2	4	Piston has left the measuring range in the nega-	Α
		tive direction	
10	20	Piston has left the measuring range in the posi-	С
		tive direction	
2 10	4 20	Piston within the measuring range at the rel-	В
		evant position	



Sensors that detect magnetic fields, such as the position transmitter SMAT, must not be secured onto the

drive using mountings made from ferritic materials, as this can lead to malfunction.

# **Position transmitters SMAT-8E, for T-slot** Selection aid

Drive	Piston $\varnothing$	Suitability
Standards-based cylinders		
Standard cylinders DSNU, ESNU		0
Standard cylinders DSN, ESN		0
Standard cylinders DNCB		++
Standard cylinders DNC		++
Standard cylinders DNG		-
Standard cylinders CDNR with se	nsor strip	_
Standard cylinders DNU	·	-
Standard cylinders ADN		++
		•
Cylinders with piston rod		
Compact cylinders ADVU, AEVU		++
Short-stroke cylinders ADVC, AEVC	Ø 6 25	-
	Ø 32 100	++
Flat cylinders EZH-10/40-40-A-B		+
Flat cylinders DZF	Ø 12, 25, 32, 40, 63	+
	Ø 18, 50	++
Flat cylinders DZH	Ø 16 25	+
•	Ø 32 63	_
Round cylinders DSNU, ESNU		0
Round cylinders DSW, ESW		0
Round cylinders DSEU, ESEU		0
Multimount cylinders DMM, EMM		+
Round cylinders CRDG		0
Round cylinders CRDSW		0
Standard cylinders CRHD		0
Standard cylinders CRDSNU		0
Standard cylinders CRDNG		
Standard cylinders CRDNGS		_
Standard cylinders enones		
Rodless cylinders		
Linear drives DGC		_
Linear drives DGP, DGPL		_
Linear drives SLG		
Linear drives DGO		_
Linear drives SLM	Ø 12, 40	++
Linear arrives SEM	Ø 16 32	0
	~ 10 )2	"
Semi-rotary drives		
Swivel modules DSM	Ø 6 10	
Semi-rotary drives DRQ	× 0 10	<del>-</del>
Semi-rotary drives DRQD	Ø 6 8 12 //0 50	-
Jenn-Tulary unives DRQD	Ø 6, 8, 12, 40, 50	
	Ø 16 32	++
Function-oriented drives		
Stopper cylinders STA, STAF		-
Linear/swivel clamps CLR		0
Swivel/linear units DSL		_

Drive	Piston $\varnothing$	Suitability
Drives with linear guide		
Mini slides SLS, SLF, SLT		-
Twin cylinders SPZ	Ø 10, 25	0
	Ø 16	++
	Ø 32	-
Slide units SLZ		-
Guided cylinders DFP	Ø 10 16	-
	Ø 25 80	0
Mini guided drives DFC		-
Guided drives DFM	Ø 12, 25, 50	++
	Ø 16, 20, 32, 40, 63, 80	+
	Ø 100	-
Guided drives DFM-B	Ø 12, 16, 25, 32	-
	Ø 20	+
	Ø 40, 50	++
	Ø 63	-
Linear units SLE		-
Twin cylinders DPZC		-
Twin cylinders DPZ		-
		•
Handling units		
Linear modules HMP		-
Linear modules HMPL		-
Handling modules HSP		-
Feed separators HPV		-
Three-point grippers HGD		-
Parallel grippers HGP		-
Parallel grippers HGPP		-
Parallel grippers HGPT		-
Angle grippers HGW		-
Radial grippers HGR		-
Cushioning components		
Hydraulic stop elements YSRWJ		_
Electrical positioning systems		
Toothed belt axes DGE-ZR		-
Spindle axes DGE-SP		-
System components		
Heavy-duty guides HD		_
W.L.		
Valve actuators		
Copac linear actuators DLP-A		_

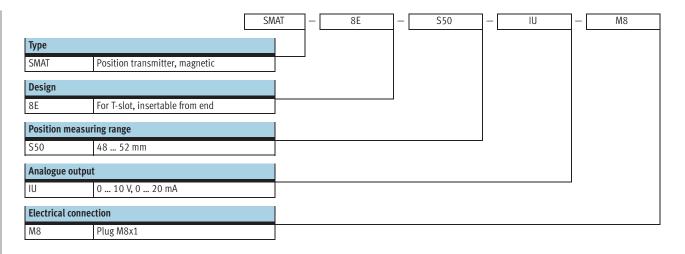
<sup>+</sup> Sensor function guaranteed without restriction; installation direction and clamping are drive-specific

o Upon request

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**FESTO** 

Type codes, technical data

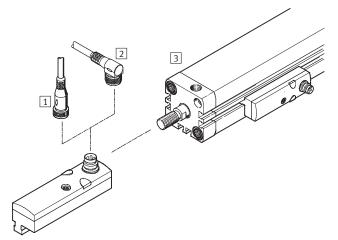


Technical data					
Design					
Design		For T-slot			
Type of mounting		Clamped, insertable in slot lengthwise			
Status display		Red LED = outside measuring range			
Electrical data					
Analogue output	[V]	0 10			
	[mA]	0 20			
Typical scanning interval	[ms]	2.85			
Displacement resolution	[mm]	0.064			
Electrical connection		Plug, M8x1, 4-pin			
Operating voltage range	[V DC]	15 30			
Protection against short circuit		Yes			
Protection against overloading		Yes			
Protection against polarity reversal		For all electrical connections			
Measuring principle		Magnetic			
Position measuring range	[mm]	48 52			
Repetition accuracy, analogue value [mm]		±0.064			
Linearity error [mm]		Typically 0.25			
Max. speed of travel [m/s]		3			
Protection class		IP65, IP67			
Operating and environmental conditions					
Ambient temperature [°C]		-20 +50 <sup>1)</sup>			
CE mark (see declaration of conformity)		In accordance with EU EMC directive			
Certification		c UL us - Listed (OL)			
		C-Tick			
Materials					
Housing		Reinforced polyamide			
11045115		Polycarbonate			
		1 discarbonate			

