adaptive shape gripper kit for robots DHEF-20-A-RA1 Part number: 8119114

FESTO

Other stroke lengths on request. Available only in standard stroke lengths 5, 10, 15, 20, 25, 30 mm.





Data sheet

Feature	Value
Size	20
Inverting cap version	Standard
Stroke	66 mm
Min. diameter to be gripped	12 mm
Max. diameter to be gripped	38 mm
Drive system	pneumatic
Assembly position	Any
Mode of operation	double-acting
Gripper function	Adaptive
Design structure	Inverting cap
Design structure	guided motion sequence
Guide	Basic guide
Position detection	For proximity sensor
Operating pressure, ball valve drive	1 8 bar
Operating pressure of cap	0.07 0.1 bar
Burst pressure of cap	0.3 bar
Max. operating frequency of gripper	1 Hz
Return-stroke time	290 ms
Advancing time	270 ms
Operating medium	Compressed air in accordance with ISO8573-1:2010 [7:4:4]
Note on operating and pilot medium	Lubricated operation not possible
Corrosion resistance classification CRC	2 - Moderate corrosion stress
PWIS conformity	VDMA24364 zone III
Ambient temperature	0 60 °C
Mass moment of inertia	1.29 kgcm2
Effective load reference value	1 kg
Product weight	475 g
Mounting type	To ISO 9409
Pneumatic connection	M5
Materials note	Conforms to RoHS
Material cap	VMQ (silicon)
Material housing	Anodised aluminium
Robot connection	Universal robots UR3/5/10 (PolyScope CB 3.8.0 or higher)
	Universal robots UR3e/5e/10e (PolyScope SW 5.0.0 or higher)
Accessories included	1x Velcro® roll
	1x solenoid valve
	1x proportional-pressure regulator
	1x USB-Stick mit URCap
	2x proximity switch
	3x connecting cable