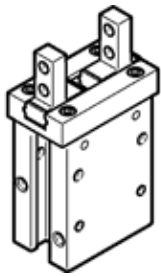


parallel gripper DHPC-10-A-NO-S

Part number: 8116759

FESTO



Data sheet

Feature	Value
Size	10
Stroke per gripper jaw	2 mm
Max. replacement accuracy	0.2 mm
Max. angular gripper jaw backlash ax,ay	0 deg
Max. gripper jaw backlash Sz	0 mm
Rotationally symmetrical	≤ 0.2 mm
Repetition accuracy, gripper	≤ 0.02 mm
Number of gripper fingers	2
Drive system	pneumatic
Assembly position	Any
Mode of operation	single-acting open
Gripper function	Parallel
Gripper force back-up	On opening
Design structure	Connection direction on the side Lever Standard mounting of gripper fingers guided motion sequence
Guide	Ball guide
Position detection	For proximity sensor
Variants	Recommended for production facilities for the manufacture of lithium-ion batteries
Total gripping force at 0.6 MPa (6 bar, 87 psi), closing	32.8 N
Operating pressure MPa	0.35 ... 0.8 MPa
Operating pressure	3.5 ... 8 bar 50.75 ... 116 psi
Max. operating frequency of gripper	3 Hz
Min. opening time at 0.6 MPa (6 bar, 87 psi)	28 ms
Min. closing time at 0.6 MPa (6 bar, 87 psi)	26 ms
Operating medium	Compressed air in accordance with ISO8573-1:2010 [7:4:4]
Note on operating and pilot medium	Lubricated operation possible (subsequently required for further operation)
Corrosion resistance classification CRC	0 - No corrosion stress
PWIS conformity	VDMA24364-B2-L
RSBP classification to CD-0033	F1a
Ambient temperature	-10 ... 60 °C
Gripping force per gripper jaw at 0.6 MPa (6 bar, 87 psi) closing	16.4 N
Mass moment of inertia	0.045 kgcm ²
Max. force on gripper jaw Fz static	29 N
Max. torque at gripper Mx static	0.13 Nm
Max. torque at gripper My static	0.27 Nm
Max. torque at gripper Mz static	0.13 Nm
Product weight	57 g
Mounting type	Direct mounting via through-holes Direct mounting via threads With through-hole and dowel pin

Feature	Value
	With internal thread and dowel pin Optional
Pneumatic connection	M3
Materials note	Conforms to RoHS
Material housing	Anodised aluminium
Material gripper jaws	High alloy steel, non-corrosive