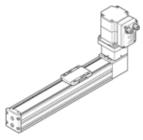
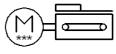
toothed belt axis unit ELGS-TB-KF-60-1500-ST-M-H1-PLK-AA Part number: 8083577

FESTO



Data sheet

Effective diameter of drive pinion 24.83 mm Working stroke 1,500 mm Size 60 Stroke reserve 0 mm Toothed-belt stretch 0.124 % Toothed-belt pitch 3 mm Assembly position Horizontal Guide Recirculating ball bearing guid Design structure Electromechanical linear axis With toothed belt with integrated drive Motor type Stepper motor Position detection Motor encoder For proximity sensor Fixed stop block positive Referencing Fixed stop block positive Reforencing Fixed stop block negative Rotor position sensor Absolute single turn encoder Rotary position encoder measuring principle Magnetic Temperature monitoring User interface Integrated precise CMOS temp Integrated end-position sensir Display LED Max. acceleration 6 m/s2 Max. speed 1.3 m/s Repetition accuracy 40,1 mm Digital logic output characteristics configurable Not electrically isolated	2
Working stroke1,500 mmSize60Stroke reserve0 mmToothed-belt stretch0.124 %Toothed-belt pitch3 mmAssembly positionHorizontalGuideRecirculating ball bearing guidDesign structureElectromechanical linear axisWith toothed beltwith integrated driveMotor typeStepper motorPosition detectionMotor encoderFor proximity sensorFixed stop block positiveReferencingFixed stop block negativeRotor position sensorAbsolute single turn encoderRotar position encoder measuring principleMagneticTemperature monitoringShutdown at over-temperatureIntegrated precise CMOS tempLEDMax. acceleration6 m/s2Max. acceleration6 m/s2Max. speed1.3 m/sRepetition accuracy±0,1 mmDigilal logic output characteristicsConfigurableDuty cycle100 %Insulation protection classB	2
Size 60 Stroke reserve 0 mm Toothed-belt stretch 0.124 % Toothed-belt pitch 3 mm Assembly position Horizontal Guide Recirculating ball bearing guid Design structure Electromechanical linear axis With toothed belt with integrated drive Motor type Stepper motor Position detection Motor encoder For proximity sensor Fixed stop block positive Referencing Fixed stop block negative Rotor position sensor Absolute single turn encoder Rotary position encoder measuring principle Magnetic Temperature monitoring Shutdown at over-temperature Integrated precise CMOS temp Integrated end-position sensir Additional functions LED Ready status display LED Max. acceleration 6 m/s2 Max. speed 1.3 m/s Repetition accuracy ±0,1 mm Digital logic output characteristics configurable Not electrically isolated Not electrically isolated Not electrically isolated	2
Toothed-belt stretch0.124 %Toothed-belt pitch3 mmAssembly positionHorizontalGuideRecirculating ball bearing guidDesign structureElectromechanical linear axis with toothed belt with integrated driveMotor typeStepper motorPosition detectionMotor encoder For proximity sensorReferencingFixed stop block positive Fixed stop block negativeRotary position sensorAbsolute single turn encoder Integrated precise CMOS tempAdditional functionsUser interface Integrated end-position sensiDisplayLEDMax. acceleration6 m/s2 	2
Toothed-belt pitch3 mmAssembly positionHorizontalGuideRecirculating ball bearing guidDesign structureElectromechanical linear axis With toothed belt with integrated driveMotor typeStepper motorPosition detectionMotor encoder For proximity sensorReferencingFixed stop block positive Fixed stop block negativeRotor position sensorAbsolute single turn encoder Integrated precise CMOS temper Integrated end-position sensirAdditional functionsUser interface Integrated end-position sensirDisplayLEDMax. acceleration6 m/s2Max. speed1.3 m/sRepetition accuracy±0,1 mmDigital logic output characteristicsconfigurable Not electrically isolated Duty cycleDuty cycle100 % Insulation protection class	2
Assembly position Horizontal Guide Recirculating ball bearing guid Design structure Electromechanical linear axis With toothed belt with integrated drive Motor type Stepper motor Position detection Motor encoder For proximity sensor Fixed stop block positive Referencing Fixed stop block negative Rotor position sensor Absolute single turn encoder Rotary position encoder measuring principle Magnetic Temperature monitoring Shutdown at over-temperature lintegrated precise CMOS temp Additional functions User interface Display LED Ready status display LED Max. speed 1.3 m/s Repetition accuracy ±0,1 mm Digital logic output characteristics configurable Not electrically isolated Duty cycle Duty cycle 100 %	2
