



# Special-function drives

### Fluidic Muscle DMSP/MAS

Key features



#### At a glance

High initial force and acceleration

- Initial force up to 10 times higher than a conventional cylinder of the same diameter
- Highly dynamic response, even at high loads

#### Judder-free operation

- No mechanical parts moving against one another
- Completely jolt-free with extremely slow movements

#### Simple positioning

■ Controlled by means of pressure using the simplest technology without displacement encoders

#### Hermetically sealed design

- Separation between operating medium and atmosphere
- Ideal for dusty and dirty environments
- Robust design
- Zero leakage

### Mode of operation

Fluidic Muscle is a tensile actuator which mimics natural muscular movement. It consists of a contraction system and appropriate connectors. The contraction system is formed by a pressure-tight length of rubber hose, sheathed in high-strength fibres. The fibres create a rhomboidal pattern with a three-dimensional grid

structure. When internal pressure is applied, the hose expands in its peripheral direction, thus creating a tensile force and a contraction motion in the muscle's longitudinal direction. The usable tensile force is at its maximum at the start of the contraction and then decreases in a virtually linear manner as a function of stroke.

An efficient operating range is provided with contractions of up to 15% of the nominal length.

The applications of Fluidic Muscle are

- Single-acting actuator
- Pneumatic spring

### \_ **≜** .

Not

Fluidic Muscle is intended for use as a tensile actuator only. The expansion in the peripheral direction cannot be used for clamping purposes, since external friction could cause damage to the muscle.

### Fluidic Muscle DMSP, with press-fitted connections



The Fluidic Muscle DMSP with pressfitted connections is the result of a thorough analysis of the requirements specification that already existed for the Fluidic Muscle MAS. The resulting new development is therefore considerably lighter, more compact and durable.

### → 1 / 5.6-8

- More compact design with more muscle, achieved thanks to a 25% more compact cross section.
- Up to 30% less weight, which translates into a superb force/weight
- Choice of three integrated adapter variants.

### Fluidic Muscle MAS, with screwed connections



The Fluidic Muscle MAS is characterised by a long service life that is made possible through the use of optimised materials. The Fluidic Muscle MAS is also available with an adapter and force-safety device.

- The force-safety device makes it possible to limit the lifting force, which can for instance protect against trapping objects.
- Use of customer-specific adaptation options.

# Special-function drives

### Fluidic Muscle DMSP/MAS

Key features

### **FESTO**

### Sizing the muscle

Sizing software

Sizing should be carried out using the MuscleSIM software. You can download this software from the Festo home

page → www.festo.com/download or request a copy on CD-ROM from Festo.

### Graphical sizing

Apart from sizing the muscle using the software, it is also possible to define the length of the muscle with the aid of force/displacement diagrams.

Graphical sizing of the muscle is explained with the aid of two examples  $\rightarrow$  32.

#### Force curve and load cases

The nominal length of the pneumatic muscle is defined in the non-pressurised, load-free state. It corresponds to

the visible muscle length between the connections. The muscle extends

when it is pretensioned by an external force. When pressurized, on the other

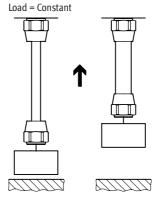
hand, the muscle contracts, i.e. its length decreases.

Sizing examples → 32

### Single-acting actuator

In the simplest case, Fluidic Muscle operates as a single-acting actuator against a constant load. Assuming that this load is permanently attached to the muscle, it will project from its initial position when in the extended non-pressurised state. This operating status is ideal with regard to the technical properties of Fluidic Muscle: when pressurised, a Fluidic Muscle pretensioned in this way develops

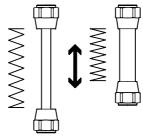
maximum force with optimum dynamic characteristics and minimum air consumption. The usable force is also at a maximum in this case. If a Fluidic Muscle is required to be free of forces in the extended state, for example to allow a load to be attached, a holding force must first be developed for lifting purposes, leaving a small force component for the motion itself.



Fluidic Muscle behaves like a spring with a changing external force: it follows the direction of action of the force. With Fluidic Muscle, both the pretensioning force of this "pneumatic spring" and its spring stiffness can be varied. Fluidic Muscle can be

operated as a spring with constant pressure or constant volume. These produce different spring characteristics that enable the spring effect to be matched perfectly to a given application.

Pressure/volume = Constant

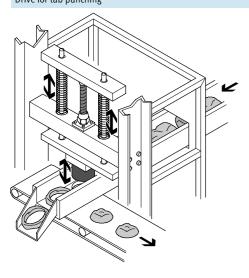




Note

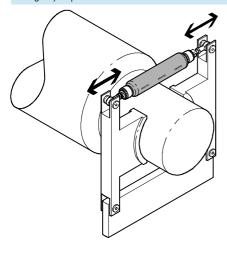
If the muscle is fed with compressed air and the volume blocked, the pressure in the muscle can increase significantly when the external force is varied. The service life of the Fluidic Muscle depends on the contraction, the operating pressure and the temperature →34.

High operating frequencies or high loads can lead to a temperature rise.



Very high cycle rates are possible with the muscle, on the one hand because of its low weight and on the other because it has no moving parts (e.g. piston). The simple construction – one muscle pretensioned using two springs – replaces a complicated toggle lever clamping system using cylinders. This makes a frequency increase of 3 to 5 Hz possible. Over 50 million load fluctuations can be achieved in this way.

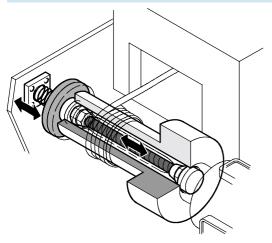
### Emergency stop for rollers



The fluidic muscle is setting new standards in applications that require fast response times. The emergency stop for rollers demands both speed and force. Long machine downtimes in the event of malfunctions can thus be prevented.

### Judder-free movements

Brake actuator for rewinding equipment



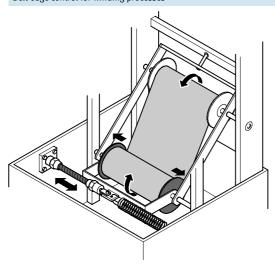
The friction-free muscle allows uniform and gentle braking of the pay-out reel, ensuring highly precise winding at constant speed. Control is provided by a proportional control valve whose signals are regulated via force sensors.

### Fluidic Muscle DMSP/MAS

Typical applications

### Judder-free movements

Belt edge control for winding processes



The aim:

uniform winding of paper, foil or textiles.

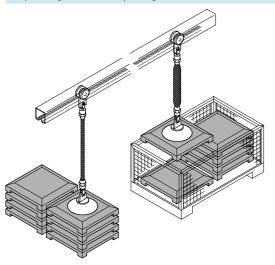
The requirement:

a friction-free drive with quick and immediate response characteristics. The solution:

Fluidic Muscle. The drum attached to a moving frame is displaced by a pneumatic muscle as soon as the sensor detects misalignment. This means that the winding edge control is 100% efficient.

