Radial gripper DHRC-25-A-S-NO Part number: 8133557



Data sheet

| Feature | Value |
|--|--|
| Size | 25 |
| Max. replacement accuracy | <= 0.2 mm |
| Max. opening angle | 180 deg |
| Rotationally symmetrical | <= 0.2 mm |
| Repetition accuracy, gripper | <= 0.1 mm |
| Number of gripper fingers | 2 |
| Drive system | pneumatic |
| Assembly position | Any |
| Mode of operation | single-acting |
| | open |
| Gripper function | radial |
| Gripper force back-up | On opening |
| Design structure | Connection direction at side |
| | guided motion sequence |
| Position detection | For proximity sensor |
| Operating pressure MPa | 0.15 0.8 MPa |
| Working pressure | 1.5 8 bar |
| Operating pressure | 21.75 116 psi |
| Max. operating frequency of gripper | <= 2 Hz |
| Min. opening time at 0.6 MPa (6 bar, 87 psi) | 147 ms |
| Min. closing time at 0.6 MPa (6 bar, 87 psi) | 45 ms |
| Operating medium | Compressed air in accordance with ISO8573-1:2010 [7:4:4] |
| Note on operating and pilot medium | Lubricated operation possible (subsequently required for further |
| | operation) |
| Corrosion resistance classification CRC | 0 - No corrosion stress |
| PWIS conformity | VDMA24364-B2-L |
| Ambient temperature | -10 60 °C |
| Total gripping torque at 0.6 MPa (6 bar, 87 psi) closing | 239.5 Ncm |
| Mass moment of inertia | 1.316 kgcm2 |
| Max. force on gripper jaw Fz static | 140 N |
| Max. torque at gripper Mx static | 7 Nm |
| Max. torque at gripper My static | 4 Nm |
| Max. torque at gripper Mz static | 7 Nm |
| Product weight | 440 g |
| Mounting type | Direct mounting via through-holes |
| | Direct mounting via threads |
| | With through-hole and dowel pin |
| | With internal thread and dowel pin |
| | Optional |
| Pneumatic connection | M5 |
| Materials note | Conforms to RoHS |
| Material cover cap | Anodised wrought aluminium alloy |
| Material housing | Anodised wrought aluminium alloy |
| Material gripper jaws | High alloy steel |



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