Assembly position Horizontal Guide Recirculating ball bearing guid Design structure Electromechanical linear axis With toothed belt with integrated drive Motor type Stepper motor Position detection Motor encoder For proximity sensor Fixed stop block positive Referencing Fixed stop block negative Rotor position sensor Absolute single turn encoder Rotary position encoder measuring principle Magnetic Temperature monitoring Shutdown at over-temperature lintegrated precise CMOS temp Additional functions User interface Display LED Ready status display LED Max. speed 1.3 m/s Repetition accuracy ±0,1 mm Digital logic output characteristics configurable Not electrically isolated Duty cycle Duty cycle 100 %	2
GuideRecirculating ball bearing guidDesign structureElectromechanical linear axis With toothed belt with integrated driveMotor typeStepper motorPosition detectionMotor encoder For proximity sensorReferencingFixed stop block positive Fixed stop block negativeRotor position sensorAbsolute single turn encoder Integrated precise CMOS tempRotary position encoder measuring principleMagneticTemperature monitoringShutdown at over-temperature Integrated precise CMOS tempAdditional functionsUser interface Integrated end-position sensir DisplayDisplayLEDMax. acceleration6 m/s2Max. acceleration6 m/s2Max. speed1.3 m/sRepetition accuracy±0,1 mmDigital logic output characteristicsconfigurable Not electrically isolated Duty cycleDuty cycle100 %Insulation protection classB	2
Design structureElectromechanical linear axis With toothed belt with integrated driveMotor typeStepper motorPosition detectionMotor encoder For proximity sensorReferencingFixed stop block positive Fixed stop block negativeRotor position sensorAbsolute single turn encoder Rotary position encoder measuring principleMagneticMagneticTemperature monitoringShutdown at over-temperature Integrated precise CMOS tempAdditional functionsUser interface Integrated end-position sensirDisplayLEDReady status displayLEDMax. speed1.3 m/sRepetition accuracy±0,1 mmDigital logic output characteristicsconfigurable Not electrically isolatedDuty cycle100 %Insulation protection classB	
With toothed belt with integrated driveMotor typeStepper motorPosition detectionMotor encoder For proximity sensorReferencingFixed stop block positive Fixed stop block negativeRotor position sensorAbsolute single turn encoderRotary position encoder measuring principleMagneticTemperature monitoringShutdown at over-temperature Integrated precise CMOS tempAdditional functionsUser interface Integrated end-position sensirDisplayLEDReady status displayLEDMax. acceleration6 m/s2Max. speed1.3 m/sRepetition accuracy±0,1 mmDigital logic output characteristicsconfigurable Not electrically isolatedDuty cycle100 %Insulation protection classB	
Motor typeStepper motorPosition detectionMotor encoder For proximity sensorReferencingFixed stop block positive Fixed stop block negativeRotor position sensorAbsolute single turn encoderRotary position encoder measuring principleMagneticTemperature monitoringShutdown at over-temperature Integrated precise CMOS tempAdditional functionsUser interface Integrated end-position sensirDisplayLEDMax. acceleration6 m/s2Max. speed1.3 m/sRepetition accuracy±0,1 mmDigital logic output characteristicsconfigurable Not electrically isolatedDuty cycle100 %Insulation protection classB	
Motor typeStepper motorPosition detectionMotor encoder For proximity sensorReferencingFixed stop block positive Fixed stop block negativeRotor position sensorAbsolute single turn encoderRotary position encoder measuring principleMagneticTemperature monitoringShutdown at over-temperature Integrated precise CMOS tempAdditional functionsUser interface Integrated end-position sensirDisplayLEDMax. acceleration6 m/s2Max. speed1.3 m/sRepetition accuracy±0,1 mmDigital logic output characteristicsconfigurable Not electrically isolatedDuty cycle100 %Insulation protection classB	
Position detectionMotor encoder For proximity sensorReferencingFixed stop block positive Fixed stop block negativeRotor position sensorAbsolute single turn encoderRotary position encoder measuring principleMagneticTemperature monitoringShutdown at over-temperature Integrated precise CMOS tempAdditional functionsUser interface Integrated end-position sensirDisplayLEDReady status displayLEDMax. acceleration6 m/s2Max. speed1.3 m/sRepetition accuracy±0,1 mmDigital logic output characteristicsconfigurable Not electrically isolatedDuty cycle100 %Insulation protection classB	
For proximity sensorReferencingFixed stop block positive Fixed stop block negativeRotor position sensorAbsolute single turn encoderRotary position encoder measuring principleMagneticTemperature monitoringShutdown at over-temperature Integrated precise CMOS tempAdditional functionsUser interface Integrated end-position sensirDisplayLEDReady status displayLEDMax. acceleration6 m/s2Max. speed1.3 m/sRepetition accuracy±0,1 mmDigital logic output characteristicsconfigurable Not electrically isolatedDuty cycle100 %Insulation protection classB	
