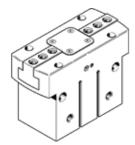
Parallel gripper HGPT-63-A Part number: 535876

sturdy.



Data sheet

Feature	Value
Size	63
Stroke per gripper jaw	16 mm
Max. replacement accuracy	<= 0.2 mm
Max. angular gripper jaw backlash ax,ay	<= 0.1 deg
Max. gripper jaw backlash Sz	<= 0.02 mm
Rotationally symmetrical	<= 0.2 mm
Repetition accuracy, gripper	<= 0.05 mm
Number of gripper fingers	2
Assembly position	Any
Mode of operation	double-acting
Gripper function	Parallel
Design structure	Inclined plane
	guided motion sequence
Position detection	For proximity sensor
Total force at 6 bar, opening	1,650 N
Total force at 6 bar, closing	1,540 N
Working pressure	3 8 bar
Working pressure, sealing air	0 0.5 bar
Max. operating frequency of gripper	<= 2 Hz
Min. opening time at 6 bar	150 ms
Min. closing time at 6 bar	135 ms
Operating medium	Dried compressed air, lubricated or unlubricated
Ambient temperature	5 60 °C
Gripping force per gripper jaw at 6 bar, opening	825 N
Gripping force per gripper jaw at 6 bar, closing	770 N
Mass moment of inertia	74.991 kgcm2
Max. force on gripper jaw Fz static	4,000 N
Max. torque at gripper Mx static	140 Nm
Max. torque at gripper My static	120 Nm
Max. torque at gripper Mz static	80 Nm
Lubrication interval for guide components	5 Mio SP
Product weight	3,633 g
Mounting type	Optional
	With through-hole and dowel pin
	With internal thread and dowel pin
Pneumatic connection, sealing air	M5
Pneumatic connection	G1/8
Materials note	Free of copper and PTFE
Materials information for cover cap	High alloy steel, non-corrosive
Materials information, housing	Aluminum
	COMPCOTE coated
Materials information for gripper jaws	Steel
	Hardened

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