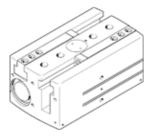
Parallel gripper HGPL-63-100-A-B Part number: 3361493







Data sheet

Feature	Value
Size	63
Stroke per gripper jaw	100 mm
Max. replacement accuracy	< 0.2 mm
Max. angular gripper jaw backlash ax,ay	< 0.2 deg
Max. gripper jaw backlash Sz	< 0.05 mm
Rotationally symmetrical	<= 0.2 mm
Repetition accuracy, gripper	< 0.03 mm
Number of gripper fingers	2
Drive system	pneumatic
Assembly position	Any
Mode of operation	double-acting
Gripper function	Parallel
Gripper force back-up	No
Design structure	twin piston
	Guide
	Piston slide
	T-shaped
	Rack and pinion
Position detection	For proximity sensor
Total gripping force at 0.6 MPa (6 bar, 87 psi), opening	2,466 N
Total gripping force at 0.6 MPa (6 bar, 87 psi), closing	2,742 N
Working pressure	3 8 bar
Max. operating frequency of gripper	(1 Hz
Min. opening time at 0.6 MPa (6 bar, 87 psi)	650 ms
Min. closing time at 0.6 MPa (6 bar, 87 psi)	600 ms
Max. mass per external gripper finger	940 g
Operating medium	Compressed air in accordance with ISO8573-1:2010 [7:4:4]
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Note on operating and pilot medium	Lubricated operation possible (subsequently required for further operation)
Corrosion resistance classification CRC	2 - Moderate corrosion stress
PWIS conformity	VDMA24364-B1/B2-L
Ambient temperature	5 60 °C
Gripping force per gripper jaw at 0.6 MPa (6 bar, 87 psi) opening	1,233 N
Gripping force per gripper jaw at 0.6 MPa (6 bar, 87 psi) closing	1,371 N
Mass moment of inertia	1,018.17 kgcm2
Max. force on gripper jaw Fz static	9,000 N
Max. torque at gripper Mx static	300 Nm
Max. torque at gripper My static	200 Nm
Max. torque at gripper Mz static	250 Nm
Lubrication interval for guide components	5 Mio SP
Product weight	13,800 g
Mounting type	Internal thread and centering sleeve
	With through-hole and centering sleeve
Pneumatic connection	G1/8
Materials note	Conforms to RoHS
Material housing	Smooth-anodised wrought aluminium alloy
Material gripper jaws	Steel, hardened