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- Quality assurance, position and rotary orientation sensing
- Picture sampling rate (full image) 150 pps
- Several cameras can be networked via Ethernet
- Integrated electronic evaluation unit
- Compact dimensions, low weight
- Protection class IP65, IP67

Greater flexibility in quality assurance

Increased system availability using a vision system. The intelligent compact vision system SBOC-Q/SBOI-Q from Festo ensures 100% quality inspection, even where there is an enormous variety of part types. Whether it's used for orientation identification of small parts, the measurement of turned parts, the precision positioning of drives or the location of objects for the control of handling equipment, the intelligent vision system provides reliable inspection results for a broad range of applications.







More compact

Zero error rate

Made-to-measure diagnosis

Compact design and low weight make this vision system an ideal tool for quality inspection. It is impressively uncomplicated to integrate into existing systems and very easy to commission by means of parameterisation. The system's ability to learn up to 256 workpieces means maximum flexibility when it comes to conversion.

All-inclusive

The sensor system for image data acquisition as well as the complete electronic evaluation unit and the interfaces (Ethernet/CAN) for communication with master controllers (PLCs) are already integrated in the system.



Spotlight on technology

- Standard software interfaces for Ethernet and CAN and integrated 24 V I/Os
- Sensor resolution 640 x 480 or 1,280 x 1,024 pixels (monochrome and colour)
- Very short exposure times (min. 27 µs): The vision system can be used even when the workpiece is travelling at high speed or the camera or workpiece is vibrating
- Compact dimensions, low weight
- IP 65, IP67



Overview of applications

- Detection of position and rotary orientation of workpieces
- Fine positioning of axes
- 2-D quality inspections
- Type identification Inclusive: integrated sorting function

Key features

Mode of operation

The sensor system for image data acquisition as well as the complete electronic evaluation unit and the interfaces for communication with master controllers are already integrated in the compact vision system. The camera can be set up, configured and commissioned using the software tools CheckKon and CheckOpti and it then operates automatically.

The process for creating a test

program is very straightforward. The user creates reference images via the camera by presenting different sample parts and then defines the desired inspection criteria, including distance, angle or area measurements. The presented sample parts define the tolerance range for each inspection characteristic, whereby each part that falls within the range is identified as good. Up to 64 characteristics can be combined in a single program and up to 256 test programs can be stored on the camera.

The camera can also be used to realise sorting functions, as it is capable of storing and distinguishing between up to 16 different part types per test program.

The characteristics calculated by the camera are not dependent on the rotary orientation and position of the inspection part, as they are determined relative to the position of the inspection part - any tilting and/or movement of the inspection part in the field of vision is therefore irrelevant for the inspection process.

The behaviour of the camera during inspection is determined by the evaluation mode. There are three different modes available.

Function		Application
Frame capture and inspection with each valid triggering signal. The triggering signal is generated by a master controller or a sensor as soon as the inspection part is in front of the	camera. The inspection results are output following the inspection, and the camera then waits for the next valid triggering signal.	Inspection of single parts when there is a triggering signal for image capture.
Image capture and inspection (without fixed frame rate) are performed con- tinuously. The triggering signal is present permanently, irrespective of whether or not there is an inspection part in front of the camera. The cam-	era acts like a basic sensor. The in- spection results are output following the inspection, and the camera then starts the next inspection immediately.	Inspection of single or continuous parts with an average to fast (continuous) flow.
Image capture and inspection are performed continuously at a defined frame rate. The triggering signal is present permanently. The inspection	results are output following the in- spection. The camera starts the next inspection in accordance with the de- fined frame rate.	Inspection of continuous parts at a constant speed.
	FunctionFrame capture and inspection with each valid triggering signal. The triggering signal is generated by a master controller or a sensor as soon as the inspection part is in front of theImage capture and inspection (without fixed frame rate) are performed con- tinuously. The triggering signal is present permanently, irrespective of whether or not there is an inspection part in front of the camera. The cam-Image capture and inspection are performed continuously at a defined frame rate. The triggering signal is present permanently. The inspection	FunctionFrame capture and inspection with each valid triggering signal. The triggering signal is generated by a master controller or a sensor as soon as the inspection part is in front of thecamera. The inspection results are output following the inspection, and the camera then waits for the next valid triggering signal.Image capture and inspection (without fixed frame rate) are performed con- tinuously. The triggering signal is present permanently, irrespective of whether or not there is an inspection part in front of the camera. The cam-era acts like a basic sensor. The in- spection results are output following the inspection, and the camera then starts the next inspection immediately.Image capture and inspection are performed continuously at a defined frame rate. The triggering signal is present permanently. The inspectionresults are output following the in- spection. The camera starts the next inspection in accordance with the de- fined frame rate.







