parallel gripper DHPS-6-A Part number: 1254039 ★ Core product range







Data sheet

Feature	Value
Size	6
Stroke per gripper jaw	2 mm
Max. replacement accuracy	<= 0.2 mm
Max. angular gripper jaw backlash ax,ay	< 1 deg
Max. gripper jaw backlash Sz	< 0.02 mm
Rotationally symmetrical	<= 0.2 mm
Repetition accuracy, gripper	< 0.02 mm
Number of gripper fingers	2
Drive system	pneumatic
Assembly position	Any
Mode of operation	double-acting
Gripper function	Parallel
Gripper force back-up	No
Design structure	Lever
Design structure	guided motion sequence
Guide	Plain-bearing guide
Position detection	For Hall sensors
Total gripping force at 0.6 MPa (6 bar, 87 psi), opening	30 N
	25 N
Total gripping force at 0.6 MPa (6 bar, 87 psi), closing	0.2 0.8 MPa
Operating pressure MPa	2 8 bar
Operating pressure	
	29 116 psi
Max. operating frequency of gripper	4 Hz
Min. opening time at 0.6 MPa (6 bar, 87 psi)	8 ms
Min. closing time at 0.6 MPa (6 bar, 87 psi)	17 ms
Max. mass per external gripper finger	10 g
Operating medium	Compressed air in accordance with ISO8573-1:2010 [7:4:4]
Note on operating and pilot medium	Lubricated operation possible (subsequently required for further operation)
Corrosion resistance classification CRC	1 - Low corrosion stress
PWIS conformity	VDMA24364-B2-L
RSBP classification to CD-0033	F5
Ambient temperature	5 60 °C
Gripping force per gripper jaw at 0.6 MPa (6 bar, 87 psi) opening	15 N
Gripping force per gripper jaw at 0.6 MPa (6 bar, 87 psi) closing	13.5 N
Mass moment of inertia	0.008 kgcm2
Max. force on gripper jaw Fz static	10 N
Max. torque at gripper Mx static	0.5 Nm
Max. torque at gripper My static	0.5 Nm
Max. torque at gripper Mz static	0.5 Nm
Lubrication interval for guide components	10 Mio SP
Product weight	19 g
Mounting type	Internal thread and centring sleeve
	With through-hole and centring sleeve
	Optional
Pneumatic connection	M3
Materials note	Conforms to RoHS
Material cover cap	PA
Material housing	Hard anodised wrought aluminium alloy
Material gripper jaws	High alloy steel, non-corrosive