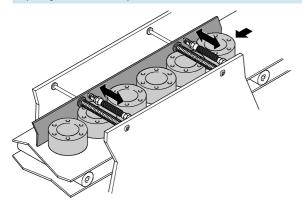
### Simple positioning systems

Simple lifting device for manipulating concrete slabs and car wheel rims



Approximate intermediate positions? No problem with pressure regulation. The workpieces can be raised or lowered as required by pressurising or exhausting the muscle via a hand lever valve. Muscle lengths up to 9 m facilitate various types of application.

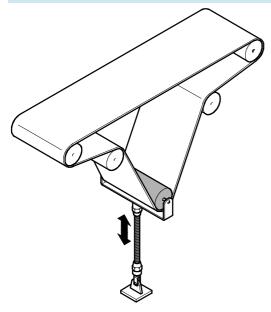
### Adjusting the width of conveyor belts



With small batch sizes, it is often necessary to adapt entire system sections to different component dimensions after a short period of time. This task can be performed with the fluidic muscle in cases where an approximate adjustment is sufficient.

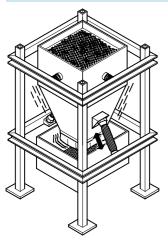
### Harsh environmental conditions

Belt tensioner for conveyed goods



In dusty or dirty environments, a hermetically sealed fluidic muscle has a major advantage over conventional drives. This seal cannot wear. It is a sturdy, contractible tube that copes with the tough demands of the cement industry with ease.

### Drive for a vibratory hopper



Hoppers and silos are susceptible to the problem of parts jamming during feeding. Fluidic Muscle facilitates stepless regulation of a pneumatic shaker between 10 and 90 Hz, thereby guaranteeing continuous delivery.

# -O- New DMSP

# Fluidic Muscle DMSP/MAS

Product range overview

**FESTO** 

nction	Version	Туре	Inside dia.	Nominal length [mm]	Lifting force [N]	Max. permissible pretensioning	Max. permissible contraction	Operating pressure [bar]	→ Page
ngle-	Fluidic Muscle		sed connectio						
oulling		DMSP	10	40 9000	0 630	3% of nominal length	25% of nominal length	0 8	1 / 5.6-8
	W W	DMSP	20	60 9000	0 1500	4% of nominal length	25% of nominal length	0 6	1 / 5.6-8
		DMSP	40	120 9000	0 6000	5% of nominal length	25% of nominal length	0 6	1 / 5.6-8
	Fluidic Muscle	with screv	ved connectio	ns					
		MAS	10	40 9000	0 630	3% of nominal length	25% of nominal length	0 8	18
		MAS	20	60 9000	0 1500	4% of nominal length	25% of nominal length	0 6	18
		MAJ	20	00 9000	0 1300	4 % of Hommat tength	23% of Homiliat teligin	0 0	10
		MAS	40	120 9000	0 6000	5% of nominal length	25% of nominal length	0 6	18

-1 - To be discontinued



#### Note

When replacing a Fluidic Muscle MAS and accessories MXAC (first-generation products available until 06/2005) as listed in the table opposite with a Fluidic Muscle MAS and mounting accessories MXAD as

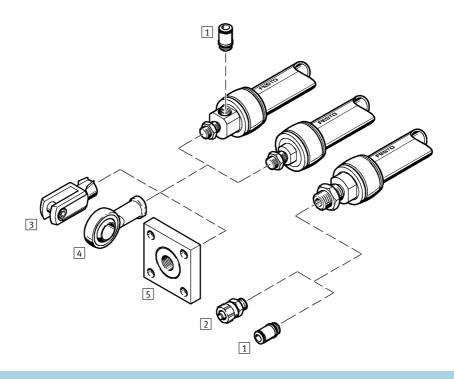
described in this document (part numbers → 28), please consult your contact person at Festo. Compatibility cannot be guaranteed in all cases due to changes in installation dimensions.

E .0 20 C										
Fluidic Mu	scle MAS	Mounting accessories MXAC								
Part No.	Туре	Part No.	Туре							
187 594	MAS-10-NAA-MCFK	187 591	MXAC-B10							
187 595	MAS-10-NAA-MOFK	187 592	MXAC-A10							
187 617	MAS-20-NAA-MCHK	187 593	MXAC-R10							
187 618	MAS-20-NAA-MCGK	187 614	MXAC-B16							
187 619	MAS-20-NAA-MOHK	187 615	MXAC-A16							
187 605	MAS-40-NAA-MCKK	187 616	MXAC-R16							
187 606	MAS-40-NAA-MCIK	187 602	MXAC-B20							
187 607	MAS-40-NAA-MOKK	187 603	MXAC-A20							
		187 604	MXAC-R20							

# Fluidic Muscle DMSP, with press-fitted connections

**FESTO** 

Peripherals overview

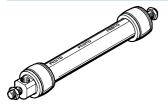


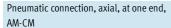
### Variants

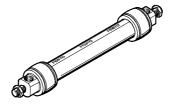
Pneumatic connection, radial, at one end,

Pneumatic connection, radial, at both ends,

Pneumatic connection, radial and axial,







Pneumatic connection, axial, at both ends,



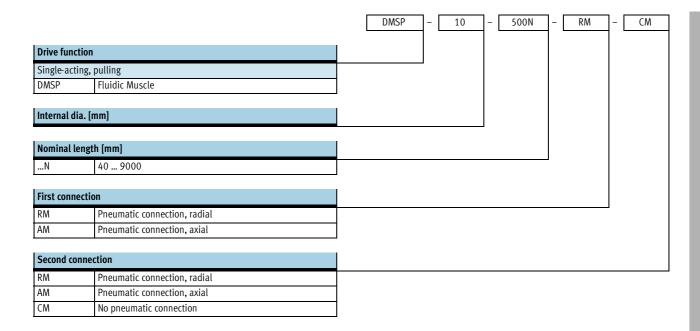


Mounting attachments and acc	Mounting attachments and accessories									
	Brief description	→ Page								
1 Push-in fittings QS	For connecting compressed air tubing with standard external diameters	Volume 3								
2 Quick connectors CK	For connecting compressed air tubing with standard internal diameters	Volume 3								
3 Rod clevis SG	Permits swivel motion of the Fluidic Muscle in one plane	17								
4 Rod eye SGS	With spherical bearing	17								
5 Coupling pieces KSG/KSZ	For compensating radial deviations	17								

