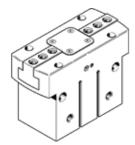
Parallel gripper HGPT-50-A Part number: 535873

sturdy.



Data sheet

Feature	Value	
Size	50	
Stroke per gripper jaw	12 mm	
Max. replacement accuracy	<= 0.2 mm	
Max. angular gripper jaw backlash ax,ay	<= 0.1 deg	
Max. gripper jaw backlash Sz	<= 0.02 mm	
Rotationally symmetrical	<= 0.2 mm	
Repetition accuracy, gripper	<= 0.05 mm	
Number of gripper fingers	2	
Assembly position	Any	
Mode of operation	double-acting	
Gripper function	Parallel	
Design structure	Inclined plane	
	guided motion sequence	
Position detection	For proximity sensor	
Total force at 6 bar, opening	960 N	
Total force at 6 bar, closing	880 N	
Operating pressure	3 8 bar	
Operating pressure, sealing air	0 0.5 bar	
Max. operating frequency of gripper	<= 2 Hz	
Min. opening time at 6 bar	85 ms	
Min. closing time at 6 bar	76 ms	
Operating medium	Dried compressed air, lubricated or unlubricated	
Ambient temperature	5 60 °C	
Gripping force per gripper jaw at 6 bar, opening	480 N	
Gripping force per gripper jaw at 6 bar, closing	440 N	
Mass moment of inertia	25.147 kgcm2	
Max. force on gripper jaw Fz static	2,500 N	
Max. torque at gripper Mx static	100 Nm	
Max. torque at gripper My static	90 Nm	
Max. torque at gripper Mz static	60 Nm	
Lubrication interval for guide components	5 Mio SP	
Product weight	1,984 g	
Mounting type	Optional	
	With through-hole and dowel pin	
	With internal thread and dowel pin	
Pneumatic connection, sealing air	M5	
Pneumatic connection	G1/8	
Materials note	Free of copper and PTFE	
Materials information for cover cap	High alloy steel, non-corrosive	
Materials information, housing	Aluminium	
	COMPCOTE coated	
Materials information for gripper jaws	Steel	
	Hardened	



