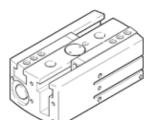
Parallel gripper HGPL-40-60-A Part number: 567825 Product to be discontinued

Type to be discontinued. Available until 2016. See Support Portal for alternative products.







Data sheet

Feature	Value
Size	40
Stroke per gripper jaw	60 mm
Max. replacement accuracy	< 0.2 mm
Max. angular gripper jaw backlash ax,ay	< 0.2 deg
Max. gripper jaw backlash Sz	< 0.05 mm
Rotationally symmetrical	<= 0.2 mm
Repetition accuracy, gripper	< 0.03 mm
Number of gripper fingers	2
Assembly position	Any
Mode of operation	double-acting
Gripper function	Parallel
Design structure	twin piston
	Guide
	Piston slide
	T-shaped
	Rack and pinion
Position detection	For proximity sensor
Total force at 6 bar, opening	1,038 N
Total force at 6 bar, closing	1,216 N
Working pressure	3 8 bar
Max. operating frequency of gripper	⟨1 Hz
Min. opening time at 6 bar	430 ms
Min. closing time at 6 bar	430 ms
Operating medium	Compressed air in accordance with ISO8573-1:2010 [7:4:4]
Note on operating and pilot medium	Lubricated operation possible (subsequently required for further
, - ,	operation)
Corrosion resistance classification CRC	2
Ambient temperature	5 60 °C
Gripping force per gripper jaw at 6 bar, opening	519 N
Gripping force per gripper jaw at 6 bar, closing	608 N
Mass moment of inertia	118.3 kgcm2
Max. force on gripper jaw Fz static	2,500 N
Max. torque at gripper Mx static	125 Nm
Max. torque at gripper My static	80 Nm
Max. torque at gripper Mz static	100 Nm
Lubrication interval for guide components	5 Mio SP
Max. ground per external gripper finger	420 g
Product weight	4,165 g
Mounting type	Internal thread and centering sleeve
	With through-hole and centering sleeve
Pneumatic connection	M5
Materials note	Free of copper and PTFE
	Conforms to RoHS
Materials information, housing	Aluminum
	Smooth anodized
Materials information for gripper jaws	Steel
	Hardened