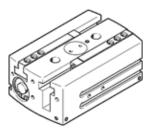
## parallel gripper HGPL-25-40-A-B Part number: 3361484 ★ Core product range







## **Data sheet**

Feature	Value
Size	25
Stroke per gripper jaw	40 mm
Max. replacement accuracy	< 0.2 mm
Max. angular gripper jaw backlash ax,ay	< 0.2 deg
Max. gripper jaw backlash Sz	< 0.05 mm
Rotationally symmetrical	<= 0.2 mm
Repetition accuracy, gripper	< 0.03 mm
Number of gripper fingers	2
Drive system	pneumatic
Assembly position	Any
Mode of operation	double-acting
Gripper function	Parallel
Gripper force back-up	No
Design structure	twin piston
	Guide
	Piston slide
	T-shaped
	Rack and pinion
Position detection	For proximity sensor
Total gripping force at 0.6 MPa (6 bar, 87 psi), opening	412 N
Total gripping force at 0.6 MPa (6 bar, 87 psi), closing	512 N
Operating pressure	3 8 bar
Max. operating frequency of gripper	⟨1 Hz
Min. opening time at 0.6 MPa (6 bar, 87 psi)	225 ms
Min. closing time at 0.6 MPa (6 bar, 87 psi)	230 ms
Max. mass per external gripper finger	250 g
Operating medium	Compressed air in accordance with ISO8573-1:2010 [7:4:4]
Note on operating and pilot medium	Lubricated operation possible (subsequently required for further
	operation)
Corrosion resistance classification CRC	2 - Moderate corrosion stress
PWIS conformity	VDMA24364-B1/B2-L
Ambient temperature	5 60 °C
Gripping force per gripper jaw at 0.6 MPa (6 bar, 87 psi) opening	206 N
Gripping force per gripper jaw at 0.6 MPa (6 bar, 87 psi) closing	256 N
Mass moment of inertia	18.88 kgcm2
Max. force on gripper jaw Fz static	1,500 N
Max. torque at gripper Mx static	100 Nm
Max. torque at gripper My static	60 Nm
Max. torque at gripper Mz static	70 Nm
Lubrication interval for guide components	5 Mio SP
Product weight	1,400 g
Mounting type	Internal thread and centring sleeve
	With through-hole and centring sleeve
Pneumatic connection	M5
Materials note	Conforms to RoHS
Material housing	Smooth-anodised wrought aluminium alloy
Material gripper jaws	Steel, hardened