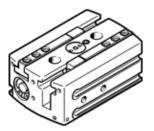
Parallel gripper HGPL-14-20-A-B Part number: 3361479 ★ Core product range







Data sheet

Feature	Value
Size	14
Stroke per gripper jaw	20 mm
Max. replacement accuracy	< 0.2 mm
Max. angular gripper jaw backlash ax,ay	< 0.2 deg
Max. gripper jaw backlash Sz	< 0.05 mm
Rotationally symmetrical	<= 0.2 mm
Repetition accuracy, gripper	< 0.03 mm
Number of gripper fingers	2
Drive system	pneumatic
Assembly position	Any
Mode of operation	double-acting
Gripper function	Parallel
Gripper force back-up	No
Design structure	twin piston
	Guide
	Piston slide
	T-shaped
	Rack and pinion
Position detection	For proximity sensor
Total gripping force at 0.6 MPa (6 bar, 87 psi), opening	126 N
Total gripping force at 0.6 MPa (6 bar, 87 psi), closing	158 N
Working pressure	3 8 bar
Max. operating frequency of gripper	⟨1 Hz
Min. opening time at 0.6 MPa (6 bar, 87 psi)	120 ms
Min. closing time at 0.6 MPa (6 bar, 87 psi)	110 ms
Max. mass per external gripper finger	80 g
Operating medium	Compressed air in accordance with ISO8573-1:2010 [7:4:4]
Note on operating and pilot medium	Lubricated operation possible (subsequently required for further
	operation)
Corrosion resistance classification CRC	2 - Moderate corrosion stress
PWIS conformity	VDMA24364-B1/B2-L
Ambient temperature	5 60 °C
Gripping force per gripper jaw at 0.6 MPa (6 bar, 87 psi) opening	63 N
Gripping force per gripper jaw at 0.6 MPa (6 bar, 87 psi) closing	79 N
Mass moment of inertia	1.4 kgcm2
Max. force on gripper jaw Fz static	500 N
Max. torque at gripper Mx static	35 Nm
Max. torque at gripper My static	35 Nm
Max. torque at gripper Mz static	35 Nm
Lubrication interval for guide components	5 Mio SP
Product weight	305 g
Mounting type	Internal thread and centering sleeve
	With through-hole and centering sleeve
Pneumatic connection	M5
Materials note	Conforms to RoHS
Material housing	Smooth-anodised wrought aluminium alloy
Material gripper jaws	Steel, hardened