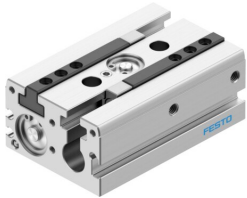


Parallel gripper HPPL-16-40-A-F1A

Part number: 8197420

FESTO



Data sheet

Feature	Value
Size	16
Total stroke	40 mm
Stroke per gripper jaws	20 mm
Max. angular gripper jaw backlash ax, ay	0.2 deg
Max. gripper jaw backlash Sz	0.05 mm
Repetition accuracy, gripper	0.03 mm
Number of gripper jaws	2
Drive system	Pneumatic
Mounting position	optional
Mode of operation	Double-acting
Cushioning	Elastic cushioning rings/pads at both ends without metal fixed stop
Gripper function	Parallel
Gripper force back-up	None
Design	Twin piston Guidance Piston gate valve T-shape Rack and pinion
Guide	Heavy-duty guide
Position detection	Via proximity switch
Variants	Metals with copper, zinc or nickel by mass as main constituent are excluded from use. Exceptions are nickel in steel, chemically nickel-plated surfaces, printed circuit boards, cables, electrical plug connectors and coils.
Operating pressure	0.2 MPa...0.8 MPa 2 bar...8 bar 29 psi...116 psi
Min. opening time at 0.6 MPa (6 bar, 87 psi)	94 ms
Min. closing time at 0.6 MPa (6 bar, 87 psi)	61 ms
Max. mass per external gripper finger	80 g
Operating medium	Compressed air to ISO 8573-1:2010 [7:4:4]
Note on operating and pilot medium	Lubricated operation possible (in which case lubricated operation will always be required)
Shock resistance	Shock test with severity level 2 to FN 942017-5 and EN 60068-2-27

Feature	Value
Corrosion resistance class CRC	1 - Low corrosion stress
LABS (PWIS) conformity	VDMA24364-B1/B2-L
Suitability for the production of Li-ion batteries	Suitable for battery production with reduced Cu/Zn/Ni values (F1a)
Vibration resistance	Transport application test with severity level 2 to FN 942017-4 and EN 60068-2-6
Degree of protection	IP40
Ambient temperature	-10 °C...80 °C
Total gripping force, opening, 0.6MPa (6bar, 87 psi)	124 N
Total gripping force, closing, 0.6MPa (6bar, 87 psi)	186 N
Gripper force per gripper jaw, opening, 0.6 MPa (6 bar, 87 psi)	62 N
Gripper force per gripper jaw, closing, 0.6 MPa (6 bar, 87 psi)	93 N
Theoretical total gripping force at 0 mm, 0.6 MPa (6 bar, 87 psi) open	160 N
Theoretical total gripping force at 0 mm, 0.6 MPa (6 bar, 87 psi), closing	222 N
Theoretical gripping force per gripper jaw at 0 mm, 0.6 MPa (6 bar, 87 psi), closing	80 N 111 N
Mass moment of inertia	2.2 kgcm ²
Max. force Fz	500 N
Max. torque at gripper Mx static	35 Nm
Max. torque at gripper My static	35 Nm
Max. torque at gripper Mz static	35 Nm
Product weight	341 g
Type of mounting	Via female thread and centring sleeve Via through-hole and centring sleeve
Pneumatic connection	M3 M5
Note on materials	RoHS-compliant Free of copper
Material cover cap	Wrought aluminium alloy, anodised
Material end plate	Anodised wrought aluminium alloy
Material housing	Anodised wrought aluminium alloy
Material gripper jaws	High-alloy stainless steel
Material piston	Wrought aluminium alloy, anodised
Material piston seal	TPE-U(PU)
Material piston rod	High-alloy stainless steel
Material o-ring	NBR
Material screws	Steel, chemically nickel-plated
Gear wheel material	High-alloy steel
Gripper finger material	Wrought aluminium alloy, anodised