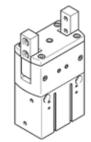
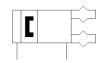
radial gripper HGRT-40-A Part number: 563912



Data sheet

| Feature | Value |
|--|--|
| Size | 40 |
| Max. replacement accuracy | <= 0.2 mm |
| Max. angular gripper jaw backlash ax,ay | <= 0.1 deg |
| Max. opening angle | 180 deg |
| Rotationally symmetrical | <= 0.2 mm |
| Repetition accuracy, gripper | <= 0.02 mm |
| Number of gripper fingers | 2 |
| Assembly position | Any |
| Mode of operation | double-acting |
| Gripper function | radial |
| Design structure | guided motion sequence |
| Position detection | For proximity sensor |
| | For inductive sensors |
| Operating pressure | 3 8 bar |
| Max. operating frequency of gripper | <= 2 Hz |
| Min. opening time at 0.6 MPa (6 bar, 87 psi) | 283 ms |
| Min. closing time at 0.6 MPa (6 bar, 87 psi) | 320 ms |
| Operating medium | Compressed air in accordance with ISO8573-1:2010 [7:4:4] |
| Note on operating and pilot medium | Lubricated operation possible (subsequently required for further |
| | operation) |
| Corrosion resistance classification CRC | 1 - Low corrosion stress |
| PWIS conformity | VDMA24364-B1/B2-L |
| Ambient temperature | 5 60 °C |
| Total gripping torque at 0.6 MPa (6 bar, 87 psi) opening | 3,892 Ncm |
| Total gripping torque at 0.6 MPa (6 bar, 87 psi) closing | 3,526 Ncm |
| Mass moment of inertia | 13.87 kgcm2 |
| Max. force on gripper jaw Fz static | 400 N |
| Max. torque at gripper My static | 17.5 Nm |
| Max. torque at gripper Mz static | 1.6 Nm |
| Lubrication interval for guide components | 10 Mio SP |
| Product weight | 1,580 g |
| Mounting type | Internal thread and centring sleeve |
| Pneumatic connection | G1/8 |
| Materials note | Conforms to RoHS |
| Material housing | Smooth-anodised wrought aluminium alloy |
| Material gripper jaws | Steel, hardened |



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