ReferencingFixed stop block positive Fixed stop block negativeRotor position sensorAbsolute single turn encoderRotary position encoder measuring principleMagneticTemperature monitoringShutdown at over-temperature Integrated precise CMOS tempAdditional functionsUser interface Integrated end-position sensirDisplayLEDReady status displayLEDMax. acceleration6 m/s2Max. speed1.3 m/sRepetition accuracy±0,1 mmDigital logic output characteristicsconfigurable Not electrically isolatedDuty cycle100 %Insulation protection classB	
Fixed stop block negativeRotor position sensorAbsolute single turn encoderRotary position encoder measuring principleMagneticTemperature monitoringShutdown at over-temperature Integrated precise CMOS tempAdditional functionsUser interface Integrated end-position sensirDisplayLEDReady status displayLEDMax. acceleration6 m/s2Max. speed1.3 m/sRepetition accuracy±0,1 mmDigital logic output characteristicsconfigurable Not electrically isolatedDuty cycle100 %Insulation protection classB	
Rotor position sensorAbsolute single turn encoderRotary position encoder measuring principleMagneticTemperature monitoringShutdown at over-temperature Integrated precise CMOS tempAdditional functionsUser interface Integrated end-position sensirDisplayLEDReady status displayLEDMax. acceleration6 m/s2Max. speed1.3 m/sRepetition accuracy±0,1 mmDigital logic output characteristicsconfigurable Not electrically isolatedDuty cycle100 %Insulation protection classB	
Rotary position encoder measuring principleMagneticTemperature monitoringShutdown at over-temperature Integrated precise CMOS tempAdditional functionsUser interface Integrated end-position sensirDisplayLEDReady status displayLEDMax. acceleration6 m/s2Max. speed1.3 m/sRepetition accuracy±0,1 mmDigital logic output characteristicsconfigurable Not electrically isolatedDuty cycle100 %Insulation protection classB	
Temperature monitoringShutdown at over-temperature Integrated precise CMOS tempAdditional functionsUser interface Integrated end-position sensirDisplayLEDReady status displayLEDMax. acceleration6 m/s2Max. speed1.3 m/sRepetition accuracy±0,1 mmDigital logic output characteristicsconfigurable Not electrically isolatedDuty cycle100 %Insulation protection classB	
Integrated precise CMOS tempAdditional functionsUser interface Integrated end-position sensirDisplayLEDReady status displayLEDMax. acceleration6 m/s2Max. speed1.3 m/sRepetition accuracy±0,1 mmDigital logic output characteristicsconfigurable Not electrically isolatedDuty cycle100 %Insulation protection classB	
Additional functions User interface Display LED Ready status display LED Max. acceleration 6 m/s2 Max. speed 1.3 m/s Repetition accuracy ±0,1 mm Digital logic output characteristics configurable Not electrically isolated Duty cycle Insulation protection class B	
Integrated end-position sensirDisplayLEDReady status displayLEDMax. acceleration6 m/s2Max. speed1.3 m/sRepetition accuracy±0,1 mmDigital logic output characteristicsconfigurable Not electrically isolatedDuty cycle100 %Insulation protection classB	
Display LED Ready status display LED Max. acceleration 6 m/s2 Max. speed 1.3 m/s Repetition accuracy ±0,1 mm Digital logic output characteristics configurable Not electrically isolated Duty cycle 100 % Insulation protection class B	g
Ready status display LED Max. acceleration 6 m/s2 Max. speed 1.3 m/s Repetition accuracy ±0,1 mm Digital logic output characteristics configurable Not electrically isolated Duty cycle 100 % Insulation protection class B	2
Max. acceleration 6 m/s2 Max. speed 1.3 m/s Repetition accuracy ±0,1 mm Digital logic output characteristics configurable Not electrically isolated Duty cycle 100 % Insulation protection class B	
Max. speed 1.3 m/s Repetition accuracy ±0,1 mm Digital logic output characteristics configurable Not electrically isolated Duty cycle 100 % Insulation protection class B	
Repetition accuracy ±0,1 mm Digital logic output characteristics configurable Not electrically isolated Not electrically isolated Duty cycle 100 % Insulation protection class B	
Digital logic output characteristics configurable Not electrically isolated Duty cycle 100 % Insulation protection class B	
Not electrically isolated Duty cycle 100 % Insulation protection class B	
Duty cycle100 %Insulation protection classB	
Insulation protection class B	
Max. current consumption 5.3 A	
Nominal voltage DC 24 V	
Nominal current 5.3 A	
Parameters configuring interface IO-Link	
User interface	
Rotor position encoder resolution 16 Bit	
Permissible voltage fluctuation +/- 15 %	
Power supply, type of connection Plug	
Power supply, connection technology M12x1, T-coded as per EN 610	
Power supply, number of pins/wires 4	76-2-111
Authorization RCM Mark	76-2-111
KC mark KC-EMV	76-2-111
CE symbol (see declaration of conformity) according to EU-EMV guideline	76-2-111
in accordance with EU RoHS di	