 $1) \quad \hbox{ Extended ambient temperature range on request} \\$ 

Ordering data				
	Analogue output	Electrical connection	Part No.	Туре
	0 10 V 0 20 mA	Plug, M8x1, 4-pin	540 191	SMAT-8E-S50-IU-M8

# Position transmitters SMAT-8E, for T-slot Peripherals overview





Ordering dat	a – Connec	Technical data → 169			
	Number of wires	Cable length [m]	Part No.	Туре	
Straight plug socket					
	4	2.5	541 342	NEBU-M8G4-K-2.5-LE4	
		5	541 343	NEBU-M8G4-K-5-LE4	
Angled plug socket					
	4	2.5	541 344	NEBU-M8W4-K-2.5-LE4	
CVA .		5	541 345	NEBU-M8W4-K-5-LE4	

### Position transmitters SMAT-8E, for T-slot

Application examples

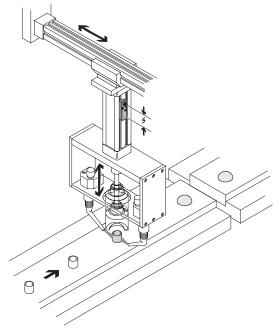


#### **Application examples**

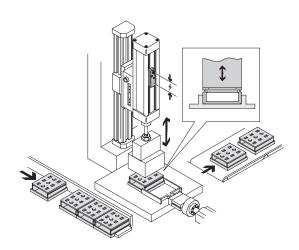
Many typical applications can be found in the areas of object detection and process monitoring:

- Joining procedures
- Clamping
- Position sensing
- Detection of good/reject parts
- Workpiece placement
- Quality inspection
- Wear monitoring
- Thickness measuring

#### Hot air riveting Ultrasonic welding

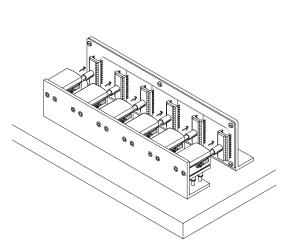


- After the rivet has been heated using hot air, the rivet head is formed by compressing it with the die
- The feed motion of the riveting die is controlled using the position transmitter.



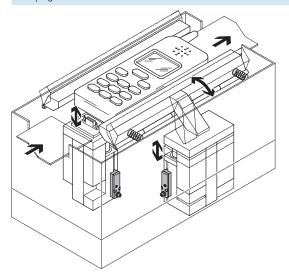
- The joining of sections of material using ultrasonics must be defined.
   The position transmitter is used for
- contactless and wear-free detection of the feed motion of the sonotrode.

#### Pressing



• Feed or press-in depth is monitored using the position transmitter.

#### Clamping

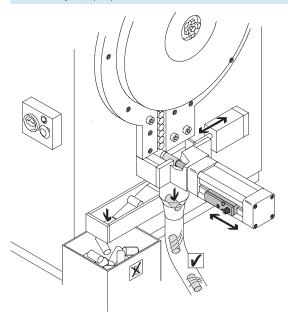


 The position and movement of the clamping jaws is fed back via the position transmitter for process monitoring/quality inspection.

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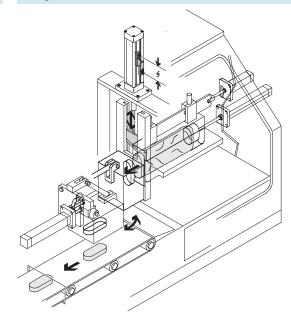
Application examples

#### Detection of good/reject parts



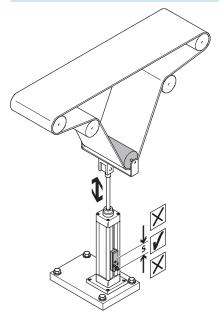
 The length or thickness of components is detected using the position transmitter and sorted into good and reject parts according to the result.

#### Cutting



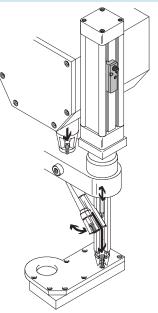
• The cutting depth of the blade is monitored and the blade is retracted when the required depth is reached.

#### Position monitoring



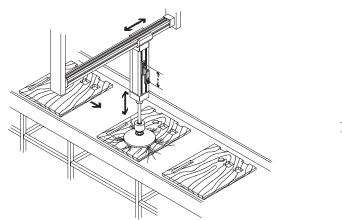
 The desired belt tension is preset using the piston position of the cylinder. The position transmitter is used to monitor an area for the preset piston position. Ageing and stretching of the belt can be detected at an early stage by means of the resulting change in the piston position.

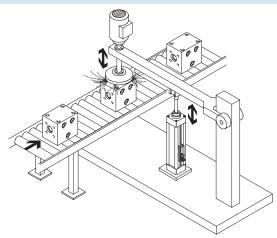
#### Automatic screwdriver application



• The feed motion of the power screwdriver and, consequently, the screw-in depth is detected using the position transmitter and the screwdriver is switched off or reversed depending on the depth. 1.1

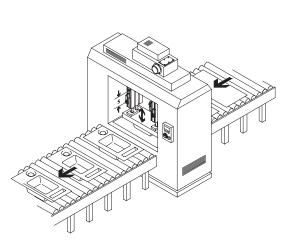
#### Grinding





• The feed motion of the grinding disc is monitored using the position transmitter.

#### Punching



• The feed motion of the punching device is monitored using the position transmitter.

