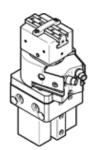
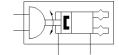
## Swivel/gripper unit HGDS-PP-20-P1-A-B Part number: 1187962

**FESTO** 

with elastic cushioning and fixed stop.





## **Data sheet**

| Feature   | Value   |
|---|---|
| Size  | 20  |
| Rotation angle adjustment range                                   | 0 210 deg   |
| Stroke per gripper jaw  | 7 mm  |
| Max. angular gripper jaw backlash ax,ay                           | 0.1 deg   |
| Max. gripper jaw backlash Sz                                      | 0.02 mm   |
| Swivel angle  | 210 deg   |
| Number of gripper fingers   | 2   |
| Cushioning of swivel actuator                                     | Elastic cushioning rings/pads at both ends, end positions adjustable, with fixed stop |
| Assembly position   | Any   |
| Fine adjustment of swivel drive                                   | -6 deg  |
| Mode of operation   | double-acting   |
| Gripper function  | Parallel  |
| Design structure  | Swivel actuator   |
|   | With parallel gripper and gripper actuator  |
| Position detection, gripper                                       | with proximity sensor   |
| Position detection, swivel actuator                               | with proximity sensor   |
| Working pressure  | 3 8 bar   |
| Max. swivel frequency at 0.6 MPa (6 bar, 87 psi)                  | 2 Hz  |
| Min. opening time at 0.6 MPa (6 bar, 87 psi)                      | 60 ms   |
| Min. closing time at 0.6 MPa (6 bar, 87 psi)                      | 70 ms   |
| Operating medium  | Compressed air in accordance with ISO8573-1:2010 [7:4:4]                              |
| Note on operating and pilot medium                                | Lubricated operation possible (subsequently required for further operation)           |
| Corrosion resistance classification CRC                           | 2 - Moderate corrosion stress   |
| PWIS conformity   | VDMA24364-B2-L  |
| Ambient temperature   | 5 60 °C   |
| Gripping force per gripper jaw at 0.6 MPa (6 bar, 87 psi) opening | 96 N  |
| Total gripping force at 0.6 MPa (6 bar, 87 psi), opening          | 192 N   |
| Gripping force per gripper jaw at 0.6 MPa (6 bar, 87 psi) closing | 84 N  |
| Total gripping force at 0.6 MPa (6 bar, 87 psi), closing          | 168 N   |
| Max. force on gripper jaw Fz static                               | 250 N   |
| Max. torque at gripper Mx static                                  | 22 Nm   |
| Max. torque at gripper My static                                  | 22 Nm   |
| Max. torque at gripper Mz static                                  | 22 Nm   |
| Theoretical torque at 0.6 MPa (6 bar, 87 psi)                     | 2.5 Nm  |
| Product weight  | 1,260 g   |
| Max. mass per external gripper finger                             | 100 g   |
| Mounting type   | Internal thread and centering sleeve  |
|   | With through-hole and centering sleeve  |
|   | With dovetail slot  |
|   | Optional  |
| Pneumatic connection  | M5  |
| Materials note  | Conforms to RoHS  |



| Feature                 | Value                           |
|-------------------------|---------------------------------|
| Material of drive shaft | Steel                           |
| Material cover          | Aluminum                        |
|                         | POM                             |
| Material seals          | NBR                             |
| Material housing        | Wrought Aluminum alloy          |
| Material gripper jaws   | High alloy steel, non-corrosive |