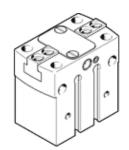
Parallel gripper HGPT-35-A Part number: 535867

sturdy.



Data sheet

Feature	Value
Size	35
Stroke per gripper jaw	8 mm
Max. replacement accuracy	<= 0.2 mm
Max. angular gripper jaw backlash ax,ay	<= 0.1 deg
Max. gripper jaw backlash Sz	<= 0.02 mm
Rotationally symmetrical	<= 0.2 mm
Repetition accuracy, gripper	<= 0.05 mm
Number of gripper fingers	2
Assembly position	Any
Mode of operation	double-acting
Gripper function	Parallel
Design structure	Inclined plane
	guided motion sequence
Position detection	For proximity sensor
Total force at 6 bar, opening	500 N
Total force at 6 bar, closing	460 N
Working pressure	3 8 bar
Working pressure, sealing air	0 0.5 bar
Max. operating frequency of gripper	<= 3 Hz
Min. opening time at 6 bar	40 ms
Min. closing time at 6 bar	40 ms
Operating medium	Dried compressed air, lubricated or unlubricated
Ambient temperature	5 60 °C
Gripping force per gripper jaw at 6 bar, opening	250 N
Gripping force per gripper jaw at 6 bar, closing	230 N
Mass moment of inertia	3.383 kgcm2
Max. force on gripper jaw Fz static	900 N
Max. torque at gripper Mx static	50 Nm
Max. torque at gripper My static	40 Nm
Max. torque at gripper Mz static	30 Nm
Lubrication interval for guide components	5 Mio SP
Product weight	625 g
Mounting type	Optional
	With through-hole and dowel pin
	With internal thread and dowel pin
Pneumatic connection, sealing air	M5
Pneumatic connection	M5
Materials note	Free of copper and PTFE
Materials information for cover cap	High alloy steel, non-corrosive
Materials information, housing	Aluminum
	COMPCOTE coated
Materials information for gripper jaws	Steel
	Hardened

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