Parallel gripper DHPC-L-16-A-NO-S Part number: 8116809

Data sheet

Feature	Value
Size	16
Stroke per gripper jaws	6 mm
Max. replacement accuracy	0.2 mm
Max. angular gripper jaw backlash ax, ay	0 deg
Max. gripper jaw backlash Sz	0 mm
Rotationally symmetrical	0.2 mm
Repetition accuracy, gripper	0.02 mm
Number of gripper jaws	2
Drive system	Pneumatic
Mounting position	optional
Mode of operation	Single-acting Open
Gripper function	Parallel
Gripper force back-up	During opening
Design	Connection direction at side Lever Standard mounting method for gripper fingers Force pilot operated motion sequence
Guide	Ball guide
Position detection	Via proximity switch
Total gripping force, closing, 0.6MPa (6bar, 87 psi)	86.8 N
Operating pressure	0.1 MPa0.8 MPa 1 bar8 bar 14.5 psi116 psi
Max. operating frequency of gripper	3 Hz
Min. opening time at 0.6 MPa (6 bar, 87 psi)	18 ms
Min. closing time at 0.6 MPa (6 bar, 87 psi)	17 ms
Operating medium	Compressed air to ISO 8573-1:2010 [7:4:4]
Note on operating and pilot medium	Lubricated operation possible (in which case lubricated operation will always be required)
Corrosion resistance class CRC	0 - No corrosion stress
LABS (PWIS) conformity	VDMA24364-B2-L
Ambient temperature	-10 °C60 °C

Feature	Value
Gripper force per gripper jaw, closing, 0.6 MPa (6 bar, 87 psi)	43.4 N
Mass moment of inertia	0.215 kgcm ²
Max. force on gripper jaw Fz static	49 N
Max. torque at gripper Mx static	0.34 Nm
Max. torque at gripper My static	0.68 Nm
Max. torque at gripper Mz static	0.34 Nm
Product weight	126 g
Type of mounting	Either: Direct mounting via through-hole Direct mounting via thread Via through-hole and dowel pin Via female thread and dowel pin
Pneumatic connection	M3
Note on materials	RoHS-compliant
Material housing	Anodised aluminium
Material gripper jaws	High-alloy stainless steel