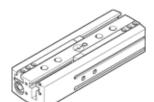
Parallel gripper HGPL-14-60-A Part number: 567821 Product to be discontinued

Type to be discontinued. Available until 2016. See Support Portal for alternative products.







Data sheet

Feature	Value
Size	14
Stroke per gripper jaw	60 mm
Max. replacement accuracy	< 0.2 mm
Max. angular gripper jaw backlash ax,ay	< 0.2 deg
Max. gripper jaw backlash Sz	< 0.05 mm
Rotationally symmetrical	<= 0.2 mm
Repetition accuracy, gripper	< 0.03 mm
Number of gripper fingers	2
Assembly position	Any
Mode of operation	double-acting
Gripper function	Parallel
Design structure	twin piston
	Guide
	Piston slide
	T-shaped
	Rack and pinion
Position detection	For proximity sensor
Total force at 6 bar, opening	126 N
Total force at 6 bar, closing	158 N
Working pressure	3 8 bar
Max. operating frequency of gripper	⟨1 Hz
Min. opening time at 6 bar	270 ms
Min. closing time at 6 bar	230 ms
Operating medium	Compressed air in accordance with ISO8573-1:2010 [7:4:4]
Note on operating and pilot medium	Lubricated operation possible (subsequently required for further
	operation)
Corrosion resistance classification CRC	2
Ambient temperature	5 60 °C
Gripping force per gripper jaw at 6 bar, opening	63 N
Gripping force per gripper jaw at 6 bar, closing	79 N
Mass moment of inertia	11.43 kgcm2
Max. force on gripper jaw Fz static	500 N
Max. torque at gripper Mx static	35 Nm
Max. torque at gripper My static	35 Nm
Max. torque at gripper Mz static	35 Nm
Lubrication interval for guide components	5 Mio SP
Max. ground per external gripper finger	80 g
Product weight	595 g
Mounting type	Internal thread and centering sleeve
	With through-hole and centering sleeve
Pneumatic connection	M5
Materials note	Free of copper and PTFE
	Conforms to RoHS
Materials information, housing	Aluminum
	Smooth anodized
Materials information for gripper jaws	Steel
Materials information for gripper laws	