# Fluidic Muscle DMSP, with press-fitted connections

**FESTO** 

Type codes



# Fluidic Muscle DMSP, with press-fitted connections

**FESTO** 

Technical data

- **Ø** - Size 10 ... 40 mm

Nominal length 40 ... 9000 mm

Lifting force 0 ... 6000 N



General technical data							
Size		10	20	40			
Pneumatic connection		G1/8	G½ G½ G3/8				
Design		Contraction membrane	·	·			
Mode of operation		Single-acting, pulling					
Internal dia.	[mm]	10	20	40			
Nominal length	[mm]	40 9000	60 9000	120 9000			
Max. additional load, freely suspended	[kg]	30	80	250			
Max. permissible pretensionsing <sup>1)</sup>		3% of nominal length	4% of nominal length	5% of nominal length			
Max. permissible contraction		25% of nominal length	·	·			
Max. hysteresis		≤ 3% of nominal length	≤ 2.5% of nominal length				
Max. relaxation		≤ 3% of nominal length					
Repetition accuracy		≤ 1% of nominal length					
Max. perm. offset of connections		Angle tolerance: ≤ 1.0°	Angle tolerance: ≤ 1.0°				
		Parallelism tolerance: ± 0.5% (up to 400 mm nominal length), ≤ 2 mm (from 400 mm nominal length)					
Type of mounting		With accessories					
Assembly position		Any (an external guide is requir	ed if lateral forces occur)				

 $1) \quad \text{The max. pretensioning is achieved when the max. permissible freely suspended useful load is attached.} \\$ 

Operating and environmental conditions									
Size		10	20	40					
Operating pressure	[bar]	0 8	0 6						
Operating medium		Filtered compressed a	Filtered compressed air, lubricated or unlubricated (other media upon request)						
Ambient temperature	[°C]	-5 +60							
Corrosion resistance class CRC <sup>2)</sup>		2							

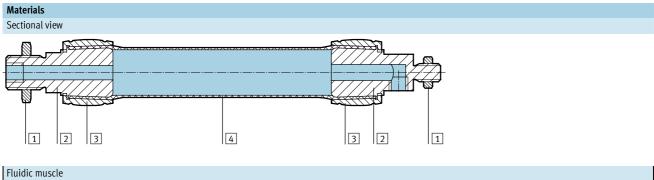
2) Corrosion resistance class 2 according to Festo standard 940 070 Components requiring moderate corrosion resistance. Externally visible parts with primarily decorative surface requirements which are in direct contact with a normal industrial environment or media such as coolants or lubricating agents.

Forces [N] at max. permissible operating pressure									
Size	10	20	40						
Theoretical force	630	1500	6000						

# Fluidic Muscle DMSP, with press-fitted connections Technical data

**FESTO** 

Weight [g]									
Size		10	20	40					
Basic weight at 0 m length	RM-CM	58	169	675					
	RM-RM	66	182	707					
	RM-AM	75	202	767					
	AM-CM	66	189	735					
	AM-AM	83	222	827					
Additional weight per 1 m length		94	178	340					



Fluidic r	luidic muscle							
1 Nu	ut	Galvanised steel						
2 Fla	lange	Wrought aluminium alloy, clear anodised						
3 SI	leeve	Wrought aluminium alloy, clear anodised						
4 M	lembrane	Chloroprene, aramide						

### Fluidic Muscle DMSP, with press-fitted connections

**FESTO** 

Technical data

### Permissible force F [N] as a function of the contraction h [%] of the nominal length

Force/displacement diagrams and sizing ranges

The limit for "freely suspended" loads is derived from the contraction. With the Fluidic Muscle DMSP-10-..., a

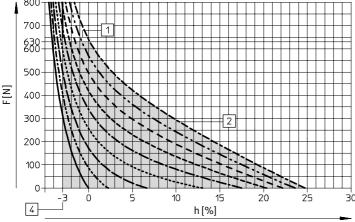
loosely attached additional load of 30 kg results in 3% pretensioning (see diagram). The limits specified in the

technical data must be complied with when using the fluidic muscle. The diagrams below illustrate the operating range of the fluidic muscle, depending on the diameter, within the boundary lines illustrated below.

### Using the diagrams

- 1. The upper limit of the grey area describes the minimum theoretical force at maximum operating pressure.
- The right limiting curve of the grey area describes the maximum permissible operating pressure.
- The right vertical limit of the grey area describes the maximum permissible contraction.
- The left limit of the grey area describes the load limit of the muscle defined by the maximum pretensioning.







0 bar

1 bar

2 bar

3 bar

4 bar

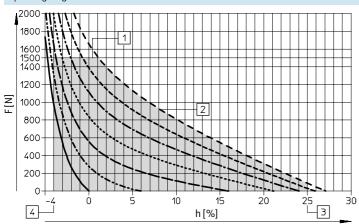
5 bar

**- -** 6 bar

### Sizing examples → 32

- 1 Min. theoretical force at max. operating pressure
- Max. operating pressure
- 4 Max. pretensioning
- Permissible operating range

### Operating range DMSP-20-200N-..



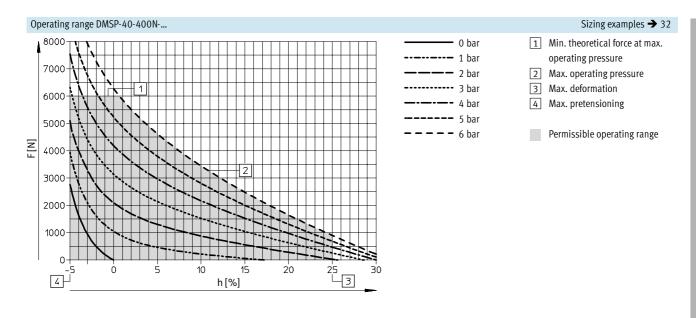
### Sizing examples → 32

- 1 Min. theoretical force at max. operating pressure
- 2 Max. operating pressure
- 3 Max. deformation
- Max. pretensioning
- Permissible operating range

### Fluidic Muscle DMSP, with press-fitted connections

**FESTO** 

Technical data



- 🖥 - Note

The diagrams were determined using muscles with standard length (standard length = 10x internal dia.), sizing should therefore be carried out using the Fluidic Muscle sizing software. The software is available at

the address www.festo.com/download or can be requested on CD-ROM from Festo.