FESTO

Feature	Value
UKCA marking (see declaration of conformity)	To UK instructions for EMC
	To UK RoHS instructions
Vibration resistance	Transport application test with severity level 1 as per FN 942017-4 and EN 60068-2-6
Shock resistance	Shock test with severity level 1 in accordance with FN 942017-5 and EN 60068-2-27
PWIS conformity	VDMA24364 zone III
Storage temperature	-20 60 °C
Relative air humidity	0 - 90 %
Protection class	IP40
Safety class	III
Ambient temperature	0 50 °C
Note on ambient temperature	Above an ambient temperature of 30 $^{\circ}\text{C}$, the power must be reduced by 2% per K.
Area moment of inertia 2nd degree ly	441E+03 mm4
Area moment of inertia 2nd degree Iz	542E+03 mm4
Max. force Fy	600 N
Max. force Fz	1,800 N
Max. torque Mx	29.1 Nm
Max. torque My	31.8 Nm
Max. torque Mz Max. feed force Fx	31.8 Nm 65 N
Reference value for working load, horizontal	4 kg
Torsional mass moment of inertia It	29.8E+03 mm4
Feed constant	78 mm/U
Moving mass	482 g
Moving mass with 0 mm stroke	482 g
Slide weight	139 g
Product weight	9,405 g
Number of 24 V DC digital logic outputs	2
Number of digital logic inputs	2
Specification, logic input	Based on IEC 61131-2, type 1
Logic input working range	24 V
IO-Link, SIO mode support	Yes
Logic input characteristics	configurable
10 Link protocol	Not electrically isolated Device V 1.1
IO-Link, protocol IO-Link, communication mode	COM3 (230.4 kbd)
IO-Link, communication mode	A
IO-Link, number of ports	1
IO-Link, process data width OUT	2 Byte
IO-Link, process data content OUT	1 bit (Move in)
	1 bit (Move out)
	1 bit (Quit Error)
IO-Link, process data width IN	2 Byte
IO-Link, process data content IN	1 bit (State Device)
	1 bit (State Move)
	1 bit (State in)
	1 bit (State out)
IO-Link, Service data contents IN	32 bit Force
	32 bit Position
	32 bit Speed
IO-Link, minimum cycle time	1 ms
IO-Link, data memory required	0.5 Kilobyte
Max. line length	15 m outputs
	15 m inputs
Switching logic outputs	20 m with IO-Link operation PNP (positive-switching)
Switching logic, outputs Input circuit logic	PNP (positive-switching) PNP (positive-switching)
IO-Link, connection technology	Plug
Logic interface, connection type	Plug
	1. 2

FESTO

Feature	Value
Logic interface, connection technology	M12x1, A-coded in accordance with EN 61076-2-101
Logic interface, number of poles/wires	8
Logic interface, connection pattern	00992264
Material of end caps	Die-cast aluminium, painted
Material of profile	Anodised wrought aluminium alloy
Materials note	Conforms to RoHS
Material cover tape	Stainless steel strip
Material drive cover	Die-cast aluminium, painted
Material guide slide	Heat-treatment steel
Material guide rail	Heat-treatment steel
Material pulleys	High alloy steel, non-corrosive
Material slide	Aluminum die cast
Material toothed belt	Polychloroprene with glass fibers