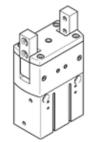
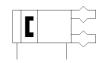
Radial gripper HGRT-40-A Part number: 563912



Data sheet

Feature	Value
Size	40
Max. replacement accuracy	<= 0.2 mm
Max. angular gripper jaw backlash ax,ay	<= 0.1 deg
Max. opening angle	180 deg
Rotationally symmetrical	<= 0.2 mm
Repetition accuracy, gripper	<= 0.02 mm
Number of gripper fingers	2
Assembly position	Any
Mode of operation	double-acting
Gripper function	radial
Design structure	guided motion sequence
Position detection	For proximity sensor
	For inductive sensors
Working pressure	3 8 bar
Max. operating frequency of gripper	<= 2 Hz
Min. opening time at 0.6 MPa (6 bar, 87 psi)	283 ms
Min. closing time at 0.6 MPa (6 bar, 87 psi)	320 ms
Operating medium	Compressed air in accordance with ISO8573-1:2010 [7:4:4]
Note on operating and pilot medium	Lubricated operation possible (subsequently required for further
	operation)
Corrosion resistance classification CRC	1 - Low corrosion stress
PWIS conformity	VDMA24364-B1/B2-L
Ambient temperature	5 60 °C
Total gripping torque at 0.6 MPa (6 bar, 87 psi) opening	3,892 Ncm
Total gripping torque at 0.6 MPa (6 bar, 87 psi) closing	3,526 Ncm
Mass moment of inertia	13.87 kgcm2
Max. force on gripper jaw Fz static	400 N
Max. torque at gripper My static	17.5 Nm
Max. torque at gripper Mz static	1.6 Nm
Lubrication interval for guide components	10 Mio SP
Product weight	1,580 g
Mounting type	Internal thread and centering sleeve
Pneumatic connection	G1/8
Materials note	Conforms to RoHS
Material housing	Smooth-anodised wrought aluminium alloy
Material gripper jaws	Steel, hardened



FESTO