Approximate sizing is possible using the force/displacement diagram. Properties that influence the dependence

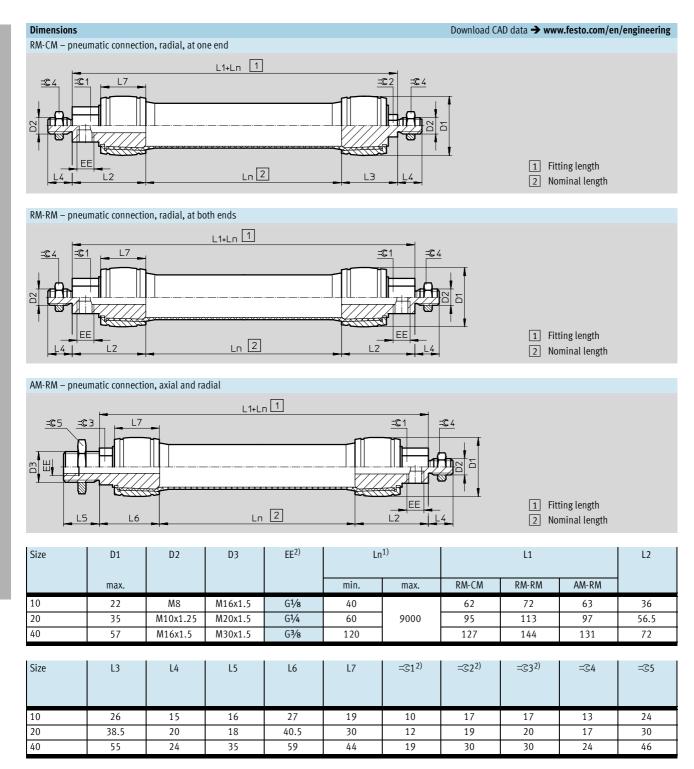
between force and displacement, such as material properties, manufacturing deviations and nominal length, are not taken into account in these diagrams. The theoretical force can therefore increase by up to ten per

cent. Deviations can be compensated by means of pressure adaptation up to the maximum permissible operating pressure.

# Fluidic Muscle DMSP, with press-fitted connections

**FESTO** 

Technical data

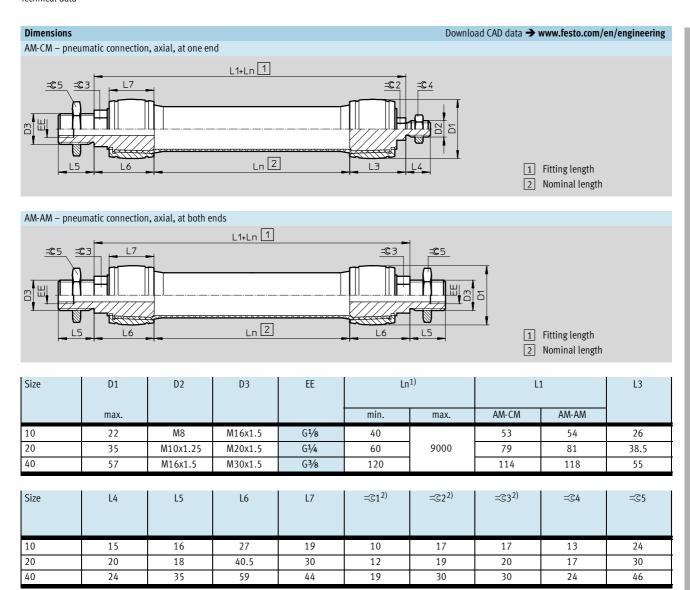


- 2) Parallel orientation of the spanner flats on the left and right connection side can lead to deviations (for production reasons).

### Fluidic Muscle DMSP, with press-fitted connections

**FESTO** 

Technical data



- Tolerance < 100 mm ±1 mm, 100 ... 400 mm ±1%, > 400 mm ±4 mm.
   Parallel orientation of the spanner flats on the left and right connection side can lead to deviations (for production reasons).

# Fluidic Muscle DMSP, with press-fitted connections Ordering data – Modular products

Closed, male thread

Connecting thread

Radial, male thread

**FESTO** 

Second connection

Λ	M Mandatory o	data									
N	Nodule No.	Function		Size		Nominal length		First connection	n	Second con	nection
5	641 403 641 404 641 405	DMSP		10 20 40		40 9 000		RM AM		CM RM AM	
0 e	Ordering example 641 404	DMSP	-	- 20		5 000 N		АМ	-	RM	
	dering table		1		1		1		la u		1
Siz	e		10		20		40		Condi- tions	Code	Enter code
N	Module No.		541 403		541 404		541 40	5			
	Function		Fluidic M	uscle with press-fitt	ed connect	ions	•			DMSP	DMSP
	Size	[mm	10		20		40				
	Nominal length				60 900	00	120 9	000		N	N
	First connection	n		ale thread						-RM	
				ng thread / supply p							
			M8 / G <sup>1</sup> /8		M10x1.2	5 / G <sup>1</sup> / <sub>4</sub>	M16x1.	5 / G3⁄8			
			Axial, ma							-AM	
				ng thread / supply p		1.01%	LM20v4	r / C3/-			
			M16x1.5	/ U-/8	M20x1.5	/ U <sup>-</sup> /4	M30x1.	) / U <sup>2</sup> /8			

Connecting thread / supply po	ort			1
M8 / G <sup>1</sup> / <sub>8</sub>	M10x1.25 / G <sup>1</sup> / <sub>4</sub>	M16x1.5 / G3/8		1
Axial, male thread			-AM	i
Connecting thread / supply po	ort			
M16x1.5 / G <sup>1</sup> / <sub>8</sub>	M20x1.5 / G <sup>1</sup> / <sub>4</sub>	M30x1.5 / G3/8		

M10x1.25

M16x1.5

Transfer order	cod	e						
		DMSP	-	-	N	-	-	

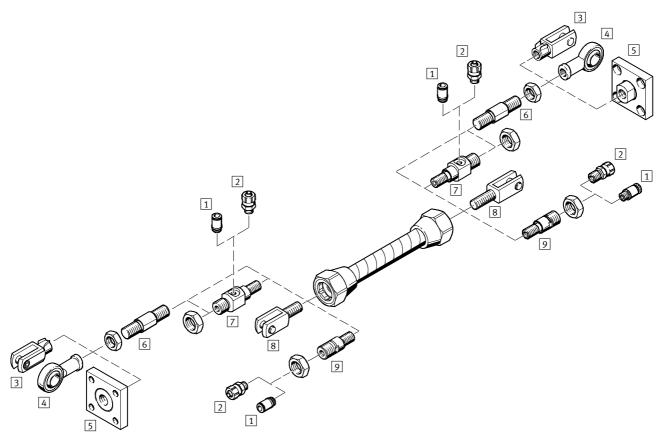
-CM

# Fluidic Muscle DMSP, with press-fitted connections Accessories

Ordering data							Technical data → 1 / 10.3-2
Designation	For size	Part No.	Туре	Designation	For size	Part No.	Туре
Rod eye SGS				Coupling piece	KSG		
~ <b>®</b>	10	9 255	SGS-M8	6	10	-	
	20	9 261	SGS-M10x1,25		20	32 963	KSG-M10x1,25
	40	9 263	SGS-M16x1,5		40	32 965	KSG-M16x1,5
					•		
Rod clevis SG				Coupling piece	KSZ		
2 🚳	10	3 111	SG-M8	6	10	36 124	KSZ-M8
	20	6 144	SG-M10x1,25		20	36 125	KSZ-M10x1,25
6	40	6 146	SG-M16x1,5		40	36 127	KSZ-M16x1,5