1 Bus connection

- 2 Ethernet connection
- 3 Power supply and inputs/outputs
- Adjusting screw for focus 4
- Status LEDs: 5
 - A Ready status
 - B Ethernet traffic C Recording
 - D Output

- Inputs:
- Camera trigger
- Error acknowledgment

Outputs (can be parametrised):

- Ready status
- Good part correctly oriented
- · Good part incorrectly oriented
- Bad part
- Error
- Warning
- External lighting system

4.1

Key features

Interfaces (continued)

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- Commissioning and diagnosis: - PC for configuration and for diagnosis with TCP/IP
- Integration of the camera in the corporate network (integrated web server)

CAN - Vision system as CPI module

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Ethernet – EasylP



All parameters can be modified and all inspection results and characteristic values can be read via the process interface with EasyIP.

- Front End Display FED, e.g. for teach-in, status signals, type selection or parameter modification
- Front End Controller FEC, e.g. for reading characteristic values (e.g. coordinates and rotation angle of parts)

CAN – I/O expansion



- can be integrated into a Festo CPI network. In this case it functions like a binary module with 16 inputs and outputs each.
- ule and a CPX fieldbus, for example, the camera can be accessed via Profibus-DP, Interbus, DeviceNet, CANopen and CC-Link.

be connected to the camera via the camera's CAN interface.

- for binary preselection of the test program
- Output module CP-A04-... for binary signalling of part types

Key features

Software

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Optical orientation detection and quality inspection Vision systems

4.1

CheckKon ------

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Using the CheckKon software, all processes within the camera - from image capture through to the input and output parameters - can be displayed, logged and adapted.

This means:

- Selection of the evaluation mode

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- Display and editing of system parameters
- Display and analysis of last inspected parts
- Display and logging of inspection part images and the characteristics derived therefrom
- Transfer of new test programs
- System documentation



CheckOpti is used for the configuration of test programs. Following the presentation of sample parts, the user defines the characteristics to be inspected with the aid of the software. This is done by selecting the characteristics from a list and then dragging and dropping them to the area of the sample part to be inspected. A total of 64 performance characteristics can thus be defined and optimised within the framework of a test program through the presentation of inspection parts. The test program can then be loaded on one of the camera's 256 memory locations.

Examples of inspection characteristics:

- Vertical length measurement
- Horizontal length measurement
- Angle measurement
- Counting of events
- Measurements on the inspection part contour
- Area definition
- Calculation of grey tone or colour differences

Key features

Application examples

Quality inspection of tube with union nut

The inspection takes place with backlighting; calculated characteristics: - Length of nut

- Threaded coupling distances
- Diameter of tube
- Thread outside diameter
- Angle measurement on the flange
- Circumference of the screw
- Area of the screw





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Screw type differentiation

The inspection takes place with top lighting; calculated characteristics:

- Center-of-mass coordinates x, y
- Average grey tone of area
- Angle of screw drive to horizontal



Compact Vision System SBOC-Q/SBOI-Q Peripherals overview

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Accessories	Brief description	→ Page
Compact vision system		
1 SBOC-Q	For standard lenses with C mount connection	5 / 4.2-56
2 SBOI-Q	With integrated lens and light	
Plug socket with cable		
3 SBOA-K30E-M12S	Ethernet diagnostic cable	5/4.1-47
4 SIM-M12-8GDPU	For supplying the operating voltage	
Cable		
– SBOA-K20CP-WD	For integration in a CPI system	5/4.1-47
– SBOA-K20CP-SUP	For I/O expansion	
Lens		
- SBOL-12	Focal distance 12 mm	5/4.1-47
– SBOL-25	Focal distance 25 mm	
Mounting attachments		
5 Adapter kit SBOA-HMSV-39	With screw-on adapter plate	5/4.1-46
6 Adapter kit SBOA-HMSV-40	Without screw-on adapter plate	
7 Adapter kit SBOA-HMSV-41	With female thread G1/4 for mounting on commercially available tripods]
- Adapter SBOL-C-5	5 mm spacer ring (CS mount to C mount)	5 / 4.1-47

3

Compact Vision System SBOC-Q/SBOI-Q Type codes

		SBO	C	-	Q	-	R1B
Function	1						
SBO	Compact vision system		J				
Design							
С	For standard lens with C mount connection						
I	Integrated lens						
Equipm	ent						
Q	Area-scan camera for quality inspection						
Sensor	resolution, sensor type						
R1B	VGA resolution (640 x 480 pixels), monochrome						
R1C	VGA resolution (640 x 480 pixels), colour						
R2B	SXGA resolution (1,280 x 1,024 pixels), monochrome						
R2C	SXGA resolution (1,280 x 1,024 pixels), colour						

Compact Vision System SBOC-Q/SBOI-Q Technical data

Temperature range -10[°]... +50 °C



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General technical data

General technical data							
		SBOC-Q-R1B	SBOC-Q-R1C	SBOI-Q-R1B	SBOI-Q-R1C	SBOC-Q-R2B	SBOC-Q-R2C
Sensor resolution	[pixels]	640 x 480		1,280 x 1,024			
Exposure time	[ms]	0.027 1,000		0.008 1,000			
Frame rate (full image)	[fps]	150		27			
Lens mounting		C mount Integrated lens		C mount			
Sensor type		Monochrome	Colour	Monochrome	Colour	Monochrome	Colour
Operating distance	[mm]	Dependent on the lens selected 22 1,000			Dependent on the lens selected		
Field of vision	[mm]	Dependent on the lens selected 14 x 10 520 x 390		Dependent on the lens selected			
Max. no. of test programs		256					
Sorting function		Up to 16 types per	test program				

