Parallel gripper DHPC-6-A-NO-Z Part number: 8116744







Data sheet

Feature	Value
Size	6
Stroke per gripper jaw	2 mm
Max. replacement accuracy	0.2 mm
Max. angular gripper jaw backlash ax,ay	0 deg
Max. gripper jaw backlash Sz	0 mm
Rotationally symmetrical	<= 0.2 mm
Repetition accuracy, gripper	<= 0.02 mm
Number of gripper fingers	2
Drive system	pneumatic
Assembly position	Any
Mode of operation	single-acting
	open
Gripper function	Parallel
Gripper force back-up	On opening
Design structure	Connection via mounting spigot
_	Lever
	Standard mounting of gripper fingers
	guided motion sequence
Guide	Ball guide
Position detection	For proximity sensor
Variants	Recommended for production facilities for the manufacture of lithium-
	ion batteries
Total gripping force at 0.6 MPa (6 bar, 87 psi), closing	7.8 N
Operating pressure MPa	0.35 0.8 MPa
Working pressure	3.5 8 bar
Operating pressure	50.75 116 psi
Max. operating frequency of gripper	3 Hz
Min. opening time at 0.6 MPa (6 bar, 87 psi)	8 ms
Min. closing time at 0.6 MPa (6 bar, 87 psi)	6 ms
Operating medium	Compressed air in accordance with ISO8573-1:2010 [7:4:4]
Note on operating and pilot medium	Lubricated operation possible (subsequently required for further
	operation)
Corrosion resistance classification CRC	0 - No corrosion stress
PWIS conformity	VDMA24364-B2-L
RSBP classification to CD-0033	F1a
Ambient temperature	-10 60 °C
Gripping force per gripper jaw at 0.6 MPa (6 bar, 87 psi) closing	3.9 N
Mass moment of inertia	0.013 kgcm2
Max. force on gripper jaw Fz static	5 N
Max. torque at gripper Mx static	0.02 Nm
Max. torque at gripper My static	0.04 Nm
Max. torque at gripper Mz static	0.02 Nm
Product weight	31 g
Mounting type	Direct mounting via through-holes
	Direct mounting via threads
	On mounting frame



Feature	Value
	Optional
Pneumatic connection	M5
Materials note	Conforms to RoHS
Material housing	Anodised aluminium
Material gripper jaws	High alloy steel, non-corrosive