# Fluidic Muscle MAS, with screwed connections Peripherals overview

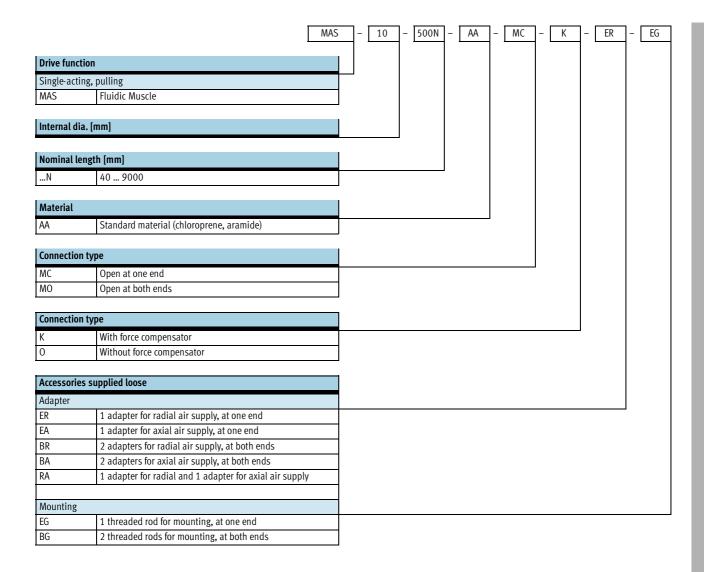
**FESTO** 



Μοι	nting attachments and accessor	ies	
		Brief description	→ Page
1	Push-in fittings QS	For connecting compressed air tubing with standard external diameters	Volume 3
2	Quick connectors CK	For connecting compressed air tubing with standard internal diameters	Volume 3
3	Rod clevis SG	Permits a swivelling movement of the fluidic muscle in one plane	31
4	Rod eye SGS	With spherical bearing	31
5	Coupling pieces KSG/KSZ	For compensating radial deviations	31
6	Threaded rod MXAD-T	For connecting drive accessories	31
7	Radial adapter MXAD-R	For connecting drive accessories and the air supply in radial direction	30
8	Rod clevis SGA	With male thread for direct mounting on fluidic muscle	31
9	Axial adapter MXAD-A	For connecting drive accessories and the air supply in axial direction	30

### Fluidic Muscle MAS, with screwed connections

Type codes



### Fluidic Muscle MAS, with screwed connections

Technical data

Size 10 ... 40 mm

Nominal length 40 ... 9000 mm

Lifting force 0 ... 6000 N



General technical data						
Size		10	20	40		
Pneumatic connection		→ Adapter MXAD from page 30	)			
Design		Contraction diaphragm				
Mode of operation		Single-acting, pulling				
Internal dia.	[mm]	10	20	40		
Nominal length	[mm]	40 9000	60 9000	120 9000		
Max. additional load, freely suspended	[kg]	30	80	250		
Max. permissible pretensionsing <sup>1)</sup>	Without force	3% of nominal length	4% of nominal length	5% of nominal length		
	compensator					
	With force	3% of nominal length	3% of nominal length	3% of nominal length		
	compensator					
Max. permissible contraction		25% of nominal length	25% of nominal length			
Max. hysteresis		≤ 3% of nominal length	≤ 2.5% of nominal length			
Max. relaxation		≤ 4% of nominal length		≤ 3% of nominal length		
Repetition accuracy		≤ 1% of nominal length				
Type of mounting		With accessories	With accessories			
Assembly position		Any (an external guide is required if lateral forces occur)				

 $1) \quad \text{The max. pretensioning is achieved when the max. permissible freely suspended useful load is attached.} \\$ 

Operating and environmental conditions								
Size		10	20	40				
Operating pressure	[bar]	0 8	0 6					
Operating medium		Filtered compress	Filtered compressed air, lubricated or unlubricated (other media upon request)					
Ambient temperature	[°C]	-5 +60	-5 +60					
Corrosion resistance class CRC <sup>2)</sup>		2						

2) Corrosion resistance class 2 according to Festo standard 940 070 Components requiring moderate corrosion resistance. Externally visible parts with primarily decorative surface requirements which are in direct contact with a normal industrial environment or media such as coolants or lubricating agents.

Forces [N] at max. permissible operating pressure									
Size	10	20	40						
Theoretical force	630	1500	6000						
Force compensation	400	1200	4000						

# Fluidic Muscle MAS, with screwed connections Technical data

Weight [g]				
Size		10	20	40
Basic weight at 0 m length		77	238	673
Additional weight per 1 m length	Additional weight per 1 m length		178	340
Connection without force compensator	MO	38	114	331
	MC	39	124	342
Connection with force compensator	MO	49	153	521
	MC	49	153	521

# Materials Sectional view 5 1 6 4 3

Fluid	lic muscle				
1	1 Union nuts Wrought aluminium alloy, clear anodised				
2	Flange	Wrought aluminium alloy, blue anodised			
3	Internal cone	Wrought aluminium alloy, clear anodised			
4	Cup springs	Steel			
5	Sealing ring	Nitrile rubber			
6	Diaphragm hose	Chloroprene, aramide			
-	Adhesive	Loctite 243 (thread locking agent)			
-	Lubricant	Klüberplex BE 31-102			
	Note on materials	Copper, PTFE and silicone-free			

### Fluidic Muscle MAS, with screwed connections



### Permissible force F [N] as a function of the contraction h [%] of the nominal length

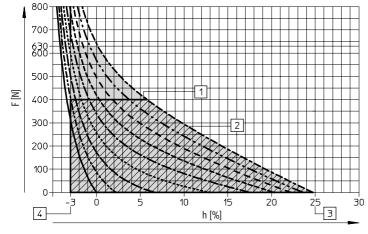
The limit for "freely suspended" loads is derived from the contraction. With the Fluidic Muscle MAS-10-..., a

loosely attached additional load of 30 kg results in 3% pretensioning (see diagram). The limits specified in the technical data must be complied with when using the fluidic muscle. The diagrams below illustrate the operating range of the fluidic muscle, depending on the diameter, within the boundary lines illustrated below.

### Using the diagrams

- The upper limit of the hatched operating range describes the maximum theoretical force when using the force compensator.
- The right limiting curve of the permissible operating ranges describes the maximum permissible operating pressure.
- The right vertical limit of the permissible operating ranges describes the maximum permissible contraction.
- The left limit of the permissible operating ranges describes the load limit of the muscle defined by the maximum pretensioning.