Electrical data		
Nominal operating voltage	[V DC]	24
Permissible voltage fluctuations		±10%
Max. residual current	[A]	1.5 at the 24 V outputs
Current consumption	[mA]	120
with load-free outputs		
Inputs		Input 1: Trigger signal
		Input 2: Apply inputs
Outputs		Output 1: Ready for operation
		Output 2 and output 3 can be parameterised:
		Good part, bad part, correctly oriented, incorrectly oriented, external lighting system
Bus connection		Ethernet interface
		IEEE802.3U (100BaseT)
		100 Mbit/s
		TCP/IP
		M12
		CAN interface
		Festo CP
		M12
Protection class		IP65, IP67

Materials Housing Anodised aluminium Acrylic butadiene styrene, glass fibre reinforced Cover Note on materials Free of copper and PTFE

4.1

Vision systems Optical orientation detection and quality inspection

Technical data

1

Operating and environmental conditions				
Ambient temperature [°C]	-10 +50			
Storage temperature [°C]	-10 +60			
Ambient conditions	Screened from extreme external light sources			
	Cleanest possible ambient air			

Weights [g]					
	SBOC-Q	SBOI-Q			
Compact vision system	182	184			



outputs	
Ordering data	
Sensor resolution	Sensor typ
640 x 480 pixels (VGA)	
For standard long with C mount connection	Monochro

2 Ethernet connection

2

<u>18.8</u>

1 Power supply and inputs/

Sensor resolution	Sensor type	Part No.	Туре
640 x 480 pixels (VGA)			
For standard lens with C mount connection	Monochrome	541 399	SBOC-Q-R1B
	Colour	548 317	SBOC-Q-R1C
Integrated lens	Monochrome	541 396	SBOI-Q-R1B
	Colour	548 316	SBOI-Q-R1C
1,280 x 1,024 pixels (SXGA)			
For standard lens with C mount connection	Monochrome	551 021	SBOC-Q-R2B
	Colour	551 022	SBOC-Q-R2C

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3 Bus connection

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Optical orientation detection and quality inspection Vision systems 4.1

Accessories

Adapter kit

SBOA-HMSV-39 With screw-on adapter plate

Material: Wrought aluminium alloy, anodised



Ordering data		
	Part No.	Туре
Adapter kit	541 599	SBOA-HMSV-39

Adapter kit SBOA-HMSV-40 Without screw-on adapter plate

Material: Wrought aluminium alloy, anodised



Ordering data		
	Part No.	Туре
Adapter kit	541 600	SBOA-HMSV-40

Adapter kit

SBOA-HMSV-41 With female thread G¹/₄ for mounting on commercially available tripods

Material: Wrought aluminium alloy, anodised



Ordering data		
	Part No.	Туре
Adapter kit	542 140	SBOA-HMSV-41

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Compact Vision System SBOC-Q/SBOI-Q Accessories

Adapter SBOL-C-5 5 mm spacer ring

(CS mount to C mount)

Material: Wrought aluminium alloy, anodised





Ordering data		
	Part No.	Туре
Adapter	541 601	SBOL-C-5

Ordering data – Lens						
	Brief description	Focal distance	Part No.	Туре		
		[mm]				
	C mount with fixed focal distance	12	549 132	SBOL-12		
		25	549 133	SBOL-25		

Ordering data – Cable M12x1					Technical data → 4 / 8.3-22	
	Assembly	Use	Connection	Cable length	Part No.	Туре
				[m]		
Straight socket						
	Union nut M12x1	Operating voltage supply	8-pin	2	525 616	SIM-M12-8GD-2-PU
Si la				5	525 618	SIM-M12-8GD-5-PU
and and	Union nut M12x1	Ethernet diagnostic cable	4-pin, d-coded	3	542 139	SBOA-K30E-M12S
ST OLD		For integration in a CPI system	5-pin	2	548 823	SBOA-K20CP-WS
		For I/O expansion]	2	548 824	SBOA-K20CP-SUP

Ordering data – Documentation					
	Brief description	Language	Part No.	Туре	
	Description User documentation in paper form is not included in the	German	548 318	P.BE-SBO-Q-DE	
	scope of delivery of the vision system.	English	548 319	P.BE-SBO-Q-EN	
	Documentation package	German	549 036	P.BE-SBO-Q-UDOK	
	The user documentation on CD-ROM is included in the scope	English			
	of delivery of the compact vision system.				

Ordering data – Software					
	Brief description	Language	Part No.	Туре	
	CheckKon software with manual	German	194 496	P.SW-CB-KON	
		English			
	CheckOpti software with manual	German	192 144	P.SW-CB-OPTI-DE	
		English	192 145	P.SW-CB-OPTI-EN	

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4.1