servo drive CMMT-ST-C8-1C-MP-S0 Part number: 8163946 Core product range





Data sheet

Feature	Value
Mounting type	Mounting plate, bolted
	with top-hat rail
Assembly position	Free convection
	Vertical
Product weight	350 g
Display	LED green/yellow/red
Authorisation	RCM Mark
	c UL us - Listed (OL)
KC mark	KC-EMV
CE mark (see declaration of conformity)	to EU directive for EMC
	to EU directive for machinery
	in accordance with EU RoHS directive
UKCA marking (see declaration of conformity)	To UK instructions for EMC
	To UK instructions for machines
	To UK RoHS instructions
Certificate issuing department	TÜV Rheinland 01/205/5696.00/19
	TÜV Rh. UK 01/205U/5696.00/22
	UL E331130
Storage temperature	-25 55 °C
Ambient temperature	0 50 °C
Note on ambient temperature	Observe derating with regard to mounting clearance and output current
Relative air humidity	5 - 90 %
	non-condensing
Max. installation height	2,000 m
Protection class	IP20
Safety class	
Overvoltage category	
Degree of contamination	2
Materials note	Conforms to RoHS
PWIS conformity	VDMA24364 zone III
Nominal voltage, load supply DC	24 48 V
Permissible range, load supply	-15 % / +15 %
Max. intermediate circuit voltage, DC	
Braking resistor, external	6 Ohm
Max. continuous output of the external braking resistor (IEC)	490 W
Nominal DC voltage, logic power supply Permissible range, logic voltage	24 V
Current consumption, logic power supply without clamping brake	± 15 %
Current consumption, logic power supply without clamping brake	2 A
Output voltage range AC	0 V up to input voltage
Nominal output current	8 A
Effective nominal current per phase	8 A
Effective peak current per phase	20 A
Max. peak current duration	3 s
Nominal controller power	300 W
Peak power	800 W
I can power	1000 AA



Feature	Value
Output frequency	> 600 Hz
Max. length of motor cable without external mains filter	25 m
Max. output current of holding brake	1 A
Max. voltage drop from logic supply to brake output	1 V
Controller operating mode	Cascade controller
	P position controller
	PI speed controller
	PI current regulator for F or M
	Profile operation with record and direct mode
	Interpolated mode via fieldbus
	Synchronised operating modes
	Homing
	Setting-up
	Autotuning
Operating mode	Open-loop operation Field-oriented closed-loop control
Operating mode	Position resolution 24 bit/U
	Real-time data acquisition
	2x Input-Capture (x, v, F)
	2x Output-Trigger (x, v, F)
	1x position sensor input
	Sampling rate 16 or 20 kHz
	PWM with 16 or 20 KHz
Adjustable current reduction	Using software
Protective function	12t monitoring
	Temperature monitoring
	Current monitoring
	Voltage failure detection
	Drag error monitoring
	Software end-position detection
Nominal current adjustment	Using software
Ethernet interface, function	Parameterisation and commissioning
Ethernet interface, protocol	TCP/IP
Fieldbus interface, protocol	EtherCAT
	EtherNet/IP
	PROFINET IRT
Fieldbus coupling	EtherCAT
	EtherNet/IP
	Modbus/TCP
	PROFINET
Communications profile	CiA402
	CoE (CANopen over EtherCAT)
	EoE (Ethernet over EtherCAT) FoE (File over EtherCAT)
	PROFIdrive
Process interface	I/O mode for 256 position sets
Process interface	Interpolated Mode CSP
	Interpolated Mode CST
	Interpolated Mode CSV
Fieldbus interface, transmission rate	100 Mbit/s
Fieldbus interface, type of connection	2x socket
Fieldbus interface, connection technology	RJ45
Encoder interface, function	BiSS-C
	Incremental encoder
Number of digital logic inputs	6
Input circuit logic	PNP (positive-switching)
Logic input characteristics	Freely configurable to a given extent
	Safety inputs in some cases
	Not electrically isolated
Specification, logic input	Based on IEC 61131-2, type 3
Logic input working range	-3 30 V



Feature	Value
Number of high-speed logic inputs	2
Time resolution of high-speed logic inputs	1 µs
Number of 24 V DC digital logic outputs	2
Switching logic, outputs	PNP (positive-switching)
Digital logic output characteristics	Not electrically isolated
Max. current, digital logic outputs	100 mA
Number of high-speed switching outputs	2
Time resolution of high-speed switching outputs	1 μs
Number of floating switching outputs	1
Max. current of the floating switching outputs	100 mA
Safety function	Safe torque off (STO)
	Safe stop 1 (SS1-time controlled)
Safety Integrity Level (SIL)	STO / SIL 2 / SILCL 2 (EC motor without diagnostics)
	STO / SIL 3 / SILCL 3 (stepper motor/EC motor with diagnostics)
Performance level (PL)	STO / cat. 3 PLd (EC motor without diagnostics)
	STO / cat. 3, PLe (stepper motor/EC motor with diagnostics)
Diagnostic coverage	STO / medium (EC motor with diagnostics)
	STO / medium (stepper motor)
	STO / low (EC motor without diagnostics)
SFF Safe Failure Fraction	99 %
Hardware fault tolerance	1
Proof test interval	STO / 20 a (stepper motor/EC motor without diagnostics)
	STO / 0.25 a (EC motor with diagnostics)
Number of safe 2-pin inputs	1
Number of diagnostic outputs	1