### Operating range MAS-10-100N-...





0 bar

1 bar

2 bar

3 bar

4 bar

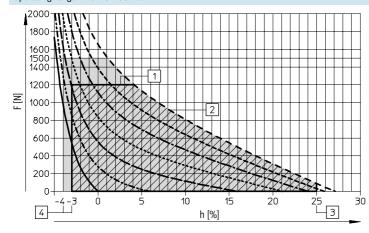
5 bar

6 bar

### Sizing examples → 32

- Force compensation with MAS-10-...-K
- 2 Max. operating pressure
- 3 Max. deformation
- 4 Max. pretensioning
- Permissible operating range for MAS-10-...
- Permissible operating range for MAS-10-...-K

### Operating range MAS-20-200N-..



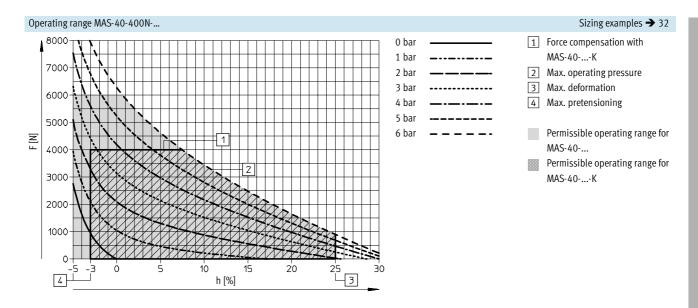


- 1 Force compensation with MAS-20-...-K
- 2 Max. operating pressure
- 3 Max. deformation
- 4 Max. pretensioning
- Permissible operating range for MAS-20-...
- Permissible operating range for MAS-20-...-K

5.6

### Fluidic Muscle MAS, with screwed connections

Technical data



- 🖣 - Note

The specified pretensioning applies to the design without force compensation – the diagrams were determined using muscles with standard length (standard length = 10x internal dia.), sizing should therefore be carried out

using the Fluidic Muscle sizing software. The software is available at the address www.festo.com/download or can be requested on CD-ROM from Festo.

Approximate sizing is possible using

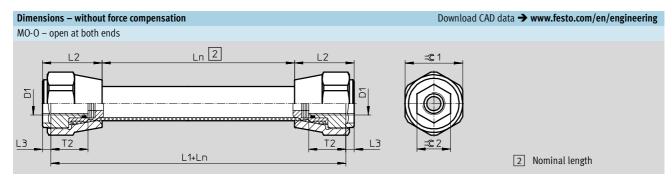
the force/displacement diagram. Properties that influence the dependence between force and displacement, such as material properties, manufacturing deviations and nominal length, are not taken into account in these

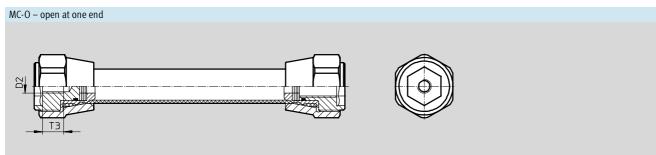
diagrams. The theoretical force can therefore increase by up to ten per cent. Deviations can be compensated by means of pressure adaptation up to the maximum permissible operating pressure.

**FESTO** 

# Fluidic Muscle MAS, with screwed connections Technical data

**FESTO** 





Size	D1	D2	Li	L1	
			min.	max.	
10	M10x1.25	M10x1.25	40		60.2
20	M16x1.5	M10x1.25	60	9000 <sup>1)</sup>	73
40	M20x1.5	M16x1.5	120		95

Size	L2	L3	T2	Т3	<b>=</b> ©1	<b>-</b> ©2
10	34.1	4	10	10	27	17
20	42.5	6	26.5	15	41	24
40	55.5	8	21.8	20	60	41

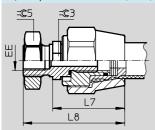
<sup>1)</sup> Tolerance ≤ 100 mm ±1 mm, 100 ... 400 mm ±1%, > 400 mm ±4 mm.

# Fluidic Muscle MAS, with screwed connections

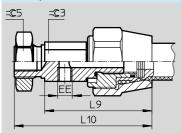
Technical data



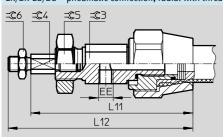
 ${\sf EA/BA-pneumatic\ connection,\ axial,\ one\ end/both\ ends}$ 



### ER/BR – pneumatic connection, radial, one end/both ends



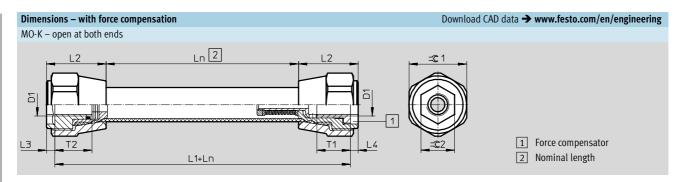
### ER/BR-EG/BG – pneumatic connection, radial with threaded rod, one end/both ends

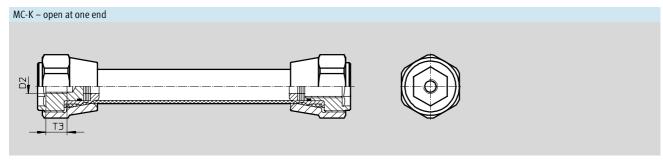


Size		EE L5 L6	L7	L8	L9		
	Axial	Radial					
10	G½8	M5	46.1	61.1	42.6	60	58.2
20	G1/4	G1/8	52.5	67.5	49	69	71
40	G3/8	G1/4	67.5	91.5	63	101	93
					•		•
Size	L10	L11	L12	=©3	=©4	=©5	=©6
			444.6	4.7	1.1	27	4.7
10	75.6	96.6	111.6	17	11	24	17
10 20	75.6 91	96.6 107	111.6	24	11	32	17

# Fluidic Muscle MAS, with screwed connections Technical data

**FESTO** 





Size	D1	D2	Ln		L1	L2
			min.	max.		
10	M10x1.25	M10x1.25	40	9000 <sup>1)</sup>	61.7	34.1
20	M16x1.5	M10x1.25	60		73.5	42.5
40	M20x1.5	M16x1.5	120		96.5	55.5

Size	L3	L4	T1	T2	T3	<b>=</b> ©1	<b>=</b> ©2
10	4	2.5	15	10	10	27	17
20	6	5.5	24	26.5	15	41	24
40	8	6.5	30	21.8	20	60	41

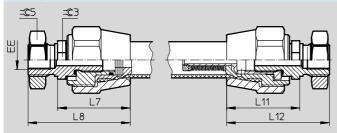
<sup>1)</sup> Tolerance ≤ 100 mm ±1 mm, 100 ... 400 mm ±1%, > 400 mm ±4 mm.

