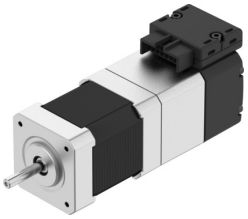
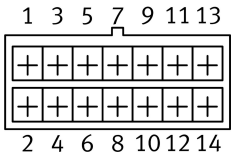
Stepper motor
EMMB-ST-42-L-SMB

Part number: 8156136





Data sheet

Feature	Value
Ambient temperature	-15 °C...40 °C
Note on ambient temperature	Up to 80°C with derating -2%/°C
Max. installation height	4000 m
Note on max. installation height	As of 1,000 m: only with derating of -1.0% per 100 m
Storage temperature	-20 °C...70 °C
Relative air humidity	0 - 90%
Conforms to standard	IEC 60034
Temperature class as per EN 60034-1	B
Max. winding temperature	130 °C
Rating class as per EN 60034-1	S1
Temperature monitoring	Dig. motor temp. via BiSS-C
Motor type to EN 60034-7	IM B5 IM V1 IM V3
Mounting position	optional
Degree of protection	IP20
Note on degree of protection	IP40 for motor shaft without rotary shaft seal
Interface code, motor out	42A
Electrical connection 1, connection type	Hybrid plug
Electrical connection 1, connector system	Connection pattern L5
Electrical connection 1, number of connections/cores	14
Note on materials	RoHS-compliant
Corrosion resistance class CRC	0 - No corrosion stress
LABS (PWIS) conformity	VDMA24364 zone III
Vibration resistance	Transport application test with severity level 2 to FN 942017-4 and EN 60068-2-6
Shock resistance	Shock test with severity level 2 to FN 942017-5 and EN 60068-2-27
Approval	RCM trademark
CE mark (see declaration of conformity)	To EU EMC Directive In accordance with EU RoHS Directive
CE marking (see declaration of conformity)	To UK instructions for EMC To UK RoHS instructions
Nominal operating voltage DC	48 V

Feature	Value
Number of pole pairs	50
Motor holding torque	0.63 Nm
Nominal torque	0.47 Nm
Peak torque	0.63 Nm
Nominal rotary speed	1000 rpm
Max. rotational speed	3200 rpm
Max. mechanical speed	9000 rpm
Stepper angle for complete step	1.8 deg
Stepping angle tolerance	±5%
Nominal power rating of motor	49 W
Continuous stall current	3.7 A
Nominal motor current	2.9 A
Peak current	4 A
Motor constant	0.162 Nm/A
Voltage constant, phase	10.6 mVmin
Phase winding resistance	0.6 Ohm
Phase winding inductance	0.8 mH
Winding longitudinal inductivity Ld (phase)	1.45 mH
Winding cross inductivity Lq (phase)	0.8 mH
Electric time constant	1.3 ms
Thermal time constant	16 min
Thermal resistance	2.4 K/W
Measuring flange	200 x 200 x 15 mm, steel
Total mass moment of inertia of output	0.09 kgcm²
Product weight	700 g
Permissible axial shaft load	10 N
Permissible radial shaft load	28 N
Rotor position sensor	Absolute multi-turn encoder
rotor position sensor, manufacturer designation	KCD-BC33B-1617-JP4F-GRQ-009
rotor position sensor, absolute detectable revolutions	16384
Rotor position encoder interface	BiSS-C
Rotor position sensor, encoder measuring principle	Magnetic
rotor position sensor, DC operating voltage	5 V
rotor position sensor, DC operating voltage range	4.5 V...5.5 V
Rotor pos. enc., sin/cosin p/r	2
rotor position sensor, position values per revolution	131072
Rotor position transducer resolution	17 bit
rotor position sensor, system accuracy of angle measurement	-310 arcsec...310 arcsec
Brake holding torque	0.63 Nm
Operating voltage DC for brake	24 V
Brake current consumption	0.34 A
Power consumption, brake	8.2 W
Brake coil resistance	70.9 Ohm
Brake coil inductivity	146 mH
Brake separation time	28 ms
Brake closing time	41 ms
DC brake response delay	8 ms
Max. brake no-load speed	9000 rpm
Max. friction per braking process	1500 J
Mass moment of inertia of brake	0.006 kgcm²
Switching cycles holding brake	10 million idle actuations (without friction work!)
Mean time to failure (MTTF), subcomponent	20 years, rotor position encoder