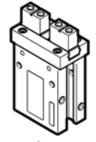
Parallel gripper DHPC-40-A-NO-S-2 Part number: 8116902







Data sheet

Size Stroke per gripper jaw Max. replacement accuracy Max. angular gripper jaw backlash ax,ay Max. gripper jaw backlash Sz Rotationally symmetrical Repetition accuracy, gripper Number of gripper fingers Drive system Assembly position Mode of operation Gripper function Gripper force back-up Design structure	40 15 mm 0.2 mm 0 deg 0 mm <= 0.2 mm <= 0.2 mm <= 0.02 mm 2 pneumatic Any single-acting open Parallel On opening Connection direction at side Flat mounting of gripper fingers
Max. replacement accuracy Max. angular gripper jaw backlash ax,ay Max. gripper jaw backlash Sz Rotationally symmetrical Repetition accuracy, gripper Number of gripper fingers Drive system Assembly position Mode of operation Gripper function Gripper force back-up	0.2 mm 0 deg 0 mm <= 0.2 mm <= 0.02 mm 2 pneumatic Any single-acting open Parallel On opening Connection direction at side
Max. replacement accuracy Max. angular gripper jaw backlash ax,ay Max. gripper jaw backlash Sz Rotationally symmetrical Repetition accuracy, gripper Number of gripper fingers Drive system Assembly position Mode of operation Gripper function Gripper force back-up	0 deg 0 mm <= 0.2 mm <= 0.02 mm 2 pneumatic Any single-acting open Parallel On opening Connection direction at side
Max. gripper jaw backlash Sz Rotationally symmetrical Repetition accuracy, gripper Number of gripper fingers Drive system Assembly position Mode of operation Gripper function Gripper force back-up	O mm <= 0.2 mm <= 0.02 mm 2 pneumatic Any single-acting open Parallel On opening Connection direction at side
Max. gripper jaw backlash Sz Rotationally symmetrical Repetition accuracy, gripper Number of gripper fingers Drive system Assembly position Mode of operation Gripper function Gripper force back-up	O mm <= 0.2 mm <= 0.02 mm 2 pneumatic Any single-acting open Parallel On opening Connection direction at side
Rotationally symmetrical Repetition accuracy, gripper Number of gripper fingers Drive system Assembly position Mode of operation Gripper function Gripper force back-up	<= 0.2 mm <= 0.02 mm pneumatic Any single-acting open Parallel On opening Connection direction at side
Repetition accuracy, gripper Number of gripper fingers Drive system Assembly position Mode of operation Gripper function Gripper force back-up	pneumatic Any single-acting open Parallel On opening Connection direction at side
Number of gripper fingers Drive system Assembly position Mode of operation Gripper function Gripper force back-up	pneumatic Any single-acting open Parallel On opening Connection direction at side
Drive system Assembly position Mode of operation Gripper function Gripper force back-up	pneumatic Any single-acting open Parallel On opening Connection direction at side
Assembly position Mode of operation Gripper function Gripper force back-up	single-acting open Parallel On opening Connection direction at side
Mode of operation Gripper function Gripper force back-up	single-acting open Parallel On opening Connection direction at side
Gripper function Gripper force back-up	open Parallel On opening Connection direction at side
Gripper force back-up	Parallel On opening Connection direction at side
Gripper force back-up	On opening Connection direction at side
· · ·	Connection direction at side
	That mounting of Supper migers
	Lever
	guided motion sequence
Guide	Ball guide
Position detection	For proximity sensor
Total gripping force at 0.6 MPa (6 bar, 87 psi), closing	675 N
Operating pressure MPa	0.25 0.8 MPa
Working pressure	2.5 8 bar
Operating pressure	
	36.25 116 psi 1 Hz
Max. operating frequency of gripper	300 ms
Min. opening time at 0.6 MPa (6 bar, 87 psi)	
Min. closing time at 0.6 MPa (6 bar, 87 psi)	67 ms
Operating medium Note on operating and pilot medium	Compressed air in accordance with ISO8573-1:2010 [7:4:4]
Note on operating and pilot medium	Lubricated operation possible (subsequently required for further operation)
Corrosion resistance classification CRC	0 - No corrosion stress
PWIS conformity	VDMA24364-B2-L
Ambient temperature	-10 60 °C
Gripping force per gripper jaw at 0.6 MPa (6 bar, 87 psi) closing	337.5 N
Mass moment of inertia	16.27 kgcm2
Max. force on gripper jaw Fz static	245 N
Max. torque at gripper Mx static	2.3 Nm
Max. torque at gripper My static	4.5 Nm
Max. torque at gripper Mz static	2.3 Nm
Product weight	1,560 g
Mounting type	Direct mounting via through-holes
	Direct mounting via threads
	On mounting frame
	· ·
Pneumatic connection	,
Material gripper jaws	High alloy steel, non-corrosive
Pneumatic connection Materials note Material housing	Direct mounting via threads On mounting frame With through-hole and dowel pin With internal thread and dowel pin Optional M5 Conforms to RoHS Anodised aluminium