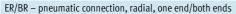
# Fluidic Muscle MAS, with screwed connections

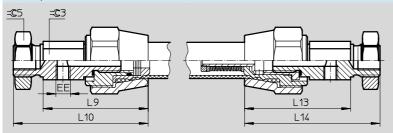
Technical data

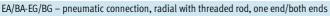


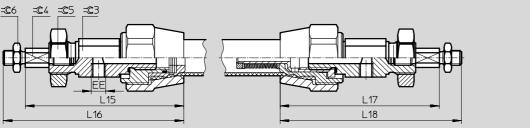
### EA/BA – pneumatic connection, axial, one end/both ends











Size	EE		L5	L6	L7	L8	L9	L10	L11	L12
	Axial	Radial								
10	G1/8	M5	46.1	61.1	42.6	60	58.2	75.6	44.1	61.5
20	G1/4	G1/8	52.5	67.5	49	69	71	91	49.5	69.5
40	G3/8	G1/4	67.5	91.5	63	101	93	131	64.5	102.5
Size	L13	L14	L15	L16	L17	L18	=©3	=©4	=©5	=©6
10	59.7	77.1	96.6	111.6	98.1	113.1	17	11	24	17
20	71.5	91.5	107	122	107.5	122.5	24	11	32	17
40	94.5	132.5	151	175	152.5	176.6	36	17	46	24

# Fluidic Muscle MAS, with screwed connections Ordering data – Modular products

**FESTO** 

M Mandatory d	data									0 0	ptions		
Module No.	Function	Inside dia.	Nominal length		Material		Connection type	Cor typ	nector e	Adapte	er	Мо	unting
34 201	MAS	10	N		AA		MC	K		ER		EG	
34 202	MAS	20	۱۷		<i>/</i> //		MO	0		EA		BG	
34 203		40					IVIO	0		BR		ВО	
34 203		40								BA			
										RA			
ordering													
xample	MAS -	10	FOON	_	A A		MC	1/		- FD		EG	
34 201	MAS -	10	500N	[	AA	-	MC	- K		– ER	_	EG	
dering table													
e rante		10		20			40			Condi-	Code		Enter
.с		10		20			40			tions	Code		code
Module No.		534 201		534 20	12		534 203			110113			couc
Function		Fluidic Muscle w					334 203				MAS		MAS
Internal dia.	[]	10		nnecuo 20	DIIS		40						IVIAS
Nominal length	[mm]	40 9000		20 60 9	000		120 90	100			N		-
Material	[mm]	Standard materia			000		120 90	000			N -AA		-AA
Connection type	•	Fluidic Muscle o	•								-AA		-AA
Connection type	e	Fluidic Muscle o	•								-MO		
Connector type		Screwed connect	•		oncator						-MO		-
Connector type		Screwed connect									-0		
					•								
Adapters, suppl	lied loose	1 adapter for rac								1	-ER		
		1 adapter for axi								1	-EA		
		2 adapters for radial air supply, at both ends						2	-BR				
	2 adapters for axial air supply, at both ends						2	-BA					
	1 adapter for radial and 1 adapter for axial air supply							2	-RA				
Mountings, supplied loose 1 threaded rod for mounting, at one end								3	-EG				
2 threaded rods for mounting				at both	ends					4	-BG		

4 BG

1 ER, EA Not in combination with connection type MO.

2 BR, BA, RA 3 EG Not in combination with connection type MC.

In combination with connection type MO only permissible in combination with adapter BR, RA.

In combination with connection type MC only permissible in combination with

In combination with connection type MO only permissible in combination with adapter BR.

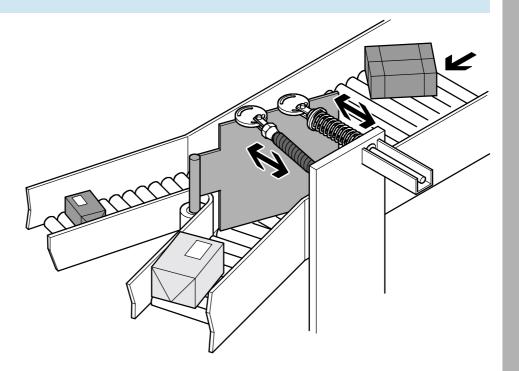
Transfer order	cod	е										
		MAS	-	_	-	Ī.	AA	_	-	-	-	

# Fluidic Muscle MAS, with screwed connections Application example

### Force and dynamism

Drive for sorting

The ideal drive for sorting tasks and stop functions in delivery processes thanks to the muscle's high speed and good acceleration behaviour. The short response times mean that cycle rates can be increased considerably.



# Fluidic Muscle MAS, with screwed connections Accessories

## Axial adapter MXAD-A

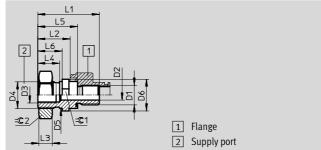
(order code EA/BA/RA)

Material:

Adapter: Anodised aluminium

Nut: Brass Seal: Nitrile rubber





**FESTO** 

Dimensions ar	Dimensions and ordering data									
For size	D1	D2	D3	D4	D5	D6	L1	L2	L3	
		Ø			Ø	Ø				
					h11					
10	M10x1.25	5	G1/8	M16x1.5	16	20	39.9	25.9	8	
20	M16x1.5	8	G1/4	M22x1.5	22	26	50.5	26.5	11	
40	M20x1.5	10	G3/8	M30x1.5	30	40	73.5	45.5	8	

For size	L4	L5	L6	=©1	=©2	Weight [g]	Part No. Type
10	15.4	29.9	17.4	17	24	33	534 400 MXAD-A10
20	18	32.5	20	24	32	69	534 402 MXAD-A16
40	35	53.5	38	36	46	184	534 404 MXAD-A20

### Radial adapter MXAD-R

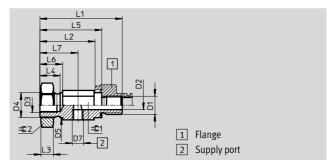
(order code ER/BR/RA)

Material:

Adapter: Anodised aluminium

Nut: Brass Seal: Nitrile rubber





Dimensions and	Dimensions and ordering data								
For size	D1	D2	D3	D4	D5	D7	L1	L2	L3
		Ø			Ø				
					h11				
10	M10x1.25	5	M10x1.25	M16x1.5	16	M5	55.5	41.5	8
20	M16x1.5	8	M10x1.25	M22x1.5	22	G1/8	72.5	48.5	11
40	M20x1.5	10	M16x1.5	M30x1.5	30	G1/4	103.5	75.5	8

For size	L4	L5	L6	L7	=©1	<b>=</b> ©2	Weight	Part No. Type
							[g]	
10	15.4	45.5	17.4	26.7	17	24	44	534 401 MXAD-R10
20	18	54.5	20	33.5	24	32	109	534 403 MXAD-R16
40	35	83.5	38	56	36	46	263	534 405 MXAD-R20

# Fluidic Muscle MAS, with screwed connections

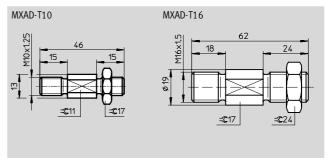
Accessories

### Threaded rod MXAD-T

(order code EG/BG)

Material: Aluminium



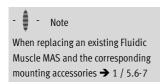


**FESTO** 

Dimensions and ordering data									
For size	Suitable for threaded connection	Weight	Part No.	Туре					
		[g]							
10/20	M10x1.25	40	187 597	MXAD-T10					
40	M16x1.5	140	187 609	MXAD-T16					

Ordering data							
Designation	For size	Part No.	Туре		Designation	Designation For size	Designation For size Part No.
Rod eye SGS <sup>1)</sup>					Coupling piece	Coupling piece KSG <sup>1)</sup>	Coupling piece KSG <sup>1)</sup>
<b>a</b>	10	9 261	SGS-M10x1,25		6	10	
9	20	9 261	SGS-M10x1,25			20	20 32 963
W C	40	9 263	SGS-M16x1,5			40	40 32 965
						·	·
Rod clevis SGA					Coupling piece	Coupling piece KSZ <sup>1)</sup>	Coupling piece KSZ <sup>1)</sup>
Pa	10	32 954	SGA-M10x1,25		6	10	
	20	32 954	SGA-M10x1,25			20	20 36 125
•	40	10 768	SGA-M16x1,5			40	40 36 127
1	•	•				•	
Rod clevis SG <sup>1)</sup>	)						
	10	6 144	SG-M10x1,25				
	20	6 144	SG-M10x1,25				
	40	6 146	SG-M16x1,5				

1) Threaded rod MXAD-T... is required.



Core Range

### Example 1

### Lifting a constant load

A Fluidic Muscle is to be used to engage free of forces with a constant load of 80 kg on a supporting surface and raise this a distance of 100 mm. The operating pressure is to be 6 bar.

The size (diameter and nominal length) of the fluidic muscle is to be found.



The sizing should be performed using the Fluidic Muscle sizing software, as the diagrams describe only a muscle of standard length (standard length =

10x internal dia.). The software is available at the address www.festo.com/download or can be requested on CD-ROM from Festo. The limits specified in the technical data must be complied with when using the muscle.

General conditions	Values
Required force at rest	0 N
Required stroke	100 mm
Required force in contracted state	approx. 800 N
Operating pressure	6 bar

#### Solution method

### Step 1

# Determining the required muscle

Determine the most suitable muscle diameter on the basis of the required force. The required force is 800 N.

MAS-20-... or MAS-40-... are available for selection.

### Step 2

Entering load point 1

Load point 1 is entered into the force/ displacement diagram for the

MAS-20-...

Force F = 0 N Pressure p = 0 bar

### Step 3

**Entering load point 2** 

Load point 2 is entered into the force/

displacement graph.

Force F = 800 N Pressure p = 6 bar

### Step 4

Reading the length change

The change in the length of the muscle is read between the load points on the

X axis (contraction in %).

Result:

9.6% contraction.

### Step 5

Calculating the nominal length

The required nominal muscle length for a stroke of 100 mm is obtained by

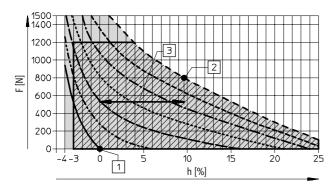
dividing by the contraction in %.

100 mm / 9.6% ~ 1042 mm.

### Step 6 Result

A Fluidic Muscle with a nominal length of 1042 mm should be ordered.

In order to attach a load of 80 kg free of forces and lift this 100 mm, a MAS-20-1042N-AA-... is required.





- 1 Load point 1
- Load point 2
- 3 Length change = 9.6%

### Example 2

### Use as a tension spring

In this example, the muscle is to be used as a tension spring.



The size (diameter and nominal length) of the fluidic muscle is to be found.

Sizing should be performed using the Fluidic Muscle sizing software, as the diagrams describe only a muscle of standard length (standard length =

10x internal dia.). The software is available at the address www.festo.com/download or can be requested on CD-ROM from Festo. The limits specified in the technical data must be complied with when using the muscle.

General conditions	Values
Required force in extended state	2000 N
Required force in contracted state	1000 N
Required stroke (spring length)	50 mm
Operating pressure	2 bar

#### Solution method

# Step 1

Determining the required muscle

Determine the most suitable muscle diameter on the basis of the required force. The required force is 2000 N, therefore an MAS-40-... is selected.

### Step 2 Entering load point 1

Load point 1 is entered into the force/ displacement diagram for the

MAS-40-...

Force F = 2000 N Pressure p = 2 bar

### Step 3 **Entering load point 2**

Load point 2 is entered into the force/ displacement graph.

Force F = 1000 N Pressure p = 2 bar

### Step 4 Reading the length change

The change in the length of the muscle is read between the load points on the X axis (contraction in %).

Result:

8.7% contraction.

Step 5 Calculating the nominal length

The required nominal muscle length for a stroke of 50 mm is obtained by dividing by the contraction in %.

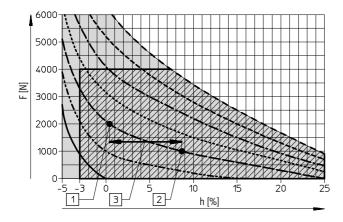
Result:

50 mm / 8.7% ~ 544 mm.

Step 6 Result

A Fluidic Muscle with a nominal length of 544 mm should be ordered.

For use as a tension spring with a force of 2000 N and a spring travel of 50 mm, a ... is required.

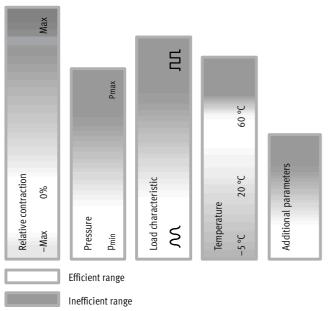




- 1 Load point 1 2 Load point 2
- 3 Length change = 8.7%

### Service life (bar height = meaning / influence)

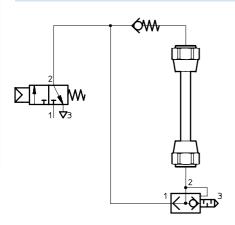
Optimisation through selection of suitable parameters



The service life of the fluidic muscle is between 100000 and 10 million switching cycles for typical applications. Optimisations can be made using the information from the left diagram. The service life thus increases due to a reduction in the

relative contraction (use of a longer muscle). It is also recommended that the pressure be reduced, which is possible because the fluidic muscle is more powerful with lower relative contraction. This measure also improves the service life.

### Reducing the thermal load



The service life of the Fluidic Muscle depends on the contraction, the operating pressure and the temperature. High operating frequencies or high loads can lead to a temperature rise. Targeted pressurisation on one side

and venting on the other side enables. the thermal load on the component to be reduced and the service life of the fluidic muscle to be increased (only with fluidic muscle open at both ends).